

S224309

System Programming, SYSPROG3

Javad Malek Shahkoohi

```

seconds = end.tv_sec - start.tv_sec;
useconds = end.tv_usec - start.tv_usec;
mtime = ((seconds) * 1000 + useconds/1000.0) +
0.5; // computing the time difference at begging of program up the time of last process
printf("Processes Elapsed time: %ld
milliseconds\n\n", mtime);

printf("MAX CHILD ID IS
:%ld\n\n",sysconf(_SC_CHILD_MAX));

printf("countrProcesses =
%d\n\n\n\n",countrProcesses);

return;
case 0: // Doing something in second child
exit(0);
break;
default: // counting the number of processes
countrProcesses++;
break;

};
} // End Of Processes While
break;

default: // First Parent 2 counts Threads
//int countrThreads=2; // parent and current child
while(1)
{
pthread_t tmpThrd; int i;
rc = pthread_create(&tmpThrd, NULL, PrintHello, (void *)i);
if (rc) {
gettimeofday(&end, NULL);
seconds = end.tv_sec - start.tv_sec;
useconds = end.tv_usec - start.tv_usec;
mtime = ((seconds) * 1000 + useconds/1000.0) + 0.5;
printf("Threads Elapsed time: %ld milliseconds\n",
mtime);

printf("countrThreads = %d\n\n\n\n",countrThreads);
pthread_exit(NULL);
return;
}
else countrThreads++;

} // End Of Threads While
break;
}
}

```

Q2:

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```
#include <stdio.h>
#include <stdlib.h>
#include <fcntl.h>
#include <errno.h>
#include <sys/types.h>
#include <unistd.h>
#include <pthread.h>
#include <sys/time.h>

/*
int Counter = 0;
it had the concurrency problem when the CounterThread thread tried to change Counter and the
solution is to use the mutex
*/

long Counter = 0;
void *Conter() //inifit increment function for increments thread
{
    while(1)
    {
        Counter++;
        //printf("Counter1 = %ld\t", Counter);
    }
}

void *Printer() // printing the value of counter in the infinit loop by a second sleep
{
    while(1)
    {
        printf("Counter2 = %ld\n", Counter);
        sleep(1);
    }
}

void main()
{
    int pid1, pid2, rc1, rc2;
    pthread_t ConterThrd, PrinterThrd;

    rc1 = pthread_create(&ConterThrd, NULL, Conter, NULL);
    if (rc1) {
        printf("Error:unable to create thread, error no: %d", rc1);
        return;
    }
}
```

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```
rc2 = pthread_create(&PrinterThrd, NULL, Printer, NULL);
if (rc2) {
    printf("Error:unable to create thread, error no: %d", rc2);
    return;
}

pthread_join( ConterThrd, NULL);
pthread_join( PrinterThrd, NULL);
}
```

Q3:

```
#include <stdio.h>
#include <stdlib.h>
#include <fcntl.h>
#include <errno.h>
#include <sys/types.h>
#include <unistd.h>
#include <pthread.h>
#include <sys/time.h>
#include <string.h>
#include <sys/stat.h>

/*
this is the Writer&Reader problem because there is a common buffer to read and write,
here I assumed the limit for the length of file
and reader starts to read first then the writer will start its jobs
*/
int length=0;
char buffer[10000];

void *Reader(void *argv_ReadFileStr)
{
    int file;
    file = open(argv_ReadFileStr, O_RDONLY);
    length = read(file,buffer, 10000);
    printf("\nlength: %d\n",length);
}

void *Writer(void *argv_WriteFileStr)
{
    int file;
    file = open(argv_WriteFileStr, O_WRONLY|O_CREAT, 0644);
    write(file,buffer, length);
}
```

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```
void main(int argc, char *argv[])
{
    if(argc != 3) {
        printf("Error in input data (Read file, write file name)");
        return;
    }

    pthread_t ReaderThrd,WriterThrd;

    pthread_create(&ReaderThrd, NULL, Reader, (void *)argv[1]); // calling the reader thread
    to read from file
    pthread_join( ReaderThrd, NULL); // the main thread wait for child thread to complete
    the its job

    pthread_create(&WriterThrd, NULL, Writer, (void *)argv[2]); //calling the writer thread to
    write into second file
    pthread_join( WriterThrd, NULL);
}
```

Q4:

```
#include <stdio.h>
#include <stdlib.h>
#include <fcntl.h>
#include <errno.h>
#include <sys/types.h>
#include <unistd.h>
#include <pthread.h>
#include <sys/time.h>

/*
the only a semaphore is not enough to protect the mutex because the turn is important , hence
the conditional variable is necessary to protect that
*/
pthread_mutex_t condition_mutex = PTHREAD_MUTEX_INITIALIZER; // a semaphore for mutex
pthread_cond_t condition_cond = PTHREAD_COND_INITIALIZER;
/* a conditional variable (because at the first time when a thread comes and it is not its turn, this
thread must release the mutex and wait for other thread to do its job)*/
int turn=0;
long Counter = 0;

void *Conter()
{
    while(1)
    {
        pthread_mutex_lock( &condition_mutex ); // choon momken hast meghdari
        baraye khoondan nabashad
        if(turn==0) pthread_cond_wait( &condition_cond, &condition_mutex );
```

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```
        turn=1;
        Counter++; // changes the shared variable

        pthread_cond_signal( &condition_cond );
        pthread_mutex_unlock( &condition_mutex );
    }
}

void *Printer()
{
    while(1)
    {
        pthread_mutex_lock( &condition_mutex );
        if(turn==1) pthread_cond_wait( &condition_cond, &condition_mutex );

        turn=1;
        printf("Counter2 = %ld\n", Counter);
        sleep(1);

        pthread_cond_signal( &condition_cond );
        pthread_mutex_unlock( &condition_mutex );
    }
}

void main()
{
    int pid1, pid2, rc1, rc2;
    pthread_t ConterThrd,PrinterThrd;

    rc1 = pthread_create(&ConterThrd, NULL, Conter, NULL);
    if (rc1) {
        printf("Error:unable to create thread, error no: %d", rc1);
        return;
    }
    rc2 = pthread_create(&PrinterThrd, NULL, Printer, NULL);
    if (rc2) {
        printf("Error:unable to create thread, error no: %d", rc2);
        return;
    }

    pthread_join( ConterThrd, NULL);
    pthread_join( PrinterThrd, NULL);
}
```

Q5:

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```
#include <stdio.h>
#include <stdlib.h>
#include <fcntl.h>
#include <errno.h>
#include <sys/types.h>
#include <unistd.h>
#include <pthread.h>
#include <sys/time.h>

/*
int shareValue = 10;
it had the concurrency problem when each thread tried to change shareValue and the solution is
to use the mutex
*/
int shareValue = 10;
void *F1() // for the second child to call for its threads
{
    printf("\n\nin PID=%d 1st shareValue = %d",getpid(),shareValue);
    //shareValue = 1;
    printf("\t new shareValue = %d\n",shareValue);
    pthread_exit(NULL);
}
void *F2()// for the first child to call for its threads
{
    printf("\n\nin PID=%d 2st shareValue = %d",getpid(),shareValue);
    //shareValue = 2;
    printf("\t PID=%d new shareValue = %d\n",shareValue);
    pthread_exit(NULL);
}
void *F3()// for the main process to call for its threads
{
    printf("\n\nin PID=%d 3st shareValue = %d",getpid(),shareValue);
    //shareValue = 3;
    printf("\t PID=%d new shareValue = %d\n",shareValue);
    pthread_exit(NULL);
}

void main()
{
    int pid1, pid2;
    pthread_t T1,T2,T3;

    shareValue=0;

