
LWA352 SNAP2 F-Engine Documentation

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INSTALLATION

The LWA 352 F-Engine pipeline is available at <https://github.com/realtimeradio/caltech-lwa>. Follow the following instructions to download and install the pipeline.

Specify the build directory by defining the `BUILDDIR` environment variable, eg:

```
export BUILDDIR=~/.src/  
mkdir -p $BUILDDIR
```

1.1 Get the Source Code

Clone the repository and its dependencies with:

```
# Clone the main repository  
cd $BUILDDIR  
git clone https://github.com/realtimeradio/caltech-lwa  
# Clone relevant submodules  
cd caltech-lwa  
git submodule init  
git submodule update
```

1.2 Install Prerequisites

1.2.1 Firmware Requirements

The LWA-253 F-Engine firmware can be built with the CASPER toolflow, and was designed using the following software stack:

- Ubuntu 18.04.0 LTS (64-bit)
- MATLAB R2019a
- Simulink R2019a
- MATLAB Fixed-Point Designer Toolbox R2019a
- Xilinx Vivado HLx 2019.1.3
- Python 3.6.9

It is *strongly* recommended that the same software versions be used to rebuild the design.

CONTROL INTERFACE

2.1 Overview

A Python class `Snap2Fengine` is provided to encapsulate control of individual blocks in the firmware DSP pipeline. The structure of the software interface aims to mirror the hierarchy of the firmware modules, through the use of multiple `Block` class instances, each of which encapsulates control of a single module in the firmware pipeline.

In testing, and interactive debugging, the `Snap2Fengine` class provides an easy way to probe board status for a SNAP2 board on the local network.

In order to integrate with the larger LWA352 control framework, control and monitoring of multiple F-Engines can also be carried out through the passing of JSON-encoded messages through an `etcd`¹ key-value store. This mechanism, shown in Fig. 2.1, utilizes the Python class `Snap2FengineEtcdClient` to translate commands and responses between the `etcd` format and the underlying `Snap2Fengine` method calls.

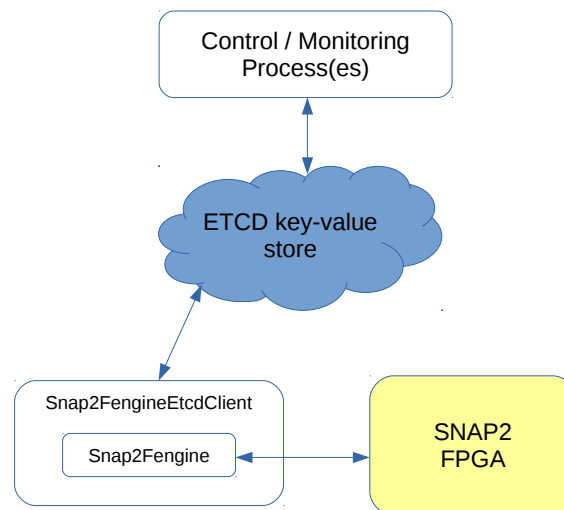


Fig. 2.1: The top-level control architecture.

¹ See etcd.io

2.2 Snap2Fengine Python Interface

The Snap2Fengine class can be instantiated and used to control a single SNAP2 board running LWA's F-Engine firmware. An example is below:

```
# Import the SNAP2 F-Engine library
from lwa_f import snap2_fengine

# Instantiate a Snap2Fengine instance to a board with
# hostname 'snap2-rev2-11'
f = snap2_fengine.Snap2Fengine('snap2-rev2-11')

# Program a board (if it is not already programmed)
# and initialize all the firmware blocks
if not f.fpga.is_programmed():
    f.program() # Load whatever firmware is in flash
    # Wait 30 seconds for the board to reboot...
    # Initialize firmware blocks, including ADC link training
    f.initialize(read_only=False)

# Blocks are available as items in the Snap2Fengine `blocks`
# dictionary, or can be accessed directly as attributes
# of the Snap2Fengine.

# Print available block names
print(sorted(f.blocks.keys()))
# Returns:
# ['adc', 'autocorr', 'corr', 'delay', 'eq', 'eq_tvlg', 'eth',
# 'fpga', 'input', 'noise', 'packetizer', 'pfb', 'reorder', 'sync']

# Grab some ADC data from the ADC card(s) on FMC 1
adc_data = f.adc.get_snapshot_interleaved(1, signed=True)
print(adc_data.shape) # returns (32 [channels], 512 [time samples])
```

Details of the methods provided by individual blocks are given in the next section.

2.2.1 Top-Level Control

The Top-level Snap2Fengine instance can be used to perform high-level control of the firmware, such as programming and de-programming FPGA boards. It can also be used to apply configurations which affect multiple firmware subsystems, such as configuring channel selection and packet destination.

Finally, a Snap2Fengine instance can be used to initialize, or get status from, all underlying firmware modules.

class lwa_f.snap2_fengine.Snap2Fengine (host, logger=None)
A control class for LWA352's SNAP2 F-Engine firmware.

Parameters

- **host** (casperfpga.CasperFpga) – CasperFpga interface for host.
- **logger** (logging.Logger) – Logger instance to which log messages should be emitted.

configure_output (antenna_ids, n_chans_per_packet, n_chans_per_xeng, chans, ips, ports=None, debug=False)

Configure channel reordering and packetizer modules to emit a selection of frequency channels.

