
FINAL CAPSTONE PROJECT :- 3 :- (RELATED TO CONVOLUTIONAL NEURAL NETWORK(CNN))

FINAL CAPSTONE PROJECT NAME :- AUTOMATIC NUMBER PLATE RECOGNITION

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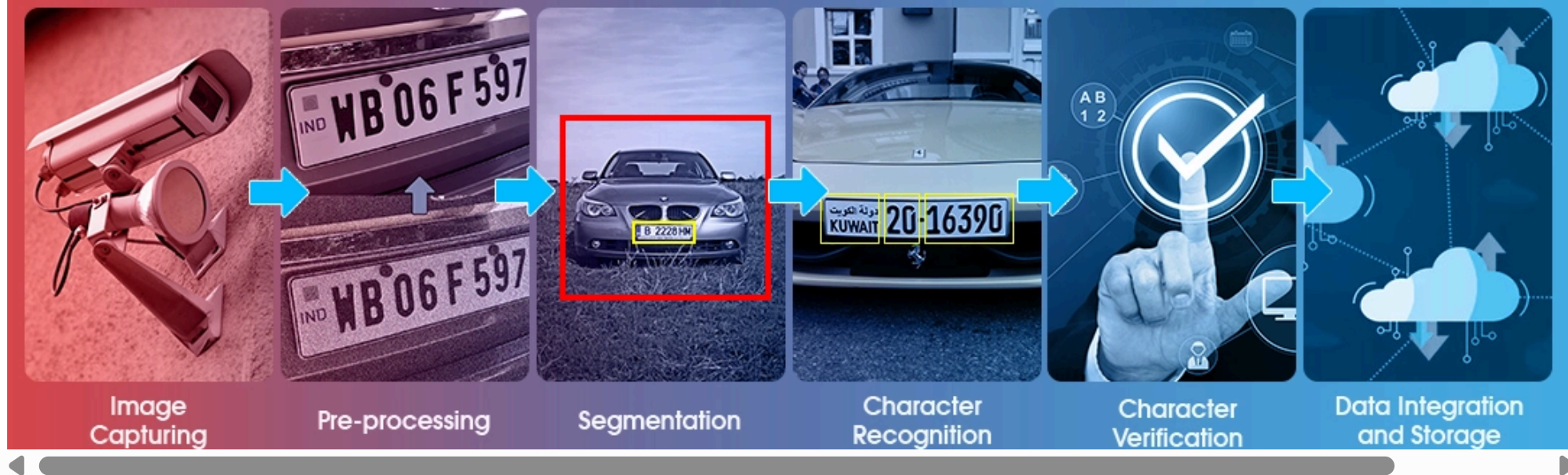
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IMAGE:-

```
from IPython import display
display.Image('/content/Automatic_number_plate_recognition.png')
```



How does ANPR work?



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```
pip install opencv-python
```

```
Requirement already satisfied: opencv-python in /usr/local/lib/python3.11/dist-packages (4.11.0.86)  
Requirement already satisfied: numpy>=1.21.2 in /usr/local/lib/python3.11/dist-packages (from opencv-python) (2.0.2)
```

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```
import cv2
```

```
import zipfile  
zip_ref = zipfile.ZipFile('/content/data.zip', 'r')  
zip_ref.extractall('/content')  
zip_ref.close()
```

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IMPORTING LIBRARIES AND DATA :-

```
import matplotlib.pyplot as plt
import numpy as np
import cv2
import tensorflow as tf
from sklearn.metrics import f1_score
from tensorflow.keras import optimizers
from tensorflow.keras.models import Sequential
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.layers import Dense, Flatten, MaxPooling2D, Dropout, Conv2D
```

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Load the data required for detecting the license plates:-

```
# Loads the data required for detecting the license plates from cascade classifier.
plate_cascade = cv2.CascadeClassifier('/content/indian_license_plate.xml')
# add the path to 'india_license_plate.xml' file.
```

