

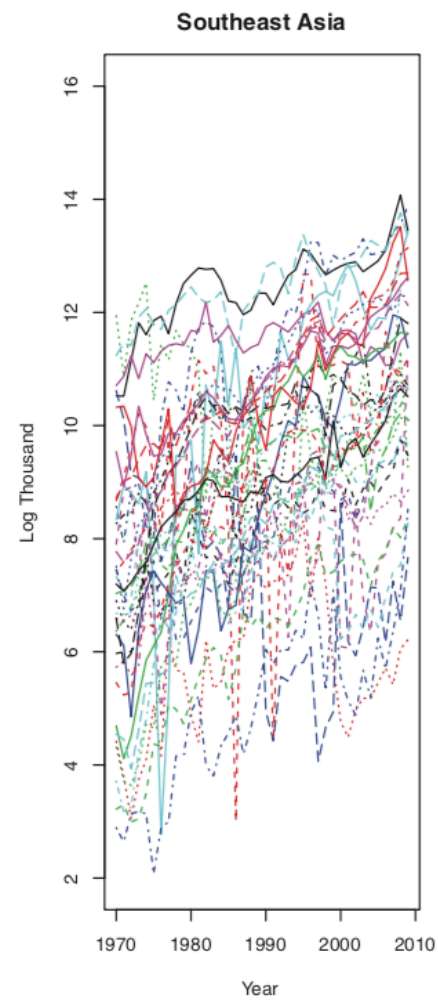
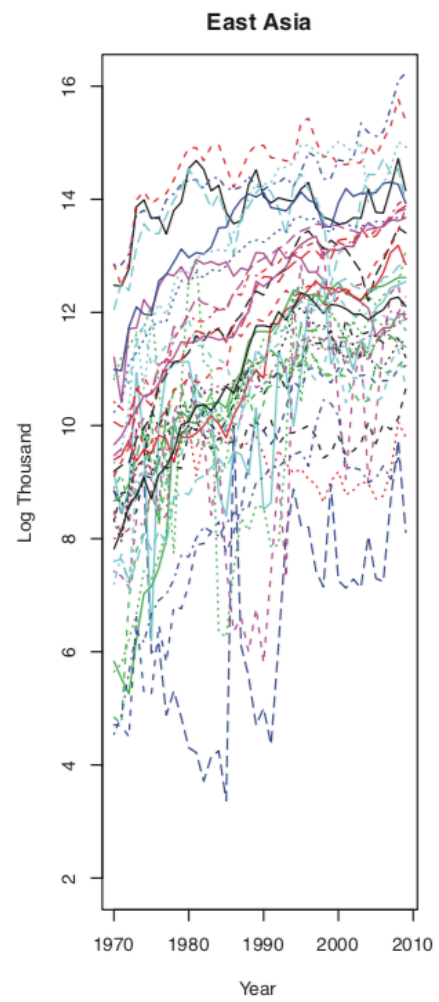
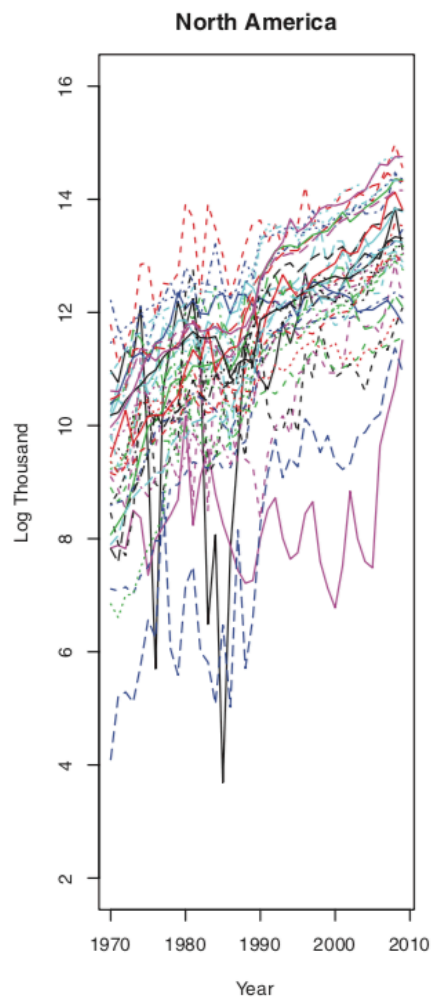
# Sparse Matrix Graphical Models

