

MFDS ASSIGNMENT

Q1) i) prove that $I - B$ is non-singular

Ans) Let us consider,
the possible Eigen values for
a Skew-Symmetric matrix.

Let 'λ' be the Eigen value for
 B , then

$$Bx = \lambda x \quad \text{--- (1)}$$

Consider L.H.S.
Multiply with conjugate of x^T on
both sides.

$$\Rightarrow \bar{x}^T B x = \bar{x}^T \lambda x$$

Consider R.H.S;

$$\Rightarrow \bar{x}^T \lambda x = \lambda \bar{x}^T x = \lambda (x^T x)$$

Consider L.H.S,

$$\bar{x}^T B x$$

This is good for dot product on

\bar{x}^T and Bx .

Apply commutative on dot product

$$= \text{I.C.} \quad \bar{x}^T B = B^T \bar{x}$$

$$\Rightarrow (Bx)^T \bar{x}$$

Q. 1

~~→~~ Apply Transpose of a product i.e.,
 $(AB)^T = B^T \cdot A^T$

$$\Rightarrow x^T \cdot B^T \cdot \bar{x} = -\textcircled{2}$$

→ In skew symmetric matrix

$$A^T = -A \quad \textcircled{3}$$

Substitute $\textcircled{3}$ in $\textcircled{2}$

$$\Rightarrow -x^T \cdot B \cdot \bar{x} = \textcircled{4}$$

Consider RHS Equation $\textcircled{1}$

$$\cancel{Ax} = \cancel{\lambda x}$$

$$\Rightarrow Bx = \lambda x \quad \text{both sides}$$

Apply conjugate on both sides

$$\bar{Bx} = \bar{\lambda x} \quad \textcircled{5}$$

Here B was real

⇒ Substitute $\textcircled{5}$ in $\textcircled{4}$

$$\Rightarrow -x^T \cdot \bar{\lambda} \cdot \bar{x} =$$

$$\Rightarrow -\bar{\lambda} \cdot \|x\|^2$$

Now try to equate L.H.S & R.H.S

$$\Rightarrow -\bar{\lambda} \cdot \|x\|^2 = -\lambda \|x\|^2$$

As x is Eigen vector, it will be
a non-zero vector.

$Q_1 P_2$

$$\Rightarrow -\bar{\lambda} = \lambda$$

The matrix will be Equal to \rightarrow
- (conjugate) only when it is zero &
 λ is purely imaginary.

So the possible Eigen vectors for
Skew Symmetric matrix will be either
Zero or purely imaginary.

\rightarrow Let get back to proof

$I - B$ is non-singular.

The Eigen Values of $I - B$ will be
of the form $1 - \lambda$

Here λ will be either 0 or $\neq 0$.

In both cases, the Eigen values
won't be negative.

So $I - B$ won't be singular.

Q) 2) $A = (I+B)(I-B)^{-1}$ &

B is skew symmetric.

Apply transpose on both sides

$$A^T = ((I+B) \cdot (I-B)^{-1})^T - \textcircled{1}$$

\Rightarrow Check R.H.S.

$$\therefore (AB)^T = B^T \cdot A^T$$

$Q_3 P_3$

$$\begin{aligned}
 \Rightarrow &= \left((I-B)^{-1} \right)^T \cdot (I+B)^T \\
 \Rightarrow &= \left((I-B)^T \right)^{-1} \cdot (I+B)^T \\
 \Rightarrow &= (I-B^T)^{-1} \cdot (I+B^T) \\
 (\because (A+B)^T &= A^T + B^T) \\
 \Rightarrow &= \cancel{(I+B)^{-1}} \cdot \cancel{(I+B^T)} \\
 \Rightarrow &= (I+B)^{-1} \cdot (I-B) \quad -\textcircled{2} \\
 \Rightarrow &= (I+B)^{-1} \cdot (I-B)
 \end{aligned}$$