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The Function detects and perfors on the number plate:-

```
def detect_plate(img, text=''): # the function detects and perfors blurring on the number plate.
    plate_img = img.copy()
    roi = img.copy()
    plate_rect = plate_cascade.detectMultiScale(plate_img, scaleFactor = 1.2, minNeighbors = 7) # detects numberplates and returns the coordinates
    for (x,y,w,h) in plate_rect:
        roi_ = roi[y:y+h, x:x+w, :] # extracting the Region of Interest of license plate for blurring.
        plate = roi[y:y+h, x:x+w, :]
        cv2.rectangle(plate_img, (x+2,y), (x+w-3, y+h-5), (51,181,155), 3) # finally representing the detected contours by drawing rectangles arou
    if text!='':
```

```
plate_img = cv2.putText(plate_img, text, (x-w//2,y-h//2),
                        cv2.FONT_HERSHEY_COMPLEX_SMALL, 0.5, (51,181,155), 1, cv2.LINE_AA)

return plate_img, plate # returning the processed image.
```

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```
import matplotlib.pyplot as plt
```

```
## Testing the above function:-
```

```
# Testing the above function
def display(img_, title=''):
    img = cv2.cvtColor(img_, cv2.COLOR_BGR2RGB)
    fig = plt.figure(figsize=(10,6))
    ax = plt.subplot(111)
    ax.imshow(img)
    plt.axis('off')
    plt.title(title)
    plt.show()

img = cv2.imread('/content/car.jpg')
display(img, 'Input image')
```



Input image



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```
## Getting plate from the processed image:-
```

```
# Getting plate from the processed image  
output_img, plate = detect_plate(img)
```

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```
## Detected License Plate in the Input Image:-
```

```
display(output_img, 'Detected License Plate in the Input Image')
```



Detected License Plate in the Input Image



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```
## Extracted License Plate From The Image:-
```

```
display(plate, 'Extracted License Plate from the Image')
```



Extracted License Plate from the Image



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Match Contours to License Plate:-

Match contours to license plate or character template

def find_contours(dimensions, img) :

Find all contours in the image

cntrs, _ = cv2.findContours(img.copy(), cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)

Retrieve potential dimensions

lower_width = dimensions[0]

upper_width = dimensions[1]

lower_height = dimensions[2]

upper_height = dimensions[3]

Check largest 5 or 15 contours for license plate or character respectively

cntrs = sorted(cntrs, key=cv2.contourArea, reverse=True)[:15]

ii = cv2.imread('contour.jpg')

x_cntr_list = []

target_contours = []

img_res = []

for cntr in cntrs :

detects contour in binary image and returns the coordinates of rectangle enclosing it


```

intX, intY, intWidth, intHeight = cv2.boundingRect(cntr)

# checking the dimensions of the contour to filter out the characters by contour's size
if intWidth > lower_width and intWidth < upper_width and intHeight > lower_height and intHeight < upper_height :
    x_cntr_list.append(intX) #stores the x coordinate of the character's contour, to used later for indexing the contours

    char_copy = np.zeros((44,24))
    # extracting each character using the enclosing rectangle's coordinates.
    char = img[intY:intY+intHeight, intX:intX+intWidth]
    char = cv2.resize(char, (20, 40))

    cv2.rectangle(ii, (intX,intY), (intWidth+intX, intY+intHeight), (50,21,200), 2)
    plt.imshow(ii, cmap='gray')

    # Make result formatted for classification: invert colors
    char = cv2.subtract(255, char)

    # Resize the image to 24x44 with black border
    char_copy[2:42, 2:22] = char
    char_copy[0:2, :] = 0
    char_copy[:, 0:2] = 0
    char_copy[42:44, :] = 0
    char_copy[:, 22:24] = 0

    img_res.append(char_copy) # List that stores the character's binary image (unsorted)

# Return characters on ascending order with respect to the x-coordinate (most-left character first)

plt.show()
# arbitrary function that stores sorted list of character indeces
indices = sorted(range(len(x_cntr_list)), key=lambda k: x_cntr_list[k])
img_res_copy = []
for idx in indices:
    img_res_copy.append(img_res[idx])# stores character images according to their index
img_res = np.array(img_res_copy)

return img_res

