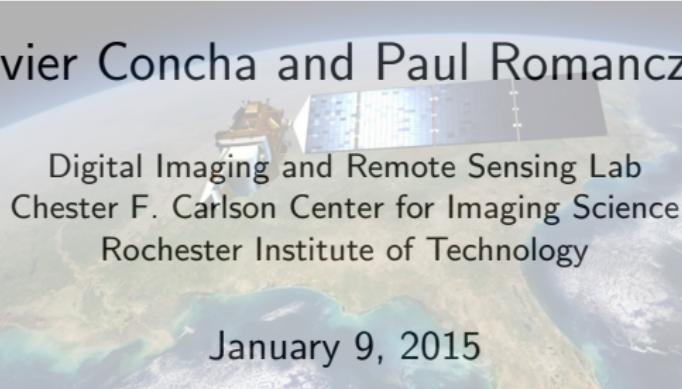


# Intro to Instrumentation and Field Measurements in Remote Sensing

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Rochester Institute of Technology

January 9, 2015

Presented for 2015 Intersession Term

# Outline

① Introduction

② Background

③ Taking Measurements

④ DIRS Instruments

# Outline

## ① Introduction

## ② Background

## ③ Taking Measurements

## ④ DIRS Instruments

# Course Goals

- Learn the importance of field measurements
- Learn how to take field measurements
- Learn about DIRS instruments

# Course Description

- Friday: Introduction
- Monday: Introduction (con't) and DIRS instruments exhibition
- Tuesday: Lab: Reflectance measurements
- Wednesday: Lab: LIDAR measurements

# Definitions

- **Remote Sensing:**

“Remote sensing is the science of obtaining information about objects or areas from a distance, typically from aircraft or satellites.”

- **Field Measurements or Groundtruth or Ground-based data or reference data or ancillary data:**

“Observations or measurements made at or near the surface of the earth in support of remote sensing.”

# Motivation

## Why is it important?

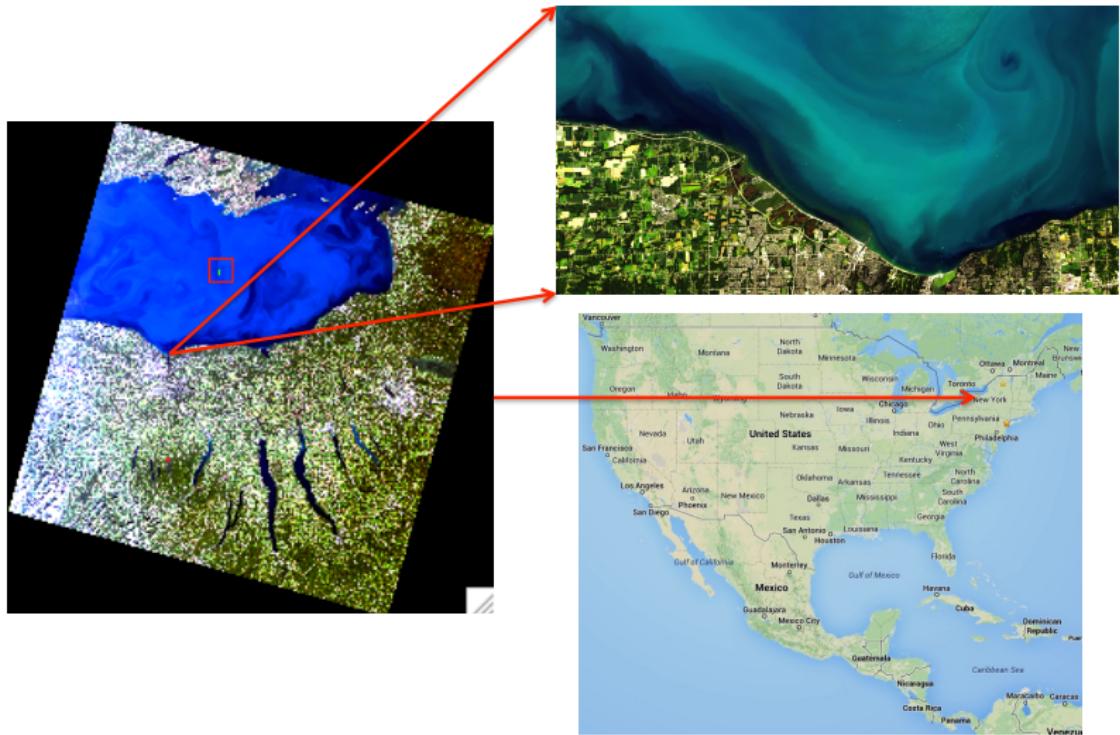
- Validation: comparison to know how close a model is to the field measurements (accuracy)
- Calibration or Correction: adjust model or instrument to be more precise (data fitting)
- Data collection to get characteristics of target, materials, etc.

