

# HW Problem 11 Lagrange Barycentric Approximation

Friday, October 9, 2020 1:13 PM

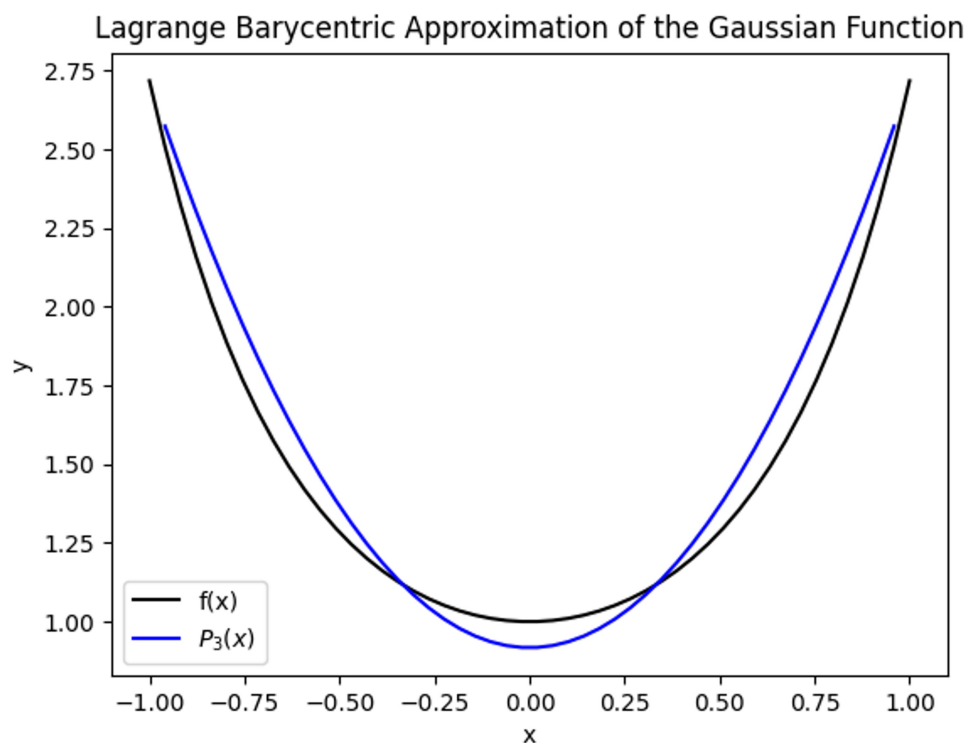
The gaussian function is defined by

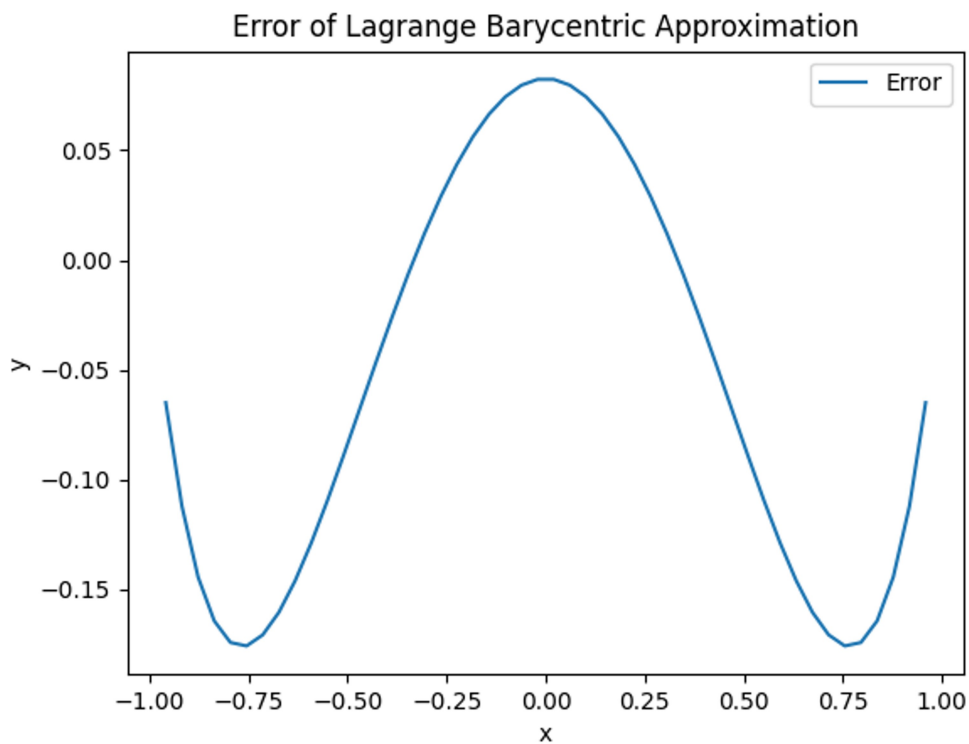
$$f(x) = e^{-x^2}.$$

- (A) Write the barycentric form of the interpolating polynomial  $p_3(x)$  for the gaussian function on the interval  $[-1, 1]$  using four evenly spaced fitting points.

