

# DATA DESIGN AND IMPLEMENTATION

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# After studying this chapter, you should be able to

- Describe an ADT from three perspectives: the logical level, the application level, and the implementation level
- Explain how a specification can be used to represent an abstract data type
- Describe the component selector at the logical level, and describe appropriate applications for the C++ built-in types: structs, classes, one-dimensional arrays, and two-dimensional arrays
- Declare a class object
- Implement the member functions of a class
- Manipulate instances of a class (objects)
- Define the three ingredients of an object-oriented programming language: encapsulation, inheritance, and polymorphism
- Distinguish between containment and inheritance
- Use inheritance to derive one class from another class
- Use the C++ exception handling mechanism
- Access identifiers within a namespace
- Explain the use of Big-O notation to describe the amount of work done by an algorithm

# What is Data?

- Data are the nouns of the programming world:
  - The objects that are manipulated
  - The information that is processed
- **Data abstractions** separate our *logical* view of data from the computer's *implementation* view

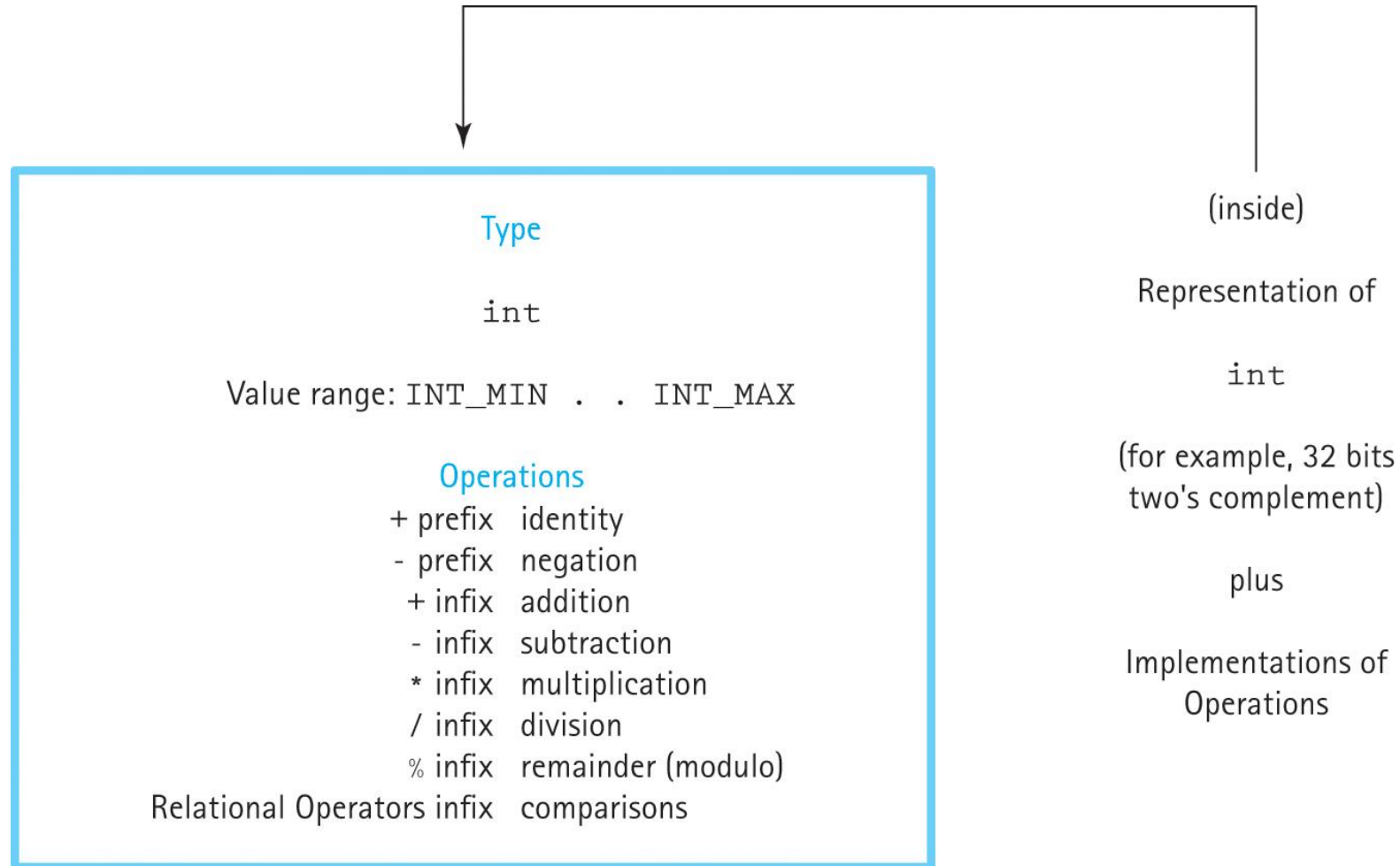
# Data Abstraction

- Logical view:
  - What are the possible values?
  - What are the operations on this data?
- Implementation view:
  - How is this data used?
  - How is it stored in memory?