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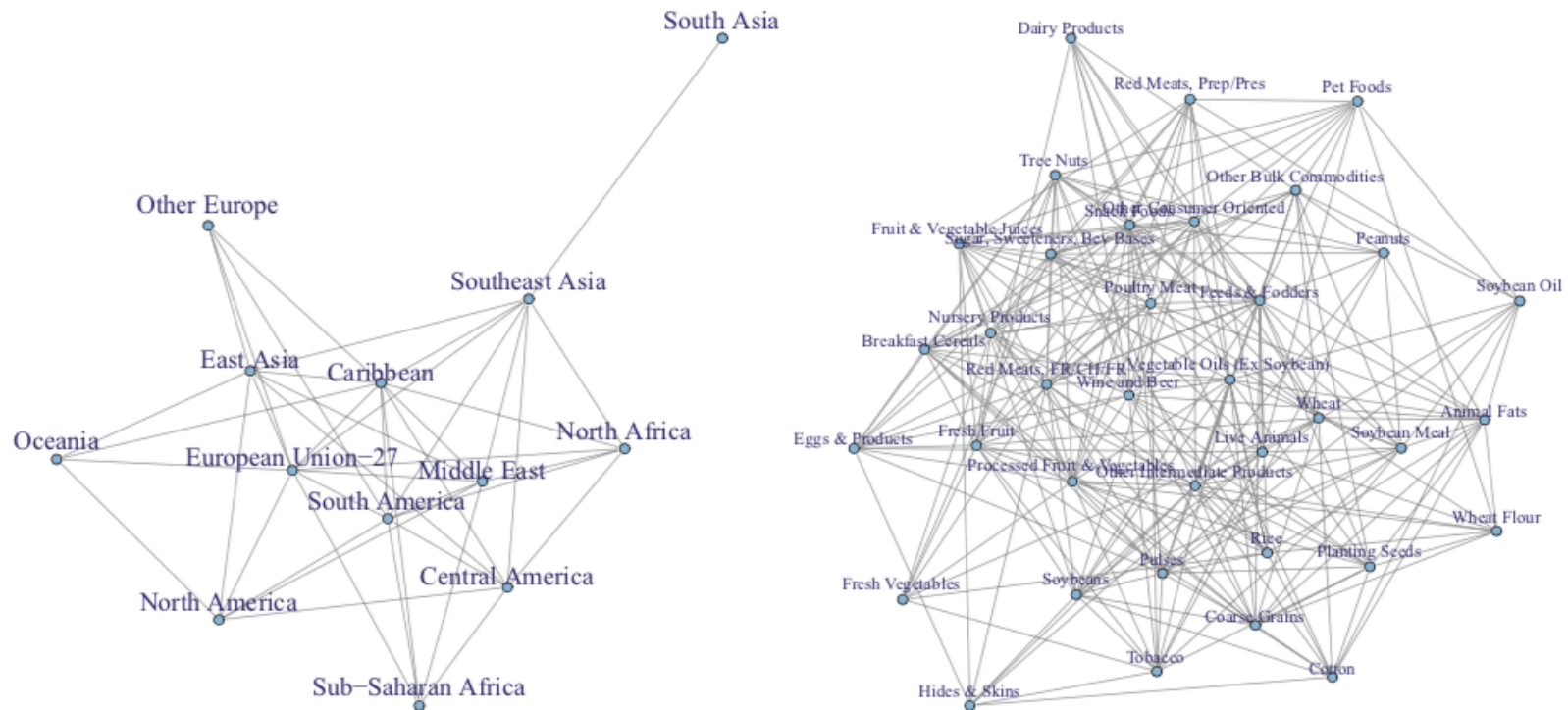
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Presented by Javier Zapata





- We would like a graph for the regions and another for the export items:



- This can be achieved by using a graphical model on a **matrix-variate normal distribution** which encodes the structural information in row and column variables.