    pid1 = fork();
    switch(pid1)
    {
```

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```

case -1:
    printf("Error in forck Function\n\n\n");
    break;
case 0:
    //execl("/bin/ls","bin/ls -l",(char *)0,0);
    /* runs the command but the other processes terminated!? */
    pid2 = fork();
    //execl("/bin/ls","bin/ls -l",(char *)0,0);
    switch(pid2)
    {
        case -1:
            printf("Error in forck Function\n\n\n");
            exit(0);
        case 0: //second child
            //execl("/bin/ls","bin/ls -l",(char *)0,0);
            /* runs the command but sometimes the other processes
            terminated! and sometimes they runned */
            pthread_create(&T1, NULL, F1, NULL);
            pthread_create(&T2, NULL, F1, NULL);
            pthread_create(&T3, NULL, F1, NULL);
            //execl("/bin/ls","bin/ls -l",(char *)0,0);
            pthread_join( T1, NULL);
            pthread_join( T2, NULL);
            pthread_join( T3, NULL);
            exit(0);
            break;
        default: //first child
            pthread_create(&T1, NULL, F2, NULL);
            pthread_create(&T2, NULL, F2, NULL);
            pthread_create(&T3, NULL, F2, NULL);
            pthread_join( T1, NULL);
            pthread_join( T2, NULL);
            pthread_join( T3, NULL);
            break;
    }
    break;

default: //father
    pthread_create(&T1, NULL, F3, NULL);
    pthread_create(&T2, NULL, F3, NULL);
    pthread_create(&T3, NULL, F3, NULL);
    pthread_join( T1, NULL);
    pthread_join( T2, NULL);
    pthread_join( T3, NULL);

    break;
}

```


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}

Q6:

```
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>

int GlobalCounter = 0, NewNumber = 0;;
pthread_mutex_t mutexsum;

void *Func1(void *threadid) // for first thread to take value and starting the programm, other
threads MUST WAITE for initializing
{
    int taskId;
    taskId = (int)threadid;

    pthread_mutex_lock (&mutexsum);
    printf("\n\nThread 1: Enter New Number To be added the Counter (0: Terminate the
process)\n");
    scanf("%d",&NewNumber);
    GlobalCounter += NewNumber;
    printf("taskId: %d ,\tThread 1: GlobalCounter is %d\n", taskId,GlobalCounter);
    pthread_mutex_unlock (&mutexsum);

    pthread_exit(NULL);
}

void *Func234(void *threadid)
{
    int taskId;
    taskId = (int)threadid;
    int TID = pthread_self();

    while (GlobalCounter == 0);// printf("\nwait please...");;
/*    this is a busy waiting and the solution is conditional variable (there is turn problem and
initialization problem at first-
it is possible for other 3rd threads to read when the value has no correct value)*/

    while(GlobalCounter >= 0)
    {
        GlobalCounter--;
        printf("taskId: %d ,\tThread ID: %d ,\t GlobalCounter is %d\n", taskId,TID,
GlobalCounter);
        sleep(1);
        pthread_mutex_unlock (&mutexsum);
    }
}
```

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```

        pthread_exit(NULL);
    }

void main(int argc, char *argv[])
{
    pthread_t threads[4];
    pthread_attr_t attr;
    void *status;
    int rc, t;

    pthread_mutex_init(&mutexsum, NULL);
    pthread_attr_init(&attr);
    pthread_attr_setdetachstate(&attr, PTHREAD_CREATE_JOINABLE);

    t = 0;    printf("Creating thread : %d\n",t);
    pthread_create(&threads[t], &attr, Func1, (void *)t);

    t = 1;    printf("Creating thread : %d\n",t);
    pthread_create(&threads[t], &attr, Func234, (void *)t);

    t = 2;    printf("Creating thread : %d\n",t);
    pthread_create(&threads[t], &attr, Func234, (void *)t);

    t = 3;    printf("Creating thread : %d\n",t);
    pthread_create(&threads[t], &attr, Func234, (void *)t);

    pthread_attr_destroy(&attr);
    for(t=0;t<4;t++)
        pthread_join(threads[t], &status);

    pthread_mutex_destroy(&mutexsum);
    pthread_exit(NULL);
}

```

Q7:

```

#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>

#define NUM_THREADS10
#define LEN_ARRAY_THREADS 10
int GlobalGeneratedValues[LEN_ARRAY_THREADS*NUM_THREADS];
pthread_mutex_t mutexsum;

void *GenerateValues(void *threadid)
{

```

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```

int taskId;
taskId = (int)threadid;
//printf("\ntaskId , %d\n", taskId);

int i=0, tmepvalue;
int LocalThreadGeneratedValues[NUM_THREADS];

for (i=0; i <= LEN_ARRAY_THREADS; i++)          // generates the random values and put
in the local array in side the thread
{
    tmepvalue = rand() % 11; // between 0 and 10
    while (tmepvalue == 0 )
        tmepvalue = rand() % 11;
    LocalThreadGeneratedValues[i] = tmepvalue;
}

int SegmentNo = (LEN_ARRAY_THREADS*taskId); // buliding the index offset of each
thread to work with array
pthread_mutex_lock (&mutexsum);      // starting the critical section
for(i=0; i < LEN_ARRAY_THREADS; i++)
{
    GlobalGeneratedValues[SegmentNo + i] = LocalThreadGeneratedValues[i];
    printf("\ntaskId:%d , GlobalGeneratedValues[%d] = %d \t", taskId,i,
LocalThreadGeneratedValues[i]);
}
pthread_mutex_unlock (&mutexsum);

pthread_exit(NULL);
}

void main(int argc, char *argv[])
{
    pthread_t threads[NUM_THREADS];
    pthread_attr_t attr;
    void *status;
    int rc, t;

    pthread_mutex_init(&mutexsum, NULL);
    pthread_attr_init(&attr);
    pthread_attr_setdetachstate(&attr, PTHREAD_CREATE_JOINABLE);

    for(t=0;t<NUM_THREADS;t++)
    {
        printf("Creating thread : %d\n", t);

        rc = pthread_create(&threads[t], &attr, GenerateValues, (void *)t);
        if (rc) { printf("ERROR; return code from pthread_create() is %d\n", rc); exit(-1);}
    }
}

```

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```

    }

    pthread_attr_destroy(&attr);
    for(t=0;t<NUM_THREADS;t++)
    {
        rc = pthread_join(threads[t], &status);
        if (rc){ printf("ERROR return code from pthread_join() is %d\n", rc);    exit(-1);
        }
    }

    int sum = 0;    // make the summation at the end, when all the threads have been
finished
    for(int i=0; i<LEN_ARRAY_THREADS*NUM_THREADS; i++)
    {
        printf("\nGlobalGeneratedValues[%d] = %d \t Sum = %d",i,
GlobalGeneratedValues[i], sum);
        sum += GlobalGeneratedValues[i];
    }
    printf("\n\n\n The sum of all generated value numbers by threads is : %d",sum);

    pthread_mutex_destroy(&mutexsum);
    pthread_exit(NULL);
}

```

Q8:

```

#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>

long GlobalSumValues = 0;
int GlobalX = 0;
pthread_mutex_t mutexsum;

void *Xpower2l(void *threadid)
{
    int taskId;
    taskId = (int)threadid;

    long i=0, tmepvalue = 1;
    int LocalPower=0;

    for (i =0; i < taskId; i++) // compute the 2^i by each thread
    {
        tmepvalue *= GlobalX;
    }
}

```

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```

pthread_mutex_lock(&mutexsum); // tyrs to add to the globl sum
GlobalSumValues += tmepvalue;
printf("\ntaskId:%d ,\tLocalSumValue = %ld,\tGlobalSumValues = %ld ",taskId,tmepvalue,
GlobalSumValues);
pthread_mutex_unlock(&mutexsum);

pthread_exit(NULL);
}

void main(int argc, char *argv[])
{
    if(argc != 3){    printf("\nInput arrguments are not correct....\n");    return; }
    GlobalX = atoi(argv[1]);
    int NUM_THREADS = atoi(argv[2]);

    pthread_t threads[NUM_THREADS];
    pthread_attr_t attr;
    void *status;
    int rc, t;

    pthread_mutex_init(&mutexsum, NULL);
    pthread_attr_init(&attr);
    pthread_attr_setdetachstate(&attr, PTHREAD_CREATE_JOINABLE);

    for(t=0;t<NUM_THREADS;t++)
    {
        printf("Creating thread : %d\n", t);

        rc = pthread_create(&threads[t], &attr, Xpower2I, (void *)t);
        if (rc) { printf("ERROR; return code from pthread_create() is %d\n", rc); exit(-1);}
    }

    pthread_attr_destroy(&attr);
    for(t=0;t<NUM_THREADS;t++)
    {
        rc = pthread_join(threads[t], &status);
        if (rc){ printf("ERROR return code from pthread_join() is %d\n", rc);    exit(-1);
    }
    }

    printf("\n\nGlobalSumValues = %ld \n",GlobalSumValues);

    pthread_mutex_destroy(&mutexsum);
    pthread_exit(NULL);
}