Multiply $A \in \mathbb{R}^{n \times n}$

$$\begin{aligned}
 \Rightarrow A \cdot A^T &= \cancel{(I+B)} \cancel{(I-B)}^{-1} \\
 \Rightarrow A^T \cdot A &= (I+B)^{-1} \cdot (I-B) (I+B) (I-B)^{-1} \\
 &\text{Apply commutative on dot product} \\
 &\text{of matrices} \\
 & (I-B) \cdot (I+B) = (I+B) \cdot (I-B) \\
 \Rightarrow A \cdot A^T &= \left((I+B)^{-1} (I+B) \right) (I-B) (I+B)^{-1} \\
 &= (\because A \cdot A^{-1} = I)
 \end{aligned}$$

$$\begin{aligned}
 A \cdot A^T &= I \cdot I \\
 \Rightarrow A \cdot A^T &= I \\
 &\text{Apply } A^{-1} \text{ on both sides} \\
 \Rightarrow A^{-1} \cdot A \cdot A^T &= A^{-1} \cdot I
 \end{aligned}$$

$$\Rightarrow A = -A^{-1}$$

Hence proved.

(Q2) Given

$$M = \{m_1, m_2, m_3, \dots, m_r\}$$

$$N = \{m_1, m_2, m_3, m_4, \dots, m_r\}$$

be two vectors of same vector space.

As Let n be vector formed by the

variables c_1, c_2, \dots, c_n on vector space

$$M \text{ i.e. } n \in \text{Span}\{M\}$$

$$\Rightarrow n = c_1 m_1 + c_2 m_2 + \dots + c_r m_r \quad (1)$$

Assume that $\text{Span}\{M\} = \text{Span}\{N\}$

Then there exists some constants for n

t_1, t_2, \dots, t_r such that that vectors

over it can form a linear combination

$$\Rightarrow n = t_1 m_1 + t_2 m_2 + \dots + t_r m_r + t_{r+1} \quad (2)$$

Equate (1) & (2)

$$\Rightarrow c_1 m_1 + c_2 m_2 + \dots + c_r m_r = t_1 m_1 + \dots + t_r m_r + t_{r+1}$$

$$\Rightarrow (c_1 - t_1) m_1 + t_2 (c_2 - t_2) m_2 + \dots + t_r (c_r - t_r) m_r = t_{r+1} (c_{r+1} - t_{r+1})$$

$$\Rightarrow \frac{c_1 - t_1}{t_{r+1}} m_1 + \dots + \frac{c_r - t_r}{t_{r+1}} m_r = t_{r+1} (c_{r+1} - t_{r+1}) \quad (3)$$

$\text{So } v = \sum k_i m_i$ where $k_i = \frac{k_i}{\|m_i\|}$

$$\Rightarrow v = \text{Span}\{M\}$$

(3)

try replacing (3) in (2)

$$\text{Span}\{M\} = t_1 m_1 + \dots + t_r m_r + \sum k_i m_i$$

$$= \sum d_i m_i + \sum k_i m_i \neq t_r$$

$$\neq \text{Span}\{M\}$$

(Q3) \Leftarrow

Ans Let $\beta = \{v_1, \dots, v_m\}$ be basis for
null(T)

\rightarrow Extend β so $\{v_1, \dots, v_{m+1}, \dots, v_n\}$ is for
basis for V .

\rightarrow Suppose $a_{m+1} T(v_{m+1}) + \dots + a_n T(v_n)$
Null vector

$$\Rightarrow T(a_{m+1} v_{m+1} + \dots + a_n v_n) = 0$$

$$\Rightarrow a_{m+1} v_{m+1} + \dots + a_n v_n \in \text{Null}(T) \quad \text{--- (1)}$$

Earlier we already considered $\{v_1, \dots, v_n\}$
be the basis \Rightarrow

$$\Rightarrow \text{Span}\{v_1, \dots, v_n\} = \text{Null}(T) \quad \text{--- (2)}$$