Parameters

- **n_chans_per_packet** (*int*) – Number of channels per packet.
- **n_chans_per_xeng** (*int*) – Number of channels per xeng.
- **chans** (*list of int*) – A list of channel indices to be sent, e.g. `range(0, 1024)`. The number of channels in this list should be an integer multiple of `n_chans_per_packet`. An assertion error is raised if this is not the case.
- **ips** (*list of str*) – A list of IP addresses to which packets should be sent. The order of values in `ips` and `chans` should reflect where different channels should be sent. The *n*th IP address in `ips` is the destination to which channels `chans[n*n_chans_per_packet : (n+1)*n_chans_per_packet]` should be sent. As such, `ips` should have `len(chans) // n_chans_per_packet` elements. IP addresses should be provided in dotted-quad string representation.
- **ports** (*list of int*) – The UDP destination ports to which packets should be transmitted. Addressing rules are the same as for `ips`. If `None`, all packets are transmitted to UDP port 10000.
- **antenna_ids** (*list*) – A list of Antenna IDs which should be written to output packet headers. Addressing rules are the same as for `ips`.
- **debug** (*bool*) – Set to `True` to print extra diagnostic information.
- **n_boards** – Transmit packets with headers indicating they came from this many different boards. For example, if `n_boards=2`, the board will transmit two streams of packets with antenna IDs `base_ant` and `base_ant+64`

deprogram()

Reprogram the FPGA into its default boot image.

get_status_all()

Call the `get_status` methods of all blocks in `self.blocks`. If the FPGA is not programmed with F-engine firmware, will only return basic FPGA status.

Returns (`status_dict`, `flags_dict`) tuple. Each is a dictionary, keyed by the names of the blocks in `self.blocks`. These dictionaries contain, respectively, the status and flags returned by the `get_status` calls of each of this F-Engine's blocks.

hostname

hostname of the F-Engine's host SNAP2 board

initialize (*read_only=True*)

Call the `initialize` methods of all underlying blocks.

Parameters **read_only** (*bool*) – If `True`, call the underlying initialization methods in a `read_only` manner.

is_connected()

Returns `True` if there is a working connection to a SNAP2. `False` otherwise.

Return type `bool`

logger

Python Logger instance

n_pols_per_board = 64

Number of analog inputs per FPGA

n_pols_per_xeng = 704

Number of analog inputs per X-engine

print_status_all (*use_color=True*)

Print the status returned by `get_status` for all blocks in the system. If the FPGA is not programmed with F-engine firmware, will only print basic FPGA status.

Parameters *use_color* (*bool*) – If True, highlight values with colors based on error codes.

program (*fpgfile=None, force=False*)

Program an .fpg file to a SNAP2 FPGA. If the name of the file matches what is already in flash, this command will simply reboot the FPGA. If the name of the file doesn't match, the new bitstream will be uploaded. This will take <=5 minutes.

Parameters

- **fpgfile** (*str*) – The .fpg file to be loaded. Should be a path to a valid .fpg file. If None is given, the image currently in flash will be loaded.
- **force** (*boolean*) – If True, write the firmware to flash even if the SNAP claims it is already loaded. Has no effect if *fpgfile=None*.

2.2.2 FPGA Control

The FPGA control interface allows gathering of FPGA statistics such as temperature and voltage levels. Its methods are functional regardless of whether the FPGA is programmed with an LWA F-Engine firmware design.

class `lwa_f.blocks.fpga.Fpga` (*host, name, logger=None*)

Instantiate a control interface for top-level FPGA control.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.

get_build_time ()

Read the UNIX time at which the current firmware was built.

Return build_time Seconds since the UNIX epoch at which the running firmware was built.

Rtype int

get_firmware_version ()

Read the firmware version register and return the contents as a string.

Return version major_version.minor_version.revision.bugfix

Rtype str

get_fpga_clock ()

Estimate the FPGA clock, by polling the `sys_clkcounter` register.

Returns Estimated FPGA clock in MHz

Return type float

get_status ()

Get status and error flag dictionaries.

Status keys:

- **programmed** (bool) : True if FPGA appears to be running DSP firmware. False otherwise, and flagged as a warning.

- `flash_firmware (str)` : The name of the firmware file currently loaded in flash memory.
- `flash_firmware_md5 (str)` : The MD5 checksum of the firmware file currently loaded in flash memory.
- `timestamp (str)` : The current time, as an ISO format string.
- `serial (str)` : The serial number / identifier for this board. Flagged with a warning if no serial is available.
- `host (str)` : The host name of this board.
- `sw_version (str)` : The version string of the control software package. Flagged as warning if the version indicates a build against a dirty git repository.
- `fw_version (str)`: The version string of the currently running firmware. Available only if the board is programmed.
- `fw_build_time (int)`: The build time of the firmware, as an ISO format string. Available only if the board is programmed.
- `sys_mon (str)` : 'reporting' if the current firmware has a functioning system monitor module. Otherwise 'not reporting', flagged as an error.
- `temp (float)` : FPGA junction temperature, in degrees C. (Only reported is system monitor is available). Flagged as a warning if outside the recommended operating conditions. Flagged as an error if outside the absolute maximum ratings. See DS892.
- `vccaux (float)` : Voltage of the VCCAUX FPGA power rail. (Only reported is system monitor is available). Flagged as a warning if outside the recommended operating conditions. Flagged as an error if outside the absolute maximum ratings. See DS892.
- `vccbram (float)` : Voltage of the VCCBRAM FPGA power rail. (Only reported is system monitor is available). Flagged as a warning if outside the recommended operating conditions. Flagged as an error if outside the absolute maximum ratings. See DS892.
- `vccint (float)` : Voltage of the VCCINT FPGA power rail. (Only reported is system monitor is available). Flagged as a warning if outside the recommended operating conditions. Flagged as an error if outside the absolute maximum ratings. See DS892.

