

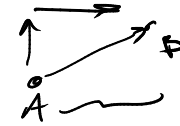
Contexto de la Mecánica

24/04/21

→ Físico-Matemático

→ Modelos → limitaciones
→ Hipótesis

Vectorial \vec{F}



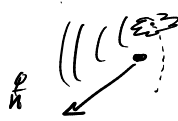
→ • Tiempo.

→ • Espacio

• Cinco postulados de Euclides → 5^{to} líneas paralelas

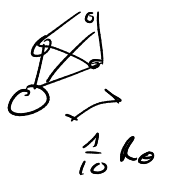
En la Física Clásica

Tiempo → Absoluto



→ Geometría Lineal
5^{to} Sem.

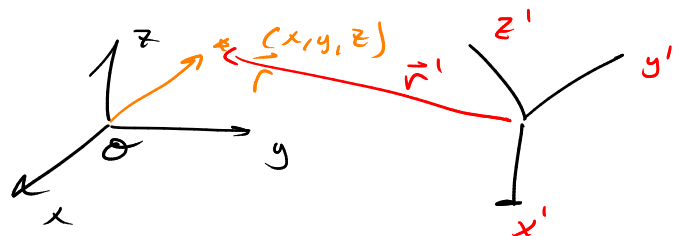
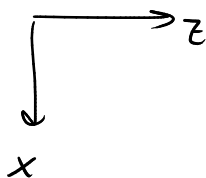
Parámetro El mismo para todos → $t = t'$



Espacio → Absoluto → Sistema de referencia

Plano

S'



\mathbb{R}^3

\mathbb{R}^3

\mathbb{R}^3

$\mathbb{R}^3 \rightarrow (x, y, z)$

$\hookrightarrow \mathbb{E}^3$

Metodología

→

Hipótesis

↓

Mecánica / Eléctrico / Térmico

↓

Ecuaciones de movimiento + Condiciones iniciales

↓

Corroboración

Dimensiones y unidades

↓
Magnitud
"Sentido físico"
"ordenamental"

↓
Medidas relativas
para poder
comparar.

↓
"Etiqueta"

T → tiempo
[s]
[h]
[días]

D → distancias
[m], [km]
[m], [ft]

$$V = \frac{\Delta x}{\Delta t} \rightarrow \Delta x = \boxed{V} \Delta t$$

$$\rightarrow V_{\square} \sim 95 \text{ km/hr}$$

$$\rightarrow V_{\square} \sim 115 \text{ km/hr}$$

$$\rightarrow V \gg V_{\square}$$

4 hrs on autobus?

3 hr → coche

30 min → avión

$$\rightarrow 8 \text{ mmols } l_3 \rightarrow C = 3 \cdot 10^5 \text{ km/s}$$

$$\Delta t \rightarrow 8 \text{ min} \quad \Delta x = C \cdot \Delta t$$



$$\rightarrow \text{CFE} \rightarrow 30 \text{ f} \rightarrow 506 \text{ Wh} \rightarrow l_3$$

$$\frac{\text{J}}{\text{s}} = W \rightarrow \frac{\text{Energía}}{\text{tiempo}} \text{ Potencia}$$

$$500 \text{ Wh} = 500 \left[\frac{\text{J}}{\text{s}} \cdot h \right] \quad h = 60 \text{ s} \quad \boxed{3000 \text{ J}}$$

$$\boxed{W \cdot h} \sim \frac{\text{E}}{\text{J}}$$

¿Qué son las unidades compuestas, "ordenamentales"?

$$\boxed{m, s, kg} \rightarrow \boxed{[L, T, M]}$$

$$N = \frac{\text{kg} \cdot \text{m}}{\text{s}^2}$$

$$J = N \cdot m = \text{kg} \left(\frac{\text{m}}{\text{s}} \right)^2$$

$$100 \rightarrow \boxed{M, T, L} \quad \underline{g}$$

$$SI \begin{cases} \rightarrow M \\ \rightarrow T \\ \rightarrow L \\ \rightarrow C \end{cases}$$

$$g \rightarrow \boxed{C} \rightarrow \text{vem} \quad \underline{emu}$$

$$\boxed{SI} \quad \text{Unidades naturais} \quad \boxed{h, c, G} = 1$$

$\downarrow \quad \quad \quad \uparrow$
 $10^{-34} \text{ Js} \quad \quad 10^6$

$$\boxed{C=1} \rightarrow \text{8 me}$$

$$\underline{\text{Converte}} \rightarrow A \rightarrow I = \frac{\Delta \omega}{\Delta t} = \boxed{\frac{C}{s}}$$