```

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Find Characters in the Resulting Images:-

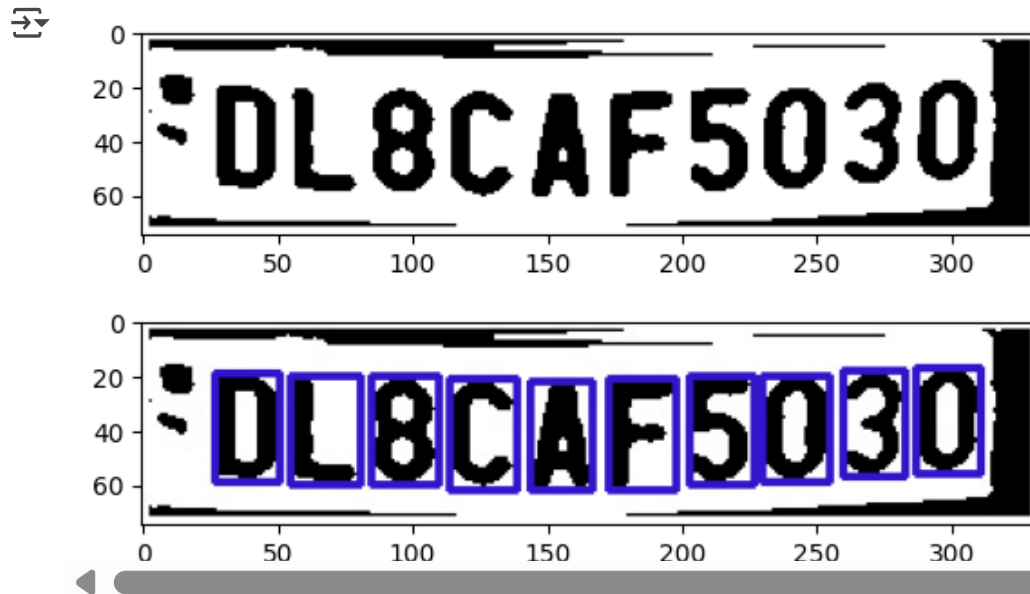
Find characters in the resulting images

```
def segment_characters(image) :  
  
    # Preprocess cropped license plate image  
    img_lp = cv2.resize(image, (333, 75))  
    img_gray_lp = cv2.cvtColor(img_lp, cv2.COLOR_BGR2GRAY)  
    _, img_binary_lp = cv2.threshold(img_gray_lp, 200, 255, cv2.THRESH_BINARY+cv2.THRESH_OTSU)  
    img_binary_lp = cv2.erode(img_binary_lp, (3,3))  
    img_binary_lp = cv2.dilate(img_binary_lp, (3,3))  
  
    LP_WIDTH = img_binary_lp.shape[0]  
    LP_HEIGHT = img_binary_lp.shape[1]  
  
    # Make borders white  
    img_binary_lp[0:3,:] = 255  
    img_binary_lp[:,0:3] = 255  
    img_binary_lp[72:75,:] = 255  
    img_binary_lp[:,330:333] = 255  
  
    # Estimations of character contours sizes of cropped license plates  
    dimensions = [LP_WIDTH/6,  
                  LP_WIDTH/2,  
                  LP_HEIGHT/10,  
                  2*LP_HEIGHT/3]  
    plt.imshow(img_binary_lp, cmap='gray')  
    plt.show()  
    cv2.imwrite('contour.jpg',img_binary_lp)  
  
    # Get contours within cropped license plate  
    char_list = find_contours(dimensions, img_binary_lp)  
  
    return char_list
```