  - How can it be implemented in C++?

# Data Encapsulation

- **Encapsulation** separates the representation of data from applications that use the data at the logical level
- The physical representation is hidden behind an interface for interacting with the data
- **Abstract Data Type:** A data type whose operations and domain of values are specified independently of any implementation

# Data Encapsulation (cont.)



**Figure 2.1** A black box representing an integer

# Data Structures

- A collection of data elements with operations that store and manipulate individual elements
  - Can be decomposed into individual elements
  - The arrangement of elements in the structure is significant
  - Arrangement and access of elements can be encapsulated
- Used to implement ADTs

# Example: Library as an ADT

- A library's data elements are the books
- ADT interface: Users can check books in or out, reserve books, and pay fines
- Data structure: Can order books randomly, alphabetically by title, or use the Dewey Decimal System
- Users don't need to know how the library organizes the books



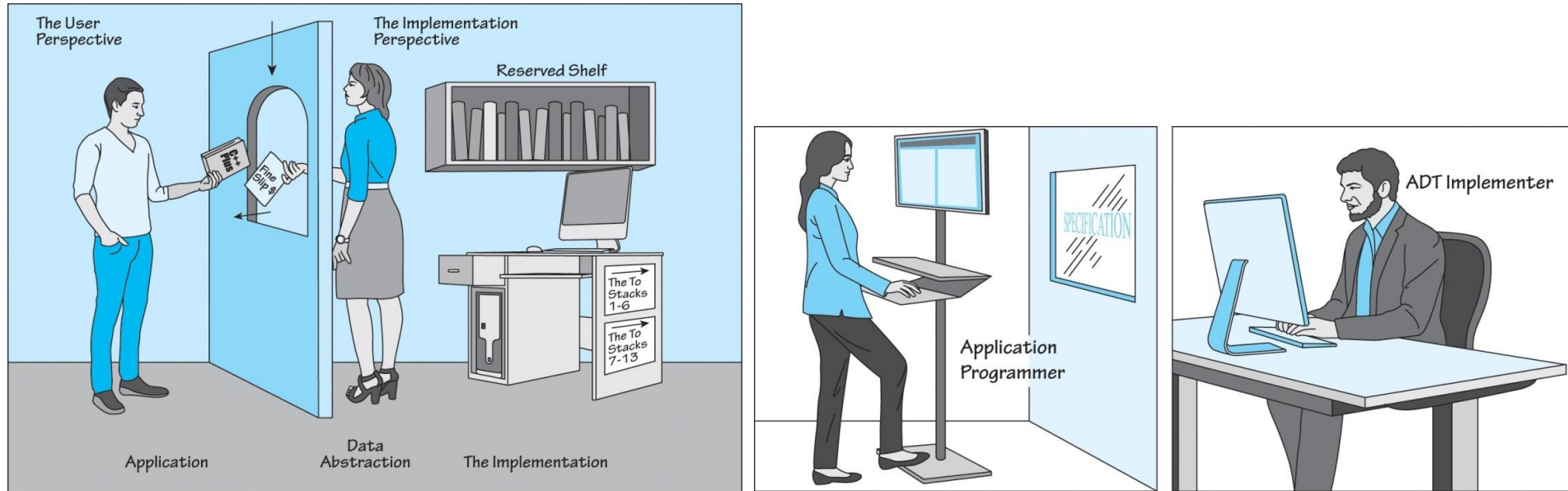
# Data From Different Levels

- **Application (user) level:** The problem domain; modeling real-life data in the problem's context
- **Logical (abstract) level:** Abstract view of data values and operations on data
  - “What” questions: What do we do to the data?
- **Implementation level:** Specific representation of data in the program
  - “How” questions: How do we implement the ADT?

