Javed Ahmad

Research Interests:

- o 3D Computer Vision, Deep Learning, Multimodal 3D Scene Perception
- o Robotic Manipulation and 3D Reconstruction

Education

11/2020 -12/2023 Ph.D in Computational Vision, Automatic Recognition and Learning

Thesis Title: Multimodal 3D Scene Perception

Research Lab: Pattern Analysis and Computer Vision (PAVIS), IIT, Italy

University: University of Genoa (UniGe), Italy

2017 - 2019 Master of Science in Electrical Engineering

University: Information Technology University (ITU), Pakistan

Major Subjects: Advanced Mathematics, Machine Learning, Control System Theory, Digital

Signal Processing

2013 - 2017 Bachelor of Science in Electrical Engineering

University: University of Central Punjab, Pakistan

Major Subjects: Signal Processing, Image Processing, Control Systems, Electronics

Experiences

02/2024 – present **PostDoc**

Research Lab: Center for Cultural Heritage Technology, IIT, Italy

- o Collaborating with CTE-Genova for 3D artifact reconstruction via robotic manipulators
- o Developing algorithms for precise 3D object understanding and reconstruction
- 11/2020 **Doctoral Researcher**
 - 12/2023 Research Lab: Pattern Analysis and Computer Vision (PAVIS), IIT, Italy
 - o Developed novel LiDAR-Camera fusion scheme, improving accuracy and reliable 3D
 - o Contributed to 3D object localization for MEMEX Project from crowd-sourced images
 - Performed LiDAR-Camera calibration procedures
- 07/2017 Research Assistant
 - 10/2020 Research Lab: CACTUS, ITU, Pakistan
 - Worked on SfM 3D reconstruction
 - O Worked on vibration signal processing via machine learning for fault diagnosis in rotating machinery
- 2017 2019 **Teaching Assistant**

University: Information Technology University (ITU), Pakistan

- o Graduate Course: Machine Learning
- o Undergrad Courses: Calculus & Analytical Geometry, Power System Analysis

Programming and Skills

Python: Advanced (Pytorch, Numpy, Pandas, Scipy)

Computer Vision: Expert (OpenCV, Open3D, bpy, Torchvision)

Robotics: Intermediate (UR-RTDE, Pyroboplan, ROS2, Moveit2, NVIDIA-Omniverse)

3D Perception: Proficient (mmdetection3D, LiDAR-Camera fusion techniques)

Parallel Experienced (Franklin-HPC: NVIDIA Tesla V100, A100)

Computation:

Other: Knowledge of Blender, C++, MATLAB

Publications

- 2024 **Ahmad, J.**, Frascella, S., Dassiè, F., et al. Automated Artifacts Position and Orientation Estimation in Cultural Heritage. IEEE/ASME Conference on Mechatronic, Embedded Systems and Applications.
- 2023 **Ahmad, J.**, Del Bue, A. mmFUSION: Multi-modal Fusion for 3D Object Detection. [arxiv link]
- 2022 **Ahmad, J.**, Toso, M., Taiana, M., James, S., Del Bue, A. Multi-view 3D Objects Localization from Street-level Scenes. [Springer DOI] [GitHub code]
- 2022 Castro, E., ..., Ahmad, J., et al. Fill in the Blank for Fashion Complementary Outfit Product Retrieval. Journal of Machine Vision and Applications. [Springer DOI]
- 2020 **Ahmad, J.**, Shamshad F., et al. Deep Unsupervised Deblurring Approach for Improving Crops Disease Classification. Poster at CVPR Workshop on Agriculture-Vision.

Summer Schools

- Jul 2023 International Computer Vision Summer School (ICVSS), Sicily
 Poster: 3D Scene Perception from Single to Multi-modalities [Poster link]
- Jul 2022 Vision and Sports Summer School (VS3), Prague Focused on advanced computer vision techniques in 2D and 3D object recognition, multimodal learning, 3D neural rendering.
- Jul 2021 Vision Understanding and Machine Intelligence Summer School (VISUM), Porto Winner of project competition on fashion product retrieval using deep learning. [Presentation link]
- Jul 2020 **Eastern European Machine Learning Summer School (EEML)**Winner of 3D historic landmark reconstruction proposal in unconference research competition.

Awards & Prizes

1st prize in VISUM 2021 and EEML 2020 competitions MS Fellowship granted by ITU, Pakistan

Community Service

Former member of Akhuwat Foundation, Pakistan, involved in charity fundraising. Currently exploring more community engagement opportunities.