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Let's see the Segmented Characters:-

```
# Let's see the segmented characters
char = segment_characters(plate)
```



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```
## Using For Loop:-
```

```
for i in range(10):
    plt.subplot(1, 10, i+1)
    plt.imshow(char[i], cmap='gray')
    plt.axis('off')
```



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Model for characters:-

```
import tensorflow.keras.backend as K
train_datagen = ImageDataGenerator(rescale=1./255, width_shift_range=0.1, height_shift_range=0.1)
path = '/content/data'
train_generator = train_datagen.flow_from_directory(
    path+'/train', # this is the target directory
    target_size=(28,28), # all images will be resized to 28x28
    batch_size=1,
    class_mode='sparse')

validation_generator = train_datagen.flow_from_directory(
    path+'/val', # this is the target directory
    target_size=(28,28), # all images will be resized to 28x28 batch_size=1,
    class_mode='sparse')
```

➡ Found 864 images belonging to 36 classes.
Found 216 images belonging to 36 classes.

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CNN MODEL:-

```
from tensorflow.keras import optimizers
K.clear_session()
model = Sequential()
model.add(Conv2D(16,kernel_size=(22,22),padding='same',activation='relu',input_shape=(28,28,3)))
model.add(Conv2D(32,kernel_size=(16,16),padding='same',activation='relu'))
model.add(Conv2D(64,kernel_size=(8,8),padding='same',activation='relu'))
model.add(Conv2D(64,kernel_size=(4,4),padding='same',activation='relu'))
model.add(MaxPooling2D(pool_size=(4, 4)))
model.add(Dropout(0.4))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dense(36, activation='softmax'))

model.compile(loss='sparse_categorical_crossentropy', optimizer=optimizers.Adam(learning_rate=0.0001), metrics=["accuracy"])
```

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```
model.summary()
```

 Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 28, 28, 16)	23,248
conv2d_1 (Conv2D)	(None, 28, 28, 32)	131,104
conv2d_2 (Conv2D)	(None, 28, 28, 64)	131,136
conv2d_3 (Conv2D)	(None, 28, 28, 64)	65,600
max_pooling2d (MaxPooling2D)	(None, 7, 7, 64)	0
dropout (Dropout)	(None, 7, 7, 64)	0
flatten (Flatten)	(None, 3136)	0
dense (Dense)	(None, 128)	401,536
dense_1 (Dense)	(None, 36)	4,644

Total params: 757.268 (2.89 MB)

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```
class stop_training_callback(tf.keras.callbacks.Callback):
    def on_epoch_end(self, epoch, logs={}):
        if(logs.get('val_accuracy') > 0.999):
            self.model.stop_training = True
```

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```
batch_size = 1
callbacks = [stop_training_callback()]
model.fit(
```

```
train_generator,  
steps_per_epoch = train_generator.samples // batch_size,  
validation_data = validation_generator,  
epochs = 80, verbose=1, callbacks=callbacks)
```

