Course title : CSE2001

Course title : Data Structures and Algorithms

Module : 6

Topic : 1

# **Graph Data Structure**

### **Objectives**

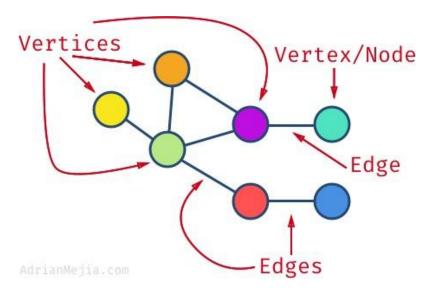
This session will give the knowledge about

- Introduction to Graphs
- Breadth First Search BFS
- Depth First Search DFS

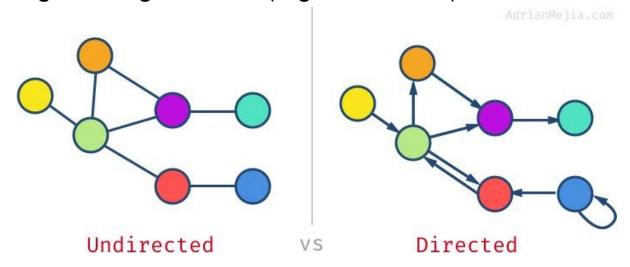
A graph is a collection of nodes (or vertices) and edges (or arcs)

Each node contains an element

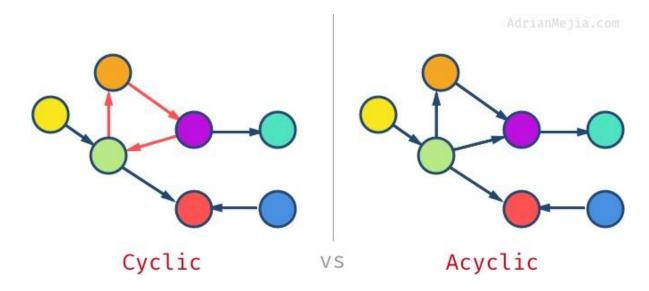
Each edge connects two nodes together (or possibly the same node to itself) and may contain an edge attribute



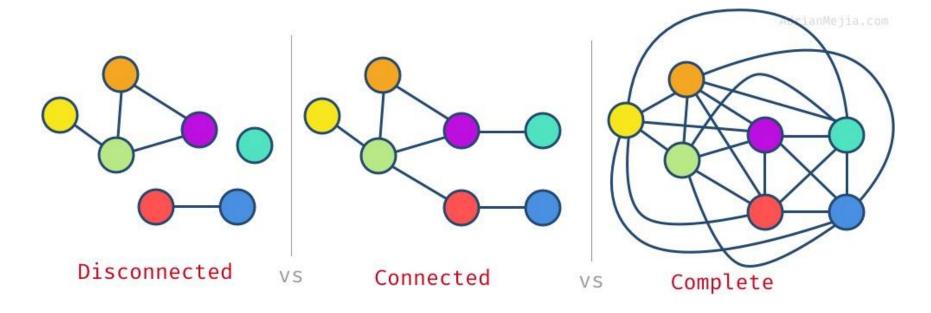
- The degree is the number of edges connected to a vertex. E.g., the purple vertex has a
  degree of 3 while the blue one has a degree of 1.
- If the edges are bi-directional, then we have an undirected graph.
- If the edges have a direction, then we have a directed graph or di-graph for short.
- Vertex can have edges that go to itself (e.g., blue node), this is called self-loop.



- A graph can have cycles which means that if you traverse through the node, you could
  get the same node more than once. The graph without cycles is called acyclic graph.
- Also, acyclic undirected graphs are called tree. We are going to cover trees in depth in the next post.



- If all nodes have at least one edge, then we have a connected graph.
- When all nodes are connected to all other nodes, then we have a complete graph.

