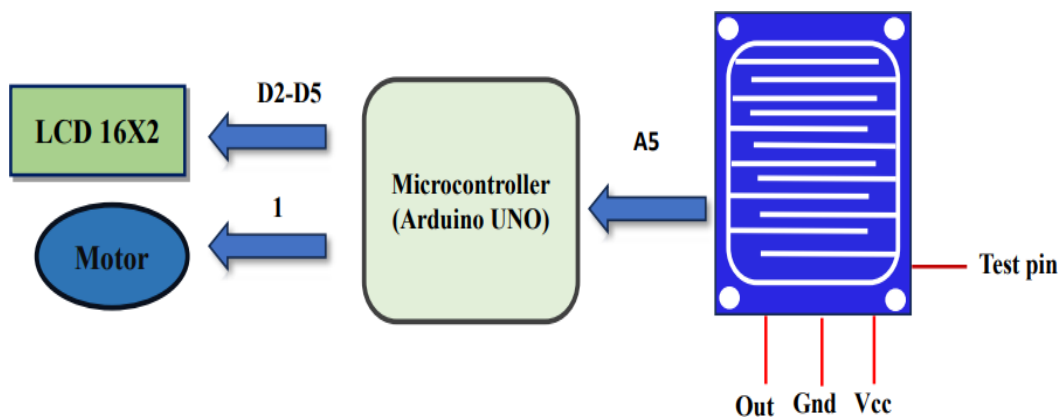


# Rain Sensing Motor Control using Arduino UNO

## Description:

The Rain-Sensing Motor Control project uses a rain sensor to detect water and activate a DC motor. The Arduino Uno board receives the signal from the rain sensor and turns the motor on or off accordingly. The LCD display shows the status of the motor as either "ON" or "OFF" in real-time. The logic state used is that the motor is on when it detects rain, and off when there is no rain.

## Block Diagram:



## Input and Output:

| S.No | Description     | Name | Type | Data Direction | Specification | Remarks     |
|------|-----------------|------|------|----------------|---------------|-------------|
| 1    | Rain Sensor OUT | A5   | INP  | DI             | Digital       | Active High |
| 2    | Rain Sensor VCC | VCC  | OUT  | DO             | Digital       | Active High |
| 3    | Rain Sensor GND | GND  | OUT  | DO             | Digital       | Active High |
| 4    | LCD RST         | RS   | OUT  | DO             | Digital       | Active High |
| 5    | LCD EN          | EN   | OUT  | DO             | Digital       | Active High |
| 6    | LCD DATA PIN    | D4   | OUT  | D0             | Digital       | Active High |
| 7    | LCD DATA PIN    | D5   | OUT  | DO             | Digital       | Active High |
| 8    | LCD DATA PIN    | D6   | OUT  | DO             | Digital       | Active High |
| 9    | LCD DATA PIN    | D7   | OUT  | DO             | Digital       | Active High |
| 10   | MOTOR           | PD1  | OUT  | D0             | Digital       | Active High |

## Source Code:

```
#include <LiquidCrystal.h>

const int rs = 12, en = 11, d4 = 5, d5 = 4, d6 = 3, d7 = 2;
LiquidCrystal lcd(rs, en, d4, d5, d6, d7); // LCD pins: RS, E, D4, D5, D6, D7
int rainSensorPin = A5;
int motorPin = 1;
int motorStatus = LOW;

void setup() {
  lcd.begin(16, 2); // Initialize the LCD
  pinMode(rainSensorPin, INPUT);
  pinMode(motorPin, OUTPUT);
}

void loop() {
  int rainStatus = digitalRead(rainSensorPin);

  if (rainStatus == HIGH) {
    motorStatus = HIGH;
    digitalWrite(motorPin, motorStatus);
    lcd.clear();
    lcd.print("Rain=on");
  } else {
    motorStatus = LOW;
    digitalWrite(motorPin, motorStatus);
    lcd.clear();
    lcd.print("No rain=off");
  }

  delay(1000); // Delay for stability
}
```