Epoch 1/80
864/864 ————— 4s 4ms/step - accuracy: 0.9818 - loss: 0.0473 - val_accuracy: 0.9815 - val_loss: 0.0445
Epoch 2/80
864/864 ————— 6s 5ms/step - accuracy: 0.9841 - loss: 0.0408 - val_accuracy: 0.9676 - val_loss: 0.1315
Epoch 3/80
864/864 ————— 3s 4ms/step - accuracy: 0.9694 - loss: 0.0880 - val_accuracy: 0.9861 - val_loss: 0.0687
Epoch 4/80
864/864 ————— 5s 4ms/step - accuracy: 0.9802 - loss: 0.0374 - val_accuracy: 0.9444 - val_loss: 0.1764
Epoch 5/80
864/864 ————— 5s 4ms/step - accuracy: 0.9538 - loss: 0.1566 - val_accuracy: 0.9907 - val_loss: 0.0220
Epoch 6/80
864/864 ————— 4s 4ms/step - accuracy: 0.9844 - loss: 0.0334 - val_accuracy: 0.9861 - val_loss: 0.0252
Epoch 7/80
864/864 ————— 6s 5ms/step - accuracy: 0.9794 - loss: 0.0550 - val_accuracy: 0.9907 - val_loss: 0.0281
Epoch 8/80
864/864 ————— 3s 4ms/step - accuracy: 0.9751 - loss: 0.0767 - val_accuracy: 0.9907 - val_loss: 0.0376
Epoch 9/80
864/864 ————— 3s 4ms/step - accuracy: 0.9704 - loss: 0.0542 - val_accuracy: 0.9815 - val_loss: 0.0862
Epoch 10/80
864/864 ————— 4s 5ms/step - accuracy: 0.9710 - loss: 0.0742 - val_accuracy: 0.9954 - val_loss: 0.0151
Epoch 11/80
864/864 ————— 4s 4ms/step - accuracy: 0.9925 - loss: 0.0318 - val_accuracy: 0.9769 - val_loss: 0.0596
Epoch 12/80
864/864 ————— 3s 4ms/step - accuracy: 0.9747 - loss: 0.0889 - val_accuracy: 0.9954 - val_loss: 0.0304
Epoch 13/80
864/864 ————— 3s 4ms/step - accuracy: 0.9915 - loss: 0.0231 - val_accuracy: 0.9815 - val_loss: 0.0480
Epoch 14/80
864/864 ————— 4s 5ms/step - accuracy: 0.9772 - loss: 0.0595 - val_accuracy: 0.9954 - val_loss: 0.0172
Epoch 15/80
864/864 ————— 3s 4ms/step - accuracy: 0.9878 - loss: 0.0433 - val_accuracy: 0.9907 - val_loss: 0.0266
Epoch 16/80
864/864 ————— 6s 5ms/step - accuracy: 0.9905 - loss: 0.0261 - val_accuracy: 0.9583 - val_loss: 0.1743
Epoch 17/80
864/864 ————— 5s 4ms/step - accuracy: 0.9870 - loss: 0.0441 - val_accuracy: 0.9769 - val_loss: 0.1166
Epoch 18/80
864/864 ————— 5s 4ms/step - accuracy: 0.9846 - loss: 0.0593 - val_accuracy: 0.9722 - val_loss: 0.0854
Epoch 19/80
864/864 ————— 4s 5ms/step - accuracy: 0.9836 - loss: 0.0362 - val_accuracy: 0.9861 - val_loss: 0.0843
Epoch 20/80
864/864 ————— 3s 4ms/step - accuracy: 0.9771 - loss: 0.0521 - val_accuracy: 0.9630 - val_loss: 0.1457

```

Epoch 21/80
864/864 ————— 3s 4ms/step - accuracy: 0.9882 - loss: 0.0428 - val_accuracy: 0.9861 - val_loss: 0.0326
Epoch 22/80
864/864 ————— 4s 5ms/step - accuracy: 0.9806 - loss: 0.0599 - val_accuracy: 0.9861 - val_loss: 0.0349
Epoch 23/80
864/864 ————— 4s 4ms/step - accuracy: 0.9904 - loss: 0.0263 - val_accuracy: 0.9769 - val_loss: 0.0665
Epoch 24/80
864/864 ————— 3s 4ms/step - accuracy: 0.9833 - loss: 0.0541 - val_accuracy: 0.9861 - val_loss: 0.0240
Epoch 25/80
864/864 ————— 4s 5ms/step - accuracy: 0.9849 - loss: 0.0297 - val_accuracy: 0.9861 - val_loss: 0.0679
Epoch 26/80
864/864 ————— 4s 4ms/step - accuracy: 0.9839 - loss: 0.0341 - val_accuracy: 0.9676 - val_loss: 0.0891
Epoch 27/80
864/864 ————— 5s 4ms/step - accuracy: 0.9863 - loss: 0.0536 - val_accuracy: 0.9907 - val_loss: 0.0355
Epoch 28/80
864/864 ————— 6s 5ms/step - accuracy: 0.9852 - loss: 0.0447 - val_accuracy: 0.9861 - val_loss: 0.0233
Epoch 29/80
864/864 ————— 4s 4ms/step - accuracy: 0.9725 - loss: 0.1012 - val accuracy: 0.9861 - val loss: 0.0748