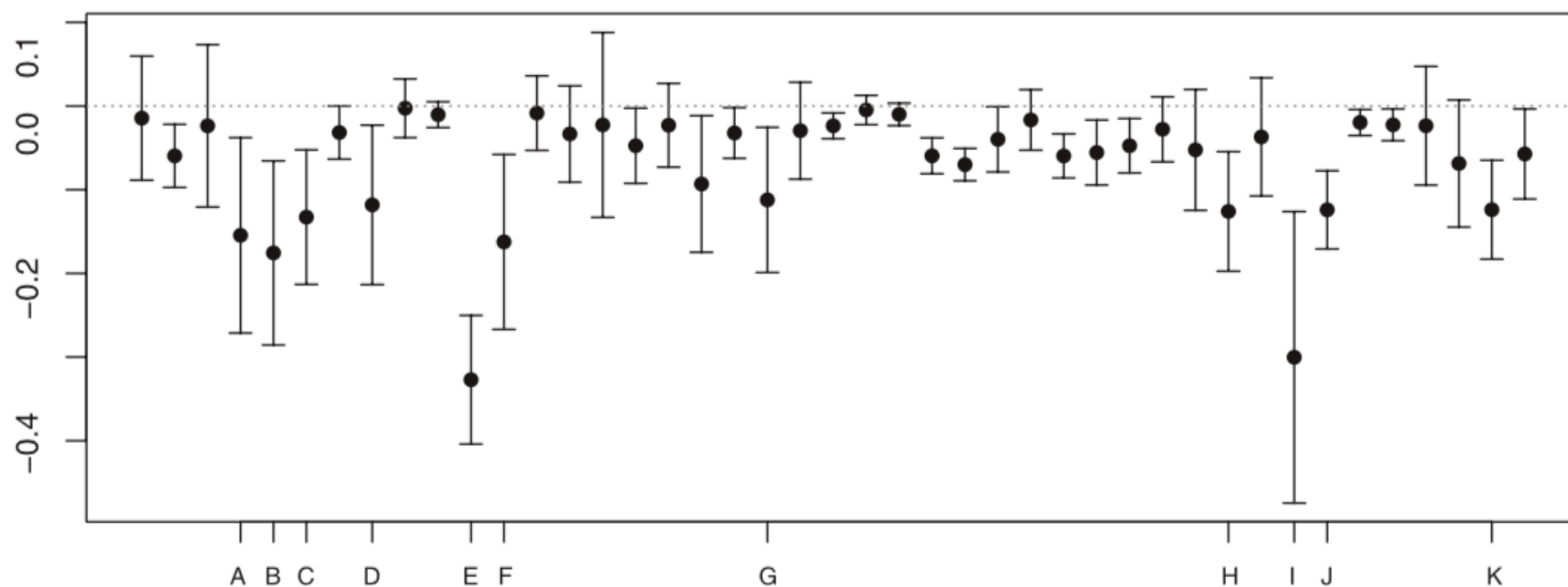


Figure 4. The estimates and the corresponding 95% confidence intervals for the 43 edges between the regions, where the largest 11 edges are marked. “A” is for CAR and SAM, “B” for CAM and SAM, “C” for NAM and EU, “D” for SAM and EU, “E” for EU and OE, “F” for NAM and EA, “G” for SAM and EU, “H” for SAM and SEA, “I” for EA and SEA, “J” for ME and SEA, and “K” for EU and OC, where EU denotes Europe Union, OE denotes Other Europe, EA denotes East Asia, SEA denotes Southeast Asia, CAM denotes Central America, NAM denotes North America, SAM denotes South America, CAR denotes Caribbean, and OC denotes Oceania.