# Motivation Examples

Include:

- Javier's example (over water mea.)
- Paul's example (LIDAR and trees?)

# Field Data Collection Area of Study



# Field Data Collection (con't)

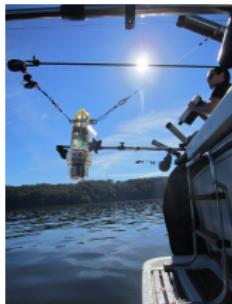
## Area of Study

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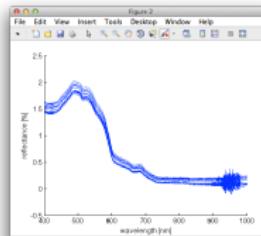
# Field Data Collection (con't)



Water Samples

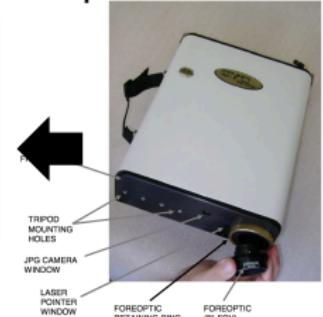


Lab Analysis



Water Leaving  
Reflectance

Spectroradiometer



Backscattering

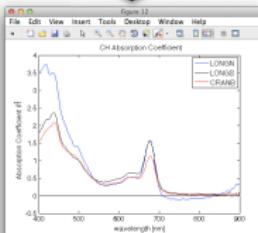
# Field Data Collection (con't)

## Lab Measurements

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### Spectrophotometer



IOPs

Hydrolight



### Filtration and Spectrophotometric Analysis

Concentrations



# Field Data Collection (con't)

2013 and 2014 Seasons

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		IOPs		Concentrations		Reflectances		Backscattering	
Date		Ponds	Lake	Ponds	Lake	Ponds	Lake	Ponds	Lake
2013	25-Aug	✓	✗	✓	✗	✗	✗	✗	✗
	19-Sep	✓	✓	✓	✓	✗	✓	✓	✓
	26-Sep	✓	✓	✓	✓	✗	✓	✗	✓
2014	17-May	✓	✗	✓	✗	✓	✗	✓	✗
	02-Jun	✗	✓	✗	✓	✗	✓	✗	✓
	11-Jul	✓	✓	✓	✓	✓	✓	✗	✓
	28-Aug	✗	✓	✗	✓	✗	✗	✗	✗
	29-Sep	✓	✓	✓	✓	✓	✓	✓	✓

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① Introduction

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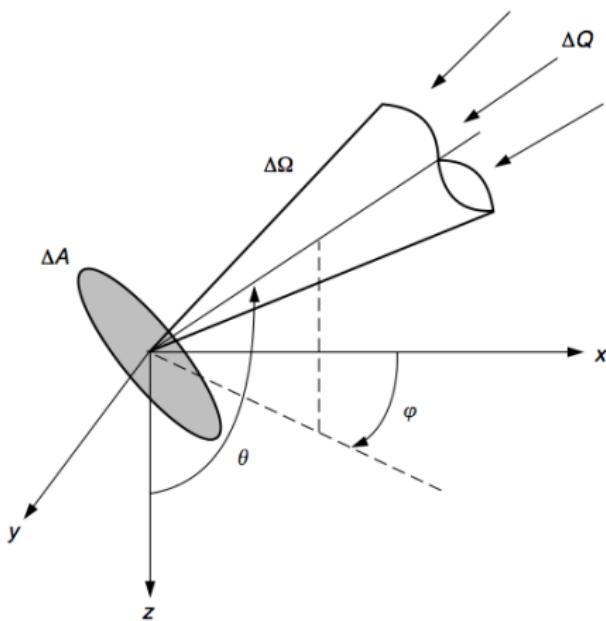
③ Taking Measurements

