
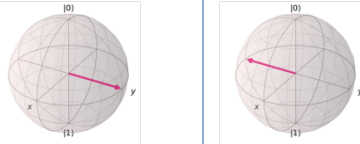

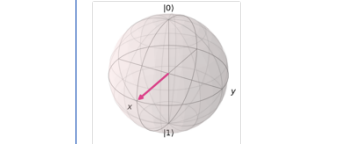
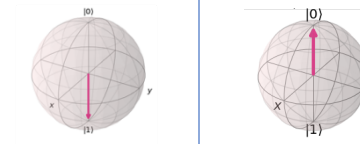
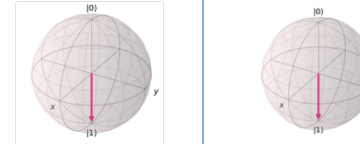
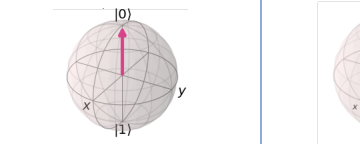
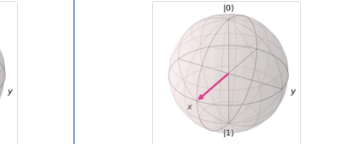
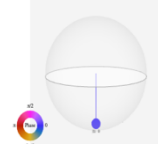

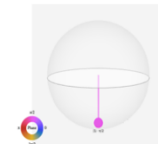

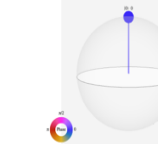

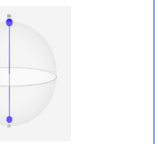
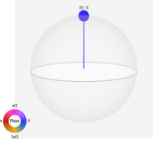
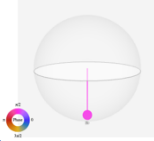
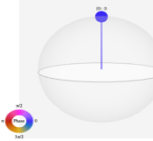
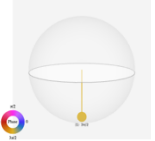


Pauli – X gate		Pauli Y gate		Pauli Z gate		Hadamard Gate	
NOT gate Bit-flip		Phase-flip and Bit flip gate		Phase-flip gate		Coin flip 50%-50 % distribution Qubit is in Superposition state in computational basis	
$X 0\rangle =  1\rangle$ $X 1\rangle =  0\rangle$		$Y 0\rangle = i 1\rangle$ $Y 1\rangle = -i 0\rangle$		$Z 0\rangle =  0\rangle$ $Z 1\rangle = - 1\rangle$		$H 0\rangle = 1/\sqrt{2}( 0\rangle +  1\rangle)$ $H 1\rangle = 1/\sqrt{2}( 0\rangle -  1\rangle)$	
$X =  1\rangle\langle 0  +  0\rangle\langle 1 $		$Y = i 1\rangle\langle 0\rangle - i 0\rangle\langle 1 $		$Z =  0\rangle\langle 0  -  1\rangle\langle 1 $		$H = \frac{ 0\rangle +  1\rangle}{\sqrt{2}} \langle 0  + \frac{ 0\rangle -  1\rangle}{\sqrt{2}} \langle 1 $	
$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$		$\begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$		$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$		$\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$	
Rotates by $\pi$ about the X-axis of the Bloch sphere		Rotates by $\pi$ about the Y-axis of the Bloch sphere		Rotates by $\pi$ about the Z-axis of the Bloch sphere		Rotation around the axis located at halfway between x and z axis or Half rotation of the Bloch Sphere	
				<b>Computational Basis on the Bloch Sphere</b>		<b>Computational Basis on the Bloch Sphere</b>	
<b>Standard Basis on the Bloch Sphere</b>		<b>Standard Basis on the Bloch Sphere</b>		<b>Standard Basis on the Bloch Sphere</b>		<b>Standard Basis on the Bloch Sphere</b>	
$ +X\rangle$ $ -X\rangle$		$ +Y\rangle$ $ -Y\rangle$		$ +Z\rangle$ $ -Z\rangle$		$ +\rangle$ $ -\rangle$	
							
$X 0\rangle =  1\rangle$ $X 1\rangle =  0\rangle$		$Y 0\rangle = i 1\rangle$ $Y 1\rangle = -i 0\rangle$		$Z 0\rangle =  0\rangle$ $Z 1\rangle = - 1\rangle$		$H 0\rangle = 1/\sqrt{2}( 0\rangle +  1\rangle)$ $H 1\rangle = 1/\sqrt{2}( 0\rangle -  1\rangle)$	
<b>States of the qubit on Bloch sphere</b>		<b>States of the qubit on Bloch sphere</b>		<b>States of the qubit on Bloch sphere</b>		<b>States of the qubit on Bloch sphere</b>	
							
<b>Qphere: No phase change</b>		<b>Phase: <math>\pi/2</math></b>		<b>Phase: <math>-\pi/2</math></b>		<b>No phase change</b>	
							
							
							