# Data Levels of a Library

- **Application level:** Library of Congress or Baltimore County Public Library
- **Logical level:** The domain is a collection of books
  - Operations include: check a book out, check a book in, pay a fine, reserve a book
- **Implementation level:** Representation of the book data structure to hold the library's data, and the coding for operations

# Application and Implementation



**Figure 2.3** Communication between the application level and implementation level

# ADT Operator Categories

Operations on ADTs can be classified as:

- **Constructors:** Create new instances (objects) of an ADT
- **Transformers:** Change the internal state of the object
- **Observers:** View the state of the object -  
Observers come in several forms: predicates, accessors, and summaries
- **Iterators:** For the sequential processing of elements

# Composite Data Type

- A **composite data type** stores a collection of individual data components under one name and allows access to individual components
- Two forms:
  - **Unstructured:** Components are not organized with respect to each other (e.g., classes)
  - **Structured:** Components are organized and it affects how they are accessed (e.g., arrays)

# Records: Logical Level

- **Record:** A finite collection of elements that are called *members* or *fields*
- Members are accessed using named selectors, such as `mystruct.fieldname`
  - Can also be used to assign values to fields

# Records: Application Level

- Collect related data in one structure
- Used to implement other data structures

	myCar									
.year	1998									
.maker	J	A	G	U	A	R	\0			
.price	40998.33									

**Figure 2.4** Record myCar

# Records: Implementation Level

- Records occupy a contiguous chunk of memory
- Each member is located at an offset from the beginning of the record
- Calculating offsets is handled automatically by the compiler and run-time system
- The implementation is structured even though the logical view is not



# Implementation of a CarType

<u>Member</u>	<u>Length</u>	<u>Offset</u>
year	1	0
maker	10	1
price	2	11

<u>Address</u>	
8500	year member (length=1)
8501	maker member (length=10)
8502	
•	
•	
8509	price member (length=2)
8510	
8511	price member (length=2)
8512	

**Figure 2.6** Implementation-level view of CarType

# Passing Records to Functions

C++ supports two ways of passing arguments:

- **By value:** A copy of the argument is passed; the original argument cannot be modified by the function
- **By reference:** The function receives the memory location of the argument, allowing changes to be made directly

# One-Dimensional Arrays: Logical Level

- **Arrays** are finite, fixed-size collections of ordered homogeneous elements
- Permit direct, random access of elements using indices: `myArray[2]` accesses the third element
- Arrays can only be passed by reference
  - Functions can change array contents
  - Can prevent changes by using the `const` keyword

# One-Dimensional Arrays: Application Level

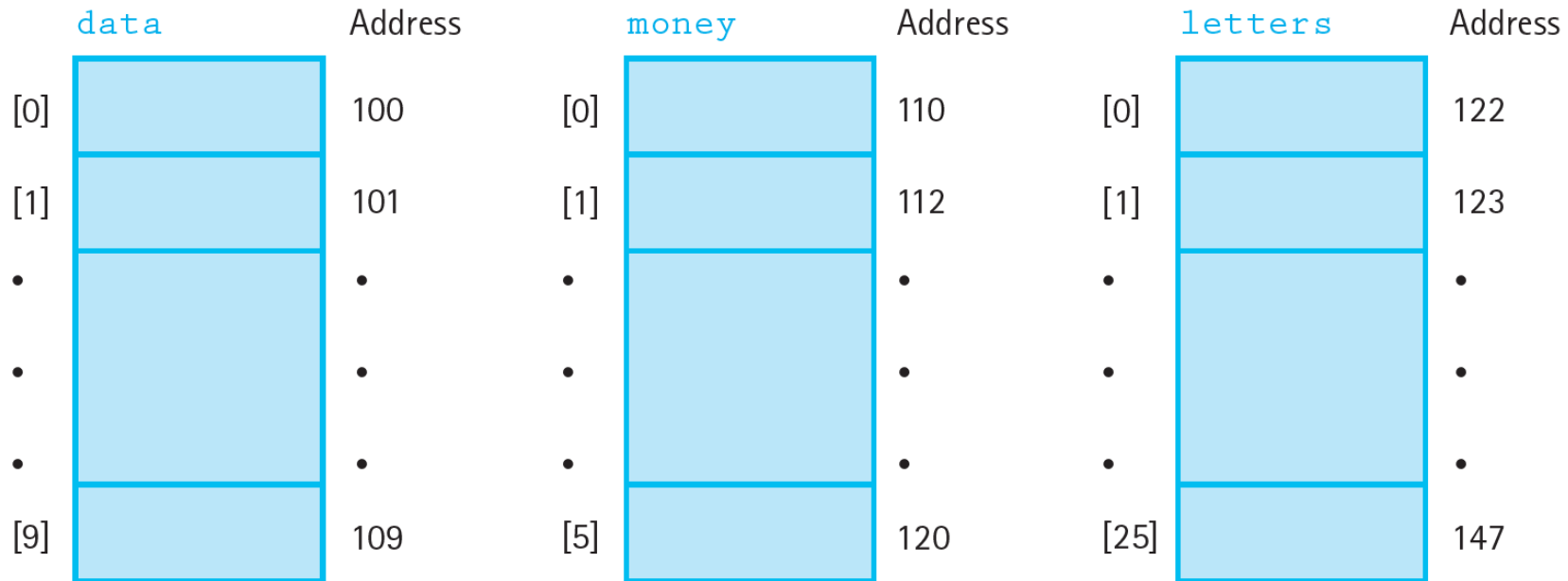
- Used to store lists of data elements
- Strings are arrays of characters
- Arrays must be homogeneous (all one type)
- Operations: Creation and element access