④ DIRS Instruments

# Examples of Kind of Measurements

- Reflectance: Radiometer
- Concentration: Spectrophotometer
- Location: GPS
- Structure: LIDAR
- Leaf Area Index (LAI): Ceptometer

# Radiometric Quantities: Radiance



$\Delta Q$ : radian energy  
incident

$\Delta t$ : time interval

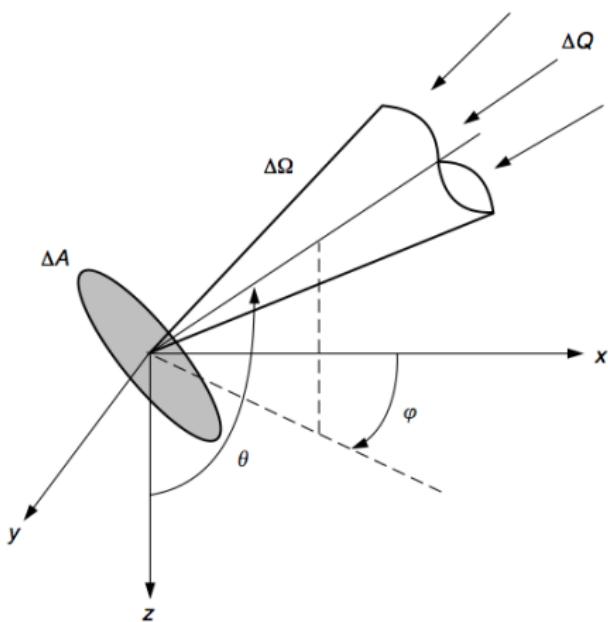
$\Delta A$ : surface area at  
location  $(x,y,z)$

$\Delta\Omega$ : solid angle in  
direction  $(\theta,\varphi)$

$\Delta\lambda$ : photons wavelength  
interval

$$L(x, y, z, t, \theta, \varphi, \lambda) \equiv \frac{\Delta Q}{\Delta t \Delta A \Delta \Omega \Delta \lambda} \quad [Js^{-1} m^{-2} sr^{-1} nm^{-1}] \quad (1)$$

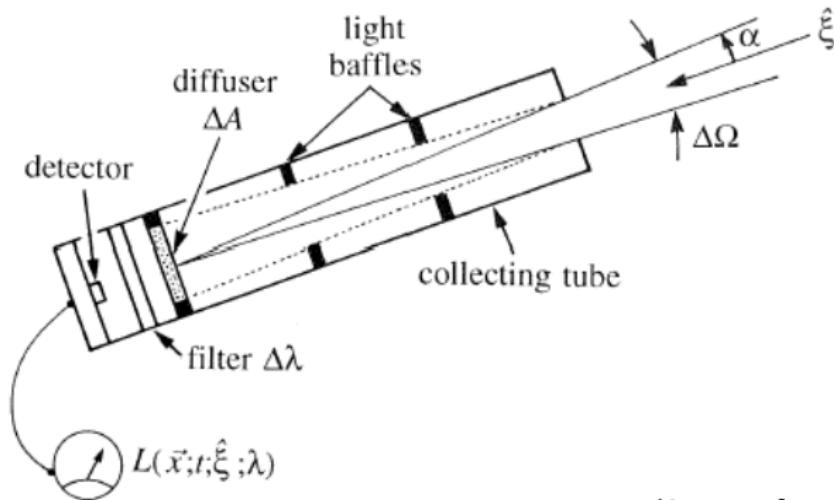
# Radiometric Quantities: Radiance



- $\Delta Q$ : radian energy incident
- $\Delta t$ : time interval
- $\Delta A$ : surface area at location  $(x,y,z)$
- $\Delta\Omega$ : solid angle in direction  $(\theta,\varphi)$
- $\Delta\lambda$ : photons wavelength interval

$$L(x, y, z, t, \theta, \varphi, \lambda) \equiv \frac{\partial^4 Q}{\partial t \partial A \partial \Omega \partial \lambda} \quad [Js^{-1} m^{-2} sr^{-1} nm^{-1}] \quad (1)$$

# Radiance Sensor



(Source: [Mobley, 2010])

# Radiometric Quantities: Irradiance

**Spectral downwelling scalar irradiance** at depth  $z$ :

$$E_{od}(z, \lambda) = \int_{2\pi_d} L(z, \theta, \varphi, \lambda) d\Omega \quad [Wm^{-2}nm^{-1}] \quad (2)$$