Returns (`status_dict`, `flags_dict`) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.

`is_programmed()`

Lazy check to see if a board is programmed. Check for the “version_version” register. If it exists, the board is deemed programmed.

Returns True if programmed, False otherwise.

Return type `bool`

2.2.3 Timing Control

The `Sync` control interface provides an interface to configure and monitor the multi-SNAP2 timing distribution system.

```
class lwa_f.blocks.sync.Sync(host, name, logger=None)
```

```
    arm_noise()
```

Arm noise generator resets

```
    arm_sync()
```

Arm sync pulse generator.

```
    count_ext()
```

Returns Number of external sync pulses received.

Rtype int

```
    count_int()
```

Returns Number of internal sync pulses received.

Rtype int

```
    get_error_count()
```

Returns Number of sync errors.

Rtype int

```
    get_latency()
```

Returns Number of FPGA clock ticks between sync transmission and reception

Rtype int

```
    get_status()
```

Get status and error flag dictionaries.

Status keys:

- `uptime_fpga_clks` (int) : Number of FPGA clock ticks (= ADC clock ticks) since the FPGA was last programmed.
- `period_fpga_clks` (int) : Number of FPGA clock ticks (= ADC clock ticks) between the last two internal sync pulses.
- `ext_count` (int) : The number of external sync pulses since the FPGA was last programmed.
- `int_count` (int) : The number of internal sync pulses since the FPGA was last programmed.

Returns (`status_dict`, `flags_dict`) tuple. `status_dict` is a dictionary of status key-value pairs. `flags_dict` is a dictionary with all, or a sub-set, of the keys in `status_dict`. The values held in this dictionary are as defined in `error_levels.py` and indicate that values in the status dictionary are outside normal ranges.

```
    initialize(read_only=False)
```

Initialize block.

Parameters `read_only` (*bool*) – If False, initialize system control register to 0 and reset error counters. If True, do nothing.

load_telescope_time (*tt*, *software_load=False*)

Load a new starting value into the telescope time counter on the next sync.

Parameters

- **tt** (*int*) – Telescope time to load
- **software_load** (*bool*) – If True, immediately load via a software trigger. Else load on the next external sync pulse arrival.

period ()

Returns The number of FPGA clock ticks between the last two external sync pulses.

Rtype int

reset_error_count ()

Reset internal error counter to 0.

reset_telescope_time ()

Reset the telescope time counter to 0 immediately.

sw_sync ()

Issue a software sync pulse

uptime ()

Returns Time in FPGA clock ticks since the FPGA was last programmed. Resolution is 2^{32} (21 seconds at 200 MHz)

Return type int

wait_for_sync ()

Block until a sync has been received.

2.2.4 ADC Control

The `Adc` control interface allows link training (aka “calibration”) of the ADC->FPGA data link.

class `lwa_f.blocks.adc.Adc` (*host*, *name*, *logger=None*)

Instantiate a control interface for an ADC block.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.

calibrate (*use_ramp=False*, *fail_hard=True*, *step_size=4*)

Compute and set all ADC data lane input delays to their optimal values. After this call, the ADCs are left in test mode.

Parameters

- **use_ramp** (*bool*) – If True, after calibration, use the ramp test pattern to verify the ADC->FPGA link is functioning correctly. If False, perform this verification with the same constant test value used for the calibration procedure.
- **fail_hard** (*bool*) – If True, raise an exception if the calibration run doesn’t go to plan.
- **step_size** (*int*) – Number of IDELAY tap steps between error counts.

Returns (status, delays, slack) tuple. `status` is True if the calibration procedure succeeded. False otherwise. `delays` is an `N_ADC_BOARD x N_ADC_CHIP x DATA_LANES_PER_CHIP` array of chosen delays. `slack` is an `N_ADC_BOARD x N_ADC_CHIP x DATA_LANES_PER_CHIP` array of slacks – the number of delay taps between the chosen delay and the nearest delay which showed ADC errors.

Return type `bool, list, list`

get_snapshot (*fmc, signed=False, trigger=True*)

Read a snapshot of data from all ADC channels on a single FMC card. Return data without interleaving ADC cores.

Parameters

- **fmc** (*int*) – Which FMC port (0 or 1) to read.
- **signed** (*bool*) – If True, return data interpreted as signed 2's complement integers. If False, return data as unsigned integers.
- **trigger** (*bool*) – If True, trigger a new simultaneous capture of data from all channels. If False, read existing data capture. Grabbing data without a new trigger may be useful if you wish to read channels from a second FMC port which were captured simultaneously with another port.

Returns Array of captured data with dimensions [ADC_CHIPS_PER_FMC, ADC_LANES, TIME_SAMPLES]. Data from ADC lanes representing the same analog input are `_not_` interleaved. Data from ADC lanes `n,n+1` are associated with the same analog input.

Return type `numpy.array`

get_snapshot_interleaved (*fmc, signed=False, trigger=True*)

Read a snapshot of data from all ADC channels on a single FMC card. Return data with ADC cores interleaved.