# One-Dimensional Arrays: Implementation Level

The *array declaration* describes the name of the array and the type and number of elements

- An array of ten integers: `int data[10];`
- To access an element, calculate the offset from the base address (beginning of the array)
- This is automatically handled by the compiler:
- $\text{Address} = \text{base} + \text{index} * \text{size of element}$

# One-Dimensional Arrays: Memory Layout



# Two-Dimensional Arrays: Logical Level

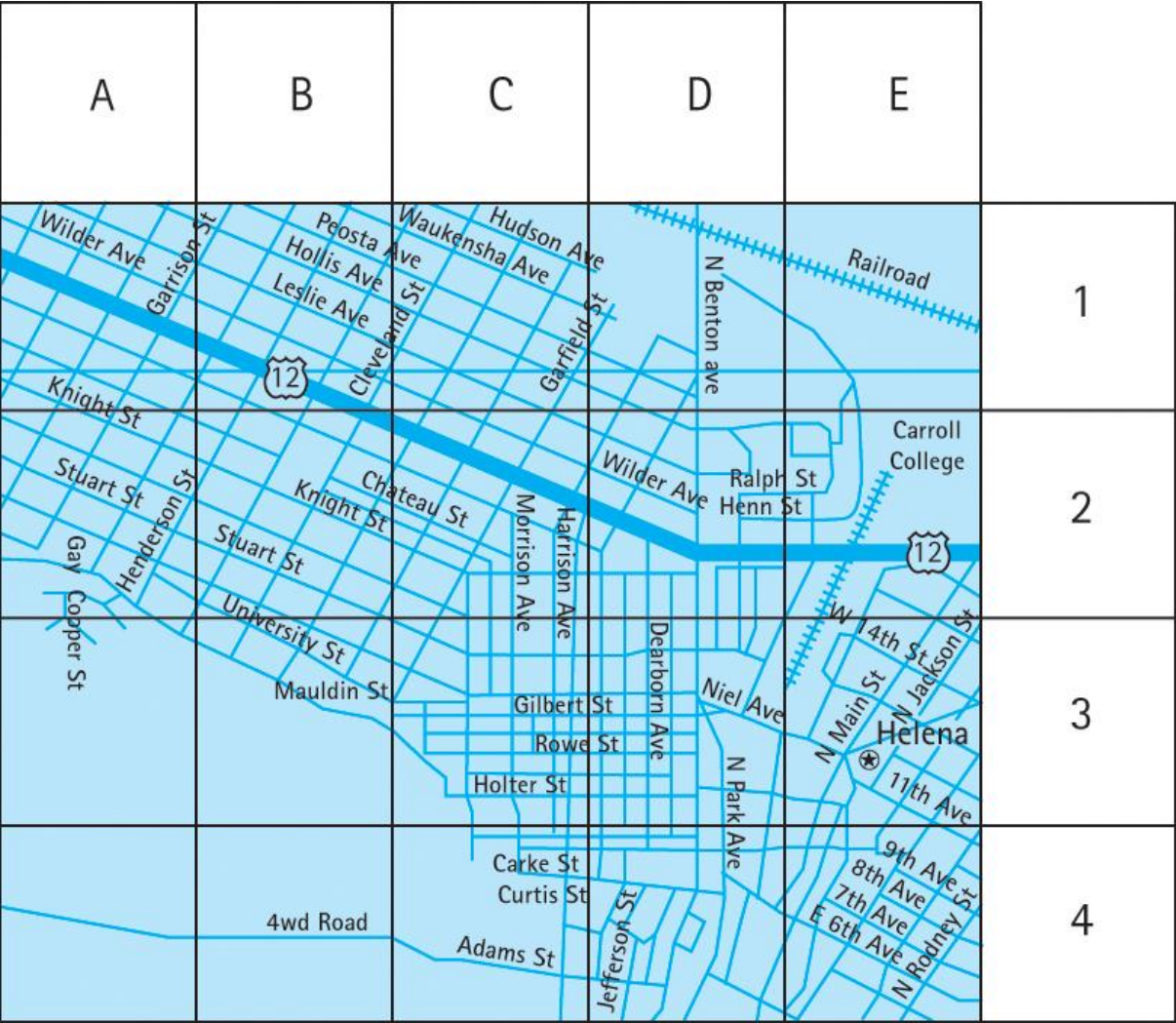
- Finite, fixed-size, ordered collections of homogeneous array elements
  - Very similar to one-dimensional arrays
- Can be thought of as a table of rows and columns: `table[row][col]`
- When used as parameters, must include the size of the second dimension:
- `int ProcessValues(int values[][5])`

