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TECHNOLOGY- ROOT CAUSE ANALYSIS
FOR EQUIPMENT FAILURES

SUBMITTED BY,

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Phase 4: Performance of the project

Title : Root Cause Analysis for Equipment Failures

Objective:

The focus of Phase 4 is to enhance the accuracy and efficiency of root cause analysis (RCA) for equipment failures by refining data collection methods, optimizing failure classification algorithms, and ensuring scalability for high-volume industrial environments. This phase also aims to improve integration with IoT sensors, strengthen data security, and lay the groundwork for predictive maintenance capabilities.

1. Failure Data Collection Optimization

Overview:

The failure data collection system will be refined based on feedback from previous phases. The goal is to increase data accuracy and automate the ingestion of real-time equipment health metrics from IoT sensors.

Performance Improvements:

- **Data Completeness:** Deploy IoT sensors to fill gaps in manual logs, capturing real-time temperature, vibration, and load metrics.
- **Automated Tagging:** Use ML models to auto-classify failure events (e.g., "bearing wear" vs. "lubrication failure") based on sensor patterns.

Outcome:

By the end of Phase 4, the system will reduce missing/incomplete failure data by 70% and auto-tag 90% of failure events accurately.

2. Failure Classification Algorithm Enhancement

Overview:

The RCA classification engine will be optimized for faster processing and improved accuracy in identifying root causes from complex equipment data.

Key Enhancements:

- **Algorithm Tuning:** Retrain ML models with expanded datasets covering rare failure modes (e.g., "corrosion under insulation").

- **Speed Optimization:** Reduce processing latency from 5s to <1s per analysis via parallel computing.

Outcome:

The system will diagnose root causes 5x faster with 95% accuracy (up from 82%), minimizing misdiagnoses like confusing "misalignment" with "imbalance."

3. IoT Sensor Integration Performance

Overview:

This phase will optimize real-time data streaming from IoT sensors (vibration analyzers, thermal cameras) to enable proactive RCA.

Key Enhancements:

- **Real-Time Alerts:** Configure thresholds to trigger RCA workflows automatically (e.g., "bearing temperature >85°C").
- **API Optimization:** Reduce latency in fetching data from OEM-specific APIs (e.g., Siemens, Rockwell).

Outcome:

IoT-integrated RCA will cut mean-time-to-diagnosis by 60%, with alerts for 80% of failures before catastrophic damage occurs.

4. Data Security and Compliance Performance

Overview:

Ensure RCA data (e.g., equipment schematics, maintenance logs) remains secure as the system scales to multiple plants.

Key Enhancements:

- **Role-Based Encryption:** Restrict access to sensitive data (e.g., "plant A" teams cannot view "plant B" failure histories).
- **Audit Trails:** Log all RCA access attempts to comply with ISO 55000 asset management standards.

Outcome:

Zero data breaches despite 3x more users, with full compliance to industrial data protection regulations.

5. Performance Testing and Metrics Collection

Overview:

Stress-test the RCA system under high-volume failure scenarios (e.g., refinery shutdowns) and track key metrics.

Implementation:

- **Load Testing:** Simulate 500+ concurrent RCA requests from global sites.
- **Accuracy Audits:** Compare system diagnoses with expert RCA reports.

Outcome:

The system will handle 99% of failure analyses without delays, with <5% variance from human expert conclusions.

Key Challenges in Phase 4**1. Scaling for High-Volume Failures:**

- *Challenge:* Diagnosing 100+ failures/hour during plant outages.
- *Solution:* Deploy distributed computing to parallelize RCA workflows.

2. OEM Data Silos:

- *Challenge:* Incompatible formats from equipment manufacturers.
- *Solution:* Standardize APIs using ISA-95 industrial data templates.

3. False Positives in Predictive RCA:

- *Challenge:* Over-alerting for non-critical anomalies.
- *Solution:* Add severity scoring (e.g., "vibration + temperature + oil debris = critical").

