## Mathematics 8: Relaxing Laplace

Numerical treatments of problems based on the Laplacian operator,  $\nabla^2$ , are usually tackled by relaxation. Once one has chosen a 'grid' to work with, an approximate value for  $\nabla^2$  may be obtained from the values of the function at the 'cage' of nearest-neighbours:

$$y(\mathbf{a} + \mathbf{x}_j) = y(\mathbf{a}) + \mathbf{x}_j \cdot \nabla y(\mathbf{a}) + \frac{1}{2} \left[ \mathbf{x}_j \cdot \nabla \right]^2 y(\mathbf{a}) + \frac{1}{6} \left[ \mathbf{x}_j \cdot \nabla \right]^3 y(\mathbf{a}) + O\left( \mid \mathbf{x}_j \mid^4 \right)$$

where  $\mathbf{x}_j$  is a vector joining nearest-neighbours, which is small if the grid is fine. When we average over nearest-neighbours, since both  $\mathbf{x}_j$  and  $-\mathbf{x}_j$  are present in the sum, the odd terms cancel, leaving:

$$\frac{1}{Z} \sum_{j} y(\mathbf{a} + \mathbf{x}_{j}) = y(\mathbf{a}) + \frac{1}{2Z} \sum_{j} \left[ \mathbf{x}_{j} . \nabla \right]^{2} y(\mathbf{a}) + O\left( |\mathbf{x}|^{4} \right)$$

where Z is the number of nearest-neighbours, the so-called coordination number.

For most choices of *symmetric* grid, the second order term is proportional to the Laplacian.

Square or Triangular:

$$rac{1}{2Z}\sum_{j}\left[\mathbf{x}_{j}.
abla
ight]^{2}y(\mathbf{a})=rac{\mid\mathbf{x}\mid^{2}}{4}
abla^{2}y(\mathbf{a})$$

so for either case:

$$\mid \mathbf{x} \mid^2 
abla^2 y(\mathbf{a}) = 4 \left[ rac{1}{Z} \sum_j y(\mathbf{a} + \mathbf{x}_j) - y(\mathbf{a}) 
ight] + O\left(\mid \mathbf{x} \mid^4
ight)$$

Relaxation involves updating the central site to be the average of its neighbours according to this quadratic approximation for  $\nabla^2 y(\mathbf{a})$ . So if we want to solve  $\nabla^2 y(\mathbf{a}) = 0$  and we have a grid set up denoted by a label i, then we set:

$$y_i \mapsto rac{1}{Z} \sum_{\langle ij 
angle} y_j$$

where  $\langle ij \rangle$  denotes all nearest-neighbours. It is often useful to 'overshoot':

$$y_i \mapsto (1+lpha) \, rac{1}{Z} \sum_{\langle ij 
angle} y_j - lpha y_i$$

to improve convergence.