

Functional Safety Concept Lane Assistance

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# Document history

**[Instructions: Fill in the date, version and description fields. You can fill out the Editor field with your name if you want to do so. Keep track of your editing as if this were a real world project.**

**For example, if this were your first draft or first submission, you might say version 1.0. If this is a second submission attempt, then you'd add a second line with a new date and version 2.0]**

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| 10/1/2017 | 1.0 | Sumit Chhabra | Functional Safety Concept |
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# Purpose of the Functional Safety Concept

**[Instructions: Answer what is the purpose of a functional safety concept?]**

The Functional Safety Concept (FSC) looks at the general functionality of the item, i.e., Vehicle Lane Assistance, without going into the technical details. FSC derives the safety goal requirements from Hazard Analysis and Risk Assessment where functions and malfunctions are analyzed methodically. FSC allocates these safety goal requirements to the system architecture diagrams, that will ensure the item behaves in the safe manner.

# Inputs to the Functional Safety Concept

## Safety goals from the Hazard Analysis and Risk Assessment

**[Instructions:**

**REQUIRED:**

**Provide the lane departure warning and lane keeping assistance safety goals as discussed in the lessons and derived in the hazard analysis and risk assessment.**

**OPTIONAL:**

**If you expanded the hazard analysis and risk assessment to include other safety goals, include them here.**

**]**

|  |  |
| --- | --- |
| **ID** | **Safety Goal** |
| Safety\_Goal\_01 | The oscillating steering torque from the lane departure warning function shall be limited |
| Safety\_Goal\_02 | The lane keeping assistance function shall be time limited, and the additional steering torque shall end after a given time interval so that the driver cannot misuse the system for autonomous driving. |

## Preliminary Architecture

**[Instructions: Provide a preliminary architecture for the lane assistance item. Hint: See Lesson 3: Item Definition]**



### Description of architecture elements

**[Instructions: Provide a description for each of the item elements; what is each element's purpose in the lane assistance item? ]**

|  |  |
| --- | --- |
| **Element** | **Description** |
| Camera Sensor | Captures and sends the image frames of road to the camera sensor ECU. |
| Camera Sensor ECU | Using the information from camera sensor, it checks for the lane boundaries and send notification to the power steering ECU as well as car display system if care leaves the lane. |
| Car Display | Dashboard to show warning symbol with light on and off to the driver. |
| Car Display ECU | Takes the input from camera sensor ECU and controls the logic to display the warning in car display if LDW or LKW are detected. |
| Driver Steering Torque Sensor | Measures the torque applied by the driver. |
| Electronic Power Steering ECU | Takes input from camera ECU and driver steering torque sensor and calculates the necessary torque needed as well as time duration for LKA. |
| Motor | Takes the input from Electronic Power Steering ECU and provides the torque to the steering wheel. |

# Functional Safety Concept

The functional safety concept consists of:

* Functional safety analysis
* Functional safety requirements
* Functional safety architecture
* Warning and degradation concept

## Functional Safety Analysis

|  |  |  |  |
| --- | --- | --- | --- |
| **Malfunction ID** | **Main Function of the Item Related to Safety Goal Violations** | **Guidewords (NO, WRONG, EARLY, LATE, MORE, LESS)** | **Resulting Malfunction** |
| Malfunction\_01 | Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver a haptic feedback | MORE | LDW function applies an oscillating torque with very high torque amplitude (above limit). |
| Malfunction\_02 | Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver a haptic feedback | MORE | LDW function applies an oscillating torque with very high torque frequency (above limit). |
| Malfunction\_03 | Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane | NO | LKA function is not limited in time duration which leads to misuse as an autonomous driving function. |

## Functional Safety Requirements

Lane Departure Warning (LDW) Requirements:

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Safe State** |
| Functional  Safety  Requirement  01-01 | The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max\_Torque\_Amplitude | C | 50ms | Off |
| Functional  Safety  Requirement  01-02 | he lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max\_Torque\_Frequency | C | 50ms | Off |

Lane Departure Warning (LDW) Verification and Validation Acceptance Criteria:

|  |  |  |
| --- | --- | --- |
| **ID** | **Validation Acceptance**  **Criteria and Method** | **Verification Acceptance**  **Criteria and Method** |
| Functional  Safety  Requirement  01-01 | Define a reasonable limit for max torque amplitude for LDW. Test how drivers will react to different torque amplitudes. | If torque amplitude crosses the defined limit, the lane assistance output is set to zero within the 50ms fault tolerant time interval. |
| Functional  Safety  Requirement  01-02 | Define a reasonable limit for max torque frequency for LDW. Test how drivers will react to different torque amplitudes. | If torque frequency crosses the defined limit, the lane assistance output is set to zero within the 50ms fault tolerant time interval. |

Lane Keeping Assistance (LKA) Requirements:

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Safe State** |
| Functional  Safety  Requirement  02-01 | The lane keeping item shall ensure that the lane keeping assistance torque is applied for only Max\_Duration | B | 500ms | Off |

Lane Keeping Assistance (LKA) Verification and Validation Acceptance Criteria:

|  |  |  |
| --- | --- | --- |
| **ID** | **Validation Acceptance**  **Criteria and Method** | **Verification Acceptance**  **Criteria and Method** |
| Functional  Safety  Requirement  02-01 | Define a reasonable limit for Max\_Duration. Test and validate the chosen value resulted in dissuading the drivers from taking their hands off the wheel. | Verify the system turn off the LKA after Max\_Duration is exceeded. |

## Refinement of the System Architecture

**[Instructions: Include the refined system architecture. Hint: The refined system architecture should include the system architecture from the end of the functional safety lesson including all of the ASIL labels.]**



## Allocation of Functional Safety Requirements to Architecture Elements

**[Instructions: Mark which element or elements are responsible for meeting the functional safety requirement. Hint: Only one ECU is responsible for meeting all of the requirements.]**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Functional  Safety  Requirement  01-01 | Electronic Power Steering ECU shall ensure torque amplitude shall not exceed Max\_Torque\_Amplitude. | **X** |  |  |
| Functional  Safety  Requirement  01-02 | Electronic Power Steering ECU shall ensure torque frequency shall not exceed Max\_Torque\_Frequency. | **X** |  |  |
| Functional  Safety  Requirement  02-01 | Electronic Power Steering ECU shall ensure LKA function will be time limited and steering torque ends after Max\_Duration is exceeded, | **X** |  |  |

## Warning and Degradation Concept

**[Instructions: Fill in the warning and degradation concept.]**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Degradation Mode** | **Trigger for Degradation Mode** | **Safe State invoked?** | **Driver Warning** |
| WDC-01 | Off | If Torque amplitude exceeds Max\_Torque\_Amplitude or Torque frequency exceeds Max\_Torque\_Frequency | Yes | Warning light in car display |
| WDC-02 | Off | If LKA torque applied exceeds the Max\_Duration time interval | Yes | Warning light in car display |