Parameters

- **fmc** (*int*) – Which FMC port (0 or 1) to read.
- **signed** (*bool*) – If True, return data interpreted as signed 2's complement integers. If False, return data as unsigned integers.
- **trigger** (*bool*) – If True, trigger a new simultaneous capture of data from all channels. If False, read existing data capture. Grabbing data without a new trigger may be useful if you wish to read channels from a second FMC port which were captured simultaneously with another port.

Returns `numpy` array of captured data with dimensions [ADC_CHANNELS_PER_FMC, TIME_SAMPLES].

Return type `numpy.ndarray`

initialize (*read_only=False, clocksource=1*)

Initialize connected ADC boards.

Parameters

- **read_only** (*bool*) – If True, don't do anything which would affect a running system. If False, train ADC->FPGA data links.
- **clocksource** (*int*) – Which ADC board (0 or 1) on an FMC card should serve as the source of the clocks. Note that while this parameter is set for boards on all FMC cards, only the FMC card selected as the clock source at Simulink compile-time will be used for clocking.

Returns True if initialization was successful. False otherwise.

mmcm_is_locked()

Read the ADC control register to determine if the clock PLLs are locked.

Returns True if the ADC clocks are locked. False otherwise.

Return type `bool`

print_sweep (*errs*, *best_delays*=None, *step_size*=4)

Print, using ASCII, the valid data capture eye as a function of delay setting. Delays are printed such that one row represents a sweep of delays for a single ADC data lane. Each column in the row is X if data contained errors at this delay, - if no errors were detected at this delay, and |, if this delay is considered the best setting in the sweep range.

Parameters

- **errs** (*list*) – Array of error counts with dimensions [DELAY_TRIALS, ADC_CHIPS, DATA_LANES_PER_ADC_CHIP] such as that returned by `_get_errs_by_delay`.
- **best_delays** (*list*) – Array of best delays, with shape [ADC_CHIPS, DATA_LANES_PER_ADC_CHIP], such as that returned by `_get_best_delays`. These delays are marked with an ASCII |.
- **step_size** (*int*) – Number of IDELAY tap steps between delay trials.

reset()

Toggle the ADC reset input.

sync()

Toggle the ADC sync input.

use_data()

Set all ADCs into normal operating mode, in which analog inputs are digitized and transmitted.

use_ramp()

Set all ADCs into the “ramp” test mode, in which ADC samples are replaced with a 10-bit counter which increments with each ADC clock.

use_toggle (*val0*, *val1*)

Set all ADCs into the “toggle” test mode, in which ADC samples are replaced with a toggling pattern of two 10-bit values.

Parameters

- **val0** (*int*) – First value ADCs should output.
- **val1** (*int*) – Second value ADCs should output.

2.2.5 Input Control

class `lwa_f.blocks.input.Input` (*host*, *name*, *n_streams*=64, *n_bits*=10, *logger*=None)

Instantiate a control interface for an Input block. This block allows switching data streams between constant-zeros, digital noise, and ADC streams.

A statistics interface is also provided, providing bit statistics and histograms.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.

- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **n_streams** (*int*) – Number of independent streams which may be delayed
- **n_bits** (*int*) – Number of bits per ADC sample.

Variables

- **n_streams** – Number of streams this interface handles
- **n_bits** – Number of bits per ADC sample

get_all_histograms()

Get histograms for all antpols, summing over all interleaving cores.

Returns (vals, hists). *vals* is a list of histogram bin centers. *hists* is an $[n_stream \times 2 \times n_bits]$ list of histogram data.

get_bit_stats()

Get the mean, RMS, and mean powers of all ADC streams.

Returns (means, powers, rmss) tuple. Each member of the tuple is an array with *self.n_streams* elements.

Rval (numpy.ndarray, numpy.ndarray, numpy.ndarray)

get_histogram(stream, sum_cores=True)

Get a histogram for an ADC stream.

Parameters

- **stream** (*int*) – ADC stream from which to get data.
- **sum_cores** (*bool*) – If True, compute one histogram from both pairs of interleaved ADC cores associated with an analog input. If False, compute separate histograms.

Returns If *sum_cores* is True, return (*vals*, *hist*), where *vals* is a list of histogram bin centers, and *hist* is a list of histogram data points. If *sum_cores* is False, return (*vals*, *hist_a*, *hist_b*), where *hist_a* and *hist_b* are separate histogram data sets for the even-sample and odd-sample ADC cores, respectively.

get_status()

Get status and error flag dictionaries.

Status keys:

- **switch_position<n>** (str) : Switch position ('noise', 'adc' or 'zero') for input stream *n*, where *n* is a two-digit integer starting at 00. Any input position other than 'adc' is flagged with "NOTIFY".
- **power<n>** (float) : Mean power of input stream *n*, where *n* is a two-digit integer starting at 00. In units of (ADC LSBs)**2.
- **rms<n>** (float) : RMS of input stream *n*, where *n* is a two-digit integer starting at 00. In units of ADC LSBs. Value is flagged as a warning if it is >30 or <5.
- **mean<n>** (float) : Mean sample value of input stream *n*, where *n* is a two-digit integer starting at 00. In units of ADC LSBs. Value is flagged as a warning if it is > 2.

Returns (status_dict, flags_dict) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.

get_switch_positions()

Get the positions of the input switches.