Compare (1) & (2)

$$\Rightarrow a_{m+1} v_{m+1} + \dots + a_n v_n = \text{Span}\{v_1, \dots, v_n\}$$

$$\Rightarrow (\because \text{Span}\{v_1, \dots, v_n\} = c_1 v_1 + c_2 v_2 + \dots + c_n v_n)$$

where c_1, c_2, \dots are constants

$$\Rightarrow a_{m+1} v_{m+1} + \dots + a_n v_n = \cancel{c_1 v_1 + c_2 v_2 + \dots + c_n v_n}$$

~~(2)~~

$$\Rightarrow -c_1v_1 - c_2v_2 - \dots - c_mv_m + a_{m+1}v_{m+1} + \dots + a_nv_n = 0$$

Here $\{v_1, \dots, v_n\}$ will be basis for TV and they are all in linear combination & linearly independent.

Now v will be written as the span linear combination of $\{v_1, \dots, v_n\}$

$$\Rightarrow \text{Span}\{v\} = \text{Span}\{v_1, v_2, \dots, v_n\} = \{c_1v_1 + \dots + c_nv_n\}$$

$$\Rightarrow v = a_1v_1 + a_2v_2 + \dots + a_nv_n$$

$$\Rightarrow R(v) = T(v) = T(a_1v_1 + a_2v_2 + \dots + a_nv_n)$$

$$\Rightarrow w_2T(v) = a_1T(v_1) + \dots + a_mT(v_m) + \dots + a_nT(v_n)$$

~~from~~ Equation ①

~~(a, T(v))~~
we considered $\{v_1, v_2, \dots, v_n\}$ was

basis over $\text{Null}(T)$

$$\Rightarrow T(v_1) = 0, T(v_2) = 0, \dots, T(v_m) = 0$$

$$\Rightarrow w_2T(v) = a_mT(v_m) + \dots + a_nT(v_n)$$

$$\Rightarrow w_2T(v) = \text{Span}\{T(v_{m+1}), \dots, T(v_N)\}$$

⇒ $w = R(T(v)) \in \text{Span}\{T(v_{m+1}) - T(v_n)\}$
⇒ Span of T contains $N-m$ items.
So, dimension of w will be $N-m$.

⇒ The dimension of w by Rank of T
will be $N-m$, considering 'm' will be
Nullity of T .

⇒ Adding Nullity of T & Rank of T dimensions
⇒ $m + (N-m)$
⇒ N which is the dimension
of Y

$Q_3 P_3$

Q4) find the Eigen Values, Eigen Vectors for the matrix $A_{n \times n}$ whose elements are given by $a_{ij} = \begin{cases} \alpha & \text{if } i=j \\ 1 & \text{if } |i-j|=1 \\ 0 & \text{else} \end{cases}$

Here α is constant.

Ans:- \Rightarrow Let λ be the eigen value

$$\Rightarrow a_n V = \lambda V \quad \dots \textcircled{1}$$

$$\Rightarrow (a_n - \lambda I_n) V = 0$$

As V is non-zero matrix.

$$|(a_n - \lambda I_n)| = 0 \quad \dots \textcircled{2}$$

Let us consider $\det(a_n - I_n \lambda) = T_n$
so we can obtain recurrence relation from

the above

$$\Rightarrow T_{n+2} - (\alpha - \lambda) T_{n+1} + T_n = 0 \quad \text{for all } n \geq 1$$

where $T_1 = \alpha - \lambda, T_2 = (\alpha - \lambda)^2 \rightarrow \textcircled{3}$

$$T_n = \frac{1}{\sqrt{\Delta}} \left(P^{n+1} - V^{n+1} \right) \rightarrow \textcircled{4}$$

