

fs_planner.FSPlanner.isEdgeFree



```
graph LR; A[fs_planner.FSPlanner.isEdgeFree] --> B[fs_planner.FSPlanner._los_key]
```

A diagram showing a call from the `isEdgeFree` method to the `_los_key` attribute. The `isEdgeFree` box is shaded gray, and the `_los_key` box is white. A blue arrow points from the right side of the `isEdgeFree` box to the left side of the `_los_key` box.

fs_planner.FSPlanner.
_los_key