**Spectral upwelling scalar irradiance** at depth  $z$ :

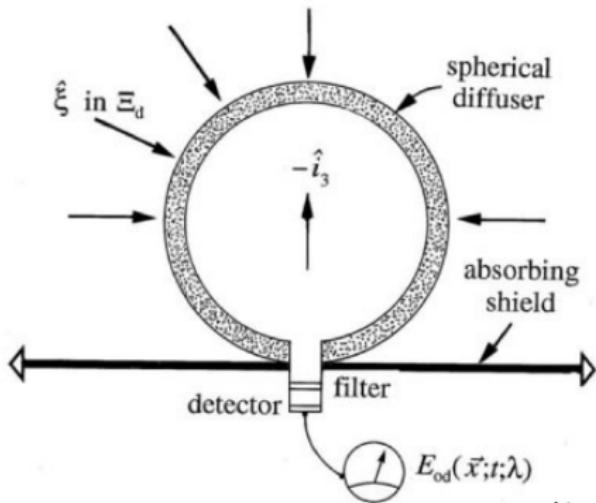
$$E_{ou}(z, \lambda) = \int_{2\pi_u} L(z, \theta, \varphi, \lambda) d\Omega \quad [Wm^{-2}nm^{-1}] \quad (3)$$

**Spectral scalar irradiance** at depth  $z$ :

$$E_o(z, \lambda) \equiv E_{od}(z, \lambda) + E_{ou}(z, \lambda) \quad (4)$$

$$= \int_{4\pi} L(z, \theta, \varphi, \lambda) d\Omega \quad (5)$$

# Scalar Irradiance Sensor



(Source: [Mobley, 2010])

# Radiometric Quantities: Irradiance

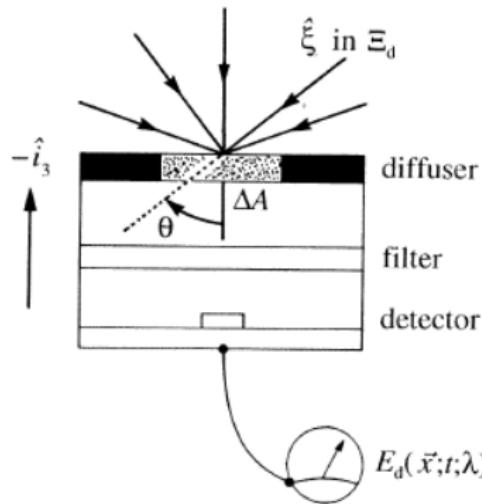
**Spectral downwelling plane irradiance** at depth  $z$ :

$$E_d(z, \lambda) = \int_{2\pi_d} L(z, \theta, \varphi, \lambda) |\cos\theta| d\Omega \quad [Wm^{-2}nm^{-1}] \quad (6)$$

Photosynthetic available radiation, **PAR**:

$$PAR(z) \equiv \int_{350nm}^{700nm} \frac{\lambda}{hc} E_o(z, \lambda) d\lambda \quad [photons s^{-1}m^{-2}] \quad (7)$$

# Planar Irradiance Sensor



(Source: [Mobley, 2010])

# Reflectance

- **Irradiance reflectance:**

$$R(z, \lambda) \equiv \frac{E_u(z, \lambda)}{E_d(z, \lambda)} \quad (8)$$

- **Remote sensing reflectance (water):**

$$R_{rs}(\theta, \varphi, \lambda) \equiv \frac{L_w(\theta, \varphi, \lambda)}{E_d(\lambda)} \quad [sr^{-1}] \quad (9)$$

where  $L_w$  is the **water-leaving radiance**

- **Bidirectional Reflectance Distribution Function (BRDF):**

$$r_{BRDF} = \frac{L(\theta_o, \phi_o)}{E(\theta_i, \phi_i)} \quad [sr^{-1}] \quad (10)$$

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# Diffuse white reference panel (Spectralon)