# **Basics: Matrix Variate Normal Distribution**

# Preliminaries: Normal Distributions

- $X \sim N(\mu, \sigma)$  has density:  $(2\pi\sigma^2)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2\sigma^2}(x - \mu)^2 \right\}, x \in \mathbb{R},$
- $\mathbf{X} = (X_1, \dots, X_p) \sim N_p(\boldsymbol{\mu}, \Sigma)$  has density:

$$(2\pi)^{-\frac{1}{2}p} \det(\Sigma)^{-\frac{1}{2}} \text{etr} \left\{ -\frac{1}{2} \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})' \right\}, \mathbf{x} \in \mathbb{R}^p, \boldsymbol{\mu} \in \mathbb{R}^p, \Sigma > 0,$$

**DEFINITION 2.2.1.** *The random matrix  $X$  ( $p \times n$ ) is said to have a matrix variate normal distribution with mean matrix  $M$  ( $p \times n$ ) and covariance matrix  $\Sigma \otimes \Psi$  where  $\Sigma$  ( $p \times p$ )  $> 0$  and  $\Psi$  ( $n \times n$ )  $> 0$ , if  $\text{vec}(X') \sim N_{pn}(\text{vec}(M'), \Sigma \otimes \Psi)$ .*

We shall use the notation  $X \sim N_{p,n}(M, \Sigma \otimes \Psi)$ .

# Matrix Variate Normal Distribution

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We shall use the notation  $X \sim N_{p,n}(M, \Sigma \otimes \Psi)$ . We now derive the density of the

**THEOREM 2.2.1.** *If  $X \sim N_{p,n}(M, \Sigma \otimes \Psi)$ , then the p.d.f. of  $X$  is given by*

$$(2\pi)^{-\frac{1}{2}np} \det(\Sigma)^{-\frac{1}{2}n} \det(\Psi)^{-\frac{1}{2}p} \text{etr} \left\{ -\frac{1}{2} \Sigma^{-1} (X - M) \Psi^{-1} (X - M)' \right\},$$

$$X \in \mathbb{R}^{p \times n}, M \in \mathbb{R}^{p \times n}.$$



## Some Properties of Matrix Variate Normal

**Theorem 2.5.** *Let  $\mathbf{X} \sim N_{p,n}(\mu \mathbf{e}'_n, \Sigma \otimes \mathbf{I}_n)$ , where  $\mu \in \mathbb{R}^p$ . Let  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  be the columns of  $\mathbf{X}$ . Then,  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  are independent identically distributed random vectors with common distribution  $N_p(\mu, \Sigma)$ .*

**THEOREM 2.3.1.** *If  $X \sim N_{p,n}(M, \Sigma \otimes \Psi)$ , then  $X' \sim N_{n,p}(M', \Psi \otimes \Sigma)$ .*

**THEOREM 2.3.3.** *Let  $X \sim N_{p,n}(M, \Sigma \otimes \Psi)$ , and  $M = (m_{ij})$ ,  $\Sigma = (\sigma_{ti})$ ,  $\Psi = (\psi_{jk})$ . Then,*

$$(i) E(x_{i_1 j_1} x_{i_2 j_2}) = \sigma_{i_1 i_2} \psi_{j_1 j_2} + m_{i_1 j_1} m_{i_2 j_2}$$

$$(ii) E(x_{i_1 j_1} x_{i_2 j_2} x_{i_3 j_3}) = m_{i_1 j_1} \sigma_{i_2 i_3} \psi_{j_2 j_3} + m_{i_2 j_2} \sigma_{i_1 i_3} \psi_{j_1 j_3} + m_{i_3 j_3} \sigma_{i_1 i_2} \psi_{j_1 j_2} \\ + m_{i_1 j_1} m_{i_2 j_2} m_{i_3 j_3}$$

# **Sparse Matrix Graphical Models**

# Sparse Matrix Graphical Models

- Let  $X_1, \dots, X_n \sim N_{p,q}(\mathbf{M}, \mathbf{\Sigma} \otimes \mathbf{\Psi})$

where  $\mathbf{M} \in \mathbb{R}^{p \times q}$  is the mean matrix,  $\mathbf{\Sigma} \in \mathbb{R}^{p \times p}$  and  $\mathbf{\Psi} \in \mathbb{R}^{q \times q}$

- WLOG assume  $\mathbf{M} = \mathbf{0}$ . Otherwise, subtract  $\hat{\mathbf{M}} = \sum X_i / n$
- Denote the precision matrices as:  $\mathbf{\Omega} = \mathbf{\Sigma}^{-1} = (\omega_{ij})$  and  $\mathbf{\Gamma} = \mathbf{\Psi}^{-1} = (\gamma_{ij})$
- The partial correlation between  $X_{ij}$  and  $X_{kl}$  is:

$$\rho_{ij,kl} = -\frac{\omega_{ik}}{\sqrt{\omega_{ii}\omega_{kk}}} \cdot \frac{\gamma_{jl}}{\sqrt{\gamma_{jj}\gamma_{ll}}}$$