Returns List of switch positions. Entry *n* contains the position of the switch associated with ADC input *n*. Switch positions are “noise” (internal digital noise generators), “adc” (digitized ADC stream), or “zero” (constant 0).

Return type list of str

initialize (*read_only=False*)

Initialize the block.

Parameters **read_only** (*bool*) – If True, do nothing. If False, set the input multiplexers to ADC data and enable statistic computation.

plot_histogram (*stream*)

Plot a histogram.

Parameters **stream** (*int*) – ADC stream from which to get data.

print_histograms ()

Print histogram stats to screen.

use_adc (*stream=None*)

Switch input to ADC.

Parameters **stream** (*int or None*) – Which stream to switch. If None, switch all.

use_noise (*stream=None*)

Switch input to internal noise source.

Parameters **stream** (*int or None*) – Which stream to switch. If None, switch all.

use_zero (*stream=None*)

Switch input to zeros.

Parameters **stream** (*int or None*) – Which stream to switch. If None, switch all.

2.2.6 Noise Generator Control

class `lwa_f.blocks.noisegen.NoiseGen` (*host, name, n_noise=5, n_outputs=64, logger=None*)

Noise Generator controller

This block controls a digital noise source, which can generate multiple independent channels of gaussian noise. These channels can be assigned to multiple outputs of this block, to create correlated or uncorrelated noise streams.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **n_noise** (*int*) – The number of independent noise generation cores in the underlying block. $2 \times n_noise$ independent noise streams will be produced.
- **n_outputs** (*int*) – The number of output channels from the block.

assign_output (*output, noise*)

Assign an output channel to a given noise stream. Note that the output stream will not be affected unless the downstream input multiplexors are set to noise mode.

Parameters

- **output** (*int*) – The index of the output stream to be assigned.
- **noise** (*int*) – The index of the noise stream to assign to *output*. Note that each noise generator core generates two independent streams, so *noise* can be in range(0, 2*self.n_noise)

get_output_assignment (*output*)

Get the index of the noise stream assigned to an output.

Parameters **output** (*int*) – The index of the output stream to query.**Returns** The index of the noise stream to assign to *output*. Note that each noise generator core generates two independent streams, so *noise* can be in range(0, 2*self.n_noise)**Return type** *int***get_seed** (*n*)

Get the seed of a noise generator.

Parameters **n** (*int*) – Noise generator ID whose seed to read.**Returns** Noise generator seed.**Rtype** *int***get_status** ()

Get status and error flag dictionaries.

Status keys:

- **noise_core<m>_seed** (*int*): Seed currently loaded into noise generator core *m*. *m* should be a two-digit integer starting at 00.
- **output_assignment<n>** (*int*): The noise generator ID currently assigned to output stream *n*, where *n* is a two-digit integer starting at 00.

Returns (*status_dict*, *flags_dict*) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.**initialize** (*read_only=False*)

Initialize the block

Parameters **read_only** (*bool*) – If False, set the seen of noise generator *n* to *n*. If True, do nothing.**set_seed** (*n*, *seed*)

Set the seed of a noise generator.

Parameters

- **n** (*int*) – Noise generator ID to seed.
- **seed** (*int*) – Noise generator seed to load.

2.2.7 Delay Control

class `lwa_f.blocks.delay.Delay` (*host, name, n_streams=64, logger=None*)

Instantiate a control interface for a Delay block.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **n_streams** (*int*) – Number of independent streams which may be delayed

MIN_DELAY = 5

minimum delay allowed

get_delay (*stream*)

Get the current delay for a given input.

Parameters **stream** (*int*) – Which ADC input index to query

Returns Currently loaded delay, in ADC samples

Return type *int*

get_max_delay ()

Query the firmware to get the maximum delay it supports.

Returns Maximum supported delay, in ADC samples

Return type *int*

get_status ()

Get status and error flag dictionaries.

Status keys:

- **delay<n>**: Currently loaded delay for ADC input index *n*. in units of ADC samples.
- **max_delay**: The maximum delay supported by the firmware.
- **min_delay**: The minimum delay supported by the firmware.

Returns (*status_dict, flags_dict*) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.

initialize (*read_only=False*)

Initialize all delays.

Parameters **read_only** (*bool*) – If True, do nothing. If False, initialize all delays to the minimum allowed value.

set_delay (*stream, delay*)

Set the delay for a given input stream.

Parameters

- **stream** (*int*) – ADC stream index to which delay should be applied.
- **delay** (*int*) – Number of ADC clock cycles delay to load.

2.2.8 PFB Control

```
class lwa_f.blocks.pfb.Pfb(host, name, logger=None)
```

```
get_status()
```

Get a dictionary of status values, with optional warning of error flags. To be overridden by individual blocks

Returns (status_dict, flags_dict) tuple. *status_dict* is a dictionary of status key-value pairs, defined on a per-block basis. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary should be as defined in *error_levels.py*.

```
initialize(read_only=False)
```

Individual blocks should override this method to configure themselves appropriately

Parameters *read_only* (*bool*) – If False, initialize blocks in a way that might change the configuration of running hardware. If True, read runtime info from blocks, but don't change anything.

