# Seungjae Lee Robot Learning, Reinforcement Learning

#### Education

• Seoul National University

B.S., Mechanical and Aerospace Engineering

Seoul, Korea

Mar. 2015 - Feb. 2021

Email: ysz0301@snu.ac.kr

• Seoul National University

M.S., Aerospace Engineering

Advisor: Prof. H. Jim Kim (Lab for Autonomous Robotics Research)

Seoul, Korea

Mar. 2021 - Present

### Publications (\* Equal Contribution) [Publications URL: sjlee.cc]

• CQM: Curriculum Reinforcement Learning with a Quantized World Model Seungjae Lee, Daesol Cho, Jonghae Park, H Jin Kim

Thirty-seventh Conference on Neural Information Processing Systems, 2023,

NeurIPS'23

• Diversify Conquer: Outcome-directed Curriculum RL via Out-of-Distribution Disagreement Daesol Cho. Seungiae Lee. H Jin Kim

Thirty-seventh Conference on Neural Information Processing Systems, 2023,

NeurIPS'23

• SNeRL: Semantic-aware Neural Radiance Fields for Reinforcement Learning Dongseok Shim\*, Seungjae Lee\*, H Jin Kim Kim

Fortieth International Conference on Machine Learning, 2023,

ICML'23

• Outcome-directed Reinforcement Learning by Uncertainty & Temporal Distance-Aware Curriculum Goal Generation

Daesol Cho\*, Seungjae Lee\*, H Jin Kim

 $Eleventh\ International\ Conference\ on\ Learning\ Representations,\ 2023,$ 

Spotlight ICLR'23

• Deep End-to-End Imitation Learning for Missile Guidance with Infrared Images Seungjae Lee, Jongho Shin, Hyeong-Geun Kim, Daesol Cho, H. Jin Kim International Journal of Control, Automation and Systems (IJCAS), 2023,

IJCAS'23

• DHRL: A Graph-Based Approach for Long-Horizon and Sparse Hierarchical Reinforcement Learning Seungjae Lee, Jigang Kim, Inkyu Jang, H Jin Kim

Thirty-sixth Conference on Neural Information Processing Systems, 2022.

Oral NeurIPS'22

• Robust and Recursively Feasible Real-Time Trajectory Planning in Unknown Environments Inkyu Jang, Dongjae Lee, Seungjae Lee, H Jin Kim
2021 IEEE/RSJ International Conference on Intelligent Robots and Systems, 2021,

IROS'21

## Teaching / Work Experience

• Teaching Assistant, Principles of Flight Vehicle Control
Department of Aerospace Engineering, Seoul National University

Mar. 2021 - Jun. 2021

• Internship, Samsung Electronics (Neural Network Quantization)

Deep Learning Algorithm Team / Device Solutions (DS)

Jul. 2020 - Sep. 2020

#### **Projects**

• Vector-Quantized Behavior Transformer for Multi-Modal Demonstrations

Co-work with Generalizable Robotics and AI Lab (Prof. Lerrel Pinto) at New York University Jul. 2023 - Present

• Training Excavator Virtual Driver based on Inverse RL

Co-work with HD Hyundai Heavy Industries Co., Ltd.

Apr. 2023 - Present

• End-to-End Machine Learning Based Guidance Research Co-work with a Korean national research institute

May. 2021 - Apr. 2023

# Awards and Achievements

• (Awards) Graduated Summa Cum Laude, Seoul National University	Feb. 2021
• (Scholarship) Hyundai Motor Chung Mong-Koo Foundation	Sep. 2021 - Present
• (Awards) NeurIPS Scholar Award	Dec. 2022
• (Awards) Global Excellence Scholarship 2022, Hyundai Motor Chung Mong-Koo Foundat	tion Dec. 2022
• (Awards) Best poster competition, SNU Artificial Intelligence Institute Spring Retreat	May. 2023
• (Awards) Global Excellence Scholarship 2023, Hyundai Motor Chung Mong-Koo Foundat	tion <i>Jun. 2023</i>