- For identifiability, set  $\omega_{11} = 1$

# Sparse Matrix Graphical Models (SMGMs)

- The negative log-likelihood is:

$$\ell(\mathbf{\Omega}, \mathbf{\Gamma}) = -\frac{nq}{2} \log |\mathbf{\Omega}| - \frac{np}{2} \log |\mathbf{\Gamma}| + \frac{1}{2} \sum_{i=1}^n \text{tr}(\mathbf{X}_i \mathbf{\Gamma} \mathbf{X}_i^T \mathbf{\Omega})$$

- Sparse models for  $\mathbf{\Omega}$  and  $\mathbf{\Sigma}$  can be obtained minimizing:

$$g(\mathbf{\Omega}, \mathbf{\Gamma}) = \frac{1}{npq} \sum_{i=1}^n \text{tr}(\mathbf{X}_i \mathbf{\Gamma} \mathbf{X}_i^T \mathbf{\Omega}) - \frac{1}{p} \log |\mathbf{\Omega}| - \frac{1}{q} \log |\mathbf{\Gamma}| + p_{\lambda_1}(\mathbf{\Omega}) + p_{\lambda_2}(\mathbf{\Gamma})$$

where  $p_{\lambda}(\mathbf{A}) = \sum_{i \neq j} p_{\lambda}(|a_{ij}|)$  for a square matrix  $\mathbf{A} = (a_{ij})$

- The article uses LASSO and SCAD penalties.

# Penalties

For LASSO:  $p_\lambda(s) = \lambda|s|$

For SCAD:  $p'_\lambda(s) = \lambda \left\{ I(s \leq \lambda) + \frac{(3.7\lambda - s)_+}{2.7\lambda} I(s > \lambda) \right\}$

