

Momento lineal

$$\vec{p} = m\vec{v} \rightarrow \text{velocidad}$$

↪ masa

Sistema
ley

$$\vec{F} = \frac{d\vec{p}}{dt} = \frac{d}{dt} \sum \vec{p}_i$$

$$\vec{F} = \frac{d\vec{p}}{dt}$$

1 partícula → N partículas
↪ 1 cuerpo físico

$$\vec{F}_{ext} = \sum_i \vec{F}_i^{ext} = \sum_i \vec{F}_{ij} = \sum_i \frac{d}{dt} \vec{p}_i = \frac{d}{dt} \left(\sum_i \vec{p}_i \right)$$

↪ $\vec{F}_{ij} = \vec{F}_{ji}$

$$\vec{r}_i = \sum m_i \vec{r}_i = \vec{P}_i$$

$$\vec{F}_i = \frac{d\vec{p}_i}{dt} = \sum m_i \frac{d\vec{r}_i}{dt}$$

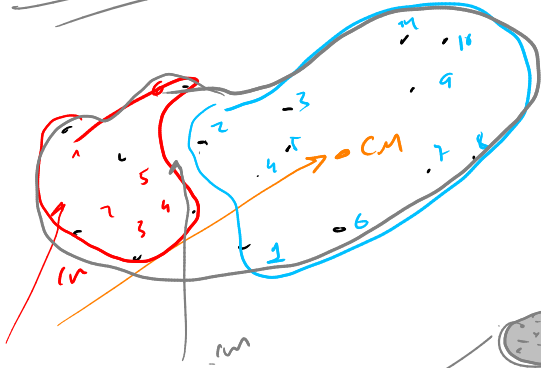
↪ $\vec{F}_i = \vec{F}_i^{ext} + \vec{F}_i^{int}$

$$\sum_{j=1}^N \vec{F}_{ij} = \vec{F}_{i1} + \vec{F}_{i2} + \dots + \vec{F}_{iN}$$

Sist. N partículas

CM → Partícula puntual

$$\vec{R}_{CM} = \frac{\sum m_i \vec{r}_i}{\sum m_i} \rightarrow \text{¿Cuáles son las partículas que sumo?}$$



suma de momentos

$$\sum m_i \rightarrow \sum \Delta m_i \xrightarrow{\Delta m_i \rightarrow 0} \int dm = M$$

$$\sum \Delta m_i \vec{r}_i \xrightarrow{\Delta m_i \rightarrow 0} \int \vec{r} dm$$

Cuerpo sólido

$$\hookrightarrow 10^{23} \frac{\text{partículas}}{\text{cm}^3}$$

$$dm = \rho dx dy dz$$

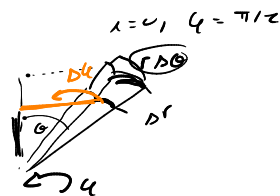
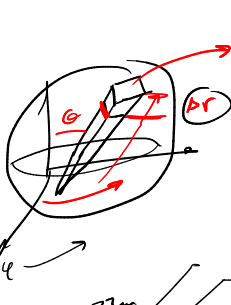
si $\Omega \in \mathbb{R}^3$

$$dm = \rho dV = \rho dx dy dz$$

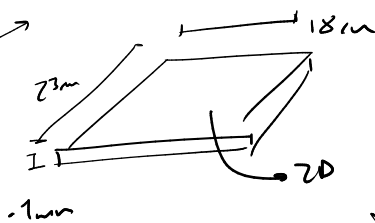
↪ volumen

$$\iiint_{\Omega} \rho(\vec{r}) \vec{r} dV$$

↪ $\vec{r} \in \Omega$



$x=0, y=\pi/2, z=0$
 $y=0, z=0$
 $(r \sin \theta \sin \phi)$
 $dV = r^2 \sin \theta dr d\theta d\phi$



$$dm = \sigma dx dy = \sigma dA$$

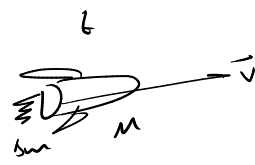
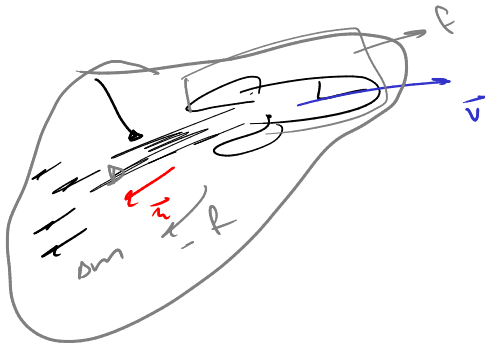
$$\vec{r}_{CM} = \frac{1}{M} \iint_{\Omega} \vec{r} \sigma(\vec{r}) dA$$

$$dm = \lambda dx = \lambda dl$$

$$\vec{r}_{CM} = \frac{1}{M} \int \vec{r} \lambda(\vec{r}) dl$$



Masa na ringu



$$\vec{P}(t) = (\Delta m + M) \vec{v}$$



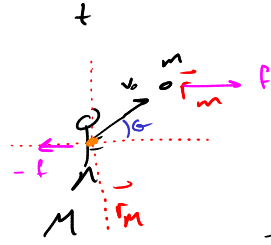
$$\Delta m$$

$$\vec{v} + \Delta \vec{v} + \vec{u}$$

$$\vec{P}(t + \Delta t) = \Delta m (\vec{v} + \Delta \vec{v} + \vec{u}) + M(\vec{v} + \Delta \vec{v})$$