Here $\Delta = (\alpha - \lambda)^2 - f$, when $\Delta \neq 0 \rightarrow \textcircled{5}$

$$P = \frac{\alpha - \lambda + \sqrt{(\alpha - \lambda)^2 - f}}{2} \rightarrow \textcircled{6}$$

$$V = \frac{\alpha - \lambda - \sqrt{(\alpha - \lambda)^2 - f}}{2}$$

Condition ② works only when

$$p^{n+1} - q^{n+1} = 0 \quad - ⑦$$

∴ $pq = 1$ (using p, q values of ⑥) - ⑧

from ⑦ & ⑧

$$(p^2)^{n+1} = 1 \quad - ⑨$$

The condition together with ⑧ leads to $p+q$

$$p = \left(\cos \frac{s\pi}{n+1} + i \sin \frac{s\pi}{n+1} \right)$$

$$s = 1, 2, \dots, (n+1) \quad - ⑩$$

$$q = \left(\cos \frac{s\pi}{n+1} - i \sin \frac{s\pi}{n+1} \right) \quad - ⑪$$

⑫

$$p = - \left(\cos \frac{s\pi}{n+1} + i \sin \frac{s\pi}{n+1} \right) \quad - ⑫$$

$$q = - \left(\cos \frac{s\pi}{n+1} + i \sin \frac{s\pi}{n+1} \right) \quad - ⑬$$

By using ⑩, ⑪, ⑫, ⑬, we can get
Same Eigen Values.

$$p+q = 2 \cos \frac{s\pi}{n+1} \quad - ⑭$$

$$\text{where } s = 1, 2, \dots, (n+1)$$

from ⑥ we have

$$p+q = \alpha \quad - ⑮$$

Replace $P + V g$ (14)

$$\Rightarrow \alpha - \lambda = 2 \cos \frac{s\pi}{n+1}$$

$$\lambda = \alpha - 2 \cos \frac{s\pi}{n+1}, \forall s = \{1, \dots, n\}$$

Here at $(n+1)$ we are getting $\Delta = 0$, so ~~for~~ the condition doesn't hold at $s = n+1$.

$$\Rightarrow \lambda = \alpha - 2 \cos \frac{s\pi}{n+1} \quad \text{and} \quad s = \sqrt{1, 2, \dots, n}$$

So the Components of Eigen Vectors
will be of form

$$V_1 = \sin \frac{n k \pi}{n+1} \text{ where } k = 1 \text{ to } n$$

Q5) Find the Singular Value decomposition of $A = \begin{pmatrix} 3 & 2 & 2 \\ 2 & 3 & 2 \end{pmatrix}$ and determine the angle of rotation induced by $U \in V$. Also, write the rank 1 decomposition of A in terms of the columns $U \in V$ of V . Can we do dimensionality reduction in this case?

Ans Given $A = \begin{pmatrix} 3 & 2 & 2 \\ 2 & 3 & 2 \end{pmatrix}$

According to SVD, A can be written in the form of $U \Sigma V^T$.

$$\Rightarrow A = U \Sigma V^T \quad \text{(Apply transpose)} \quad \text{①}$$

$$A^T = V \Sigma^T U^T \quad \text{②}$$

$$\text{Multiply ① ② ②}$$

$$\Rightarrow A \cdot A^T = U \Sigma^T U^T \quad \text{③}$$

$$\Rightarrow A \cdot A^T = U \Sigma^T U^T \quad \text{for } A \cdot A^T$$

Calculate eigen vectors for $A \cdot A^T$

$$\Rightarrow A \cdot A^T x = \lambda \cdot x$$

$$\Rightarrow (A \cdot A^T - I \lambda) x = 0$$

As 'x' is non-zero matrix

$$|A \cdot A^T - \lambda I| = 0 \quad \text{④}$$

\Rightarrow Calculate $A \cdot A^T$

$$\Rightarrow \begin{bmatrix} 3 & 2 & 2 \\ 2 & 3 & 2 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 17 & 16 \\ 16 & 17 \end{bmatrix} - \textcircled{5}$$

Replace Equation $\textcircled{5}$ in $\textcircled{7}$

$$\Rightarrow \begin{vmatrix} 17-\lambda & 16 \\ 16 & 17-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (17-\lambda)^2 - 16^2 = 0$$

$$\Rightarrow \lambda = [1, 33]$$

Possible Eigen vectors will be

$$v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

\Rightarrow Length of Eigen vectors = $\sqrt{\lambda \sum (\text{values in vector})}$

$$\Rightarrow \text{length of } v_1 = \lambda_1 = \sqrt{1^2 + 1^2} = \sqrt{2}$$

$$\text{length of } v_2 = \lambda_2 = \sqrt{(-1)^2 + 1^2} = \sqrt{2}$$

\Rightarrow possible unit vectors will be

$$v_1 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$v_2 = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