2.2.9 Auto-correlation Control

```
class lwa_f.blocks.autocorr.AutoCorr(host, name, acc_len=32768, logger=None,  
                                     n_chans=4096, n_pols=64, n_parallel_streams=8,  
                                     n_cores=4, use_mux=True)
```

Instantiate a control interface for an Auto-Correlation block.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **acc_len** (*int*) – Accumulation length initialization value, in spectra.
- **n_chans** (*int*) – Number of frequency channels.
- **n_pols** (*int*) – Number of individual data streams.
- **n_parallel_streams** (*int*) – Number of streams processed by the firmware module in parallel.
- **n_cores** (*int*) – Number of accumulation cores in firmware design.
- **use_mux** (*bool*) – If True, only one core is instantiated and a multiplexer is used to switch different inputs into it. If False, multiple cores are instantiated simultaneously in firmware.

```
get_acc_len()
```

Get the currently loaded accumulation length in units of spectra.

Returns Current accumulation length

Return type *int*

```
get_new_spectra(core=0)
```

Get a new average power spectra.

Parameters *core* (*int*) – If using multiplexing, read data for this core. If not using multiplexing, read data from all cores.

Returns Float32 array of dimensions [POLARIZATION, FREQUENCY CHANNEL] containing autocorrelations with accumulation length divided out.

Return type numpy.array

get_status()

Get status and error flag dictionaries.

Status keys:

- **acc_len** (int) : Currently loaded accumulation length in number of spectra.

Returns (status_dict, flags_dict) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.

initialize (*read_only=False*)

Initialize the block, setting (or reading) the accumulation length.

Parameters **read_only** (*bool*) – If False, set the accumulation length to the value provided when this block was instantiated. If True, use whatever accumulation length is currently loaded.

plot_spectra (*core=0, db=True, show=True*)

Plot the spectra of all polarizations in a single core, with accumulation length divided out

Parameters

- **core** (*int*) – If using multiplexing, read data for this core. If not using multiplexing, read data from all cores.
- **db** (*bool*) – If True, plot $10\log_{10}(\text{power})$. Else, plot linear.
- **show** (*bool*) – If True, call matplotlib's *show* after plotting

Returns matplotlib.Figure

set_acc_len (*acc_len*)

Set the number of spectra to accumulate.

Parameters **acc_len** (*int*) – Number of spectra to accumulate

2.2.10 Correlation Control

class lwa_f.blocks.corr.Corr (*host, name, acc_len=1024, logger=None, n_chans=1024*)

Instantiate a control interface for a Correlation block.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **acc_len** (*int*) – Accumulation length initialization value, in spectra.
- **n_chans** (*int*) – Number of frequency channels in the correlation output.

get_acc_len()

Get the currently loaded accumulation length in units of spectra.

Returns Current accumulation length

Return type `int`

get_new_corr (*pol1*, *pol2*, *flush_vacc=True*)

Get a new correlation.

Parameters

- **pol1** (*int*) – First (unconjugated) polarization index.
- **pol2** (*int*) – Second (conjugated) polarization index.
- **flush_vacc** (*bool*) – If True, throw away the first accumulation after setting the input selection registers. This is good practice the first time a new polarization pair is read.

Returns Complex-valued cross-correlation spectra of *pol1* and *pol2* with accumulation length divided out.

Return type `numpy.array`

get_status ()

Get status and error flag dictionaries.

Status keys:

- **acc_len** : Currently loaded accumulation length in number of spectra.

Returns (*status_dict*, *flags_dict*) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.

initialize (*read_only=False*)

Initialize the block, setting (or reading) the accumulation length.

Parameters **read_only** (*bool*) – If False, set the accumulation length to the value provided when this block was instantiated. If True, use whatever accumulation length is currently loaded.

plot_corr (*pol1*, *pol2*, *show=False*)

Plot a correlation spectra.

Parameters

- **pol1** (*int*) – First (unconjugated) polarization index.
- **pol2** (*int*) – Second (conjugated) polarization index.
- **show** (*bool*) – If True, call matplotlib's *show* after plotting

Returns `matplotlib.Figure`

set_acc_len (*acc_len*)

Set the number of spectra to accumulate.

Parameters **acc_len** (*int*) – Number of spectra to accumulate

2.2.11 Post-FFT Test Vector Control

class `lwa_f.blocks.eqtvq.EqTVg` (*host, name, n_streams=64, n_chans=4096, logger=None*)

Instantiate a control interface for a post-equalization test vector generator block.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **n_streams** (*int*) – Number of independent streams which may be delayed
- **n_chans** (*int*) – Number of frequency channels.

get_status ()

Get status and error flag dictionaries.

Status keys:

- **tvq_enabled**: Currently state of test vector generator. `True` if the generator is enabled, else `False`.

Returns (*status_dict, flags_dict*) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.

initialize (*read_only=False*)

Initialize the block.

Parameters **read_only** (*bool*) – If `True`, do nothing. If `False`, load frequency-ramp test vectors, but disable the test vector generator.

read_stream_tvq (*stream*)

Read the test vector loaded to an ADC stream.

Parameters **stream** (*int*) – Index of stream from which test vectors should be read.

Returns Test vector array, as loaded to the FPGA in 8-bit unsigned integer representation.

Return type `numpy.ndarray`

tvq_disable ()

Disable the test vector generator

tvq_enable ()

Enable the test vector generator.

tvq_is_enabled ()

Query the current test vector generator state.

Returns `True` if the test vector generator is enabled, else `False`.