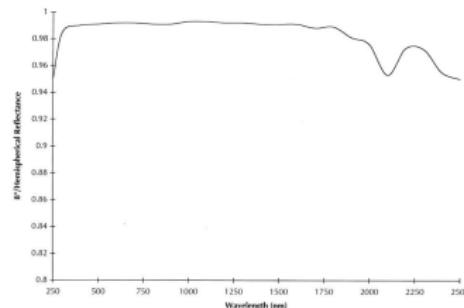
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- For a Lambertian surface:

$$L = \frac{E_d r}{\pi} \Rightarrow E_d = \frac{L\pi}{r}$$

- For spectralon  $r \approx 1$   
( $\approx 100\%$ )  
 $\Rightarrow E_d = L\pi$



# Diffuse white reference panel (Spectralon)

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$$L = \underbrace{E'_s \cdot \cos \sigma' \cdot \tau_1 \cdot \tau_2 \cdot \frac{\rho}{\pi}}_{\text{solar}} + \underbrace{F \cdot E_{ds} \cdot \tau_2 \cdot \frac{\rho_d}{\pi}}_{\text{sky}} + \underbrace{(1 - F) \cdot E_{bs} \cdot \tau_2 \cdot \frac{\rho_d}{\pi}}_{\text{adjacency}} + \underbrace{L_{us}}_{\text{upwelling}}$$

(11)

Eqn. 4.69 from [Schott, 2007].

$$L = m \cdot \rho + b \quad (12)$$

$$L_{tar} = m \cdot \rho_{tar} + b \quad (13)$$

$$L_{ref} = m \cdot \rho_{ref} + b \quad (14)$$

$$\rho_{tar} = \frac{L_{tar} - b}{m} \quad (15)$$

$$m = \frac{L_{ref} - b}{\rho_{ref}} \quad (16)$$

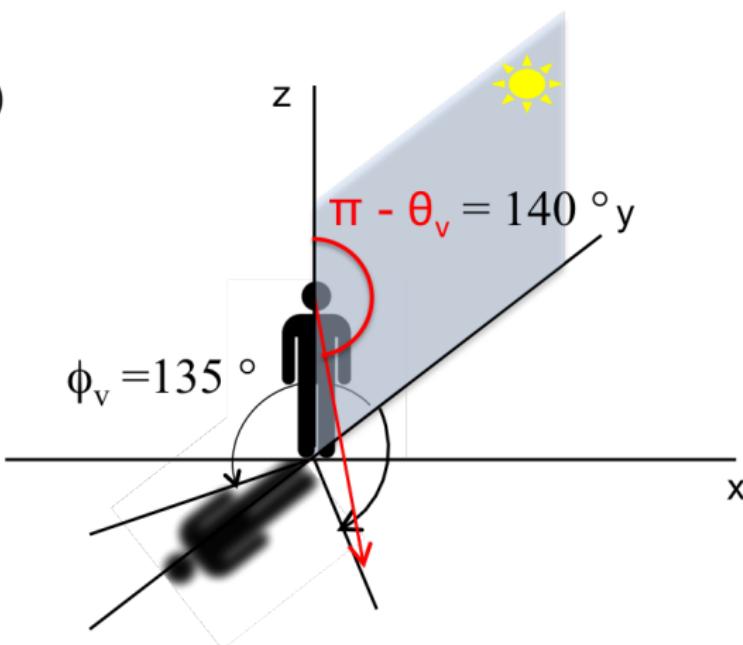
$$\rho_{tar} = \frac{L_{tar} - b}{L_{ref} - b} \cdot \rho_{ref} \quad (17)$$