Converte
Temperatura
metros

$$\Delta x = c \Delta t$$

$$\boxed{\Delta x = \Delta t}$$

$$V = \frac{c}{10} = \frac{1}{10}$$

$$N \rightarrow \frac{\text{kg m}}{\text{s}^2} \quad \text{cgs} \quad \text{dias} \quad \underline{10 \text{ dias} = 1N}$$

$$J = Nm = \frac{\text{kg m}^2 \cdot \text{cm}}{10}$$

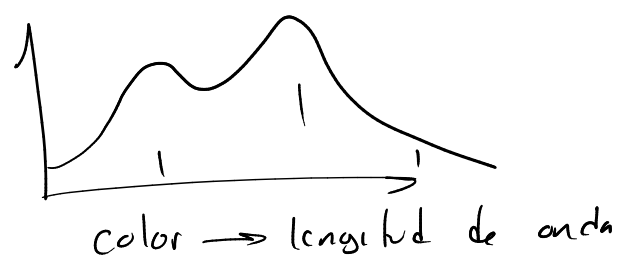
$$F = \frac{1}{k} \frac{q_1 q_2}{r^2} \quad k=1$$

$$F = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{m^2}$$

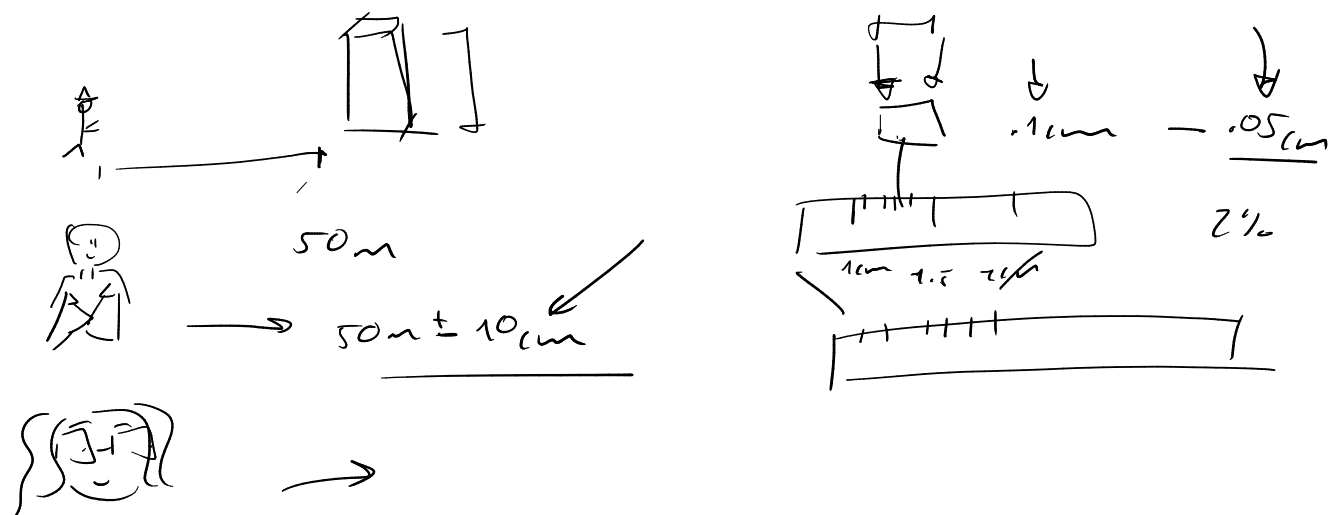
$$\left[\frac{\text{kg m}}{\text{s}^2} \right] = \frac{(\text{emu})^2}{m^2}$$

$$\text{emu} = \frac{\text{kg m}^{3/2}}{\text{s}}$$

$$\frac{c^2}{m^2 [\epsilon_0]} = N$$



Medición \rightarrow Errores o incertidumbres.