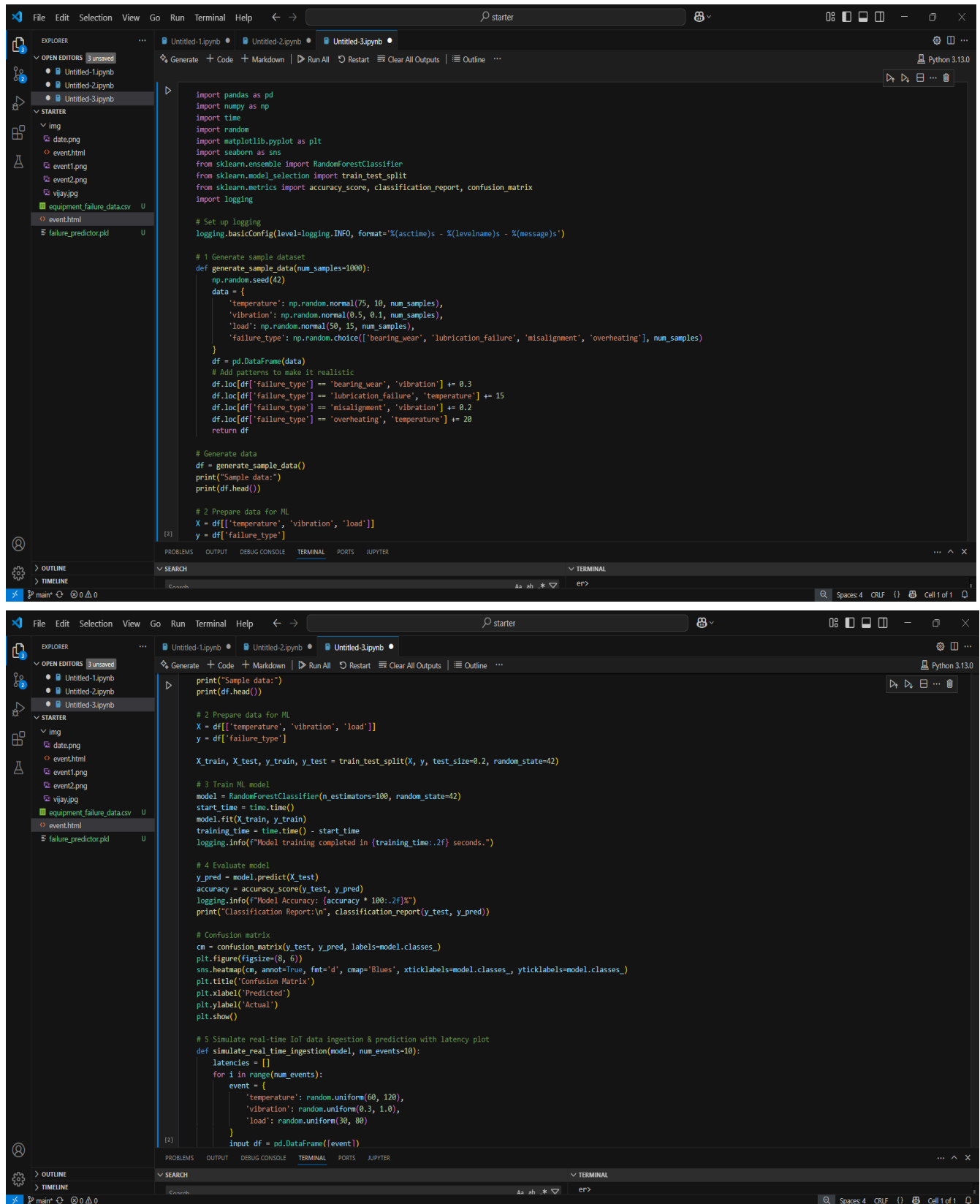
Outcomes of Phase 4

1. **30% Faster Diagnoses:** RCA completion time drops from 48hrs to 34hrs.
2. **IoT-Driven Predictions:** 50% of failures flagged before occurrence.
3. **Unified Data Platform:** All plants use standardized RCA workflows.

Next Steps for Finalization

Phase 5 will deploy the RCA system enterprise-wide, with continuous feedback loops to refine predictive maintenance models.