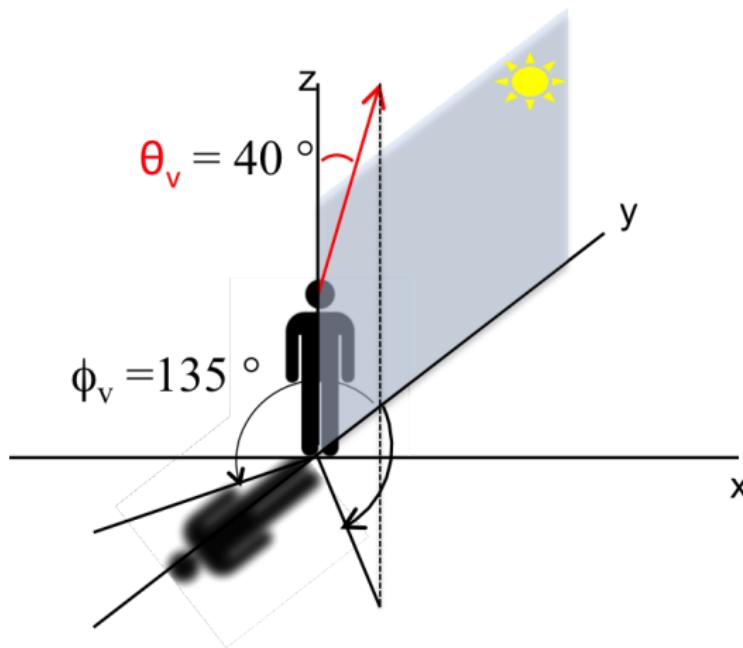
# Reflectance

- **Reflectance:**  $R(z, \lambda) \equiv \frac{L_u(z, \lambda)}{E_d(z, \lambda)}$
- Two measurements:
  - $E_d$ : Spectralon
  - $L_u$ : Target or sample

# Remote-Sensing Reflectance

- 3 measurements:
  - $L_g$  (spectralon)
  - $L_t = L_r + L_w$  (water)
  - $L_{sky}$
- Remote-sensing reflectance:
$$R_{rs} = L_w/E_d \\ = (L_t - L_r)/E_d$$
with  $L_r = 0.028 * L_{sky}$ 
  - $E_d = L_g * \pi$
  - $\phi$  : azimuthal angle
  - $\theta$  : zenith angle





# Things to consider for a field campaign

- have a good datasheet
- download and look data ASAP
- tools for in-field repairs and cleaning
- water, food, field clothes, first aid
- plan collection ahead of time
- write down procedure
- setting up plots/sites
- take pictures
- read manual
- charge batteries
- check batteries
- check instrument in advance
- The data should be taken as close to the time of acquisition as possible (due to inevitable landscape changes)

# Field Campaigns

- Brings theory to practice
- It is FUN!

SHOW PICTURES HERE!

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# DIRS Lab Instruments

- ASD
- SVC
- RIT LIDAR
- GRIT
- WASP
- GPS
- HydroScat-2
- AccuPAR LP-80
- WASP
- WASP Lite
- MISI
- Thermistor
- Camera
- Tape measures

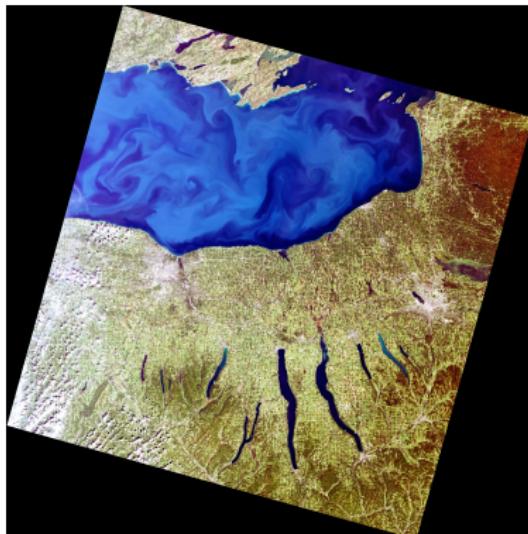
# Data Extraction

- Data in proprietary format
- Translate or export to ASCII (text file)
- Text files manipulation (IDL, Matlab, Python, C++, bash).

Thanks for your attention!

QUESTIONS?

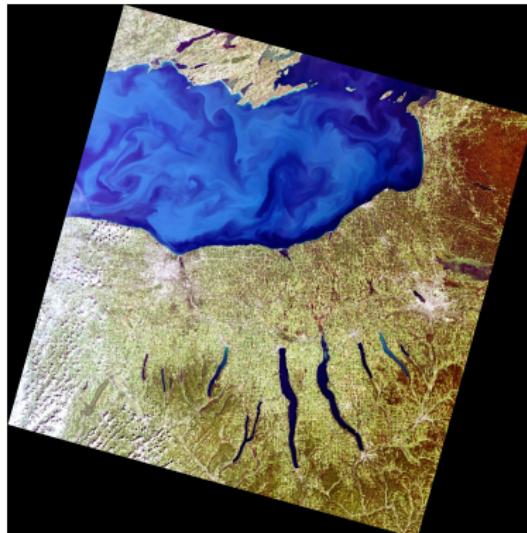
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(09/19/2013)

Thanks for your attention!  
**QUESTIONS?**

Javier A. Concha  
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# References

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