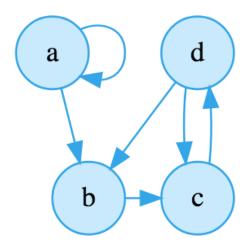


### **Graph Terminologies**

- The size of a graph is the number of nodes in it
- The empty graph has size zero (no nodes)
- If two nodes are connected by an edge, they are neighbors (and the nodes are adjacent to each other)
- The degree of a node is the number of edges it has
- · For directed graphs,
  - If a directed edge goes from node S to node D, we call S the source and D the destination of the edge
    - The edge is an out-edge of S and an in-edge of D
    - S is a predecessor of D, and D is a successor of S
  - The in-degree of a node is the number of in-edges it has
  - The out-degree of a node is the number of out-edges it has

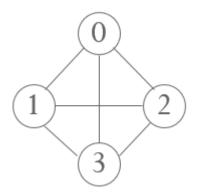
There are two primary ways of representing graph:

- Adjacency list
- Adjacency Matrix

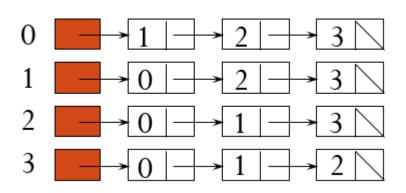


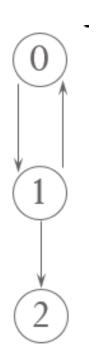
```
Adjacency List

1  a -> { a b }
2  b -> { c }
3  c -> { d }
4  d -> { b c }
```

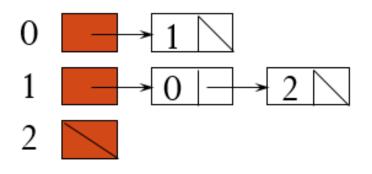


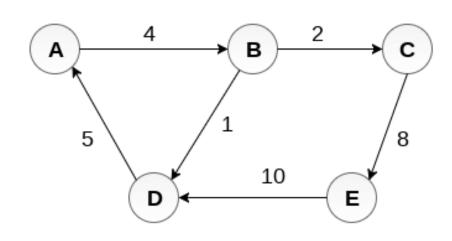
$\lceil 0 \rceil$	1	1	1
1	0	1	1
$\begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}$	1	0	1 1 0
1	1	1	0



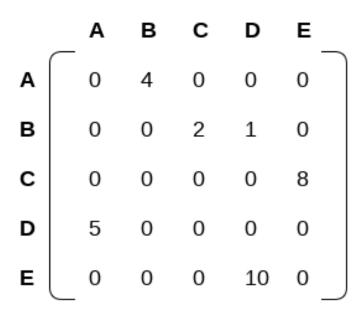


0	1	0
0 1 0	0	0 1 0
0	0	0

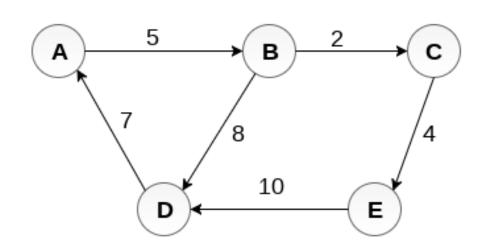




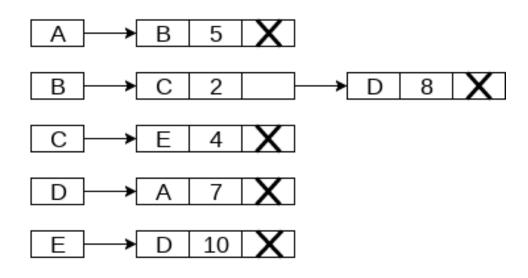
Weighted Directed Graph



**Adjacency Matrix** 



Weighted Directed Graph



**Adjacency List** 

### **Graph Traversal**

- BFS (Breadth First Search)
  - Start from a vertex, visit all the reachable vertices in a breadth first manner
  - Uses Queue for non-recursive implementation
- DFS (Depth First Search)
  - Start from a vertex, visit all the reachable vertices in a depth first manner
  - Uses Stack for non-recursive implementation

### **Depth First Search (DFS) Algorithm**

#### Algorithm

```
Step 1: SET STATUS = 1 (ready state) for each node in G
```

Step 2: Push the starting node A on the stack and set its STATUS = 2 (waiting state)

Step 3: Repeat Steps 4 and 5 until STACK is empty

Step 4: Pop the top node N. Process it and set its STATUS = 3 (processed state)