							
XXX= X XYX= Y XZX= Z		YXY=-X YYY= Y YZY=-Z		ZXZ=-X ZYZ=-Y ZZZ= Z		HXH = Z HYH = -Y HZH = X	

S gate gate	Sdg/ S dagger/ S <sup>†</sup>	T gate	Tdg gate/ T dagger/ T <sup>†</sup>	P gate
<ul style="list-style-type: none"> <li>Induces <math>\pi/2</math> phase</li> <li>Square root of Z gate</li> <li>2VZ-gate</li> <li>Also called as <math>\pi/4</math></li> <li>S-gate is not its own inverse</li> </ul>	<ul style="list-style-type: none"> <li>Induces <math>-\pi/2</math> phase</li> <li>S dagger is the conjugate transpose(or Hermitian transpose) of the S gate</li> <li>Inverse of the S gate</li> </ul>	<ul style="list-style-type: none"> <li>Induces <math>\pi/4</math> phase</li> <li>fourth root of the Z gate</li> <li>4VZ-gate</li> <li>Also called as <math>e^{i\frac{\pi}{8}} \begin{bmatrix} e^{-i\frac{\pi}{8}} &amp; 0 \\ 0 &amp; e^{i\frac{\pi}{8}} \end{bmatrix}</math></li> </ul>	<ul style="list-style-type: none"> <li>Induces <math>-\pi/4</math> phase</li> <li>T dagger is the conjugate transpose(or Hermitian transpose) of the T gate</li> <li>Inverse of the T gate</li> </ul>	<ul style="list-style-type: none"> <li>Phase gate</li> <li>Parametrised gate</li> <li>Requires a parameters (<math>\phi</math>)</li> </ul>
SS=Z P-gate with $\phi=\pi/2$	S <sup>†</sup> S <sup>†</sup> = Z P-gate with $\phi=-\pi/2$	TTTT=Z P-gate with $\phi=\pi/4$	T <sup>†</sup> T <sup>†</sup> T <sup>†</sup> T <sup>†</sup> = Z P-gate with $\phi=-\pi/4$	P( $\phi$ ) $\phi$ is a real number
quarter -turn around the Bloch sphere rotates the qubit by $\pi/2$ radians along the z-axis		rotates the qubit by $\pi/4$ radians along the z-axis		Rotates the qubit with the parameters $\phi$ around the Z-axis direction.
S 0>=  0> S 1>= i 1>	S <sup>†</sup>  0>=  0> S <sup>†</sup>  1>= -i 1>	T 0>=  0> T 1>= i 1>	T <sup>†</sup>  0>=  0> T <sup>†</sup>  1>= -i 1>	$\Phi=0$ , we get identity
$\begin{bmatrix} 1 & 0 \\ 0 & e^{i\frac{\pi}{2}} \end{bmatrix}$ or $\begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix}$	$\begin{bmatrix} 1 & 0 \\ 0 & e^{-i\frac{\pi}{2}} \end{bmatrix}$ or $\begin{bmatrix} 1 & 0 \\ 0 & -i \end{bmatrix}$	$\begin{bmatrix} 1 & 0 \\ 0 & e^{i\frac{\pi}{4}} \end{bmatrix}$ or $\begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{\sqrt{2}}(1+i) \end{bmatrix}$	$\begin{bmatrix} 1 & 0 \\ 0 & e^{-i\frac{\pi}{4}} \end{bmatrix}$ or $\begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{\sqrt{2}}(1-i) \end{bmatrix}$	$\begin{bmatrix} 1 & 0 \\ 0 & e^{i\phi} \end{bmatrix}$
S 0>= 0> S 1>= i 1>	S <sup>†</sup>  0>= 0> S <sup>†</sup>  1>= -i 1>	T 0>= 0> T 1>= i 1>	T <sup>†</sup>  0>= 0> T <sup>†</sup>  1>= -i 1>	P 0>= 0> $\phi = \pi$ , P 1>= -1> $\phi = \pi/2$ , P 1>= i 1> $\phi = \pi/4$ , P 1>= -i 1>
				$\phi = \pi$ , Z $\phi = \pi/2$ , S $\phi = \pi/4$ , T

Identity gate	Rotation Gates: Non-Clifford gates	Phase Gates	U
No operation, basis remain unchanged	Rotation through angle $\theta$ (radians) around the x-axis $R_x(\theta) = \begin{pmatrix} \cos(\frac{\theta}{2}) & -i \sin(\frac{\theta}{2}) \\ i \sin(\frac{\theta}{2}) & \cos(\frac{\theta}{2}) \end{pmatrix}$	Z	$\begin{bmatrix} \cos(\frac{\theta}{2}) & -e^{i\lambda} \sin(\frac{\theta}{2}) \\ e^{i\phi} \sin(\frac{\theta}{2}) & e^{i(\phi+\lambda)} \cos(\frac{\theta}{2}) \end{bmatrix}$ <ul style="list-style-type: none"> <li>General form of a single unitary</li> <li>Single qubit rotation with <math>U(\theta, \phi, \lambda)</math></li> <li>parametrised gate</li> <li>most general of all single-qubit quantum gates</li> <li>Superposition : <math>u(\pi/2, 0, \pi)</math></li> <li>P gate using <math>u(0, 0, \lambda)</math></li> </ul>
I 0>= 0> I 1>= 1> Matrix representation:	Rotation through angle $\theta$ (radians) around the y-axis $R_y(\theta) = \begin{pmatrix} \cos(\frac{\theta}{2}) & -\sin(\frac{\theta}{2}) \\ \sin(\frac{\theta}{2}) & \cos(\frac{\theta}{2}) \end{pmatrix}$	S	
$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$	Rotation through angle $\theta$ (radians) around the z-axis $R_z(\theta) = \begin{pmatrix} e^{-i\frac{\theta}{2}} & 0 \\ 0 & e^{i\frac{\theta}{2}} \end{pmatrix}$	Sdg	
		T	
		Tdg	
		P	