```

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Q9:

```

#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>

int IsPrime = 1;
int Golba_N = 0; // the value to check prime
int Global_P = 0; // the number of threads
int SubSetLen = 0; // sub length to check by thread
int RemainedThread = 0;
/*
here we divided SubSetLen = Golba_N/Global_P; to find the length of computation by each thread
*/

pthread_mutex_t mutexsum;

void *CheckPrime(void *threadid)
{
    int taskId, i=0;
    taskId = (int)threadid;

    int startIndex = (SubSetLen * taskId); // the offset to startIndex
    if(taskId == 0) i=2; // the first task must skip 1,2
    /*
    (Golba_N/2) >= (startIndex + i) to avoid over computation when we reach to the N/2
    (startIndex + i) != 1; when the length is 1 all the time Golba_N % 1 = 0 then the
    computation ahead on wrong way
    */
    for(; i<SubSetLen && (Golba_N/2) >= (startIndex + i) && (startIndex + i) != 1; i++)
    {
        if(Golba_N % (startIndex + i) == 0)
        {
            pthread_mutex_lock(&mutexsum);
            IsPrime = 0;
            printf("taskId:%d ,\tisnot Prime: %d/%d=0\n",taskId,Golba_N,(startIndex
+ i));

            pthread_mutex_unlock(&mutexsum);return;
            pthread_exit(NULL);
        }
    }

    /*// other semaphore to count the number of processes because when the number is not
    prime, we can find the end of computation*/
    pthread_mutex_lock(&mutexsum);
    RemainedThread--;
    printf("taskId:%d ,\tRemainedThread = %d \n",taskId,RemainedThread);

```

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```

        pthread_mutex_unlock(&mutexsum);

        pthread_exit(NULL);
    }

void main(int argc, char *argv[])
{
    if(argc != 3){    printf("\nInput arguments are not correct Global_P Golba_N ...\n");
        return; }
    Global_P = atoi(argv[1]);
    RemainedThread = Global_P;
    Golba_N = atoi(argv[2]);

    SubSetLen = Golba_N/Global_P; // tool subset har thread
    if(SubSetLen == 0)
    {
        printf("\nThe number of threads are more than N, Global_P must be less than
Golba_N because it is impossible to divid the elements among threads\n");
        return;
    }

    pthread_t threads[Global_P];
    pthread_attr_t attr;
    int rc, t;

    pthread_mutex_init(&mutexsum, NULL);

    for(t=0; t < Global_P; t++)
    {
        printf("Creating thread : %d\n", t);

        rc = pthread_create(&threads[t], NULL, CheckPrime, (void *)t);
        if (rc) { printf("ERROR: return code from pthread_create() is %d\n", rc); exit(-1);}
    }

    /*the unlimited loop up to the time one of threads changes the value of IsPrime = 0 Or
one of threads remained
    Isprime checked by main thread continuosly */
    while(1) // ta zamanike yeki az thread ha IsPrime ra 0 kond ya hanooz threadei baghi
mandeh bashad
    {
        if (IsPrime == 0) // Is not prime
        {
            printf("\n\nMain Function: Golba_N = %d isnot prime \n", Golba_N);
            pthread_mutex_destroy(&mutexsum);
            pthread_exit(NULL);
            return;
        }
    }
}

```

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```
        }  
        if(RemainedThread == 0)      // no one of threads changed the value of IsPrime  
and all of them terminated completely  
        {  
            printf("\n\nMain Function: Golba_N = %d is prime \n", Golba_N);  
            pthread_mutex_destroy(&mutexsum);  
            pthread_exit(NULL);  
            return;  
        }  
    }  
}
```