Return type `bool`

write_const_per_stream ()

Write a constant to all the channels of a stream, with stream *i* taking the value *i*.

write_freq_ramp ()

Write a frequency ramp to the test vector that is repeated for all ADC inputs. Data are wrapped to fit into 8 bits. I.e., the test vector value for channel 257 takes the value 1.

write_stream_tvg (*stream*, *test_vector*)

Write a test vector pattern to a single signal stream.

Parameters

- **stream** (*int*) – Index of stream to which test vectors should be loaded.
- **test_vector** (*list or numpy.ndarray*) – *self.n_chans*-element test vector. Values should be representable in 8-bit unsigned integer format. Data are loaded such that the most-significant 4 bits of the test_vectors are interpreted as the 2's complement 4-bit real sample data. The least-significant 4 bits of the test vectors are interpreted as the 2's complement 4-bit imaginary sample data.

2.2.12 Equalization Control

class `lwa_f.blocks.eq.Eq` (*host*, *name*, *n_streams*=64, *n_coeffs*=512, *logger*=None)

Instantiate a control interface for an Equalization block.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **n_streams** (*int*) – Number of independent streams which may be delayed
- **n_coeffs** (*int*) – Number of coefficients per input stream. Coefficients are shared among neighbouring frequency channels.

clip_count ()

Get the total number of times any samples have clipped, since last sync.

Returns Clip count.

Return type *int*

get_coeffs (*stream*)

Get the coefficients currently loaded. Reads the actual coefficients from the board.

Parameters **stream** (*int*) – ADC stream index to query.

Returns (*coeffs*, *binary_point*). *coeffs* is an array of *self.n_coeffs* integer coefficients currently being applied. *binary_point* is the position of the binary point by which these integers are scaled on the FPGA.

Return type (*numpy.ndarray*, *int*)

get_status ()

Get status and error flag dictionaries.

Status keys:

- *clip_count*: Number of clip events in the last sync period.
- *width*: Bit width of coefficients
- *binary_point*: Binary point position of coefficients
- *coefficients<n>*: The currently loaded, integer-valued coefficients for ADC stream *n*.

Returns (status_dict, flags_dict) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.

initialize (*read_only=False*)

Initialize block.

Parameters *read_only* (*bool*) – If False, set all coefficients to some nominally sane value. Currently, this is 100.0. If True, do nothing.

set_coeffs (*stream, coeffs*)

Set the coefficients for a data stream. Clipping and saturation will be applied before loading.

Parameters

- **stream** (*int*) – ADC stream index to which coefficients should be applied.
- **coeffs** (*list* or *numpy.ndarray*) – Array of coefficients to load. This should be of length `self.n_coeffs`, else an `AssertionError` will be raised.

2.2.13 Channel Selection Control

class `lwa_f.blocks.chanreorder.ChanReorder` (*host, name, n_chans=1024, logger=None*)

Instantiate a control interface for a Channel Reorder block.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **n_chans** (*int*) – Number of channels in the system.

initialize (*read_only=False*)

Initialize the block.

Parameters *read_only* (*bool*) – If True, this method is a no-op. If False, initialize the block with the identity map. I.e., map channel *n* to channel *n*.

n_parallel_chans = 8

Number of channels per reorder word

read_reorder (*raw=False*)

Read the currently loaded reorder map.

Parameters *raw* (*bool*) – If True, return the map as loaded onto the FPGA. If False, return the resulting channel map – i.e., the channel ordering being output by this F-engine.

Returns The reorder map currently loaded.

Return type *list*

set_channel_order (*order*)

Re-order channels so that they are sent with the order in the specified map.

There are various requirements of the map which must be met.

- Every integer multiple of *self.n_parallel_chans* of the map must start on an integer multiple of *n_parallel_chans*. Eg., for *n_parallel_chans* = 8 *order*[0] = 16 is acceptable. *order*[0] = 4 is not.

- Blocks of `n_parallel_channels` must be consecutive. Eg., if `n_parallel_chans=8`, `order[16:24] = [0,1,2,3,4,5,6,7]` is acceptable. `order[16:24] = [0,1,2,3,8,9,10,11]` is not.
- The provided map must be `self.n_chans` elements long.

Parameters `order` (*list of int*) – The order to which data should be mapped. I.e., if `order[0] = 16`, then the first channel out of the F-engine will be channel 16. The order map should meet the above criteria. A `ValueError` exception will be raised if they are not.

2.2.14 Packetization Control

class `lwa_f.blocks.packetizer.Packetizer` (*host, name, n_chans=4096, n_pols=64, sample_rate_mhz=200.0, logger=None*)

The packetizer block allows dynamic definition of packet sizes and contents. In firmware, it is a simple block which allows insertion of header entries and EOFs at any point in the incoming data stream. It is up to the user to configure this block such that it behaves in a reasonable manner – i.e.

- Output data rate does not overflow the downstream Ethernet core
- Packets have a reasonable size
- EOFs and headers are correctly placed.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.
- **n_chans** (*int*) – Number of frequency channels in the correlation output.
- **n_pols** (*int*) – Number of independent analog streams in the system
- **sample_rate_mhz** (*float*) – ADC sample rate in MHz. Used for data rate checks.

get_packet_info (*n_pkt_chans, occupation=0.95, chan_block_size=8*)

Get the packet boundaries for packets containing a given number of frequency channels.

Parameters

- **n_pkt_chans** (*int*) – The number of channels per packet.
- **occupation** (*float*) – The maximum allowed throughput capacity of the underlying link. The calculation does not include application or protocol overhead, so must necessarily be < 1 .
- **chan_block_size** (*int*) – The granularity with which we can start packets. I.e., packets must start on an $n \times \text{chan_block}$ boundary.