Now Calculate the Eigen Values for

$$A^T \cdot A = \begin{bmatrix} 3 & 2 \\ 2 & 3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 3 & 2 & 2 \\ 2 & 3 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 13 & 12 & 10 \\ 12 & 13 & 10 \\ 10 & 10 & 8 \end{bmatrix}$$

Calculate Eigen Vectors for $A^T \cdot A$

$$\Rightarrow |A^T \cdot A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 13-\lambda & 12 & 10 \\ 12 & 13-\lambda & 10 \\ 10 & 10 & 8-\lambda \end{vmatrix} = 0$$

$$\Rightarrow = (13-\lambda)((13-\lambda)(8-\lambda) - 100) - 12(12(8-\lambda) - 100) + 10(120 - 10(13-\lambda))$$

$$\Rightarrow = -\lambda^3 + 34\lambda^2 - 33\lambda = 0$$

$$\Rightarrow \lambda = \lambda(1) (\lambda - 33) = 0$$

$$\Rightarrow \lambda = 0, 1, 33$$

Now replace λ values to find

Eigen Vectors.

$$\lambda_1 = 0 \Rightarrow v_1 = \begin{bmatrix} -0.7 \\ -0.4 \\ 1 \end{bmatrix}$$

$$\Rightarrow \lambda_2 = 1 \Rightarrow v_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow \lambda_3 = 33 \Rightarrow v_3 = \begin{bmatrix} 1.2 \\ 1.2 \\ 1 \end{bmatrix}$$

Length of Eigen vectors will be =

$$\sqrt{a^2 + b^2 + c^2}$$

$$\Rightarrow \lambda_1 = 0 \Rightarrow v_1 = \begin{bmatrix} -0.4 \\ -0.4 \\ 1 \end{bmatrix} \Rightarrow l_1 = \sqrt{(-0.4)^2 + (0.4)^2 + 1^2}$$

$$\Rightarrow \lambda_2 = 1, v_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \Rightarrow l_2 = \sqrt{(-1)^2 + 1^2 + 0^2} = \sqrt{2}$$

$$\Rightarrow \lambda_3 = 33, v_3 = \begin{bmatrix} 1.2 \\ 1.2 \\ 1 \end{bmatrix} \Rightarrow l_3 = \sqrt{1.2^2 + 1.2^2 + 1^2} = 1.9697$$

→ Making into unit vectors

$$\Rightarrow v_{12} = \begin{bmatrix} -0.4/1.1 \\ -0.4/1.1 \\ 1/1.1 \end{bmatrix} = \begin{bmatrix} -0.36 \\ -0.36 \\ 0.91 \end{bmatrix}$$

$$\Rightarrow v_{22} = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix} = \begin{bmatrix} -0.707 \\ 0.707 \\ 0 \end{bmatrix}$$

$$\Rightarrow v_{32} = \begin{bmatrix} 1.2/1.9697 \\ 1.2/1.9697 \\ 1/1.9697 \end{bmatrix} = \begin{bmatrix} 0.6092 \\ 0.6092 \\ 0.5076 \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} \sqrt{33} & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 5.74 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$U = (u, v_2) = \begin{bmatrix} 0.707 & -0.707 \\ 0.707 & 0.707 \end{bmatrix} \quad (8)$$

$\Rightarrow V$ can be formed using

$$V_i = \frac{1}{\sigma} A^T v_i$$

$$\text{Now, } \Sigma = \begin{bmatrix} \sqrt{33} & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 5.74 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \quad (9)$$

$$V = \begin{bmatrix} v_{11} & v_{21} & v_{31} \end{bmatrix} = \begin{bmatrix} 0.6092 & -0.707 & -0.36 \\ 0.6092 & 0.707 & -0.36 \\ 0.5076 & 0 & 0.91 \end{bmatrix}$$

$$\bar{V} = \begin{bmatrix} 0.6092 & 0.6092 & 0.5076 \\ -0.707 & 0.707 & 0 \\ -0.36 & -0.36 & 0.91 \end{bmatrix} \quad (10)$$