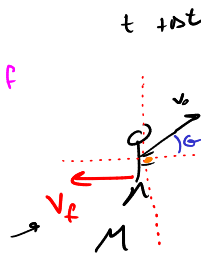
$$\left| \frac{d\vec{P}}{dt} \right|_{t \rightarrow 0} = M \frac{d\vec{v}}{dt} - \vec{u} \frac{dM}{dt} = \vec{F}_{\text{ext}}$$

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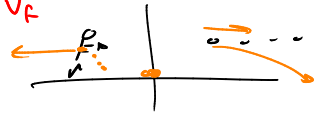


$$p_i(t) = (M+m)v$$

$$p_i(t) = 0 \leftarrow$$



$$p_x(t+\Delta t) = -Mv_f + m(v_o \cos \theta - v_f) = 0$$



$$\vec{P} = \vec{p}_o + \vec{p}_{b, m} = \vec{P} = \vec{F} \rightarrow \dot{P}_x = 0 \quad P_x(t) = P_x(t+\Delta t) = 0$$

$$\dot{P}_y = -(M+m)g$$

$$v_f = \frac{v_o m \cos \theta}{m+M}$$

$$M \ddot{x}_M = -f_{m \rightarrow M} = f_{M \rightarrow m} = -m \ddot{x}_m$$

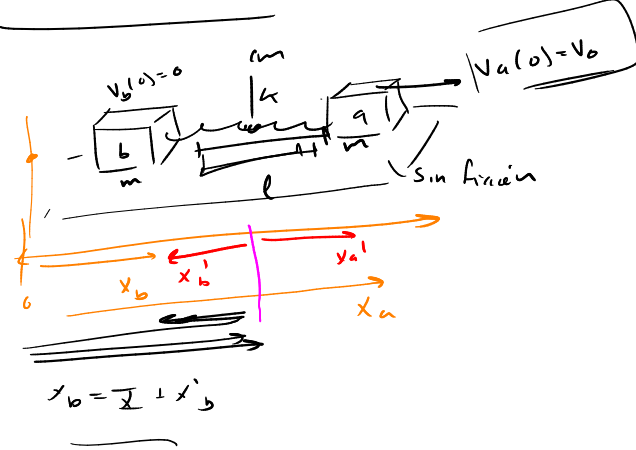
has integral

$$m \dot{x}_m(t) - M \dot{x}_M(t) = - \int_0^t f dt = m \dot{x}_m(0) - m \dot{x}_m(t)$$

$$M \dot{x}_M(t) + m \dot{x}_m(t) = M \dot{x}_M(0) + m \dot{x}_m(0) \rightarrow P_x = 0$$

$$\dot{P}_x = 0$$

$$\vec{X} = \frac{m \vec{x}_m + M \vec{x}_M}{m+M} \rightarrow \dot{\vec{X}} = \frac{m \dot{x}_m + M \dot{x}_M}{m+M} = 0$$



$$m_a = m_b = m$$

$$\bar{X} = \frac{m x_a + m x_b}{2m} = \frac{1}{2} (x_a + x_b)$$

$$x'_b = x_b - \bar{X} = x_b - \frac{1}{2} (x_a + x_b)$$

$$= \frac{1}{2} (x_b - x_a) = \frac{m_a}{m_a + m_b} (x_b - x_a)$$

$$x'_a = -\frac{1}{2} (x_b - x_a) = -\frac{m_b}{m_a + m_b} (x_b - x_a)$$

$$F = -k |x_b - x_a - l| = -k |x'_b - x'_a - l|$$

$$m \ddot{x}'_a = -k (x'_a - x'_b - l) \quad (1)$$

$$m \ddot{x}'_b = +k (x'_a - x'_b - l) \quad (2)$$

$$(1) - (2)$$

$$m (\ddot{x}'_a - \ddot{x}'_b) = -2k (x'_a - x'_b - l)$$

$$\frac{d^2}{dt^2} (x'_a - x'_b - l) = -\frac{2k}{m} (x'_a - x'_b - l)$$

$$y(t) = y_o \cos(\omega t + \phi_o)$$

$$\omega = \sqrt{\frac{2k}{m}}$$

$$\ddot{y} = -\frac{2k}{m} y$$

$$x'_a - x'_b = l \left(\cos\left(\sqrt{\frac{\tau k}{m}} t\right) + 1 \right) = x_a - x_b$$

$$\dot{x}'_a - \dot{x}'_b = -l \sqrt{\frac{\tau k}{m}} \sin\left(\sqrt{\frac{\tau k}{m}} t\right) = \dot{x}_a - \dot{x}_b$$

$$\vec{P} = 0 = m(\dot{x}'_a + \dot{x}'_b) = 0$$

$$\left\{ \begin{array}{l} \dot{x}_a = \dot{x}'_a + \dot{X} \\ \dot{x}_b = \dot{x}'_b + \dot{X} \end{array} \right\} \quad \dot{X} = \frac{\dot{x}_a + \dot{x}_b}{2} - \frac{\dot{x}'_a - \dot{x}'_b}{2} = \frac{1}{2} (\dot{x}_a + \dot{x}_b)$$