# Two-Dimensional Arrays: Application Level

- Ideal for representing tables of data
- Operations: Creation and element access
- Primarily used to implement other data structures
- Can be thought of as an array of arrays, or as a two-dimensional matrix



# Map as a 2-D Array:



# Two-Dimensional Arrays: Implementation Level

- Stored as a single contiguous piece of memory
- **Row-major order:** Two-dimensional arrays in C++ are stored row-by-row
  - An  $N \times M$  array uses  $(N * M * \text{element size})$  memory
  - The first  $M$  cells are the first row, and so on
  - In *column-major order*, the first  $N$  cells would be the first column

# C++ Class Type

- An unstructured type that encapsulates a fixed number of data components along with functions that manipulate them
- Operations: Member access and whole assignment
  - More operations can be defined per class

# Using Classes

- A variable of a class type is called an *object* or *instance* of the class
- Software that uses instances of a class is called a *client*
- Clients must have `#include "ClassName.h"` in order to be able to use `ClassName` objects
- Clients can only access public members of an object

# Class Specification

- Describes data fields and functions of the class
- Typically in its own file with “.h” extension
- The implementation resides in a separate file
  - Allows for a cleaner interface
  - Programmers can focus on designing a class without worrying about implementation details
  - Can easily change the implementation without touching the interface

# Class Implementation

- Must define all constructors and methods
- Use the **scope resolution operator** “::” to indicate a function implementation belongs to a class:  
`int DateType::GetMonth() const`

# Using “Self”

- Don't need to qualify member names in class functions
  - e.g., If a class has a member “foo,” then the name “foo” in the function refers to the object's field
- The “self” keyword can be used to refer to the object on which the member function is called
  - e.g., In today.GetMonth(), “self” points to today