$$p_3(x) = \frac{\frac{2.718}{x+1} + \frac{-3.353}{x+0.3} + \frac{3.353}{x-0.3} + \frac{-2.718}{x-1}}{\frac{1}{x+1} + \frac{-3}{x+0.3} + \frac{3}{x-0.3} + \frac{-1}{x-1}}$$

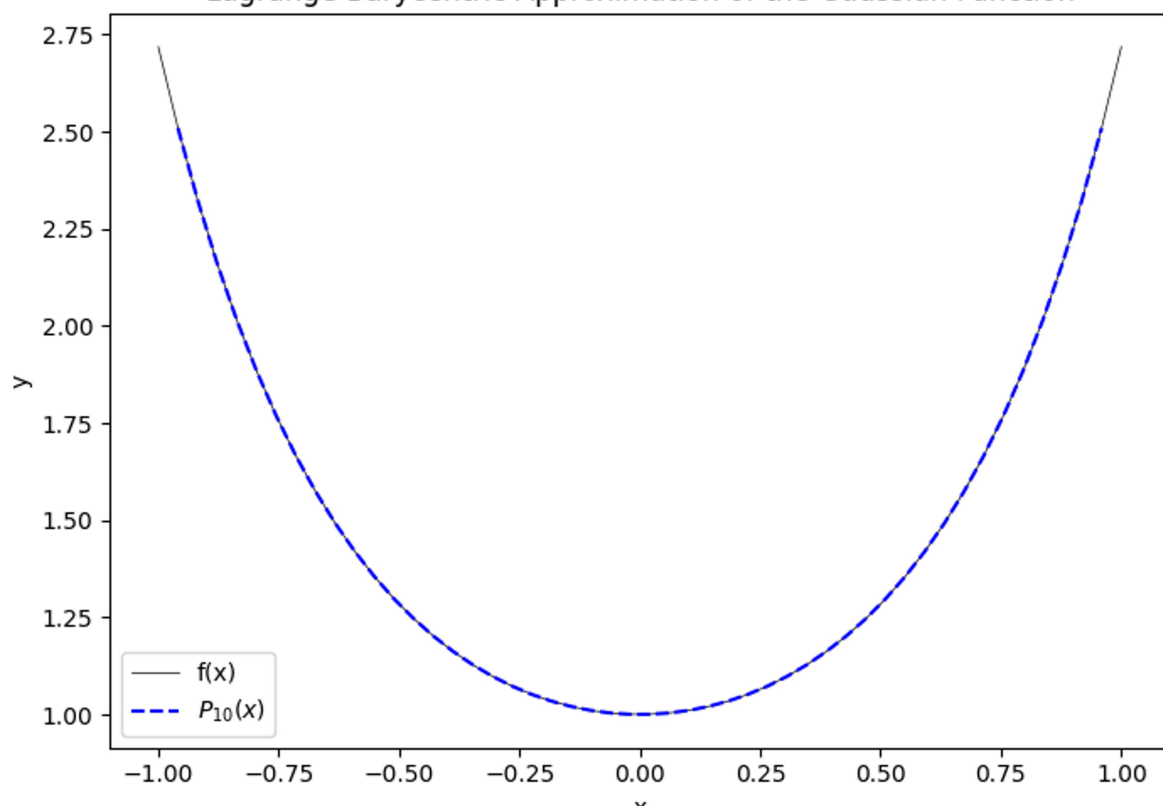
- (B) Use MATLAB to plot the gaussian function and the  $p_3(x)$  you obtained in (A) on the same axes. Also plot the error on a separate graph.