```

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Predicting the Output:-

```

# Predicting the output
def fix_dimension(img):
    new_img = np.zeros((28,28,3))
    for i in range(3):
        new_img[:, :, i] = img
    return new_img

def show_results():
    dic = {}
    characters = '0123456789ABCDEFGHIJKLMNOPQRSTUVWXYZ'
    for i,c in enumerate(characters):
        dic[i] = c

    output = []
    for i,ch in enumerate(char): #iterating over the characters
        img_ = cv2.resize(ch, (28,28), interpolation=cv2.INTER_AREA)
        img = fix_dimension(img_)
        img = img.reshape(1,28,28,3) #preparing image for the model
        y_ = model.predict(img)[0] #predicting the class

```

```

# Get the index of the predicted class (class with highest probability)
character_index = np.argmax(y_)
character = dic[character_index] # Use character_index as key to access dictionary
output.append(character) #storing the result in a list

plate_number = ''.join(output)

return plate_number

print(show_results())

```

```

➡ 1/1 _____ 1s 1s/step
   1/1 _____ 0s 67ms/step
   1/1 _____ 0s 83ms/step
   1/1 _____ 0s 52ms/step
   1/1 _____ 0s 108ms/step
   1/1 _____ 0s 91ms/step
   1/1 _____ 0s 126ms/step
   1/1 _____ 0s 89ms/step
   1/1 _____ 0s 66ms/step
   1/1 _____ 0s 51ms/step
DL8CAF5030

```

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Segmented Characters and their Predicted Value:-

```

# Segmented characters and their predicted value.
plt.figure(figsize=(10,6))
for i,ch in enumerate(char):
    img = cv2.resize(ch, (28,28), interpolation=cv2.INTER_AREA)
    plt.subplot(3,4,i+1)
    plt.imshow(img,cmap='gray')
    plt.title(f'Predicted: {show_results()[i]}')
    plt.axis('off')
plt.show()

```




1/1	0s 41ms/step
1/1	0s 44ms/step
1/1	0s 50ms/step
1/1	0s 82ms/step
1/1	0s 42ms/step
1/1	0s 79ms/step
1/1	0s 93ms/step
1/1	0s 47ms/step
1/1	0s 46ms/step
1/1	0s 43ms/step
1/1	0s 41ms/step
1/1	0s 45ms/step
1/1	0s 45ms/step
1/1	0s 45ms/step
1/1	0s 47ms/step
1/1	0s 50ms/step
1/1	0s 45ms/step
1/1	0s 44ms/step
1/1	0s 44ms/step
1/1	0s 47ms/step
1/1	0s 28ms/step
1/1	0s 29ms/step
1/1	0s 34ms/step
1/1	0s 27ms/step
1/1	0s 29ms/step
1/1	0s 31ms/step
1/1	0s 29ms/step
1/1	0s 28ms/step
1/1	0s 28ms/step
1/1	0s 29ms/step
1/1	0s 28ms/step
1/1	0s 27ms/step
1/1	0s 30ms/step
1/1	0s 28ms/step
1/1	0s 31ms/step
1/1	0s 32ms/step
1/1	0s 41ms/step
1/1	0s 29ms/step
1/1	0s 29ms/step
1/1	0s 29ms/step
1/1	0s 28ms/step
1/1	0s 28ms/step
1/1	0s 28ms/step
1/1	0s 30ms/step