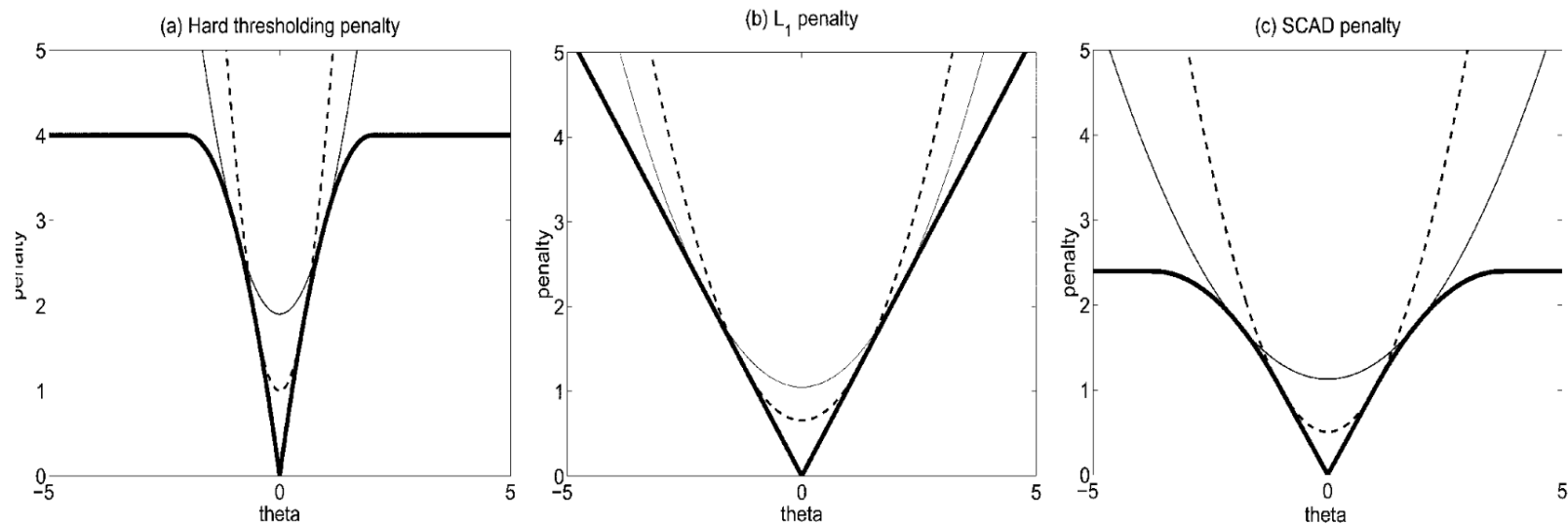


Figure 1. Three Penalty Functions  $p_\lambda(\theta)$  and Their Quadratic Approximations. The values of  $\lambda$  are the same as those in Figure 5(c).

# SMGM Implementation

$$g(\mathbf{\Omega}, \mathbf{\Gamma}) = \frac{1}{npq} \sum_{i=1}^n \text{tr}(\mathbf{X}_i \mathbf{\Gamma} \mathbf{X}_i^T \mathbf{\Omega}) - \frac{1}{p} \log |\mathbf{\Omega}| - \frac{1}{q} \log |\mathbf{\Gamma}| + p_{\lambda_1}(\mathbf{\Omega}) + p_{\lambda_2}(\mathbf{\Gamma})$$

- Let  $\tilde{\mathbf{\Sigma}} = \sum_{i=1}^n \mathbf{X}_i^T \mathbf{\Omega} \mathbf{X}_i / q$  and  $\tilde{\mathbf{\Psi}} = \sum_{i=1}^n \mathbf{X}_i \mathbf{\Gamma} \mathbf{X}_i^T / p$ .
- The penalized log-likelihood is not convex. But is conditionally convex if the penalty function is convex. When  $\mathbf{\Omega}$  is fixed, solve:

$$\min_{\mathbf{\Gamma}} \frac{1}{q} \text{tr}(\mathbf{\Gamma} \tilde{\mathbf{\Sigma}}) - \frac{1}{q} \log |\mathbf{\Gamma}| + p_{\lambda_2}(\mathbf{\Gamma}).$$

- When  $\mathbf{\Gamma}$  is fixed, solve:

$$\min_{\mathbf{\Omega}} \frac{1}{p} \text{tr}(\tilde{\mathbf{\Psi}} \mathbf{\Omega}) - \frac{1}{p} \log |\mathbf{\Omega}| + p_{\lambda_1}(\mathbf{\Omega})$$

# SMGM Implementation

- The computational algorithm
  1. Start with  $\mathbf{\Gamma}^{(0)} = \mathbf{I}_q$ , and minimize (4) to get  $\mathbf{\Omega}^{(0)}$ . Normalize  $\mathbf{\Omega}^{(0)}$  such that  $\omega_{11}^{(0)} = 1$ . Let  $m = 1$ .
  2. Fix  $\mathbf{\Omega}^{(m-1)}$  and minimize (5) to get  $\mathbf{\Gamma}^{(m)}$ .
  3. Fix  $\mathbf{\Gamma}^{(m)}$  and minimize (4) to get  $\mathbf{\Omega}^{(m)}$ . Normalize such that  $\omega_{11}^{(m)} = 1$ . Let  $m \leftarrow m + 1$ .
  4. Repeat Steps 2 and 3 until convergence.
- For  $n < \min(p, q)$ : The algorithm converges to a local stationary point of  $g(\mathbf{\Omega}, \mathbf{\Gamma})$ . But there is no guarantee on the global minimum.
- For  $n > \max(p, q)$ : MLE exists and is unique. Moreover the algorithm guarantees global optimal solution for LASSO or ridge.