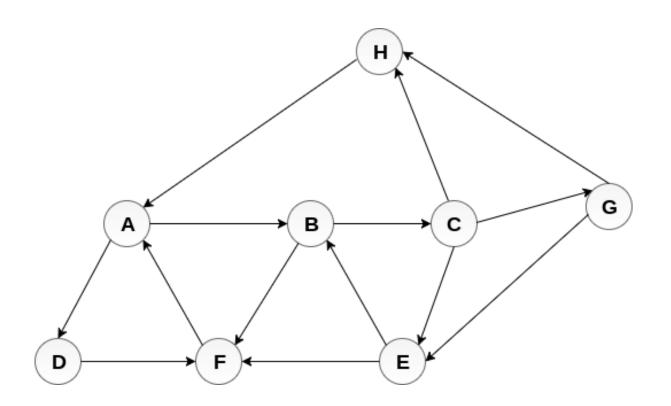
Step 5: Push on the stack all the neighbours of N that are in the ready state (whose

STATUS = 1) and set their

STATUS = 2 (waiting state)

[END OF LOOP]

Step 6: EXIT



#### **Adjacency Lists**

A : B, D

B: C, F

C : E, G, H

G : E, H

E:B,F

F:A

D:F

H:A

Step1: Push H onto the stack Step3: Pop A and Push all its adjacent



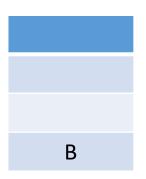
Step2: Pop H and Push all its adjacent Step4: Pop D and Push all its adjacent



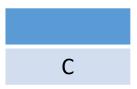
Step5: Pop F and Push all its

adjacent. But A is already visited. So no

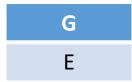
Push



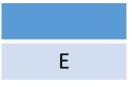
Step6: Pop B and Push all its adjacent. F is already visited



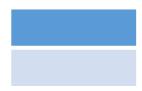
Step7: Pop C and Push all its adjacent. H is already visited



Step8: Pop G and Push all its adjacent. But B, F already visited. So no push



Step9: Pop E and Push all its adjacent. But B, E is already visited. So no Push



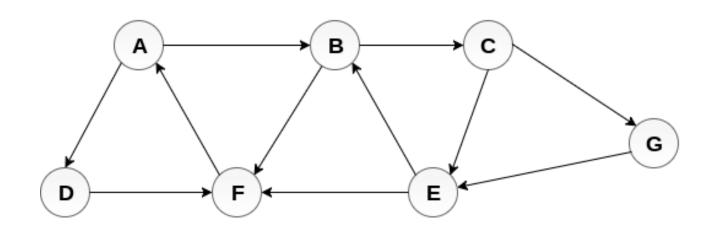
Now the stack is empty. Stop the process. List all the popped elements

$$DFS = H \rightarrow A \rightarrow D \rightarrow F \rightarrow B \rightarrow C \rightarrow G \rightarrow E$$

#### **Breadth First Search (BFS) Algorithm**

#### Algorithm

```
Step 1: SET STATUS = 1 (ready state) for each node in G
Step 2: Enqueue the starting node A and set its STATUS = 2 (waiting state)
Step 3: Repeat Steps 4 and 5 until QUEUE is empty
Step 4: Dequeue a node N. Process it and set its STATUS = 3 (processed state).
Step 5: Enqueue all the neighbours of N that are in the ready state
          (whose STATUS = 1) and set
          their STATUS = 2 (waiting state)
          [END OF LOOP]
Step 6: EXIT
```



#### **Adjacency Lists**

A: B, D

B: C, F

C : E, G

G:E

E: B, F

F:A

D:F

Step1: Enque A onto the Queue Q1

Q1: A

Step2: Deque A and Enque all its adjacent

Q1: B D

Step3: Deque B and Enque all its adjacent

Q1: D C F

Step4: Deque D and Enque all its adjacent. But F is already inserted. So no Enque

Q1: C F

Step5: Deque C and Enque all its adjacent

Q1: F E G

Step6: Deque F and Enque all its adjacent. But A already visited so no Enque.

Q1: E G

Step7: Deque E and Enque all its adjacent. But B, F is already inserted. So no Enque

Q1: G

Step8: Deque G and Enque all its adjacent. But E already visited

Q1:

Now queue is empty, Display all deque element is order

BFS: A, B, D, C, F, E, G

### **Summary**

At the end of this session we learned about

- Graphs
- Breadth First Search BFS
- Depth First Search DFS