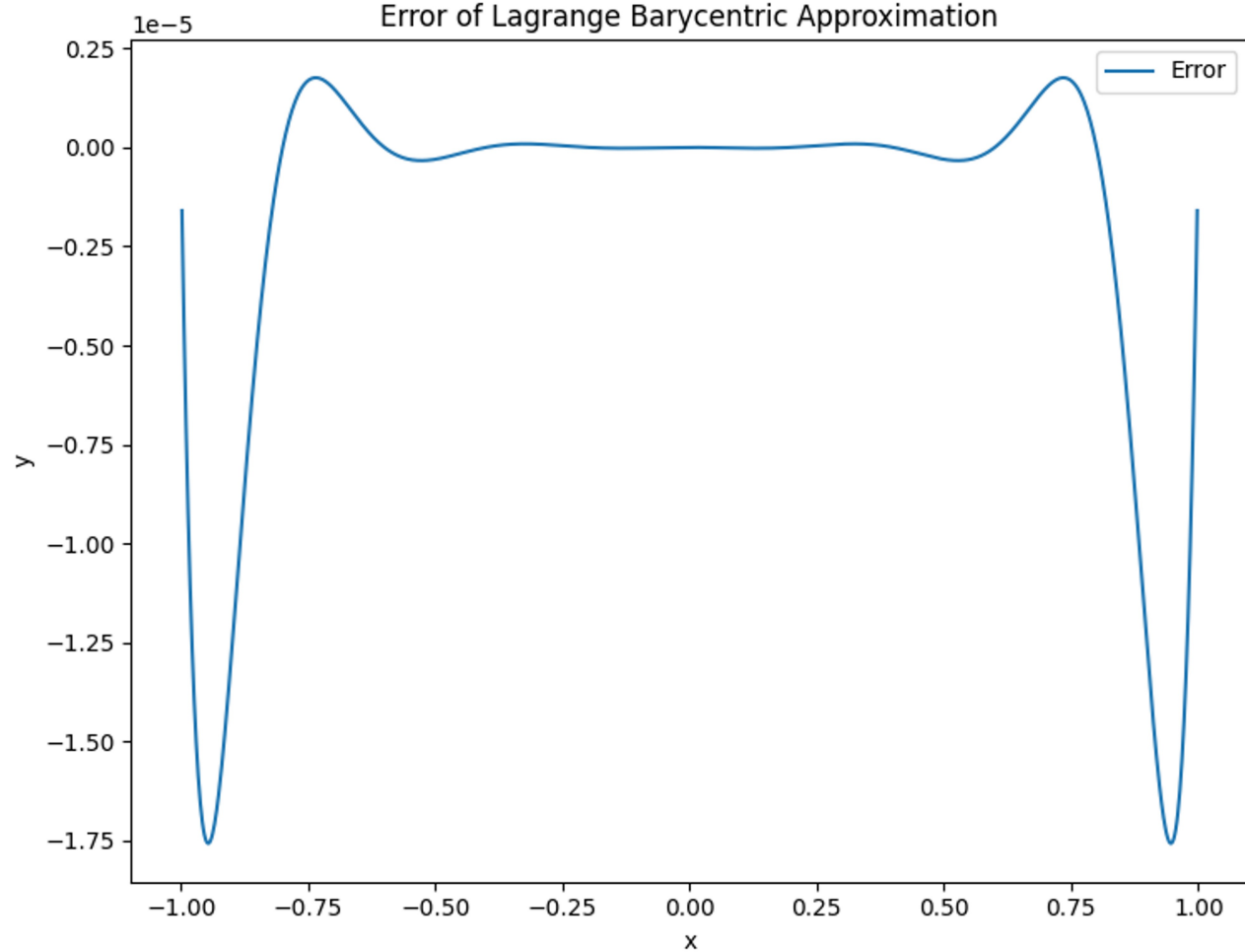


- (C) Use MATLAB to plot a tenth-order interpolating polynomial  $p_{10}(x)$  using the barycentric form of the polynomial and eleven evenly spaced fitting points on the same axis as the gaussian. Also plot the error on a separate graph.

Lagrange Barycentric Approximation of the Gaussian Function



Error of Lagrange Barycentric Approximation



(D) Compare and contrast the two interpolating polynomials.

Clearly the tenth-order interpolating polynomial has much less error than the third-order polynomial. The error for the first polynomial is on the magnitude of  $E^{-1}$  while the tenth-order error is on a scale of  $E^{-5}$ . Plotting both the gaussian function and tenth-order barycentric approximation together makes them virtually indistinguishable.