Taking \bar{V} as unit vectors

~~$A_{2 \times 3}$~~ Combining (8) (9) & (10)

$$A = U \Sigma V^T$$

$$\Rightarrow A_{2 \times 3} = \begin{bmatrix} 0.707 & -0.707 \\ 0.707 & 0.707 \end{bmatrix} \cdot \begin{bmatrix} 5.74 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0.6092 & 0.6092 & 0.5076 \\ -0.707 & 0.707 & 0 \\ -0.36 & -0.36 & 0.91 \end{bmatrix}$$

Q, P₅

(ii) For calculating the angle of rotation we need to calculate the trace of the diagonal.

$$\text{Trace of } U_{2 \times 2} = 0.707 + 0.0707 \\ = 1.414$$

$$\text{Trace of } V_{3 \times 3} = 6.6092 + 0.707 + 0.91 \\ = 1.3162$$

$$\text{Angle of rotation} = \cos^{-1} \left(\frac{\text{Trace} - 1}{2} \right)$$

$$\text{Angle of rotation of } U = \cos^{-1} \left(\frac{1.414 - 1}{2} \right) \\ = \cos^{-1} \left(\frac{0.414}{2} \right) \\ = \cos^{-1} (0.207) \\ = 1.362$$

$$\text{Angle of rotation of } V_2 = \cos^{-1} \left(\frac{0.3162}{2} \right) \\ = 0.1581 \\ = 1.412$$

(ii) Rank 1 decomposition of A in terms of column matrix of U & row matrix of V

→ In SVD, the three rank one matrices in the form

$$\begin{aligned}
 A &= U \Sigma V^T = 5.74 U_1 V_1^T + 1 \cdot U_2 V_2^T + 0 \cdot U_3 V_3^T \\
 &= 5.74 \begin{bmatrix} 0.707 \\ 0.707 \end{bmatrix} \begin{bmatrix} 0.6092 & 0.6092 & 0.5076 \end{bmatrix} \\
 &\quad + 1 \begin{bmatrix} -0.707 \\ 0.707 \end{bmatrix} \begin{bmatrix} -0.707 & 0.707 & 0 \end{bmatrix} \\
 &= \begin{bmatrix} 2.495 & 2.495 & 2 \\ 2.495 & 2.495 & 2 \end{bmatrix} + \\
 &\quad \begin{bmatrix} 0.49 & -0.49 & 0 \\ -0.49 & 0.49 & 0 \end{bmatrix} \\
 &\quad + \begin{bmatrix} 3 & 2 & 2 \\ 2 & 3 & 2 \end{bmatrix}
 \end{aligned}$$

(iv) Can we do dimensionality reduction

Sol: Yes, we can as one of singular values have the outcome of 0. Since right singular matrices give the new axis and the variance of data across new axis.

$P_5 P_3$

Which means r not contributing at all in segregating the data, hence we can drop that axis.

We can validate by removing V_3 in $\Sigma \in V$, still we will get same streak

$$\Rightarrow \begin{pmatrix} 1 & 3 & 2 & 2 \\ 2 & 3 & 2 \end{pmatrix}_{2 \times 3} = \begin{pmatrix} 0.707 & 0.707 \\ 0.707 & 0.707 \end{pmatrix}_{2 \times 2} \begin{pmatrix} 0.54 & 0 \\ 0 & 1 \end{pmatrix}_{2 \times 2} \begin{pmatrix} 0.609 & 0.609 & 0.491 \\ -0.707 & +0.707 & 0 \end{pmatrix}_{2 \times 3}$$

Can we do dimensionality reduction
in V , we can do Principal Component Analysis
Values have to be orthogonal
So we get orthogonal matrix
Now we can take the values of the
orthogonal matrix.

Q.P