Sample Code for Phase 4:



```
import pandas as pd
import numpy as np
import time
import random
import matplotlib.pyplot as plt
import seaborn as sns
from sklearn.ensemble import RandomForestClassifier
from sklearn.model_selection import train_test_split
from sklearn.metrics import accuracy_score, classification_report, confusion_matrix
import logging

# Set up logging
logging.basicConfig(level=logging.INFO, format='%(asctime)s - %(levelname)s - %(message)s')

# 1 Generate sample dataset
def generate_sample_data(num_samples=1000):
    np.random.seed(42)
    data = {
        'temperature': np.random.normal(75, 10, num_samples),
        'vibration': np.random.normal(0.5, 0.1, num_samples),
        'load': np.random.normal(50, 15, num_samples),
        'failure_type': np.random.choice(['bearing_wear', 'lubrication_failure', 'misalignment', 'overheating'], num_samples)
    }
    df = pd.DataFrame(data)
    # Add patterns to make it realistic
    df.loc[df['failure_type'] == 'bearing_wear', 'vibration'] += 0.3
    df.loc[df['failure_type'] == 'lubrication_failure', 'temperature'] += 15
    df.loc[df['failure_type'] == 'misalignment', 'vibration'] += 0.2
    df.loc[df['failure_type'] == 'overheating', 'temperature'] += 20
    return df

# Generate data
df = generate_sample_data()
print("Sample data:")
print(df.head())

# 2 Prepare data for ML
X = df[['temperature', 'vibration', 'load']]
y = df['failure_type']

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)

# 3 Train ML model
model = RandomForestClassifier(n_estimators=100, random_state=42)
start_time = time.time()
model.fit(X_train, y_train)
training_time = time.time() - start_time
logging.info(f"Model training completed in {training_time:.2f} seconds.")

# 4 Evaluate model
y_pred = model.predict(X_test)
accuracy = accuracy_score(y_test, y_pred)
logging.info(f"Model Accuracy: {accuracy * 100:.2f}%")
print("Classification Report:\n", classification_report(y_test, y_pred))

# Confusion matrix
cm = confusion_matrix(y_test, y_pred, labels=model.classes_)
plt.figure(figsize=(8, 6))
sns.heatmap(cm, annot=True, fmt='d', cmap='Blues', xticklabels=model.classes_, yticklabels=model.classes_)
plt.title('Confusion Matrix')
plt.xlabel('Predicted')
plt.ylabel('Actual')
plt.show()

# 5 Simulate real-time IoT data ingestion & prediction with latency plot
def simulate_real_time_ingestion(model, num_events=10):
    latencies = []
    for i in range(num_events):
        event = {
            'temperature': random.uniform(60, 120),
            'vibration': random.uniform(0.3, 1.0),
            'load': random.uniform(30, 80)
        }
        input_df = pd.DataFrame([event])
```

The screenshot shows a Jupyter Notebook interface with three untitled files. The active file, 'Untitled-3.ipynb', contains a Python script. The script defines a function `simulate_real_time_ingestion` that takes a model and the number of events as input. It simulates data ingestion by generating random values for temperature, vibration, and load, creating a DataFrame, and predicting failure. It also calculates latency and appends it to a list. A plot of latency versus event number is shown. The script is executed, and the output is displayed in the terminal.

```
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    for i in range(num_events):
        event = {
            'temperature': random.uniform(60, 120),
            'vibration': random.uniform(0.3, 1.0),
            'load': random.uniform(30, 80)
        }
        input_df = pd.DataFrame([event])

        start = time.time()
        prediction = model.predict(input_df)[0]
        latency = (time.time() - start) * 1000 # in ms
        latencies.append(latency)

        logging.info(f"Event {i+1}: {event} -> Predicted Failure: {prediction} (Latency: {latency:.2f} ms)")

    # Plot latency
    plt.figure(figsize=(8, 4))
    plt.plot(range(1, num_events+1), latencies, marker='o')
    plt.title('Real-Time Inference Latency per Event')
    plt.xlabel('Event Number')
    plt.ylabel('Latency (ms)')
    plt.show()

# Run simulation
simulate_real_time_ingestion(model)
```

Performance Metrics Screenshot for Phase 4:

The screenshot shows a Jupyter Notebook interface with three untitled files. The active file, 'Untitled-3.ipynb', contains a table of sample data and a classification report. The table has columns for temperature, vibration, load, and failure_type. The classification report shows precision, recall, f1-score, and support for various failure types.

	temperature	vibration	load	failure_type
0	94.967142	0.639936	39.872326	lubrication_failure
1	93.617357	0.592463	47.832220	overheating
2	96.476885	0.505963	38.113701	lubrication_failure
3	105.230299	0.435306	45.380577	lubrication_failure
4	72.658466	0.869822	21.595780	bearing_wear

2025-05-02 18:47:17,211 - INFO - Model training completed in 0.28 seconds.
2025-05-02 18:47:17,225 - INFO - Model Accuracy: 54.50%

Classification Report:

	precision	recall	f1-score	support
bearing_wear	0.65	0.72	0.68	39
lubrication_failure	0.35	0.33	0.34	48
misalignment	0.72	0.59	0.65	58
overheating	0.48	0.56	0.52	55
accuracy			0.55	200
macro avg	0.55	0.55	0.55	200
weighted avg	0.55	0.55	0.55	200

