

cbf_rrt.CBFRRT.getNearestNode

rrt.RRT.getNearestNode

rrt.RRT.dist

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graph LR; A[cbf_rrt.CBFRRT.getNearestNode] --> C[rrt.RRT.dist]; B[rrt.RRT.getNearestNode] --> C;
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The diagram illustrates a dependency or assignment relationship. Two source nodes, 'cbf_rrt.CBFRRT.getNearestNode' and 'rrt.RRT.getNearestNode', are shown in white boxes on the left. Two blue arrows originate from these boxes and point towards a target node, 'rrt.RRT.dist', which is shown in a gray box on the right. This suggests that the value of 'rrt.RRT.dist' is determined by the outputs of these two functions.