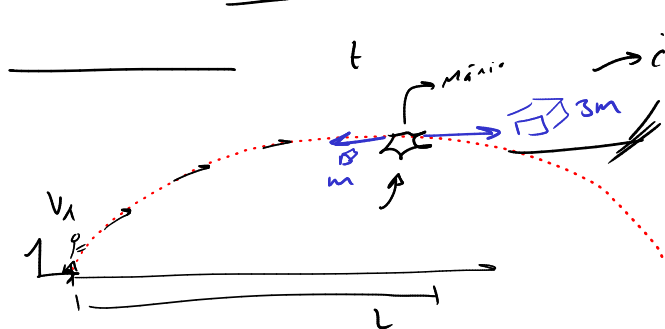
$$\dot{X}(t) = \dot{X}(0) = \frac{1}{2} (\dot{x}_a(0) + \dot{x}_b(0)) = \frac{1}{2} v_0$$

$$X = \frac{1}{2} v_0 t + \frac{x_a(0) + x_b(0)}{2}$$

$$x'_a = \frac{1}{2} v_0 t + X_0 + l(\cos(\sqrt{\frac{\tau k}{m}} t) + 1)$$

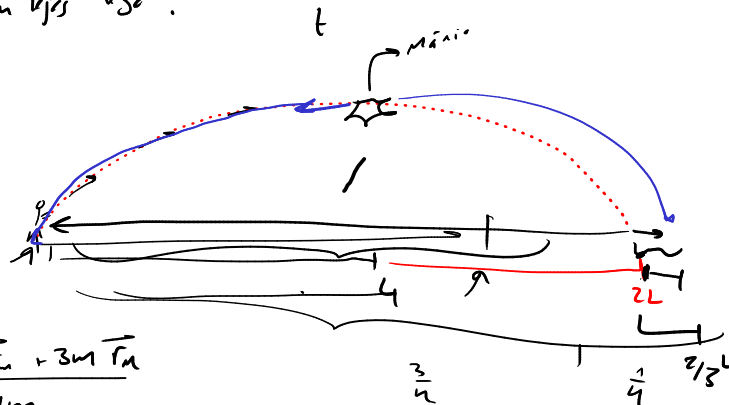
$$x'_a = \frac{1}{2} \Delta x +$$

$$x'_b = \frac{1}{2} v_0 t + X_0 + l(\cos(\sqrt{\frac{\tau k}{m}} t) - 1)$$



$$M = m + 3m = 4m$$

$$\vec{Q} = \frac{m\vec{r}_m + 3m\vec{r}_M}{4m}$$

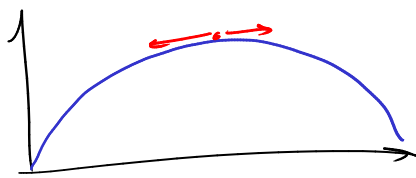


$$X = \frac{m x_m + 3m x_M}{4m} = \frac{x_m + 3x_M}{4} \quad \checkmark =$$

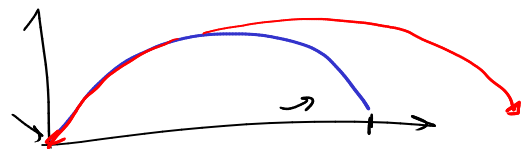
$$\text{Equilibrium quando } \dot{X} = 2L, \quad x_m = 0 \quad \rightarrow \quad 2L = \frac{3}{4} x_M \rightarrow x_M = \left(2L + \frac{2}{3}L\right)$$

$$\dot{X} = \frac{m \dot{x}_m + 3m \dot{x}_M}{4m} = \frac{\dot{x}_m + 3\dot{x}_M}{4} = v_0 \quad \rightarrow \quad \text{No resaca qd muda.}$$

$$\begin{aligned} \rightarrow x'_m &= x_m - X = x_m - \frac{x_m}{4} - \frac{3}{4} x_M = \frac{3}{4} (x_m - x_M) = \frac{3}{4} \left(-\frac{8}{3}\right) L = -2L \\ \rightarrow v'_M &= x_m - \frac{x_m}{4} - \frac{3}{4} x_M = \frac{1}{4} (x_m - x_M) = \frac{1}{4} \left(-\frac{8}{3}\right) = -\frac{2}{3} L \end{aligned}$$



R_{cm} (1 obs)



R_{cm} (+unk Ls)

$$R_{cm} = ZL = \frac{\cancel{m} R}{m + M} = \frac{3}{4} R$$