# Classes vs. Structs

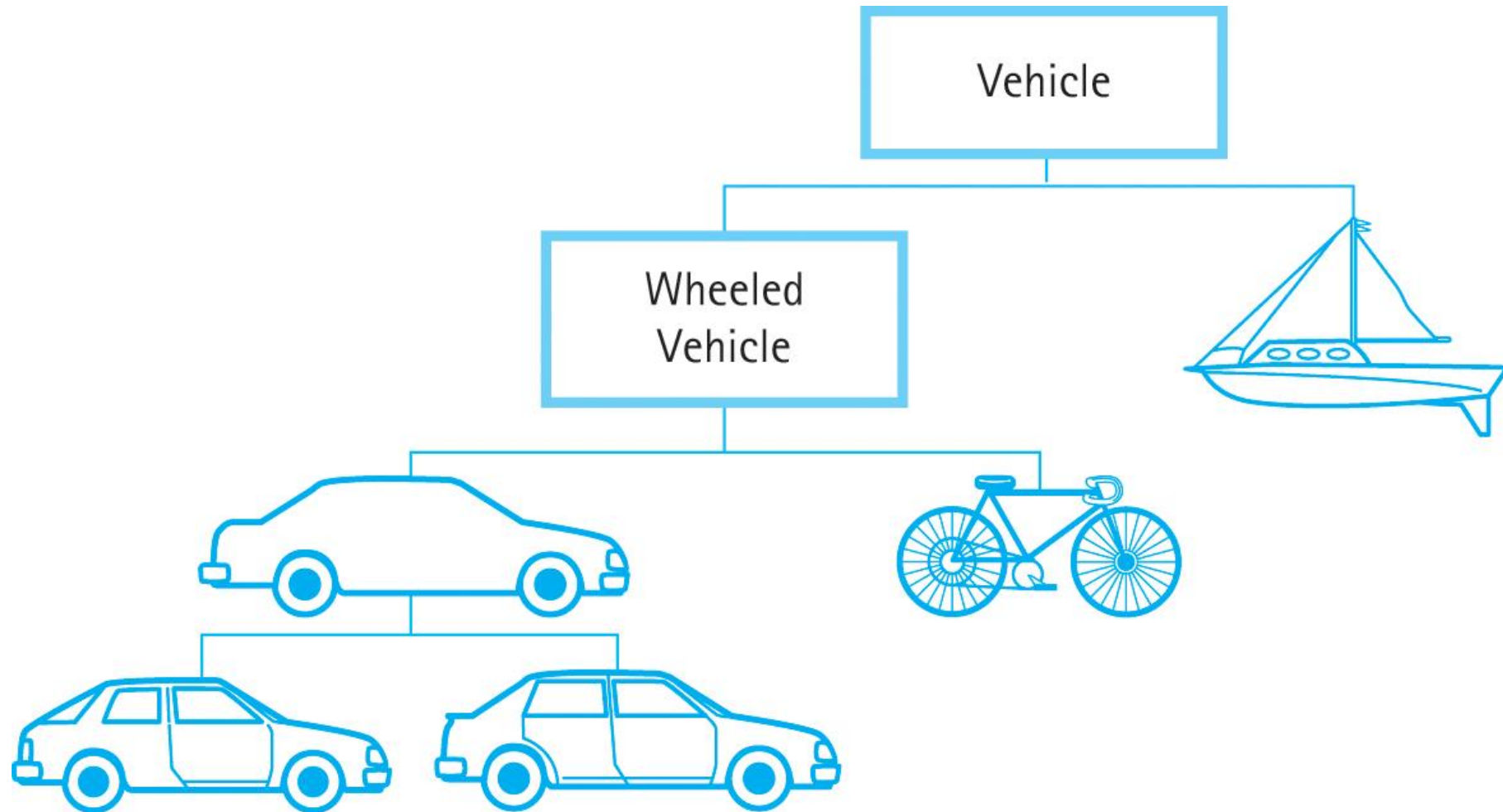
- Both are unordered collections of members
- **Structs:** All members *public* by default, typically used as basic container of related data, operations on data are performed by passing struct to global functions
- **Classes:** All members *private* by default, operations on data are defined as member functions



# Inheritance

- Classes can **inherit** properties (data and methods) from other classes
  - Base class: The class being inherited from
  - Derived class: The class that inherits
- Derived classes are more specialized and typically have more fields
- Inheritance creates a hierarchy of classes
- Can be viewed as an “is-a” relationship

# Inheritance Hierarchy



**Figure 2.7:** Inheritance hierarchy

# Polymorphism

- **Overloading:** When multiple functions have the same name
  - They must have unique signatures, such as different numbers or types of parameters
- **Polymorphism:** The ability to statically or dynamically determine which version of an overloaded function to use

# Binding

- **Binding Time:** The time at which a name or symbol is bound to some code
- **Static Binding:** Occurs at compile time
- **Dynamic Binding:** Occurs during run time
- Polymorphism can use either kind of binding when determining which function to use

# C++ Constructs for OOP

- **Composition:** A class contains an object of another class type; also called *containment*
- **Inheritance:** In the form of
- `class Derived : public Base`
- **Virtual Methods:** Allow for dynamic binding, used to implement polymorphism

