

Question 1

Force balance on annulus (same as for Newtonian as done in class):

$$\begin{aligned} & 2\pi r \Delta r (P(z) - P(z+\Delta z)) \\ & + \tau_{rz}(r+\Delta z) 2\pi(r+\Delta r)\Delta z \\ & - \tau_{rz}(r) 2\pi r \Delta z = 0 \\ & \div \text{ by } 2\pi \Delta z \Delta r \end{aligned}$$

$$\begin{aligned}
 & -r \frac{P(z+\Delta z) - P(z)}{\Delta z} \\
 & + \frac{\tau_z(r+\Delta r)(r+\Delta r) - \tau_z(r)r}{\Delta r} \\
 & = 0
 \end{aligned}$$

$$\begin{aligned}
 \lim_{\Delta r \rightarrow 0} & \quad \lim_{\Delta z \rightarrow 0} \\
 & -r \frac{\partial P}{\partial z} \\
 & + \frac{d}{dr} (\tau_{rz} r) \\
 & = 0
 \end{aligned}$$

$$\frac{\partial P}{\partial z} = - \frac{\Delta P}{L}$$

$$\frac{d}{dr} (\tau_{rz} r) = -r \frac{\Delta P}{L}$$

$$\tau_{rz} = - \frac{\Delta P}{2L} r + \frac{A}{r}$$

Symmetry: At $r=0$
 $\tau_{rz} = 0$

$$\therefore A = 0$$

$$\tau_{rz} = -\frac{\Delta P}{2L} r$$

τ_{rz} is negative

$$\therefore \left| \frac{du_z}{dr} \right| = -\frac{du_z}{dr}$$

$$\tau_{rz} = -k \left(-\frac{du_z}{dr} \right)^n$$

$$\left(-\frac{du_z}{dr} \right)^n = \frac{\Delta P}{2Lk} r$$

$$\frac{du_z}{dr} = - \left(\frac{\Delta P}{2Lk} \right)^{\frac{1}{n}} r^{\frac{1}{n}}$$

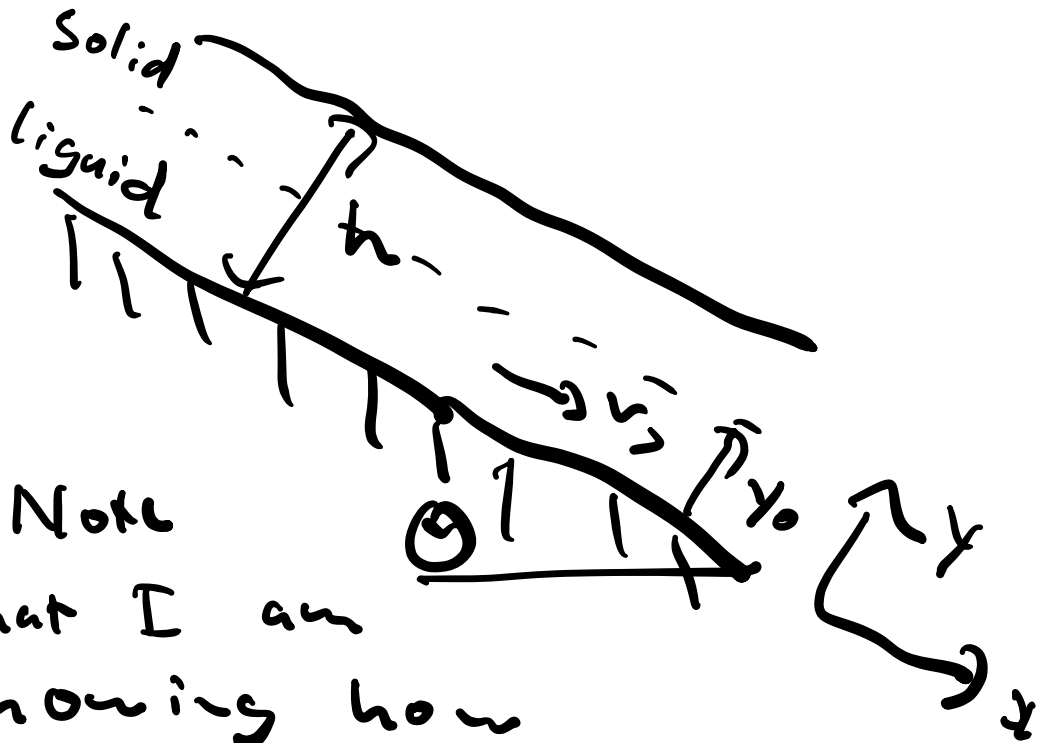
$$u_z = \frac{-n}{n+1} \left(\frac{\Delta P}{2Lk} \right)^{\frac{1}{n}} r^{\frac{n+1}{n}} + B$$