# Asymptotics

*Theorem 1.* [Rate of convergence] Under Conditions A1–A4, as  $n \rightarrow \infty$ ,  $(p + s_1) \log p / (nq) \rightarrow 0$ , and  $(q + s_2) \log q / (np) \rightarrow 0$ , there exists a local minimizer of (3) such that

$$\frac{\|\hat{\mathbf{\Omega}} - \mathbf{\Omega}_0\|_{\text{F}}^2}{p} = O_p \left\{ \left( 1 + \frac{s_1}{p} \right) \log p / (nq) \right\}$$

and

$$\frac{\|\hat{\mathbf{\Gamma}} - \mathbf{\Gamma}_0\|_{\text{F}}^2}{q} = O_p \left\{ \left( 1 + \frac{s_2}{q} \right) \log q / (np) \right\}.$$



# Asymptotics

*Theorem 2.* [Sparsistency] Under Conditions A1–A4, for local minimizers  $\hat{\mathbf{\Omega}}$  and  $\hat{\mathbf{\Gamma}}$  satisfying  $\|\hat{\mathbf{\Omega}} - \mathbf{\Omega}_0\|_F^2 = O_p\{(p + s_1) \log p/(nq)\}$ ,  $\|\hat{\mathbf{\Gamma}} - \mathbf{\Gamma}_0\|_F^2 = O_p\{(q + s_2) \log q/(np)\}$ ,  $\|\hat{\mathbf{\Omega}} - \mathbf{\Omega}_0\| = O_p(\eta_{1n})$ ,  $\|\hat{\mathbf{\Gamma}} - \mathbf{\Gamma}_0\| = O_p(\eta_{2n})$  for sequences  $\eta_{1n}$  and  $\eta_{2n}$  converging to 0,  $\log p/(nq) + \eta_{1n} + \eta_{2n} = O_p(\lambda_1^2 p^2)$ , and  $\log q/(np) + \eta_{1n} + \eta_{2n} = O_p(\lambda_2^2 q^2)$ , with probability tending to 1, we have  $\hat{\omega}_{ij} = 0$  and  $\hat{\gamma}_{ij} = 0$  for all  $(i, j) \in S_1^c$  and  $(i, j) \in S_2^c$ .

- Sparsistency when the off-diagonal nonzeros of  $\mathbf{\Omega}_0$  and  $\mathbf{\Gamma}_0$  are:
  - For LASSO: at most  $O(p)$  and  $O(q)$
  - For SCAD: at most  $O(p^2)$  and  $O(q^2)$

# Asymptotics

Fast rates of convergence  $\sqrt{nq}$  and  $\sqrt{np}$  for estimating the precision matrices

*Theorem 3.* [Asymptotic normality] Under Conditions A1–A4,  $(p + s_1)^2/(nq) \rightarrow 0$  and  $(q + s_2)^2/(np) \rightarrow 0$  as  $n \rightarrow \infty$ , for the local minimizer  $\hat{\mathbf{\Omega}}$  and  $\hat{\mathbf{\Gamma}}$  in Theorem 1, we have

$$\begin{aligned} & \sqrt{nq} \boldsymbol{\alpha}_p^\top \left\{ \boldsymbol{\Sigma}_0^{\otimes 2} (\mathbf{I} + \mathbf{K}_{pp}) \right\}_{S_1 \times S_1}^{-1/2} \left( \boldsymbol{\Lambda}_{1n} + \boldsymbol{\Sigma}_0^{\otimes 2} \right)_{S_1 \times S_1} \\ & \quad \times \{ \text{vec}(\hat{\mathbf{\Omega}}) - \text{vec}(\mathbf{\Omega}_0) + \mathbf{b}_{1n} \}_{S_1} \xrightarrow{d} N(0, 1), \\ & \sqrt{np} \boldsymbol{\alpha}_q^\top \left\{ \boldsymbol{\Psi}_0^{\otimes 2} (\mathbf{I} + \mathbf{K}_{qq}) \right\}_{S_2 \times S_2}^{-1/2} \left( \boldsymbol{\Lambda}_{2n} + \boldsymbol{\Psi}_0^{\otimes 2} \right)_{S_2 \times S_2} \\ & \quad \times \{ \text{vec}(\hat{\mathbf{\Gamma}}) - \text{vec}(\mathbf{\Gamma}_0) + \mathbf{b}_{2n} \}_{S_2} \xrightarrow{d} N(0, 1), \end{aligned}$$

where  $\boldsymbol{\alpha}_d$  denotes a  $d$ -dimensional unit vector and  $\xrightarrow{d}$  denotes convergence in distribution.