$$X = X_0 \pm \delta X_0 \rightarrow 2X_0 \pm 2\delta X_0$$

$$y = y_0 + \delta y_0 \rightarrow x+y = (x_0 \pm \delta x_0) + (y_0 \pm \delta y_0)$$

$$= (x_0 + y_0) \pm (\delta x_0 + \delta y_0)$$

$$x-y = (x-y) + (x)(\pm \delta y) + (y)(\pm \delta x) + (\delta x)(\delta y)$$

$$= (x-y) \pm (x\delta y + y\delta x)$$

$$\frac{x}{y} = \left[x \cdot y^{-1} \right]$$

$$\frac{1}{y} = \frac{1}{y \pm \delta y} \cdot \frac{y \pm \delta y}{y \pm \delta y}$$

$$= \frac{y \pm \delta y}{y^2 \pm 2y\delta y}$$

$$x \cdot y^{-1} = x \cdot y^{-1} \pm (x\delta y^{-1} + y^{-1}\delta x)$$

$$= \frac{x}{y} \pm \left(\frac{x\delta y}{y^2} + \frac{\delta x}{y} \frac{y}{y} \right) = \frac{x}{y} \pm \frac{\delta y}{y^2} \pm \frac{\delta x}{y}$$

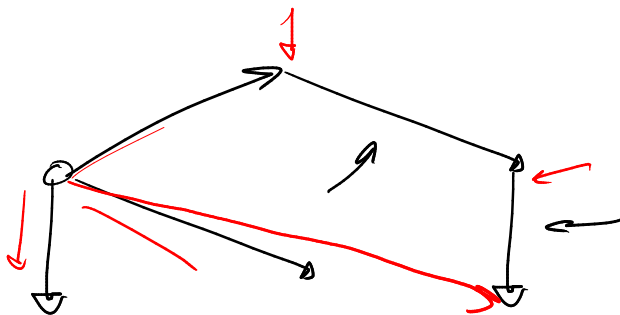
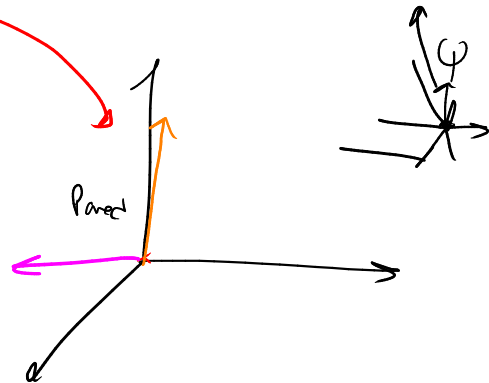
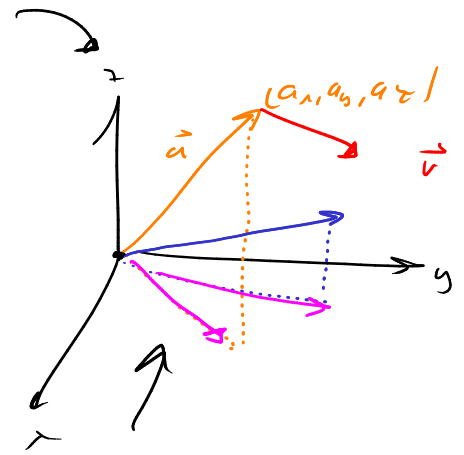
$$= \frac{x}{y} \pm \left(\frac{x\delta y + y\delta x}{y^2} \right) = \frac{x}{y} \pm \frac{\delta y}{y^2}$$

$$(x, y, z) = \vec{r} = x \hat{e}_x + y \hat{e}_y + z \hat{e}_z$$

$$\vec{a} = a_x \hat{e}_x + a_y \hat{e}_y + a_z \hat{e}_z$$

$$\vec{b} = b_x \hat{e}_x + b_y \hat{e}_y + b_z \hat{e}_z$$

$$c = c_x \hat{e}_x + c_y \hat{e}_y + c_z \hat{e}_z$$



$$\vec{c} = (a_x + b_x + c_x) \hat{e}_x + \dots$$

$$\vec{a} \cdot \vec{v}$$



$$\bullet : V \times V \rightarrow C$$

Producto punto

↳ Proyecciones.

$$\vec{a}, \vec{b} \rightarrow \vec{a} \cdot \vec{b} = \lambda$$

$$\vec{a} \cdot \vec{b} = (a_x b_x + a_y b_y + a_z b_z)$$

$$= |\vec{a}| |\vec{b}| \cos \theta$$