$$\text{at } r = R \quad u_z = 0$$

$$\therefore B = \frac{n}{n+1} \left(\frac{\Delta P}{2Lk} \right)^{\frac{1}{n}} R^{\frac{n+1}{n}}$$

$$\therefore u_z = \frac{n}{n+1} \left(\frac{\Delta P}{2Lk} \right)^{\frac{1}{n}} \left(R^{\frac{n+1}{n}} - r^{\frac{n+1}{n}} \right)$$

Question 2



Note
that I am
showing how
to do it with
different axes than I
used in class (and
the angle is from the
horizontal rather
than the vertical):

Force balance in
y direction (only
gravity and viscous
forces):

$$\left(\tau_{yx}(y+\Delta y) - \tau_{yx}(y) \right) \Delta x \\ + \rho g_x \Delta x \Delta y = 0$$

$$\div \Delta x \Delta y$$

$$\frac{\tau_{yx}(y+\Delta y) - \tau_{yx}(y)}{\Delta y} + \rho g_x \\ = 0$$

$$\lim_{\Delta y \rightarrow 0} \frac{d\tau_{yx}}{dy} = -\rho g_x$$

$$g_x = \sin \theta g$$

$$\tau_{yx} = -\rho g \sin \theta y + A$$

No shear at the free surface!

$$\tau_{yx} = 0 \quad \text{at } y = h$$

$$\tau_{yx} = \rho g \sin \theta (h - y)$$

Solid/liquid like transition

$$\tau_{yx} = \tau_0$$

$$\tau_0 = \rho g \sin \theta (h - y_0)$$

$$y_0 = h - \frac{\tau_0}{\rho g \sin \theta}$$

Liquid region

$$y < y_0$$

τ_{yx} is +ve everywhere
[note that this is
the opposite of when the
axes run from the surface]

$$\therefore \left| \frac{dv_x}{dy} \right| = \frac{dv_x}{dy}$$

$$\tau_{yx} = \left(\mu_0 \frac{dv_x}{dy} + \tau_0 \right)$$

$$\mu_0 \frac{dv_x}{dy} + \tau_0 = \rho g \sin \theta (h - y)$$

$$\frac{dv_x}{dy} = \frac{\rho g \sin \theta}{\mu_0} (h - y) - \frac{\tau_0}{\mu_0}$$

$$v_x = \frac{\rho g \sin \theta}{\mu_a} \left(h y - \frac{y^2}{2} \right) - \frac{\tau_0}{\mu_a} y + B$$

at $y = 0$ $v_x = 0$

$\therefore B = 0$

if $y < y_0$

$$v_x = \frac{\rho g \sin \theta}{\mu_a} \left(h y - \frac{y^2}{2} \right) - \frac{\tau_0}{\mu_a} y$$

if $y > y_0$

$$v_x = \frac{\rho g \sin \theta}{\mu_a} \left(h y_0 - \frac{y_0^2}{2} \right) - \frac{\tau_0}{\mu_a} y_0$$

where $y_0 = h - \frac{T_0}{\rho g \sin \theta}$

Initially just at rest:

$$y_0 = 0$$

$$h = \frac{T_{0 \text{ original}}}{\rho g \sin \theta}$$

$$T_{0 \text{ original}} = 4905 \text{ Pa}$$

After rain:

$$T_0 = 3924$$

$$y_0 = 0.2 \text{ m}$$

$$v_{\max} = \frac{\rho g \sin \theta}{m_a} \left(h y_0 - \frac{y_0^2}{2} \right) - \frac{T_0}{m_a} y_0$$

$$V_{\max} = 2.981 \text{ m/s}$$