# UGP Presentation

# Local Envy Free Allocation in Network Graph Setting

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- We will consider the setting in which agents are present in a connected network graph.
- We also assume that agents have a limited information, i.e, they can get the info for only those agents who are directly connected to them.
- Our aim in this presentation is to find the fair allocation for this setting.

# Literature Review

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#### Literature Review

- We focus on the problem DEC-LEF: to find out whether the local-envy free allocation exists or not?
- It is known that even for sparse graphs, and for regular graphs of degree n-3 the problem of determining the existence of local envy-free allocations is NP-hard.
- We showed that if we restrict the agents domain to Single Peak and even less strict domain like local-Single Peak there is an efficient procedure to determine the existence of a local envy-free allocation.

### Previous Results

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- DEC-LEF is polynomial for regular graphs with degree at least n-2.
- DEC-LEF is NP-hard even for regular graphs with degree n-3. The proof of this result is through reduction from 3(2B)-SAT.

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  - (1)  $a \triangleright b \triangleright o^* \rightarrow b \succ_i a$
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- Locally single peaked with fixed ordering: The problem e is locally single peaked with fixed ordering if there exists an ordering  $\triangleright$  over the objects O such that  $\forall i \in N$ , the set  $N_i$  is single peaked with respect to  $\triangleright$ .

### Problem Statement

• **Problem:** Given a regular graph G = (N,E) with each vertex degree = n-k and the preference profile is single peaked, then we have to return the local envy free allocation(if exists), otherwise return no, i.e. no such allocation exists.

# Problem Statement

- **Problem:** Given a regular graph G = (N,E) with each vertex degree = n-k and the preference profile is single peaked, then we have to return the local envy free allocation(if exists), otherwise return no, i.e. no such allocation exists.
- We will describe the algorithm that will solve this problem in O(n) time where n = |N|.

### Observations

• Since the degree of each vertex is n-k, then an agent is **local envy free** only if he gets an object from his **top k preferences**.

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  Therefore, we will focus only on the top k preferred objects of each agent.
- Since the profile is **single peaked**, lets say over ▷. Then the top k preferred objects of each agent forms an interval in the ordering ▷ over the objects.

• Without loss of generality, assume that  $\triangleright$  is  $o_1, o_2, o_3, ...o_n$ , and agents are single peaked over this  $\triangleright$ .

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- Let  $r_i(j)$  denotes the  $j^{th}$  preferred(ranked) object by agent i. So,  $r_i(1), r_i(2), r_i(3)$  denotes the first, second and third preferred object of the agent i respectively.

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- Let  $p_i$  denotes the position of the leftmost positioned object among the  $r_i(1), r_i(2), r_i(3), ..., r_i(k)$  objects in the ordering  $\triangleright$ . So, objects at  $p_i, p_i + 1, p_i + 2, ..., p_i + k 1$  will denote the positions of top-k preferred objects.

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- Let  $a_1, a_2, a_3, ... a_n$  denotes the agents. We define A(i) agents at position i, as the set of agents such that  $\{a_j|p_j=i\}$ . Therefore, the number of agents at position i is |A(i)|.

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- We denote **stage** i as the point when agents in  $A(1) \cup A(2) \cup A(3) ... \cup A(i)$  gets the envy free allocation.

• if |A(i)| > k, then there doesn't exist any envy free allocation. Since, all the agents in A(i) needs the objects from  $o_i, o_{i+1}, o_{i+2}, ... o_{i+k-1}$ , and by pigeon hole principal at least one agent will not receive the object.

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- If we find the envy free allocation for the agents in  $A(1) \cup A(2) \cup A(3) \cup ... \cup A(i)$ , then the agents in  $A(1) \cup A(2) \cup ... + A(i) = A(i)$  are always local envy-free because for any extension of this allocation all the other agents get the object of lower preference than their own.

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- The agents A(i) can't be envy to other agent for the objects at position 1, 2, ..., i-1. Hence, agents in  $A(i+1) \cup A(i+2)... \cup A(n)$  will care only for the objects  $o_i$  onwards.

Continued ...

• From previous 2 arguments, we can say that given the allocation of agents A(i-k+2), A(i-k+3), ... A(i-1), A(i) all the possible local envy free allocation of  $A(1) \cup A(2) \cup A(3) \cup ... \cup A(i)$  comes in the same equivalence class. Hence, no of equivalence class  $< k^{k-1}$  at each stage.

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- This is the crux of our incremental algorithm that number of equivalent class at each stage is independent of n.

# Algorithm ...

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- Shift from stage i to stage i+1: Given the equivalent classes at stage i, we need to find the equivalent classes at stage i+1. For a given stage-i equivalent class, to find the stage i+1 equivalence class, we just need to try all the ways of assigning objects to agents in A(i+1) which is < k!. Hence time complexity to shift stage  $< k^{k-1} * k!$ .

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- Total time complexity is the time to reach the stage-n starting from stage-2 and repeated using the previous step. Hence, overall time complexity  $< nk^{k-1}k!$ .

### Conclusion

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- We can also extend this result for the graphs whose minimum degree is n-k when the agents profile is single peaked.
- We can also extend this result for the graphs when the minimum degree is n-k but the agents profile preference is local single peaked(less stricter than single peaked).