# Exceptions

- Enable programs to gracefully handle exceptional conditions
- *Try-catch* statement: *try* clause protects code that can cause exceptions, *catch* clause is executed if an exception is thrown
  - Keyword *throw* is used to trigger exceptions
- C++ standard library has many predefined exception classes

# Try-Catch Block

```
try {  
    // code that contains a possible error  
    // when the error occurs:  
    throw string("An error has occurred...");  
}  
catch (string message) {  
    // execution continues here  
    std::cout << message << std::endl;  
    return 1;  
}
```

# Exceptions in Code

```
try
{
    infile >> value;
    do
    {
        if (value < 0)
            throw string("Negative value");
        sum = sum + value;
    } while (infile);
}
catch (string message)
// Parameter of the catch is type string
{
    // Code that handles the exception
    cout << message << " found in file. Program aborted."
    return 1;
}
// Code to continue processing if exception not thrown
cout << "Sum of values on the file: " << sum;
```



# Comparison of Algorithms

- How do we compare the efficiency of different algorithms?
- Comparing execution time: Too many assumptions, varies greatly between different computers
- Compare number of instructions: Varies greatly due to different languages, compilers, programming styles...

# Big-O Notation

- The best way is to compare algorithms by the amount of work done in a critical loop, as a function of the number of input elements ( $N$ )
- **Big-O:** A notation expressing execution time (complexity) as the term in a function that increases most rapidly relative to  $N$
- Consider the *order of magnitude* of the algorithm

# Common Orders of Magnitude

- $O(1)$ : Constant or *bounded* time; not affected by  $N$  at all
- $O(\log_2 N)$ : Logarithmic time; each step of the algorithm cuts the amount of work left in half
- $O(N)$ : Linear time; each element of the input is processed
- $O(N \log_2 N)$ :  $N \log_2 N$  time; apply a logarithmic algorithm  $N$  times or vice versa

# Common Orders of Magnitude (cont.)

- $O(N^2)$ : Quadratic time; typically apply a linear algorithm  $N$  times, or process every element with every other element
- $O(N^3)$ : Cubic time; naive multiplication of two  $N \times N$  matrices, or process every element in a three-dimensional matrix
- $O(2^N)$ : Exponential time; computation increases dramatically with input size

# What About Other Factors?

- Consider  $f(N) = 2N^4 + 100N^2 + 10N + 50$
- We can ignore  $100N^2 + 10N + 50$  because  $2N^4$  grows so quickly
- Similarly, the 2 in  $2N^4$  does not greatly influence the growth
- The final order of magnitude is  $O(N^4)$
- The other factors may be useful when comparing two very similar algorithms

# Elephants and Goldfish

- Think about buying elephants and goldfish and comparing different pet suppliers
- The price of the goldfish is trivial compared to the cost of the elephants
- Similarly, the growth from  $100N^2 + 10N + 50$  is trivial compared to  $2N^4$
- The smaller factors are essentially noise

# Example: Phone Book Search

- Goal: Given a name, find the matching phone number in the phone book
- Algorithm 1: Linear search through the phone book until the name is found
- Best case:  $O(1)$  (it's the first name in the book)
- Worst case:  $O(N)$  (it's the final name)
- Average case: The name is near the middle, requiring  $N/2$  steps, which is  $O(N)$

# Example: Phone Book Search (cont.)

Algorithm 2: Since the phone book is sorted, we can use a more efficient search

- 1) Check the name in the middle of the book
- 2) If the target name is less than the middle name, search the first half of the book
- 3) If the target name is greater, search the last half
- 4) Continue until the name is found



# Example: Phone Book Search (cont.)

## Algorithm 2 Characteristics:

- Each step reduces the search space by half
- Best case:  $O(1)$  (we find the name immediately)
- Worst case:  $O(\log_2 N)$  (we find the name after cutting the space in half several times)
- Average case:  $O(\log_2 N)$  (it takes a few steps to find the name)

# Example: Phone Book Search (cont.)

Which algorithm is better?

- For very small  $N$ , algorithm may be faster
- For target names in the very beginning of the phone book, algorithm 1 can be faster
- Algorithm 2 will be faster in every other case
- Success of algorithm 2 relies the fact that the phone book is sorted

Data structures matter!

# The End!