Returns

`packet_starts, packet_payloads, channel_indices`

packet_starts [list of ints] The word indexes where packets start – i.e., where headers should be written. For example, a value `[0, 1024, 2048, ...]` indicates that headers should be written into underlying brams at addresses 0, 1024, etc.

packet_payloads [list of range()] The range of indices where this packet's payload falls. Eg: [range(1,257), range(1025,1281), range(2049,2305), ... etc] These indices should be marked valid, and the last given an EOF.

channel_indices [list of range()] The range of channel indices this packet will send. Eg: [range(1,129), range(1025,1153), range(2049,2177), ... etc] Channels to be sent should be re-indexed so that they fall into these ranges.

write_config (*packet_starts, packet_payloads, channel_indices, ant_indices, dest_ips, dest_ports, nchans_per_packet, nchans_per_xeng, npols_per_packet, npols_per_xeng, print_config=False*)

Write the packetizer configuration BRAMs with appropriate entries.

Parameters

- **packet_starts** (*list of int*) – Word-indices which are the first entry of a packet and should be populated with headers (see *get_packet_info()*)
- **packet_payloads** (*list of range()*s) – Word-indices which are data payloads, and should be mared as valid (see *get_packet_info()*)
- **channel_indices** (*list of ints*) – Header entries for the channel field of each packet to be sent
- **ant_indices** (*list of ints*) – Header entries for the antenna field of each packet to be sent
- **dest_ips** – list of str IP addresses for each packet to be sent.
- **dest_ports** (*list of int*) – UDP destination ports for each packet to be sent.
- **nchans_per_packet** (*int*) – Number of frequency channels per packet sent.
- **nchans_per_xeng** (*int*) – Total number of frequency channels sent to each destination IP.
- **npols_per_packet** (*int*) – Number of antpols in each packet sent.
- **npols_per_xeng** (*int*) – Number of antpols expected by each destination IP.
- **print** (*bool*) – If True, print config for debugging

All parameters should have identical lengths.

2.2.15 Ethernet Output Control

class `lwa_f.blocks.eth.Eth` (*host, name, logger=None*)

Instantiate a control interface for a 40 GbE block.

Parameters

- **host** (*casperfpga.CasperFpga*) – CasperFpga interface for host.
- **name** (*str*) – Name of block in Simulink hierarchy.
- **logger** (*logging.Logger*) – Logger instance to which log messages should be emitted.

add_arp_entry (*ip, mac*)

Set a single arp entry.

Parameters

- **ip** (*str*) – The IP address matching the given MAC in dotted-quad string notation. Eg. ‘10.10.10.1’.
- **mac** (*int*) – The MAC address to be loaded to the ARP cache.

configure_source (*mac, ip, port*)

Configure the Ethernet interface source address parameters.

Parameters

- **ip** (*str*) – IP address of the interface, in dotted-quad string notation. Eg. ‘10.10.10.1’
- **mac** (*int*) – MAC address of the interface.
- **port** (*int*) – UDP source port for packets sent from the interface.

disable_tx ()

Disable Ethernet transmission.

enable_tx ()

Enable Ethernet transmission.

get_status ()

Get status and error flag dictionaries. See also: `status_reset`.

Status keys:

- `tx_of` : Count of TX buffer overflow events.
- `tx_full` : Count of TX buffer full events.
- `tx_vld` : Count of 64-bit words marked as valid for transmission.
- `tx_ctr`: Count of transmission End-of-Frames marked valid.

Returns (`status_dict`, `flags_dict`) tuple. *status_dict* is a dictionary of status key-value pairs. *flags_dict* is a dictionary with all, or a sub-set, of the keys in *status_dict*. The values held in this dictionary are as defined in *error_levels.py* and indicate that values in the status dictionary are outside normal ranges.

initialize (*read_only=False*)

Initialize the block. See also: `configure_source`, which sets transmission source attributes.

Parameters **read_only** (*bool*) – If False, reset error counters. If True, do nothing.

reset ()

Disable, then reset the 40 GbE core. It must be enabled with `enable_tx` before traffic will be transmitted.

status_reset ()

Reset all status counters.

2.3 etcd Interface

The `etcd` F-Engine interface provides a mechanism to control multiple SNAP2 boards running F-Engine firmware via the passing of messages through an `etcd` key-value store.

In order to use the `etcd` control interface, a daemon `Snap2FEngineEtcdClient` instance is required to be running on a server with network access to the SNAP2 hardware being controlled.

2.3.1 Key Organization

For an F-Engine running on a SNAP2 `hostname`, there are three relevant `etcd` key paths.

Command

The command key is:

```
/cmd/snap/<id>
```

`id` is the one-indexed ID number of the SNAP board which should respond to these commands. Commands issues to `id=0` are processed by all SNAP boards.

Writing messages to this key results in the execution of `Snap2FEngine` command methods.

Response

Each command written to the command key will elicit a response published to the key:

```
/resp/snap/<id>
```

The response message will indicate the success or failure of the command, and may contain a command-dependent data payload. For example, a spectra, or snapshot of ADC samples.

Monitor

In addition to the command/response interface described above, a set of basic status values are continuously-polled and written to `etcd`. This allows basic monitoring scripts to simply watch the `etcd` keystore to determine system health, rather than having to issue commands.

Each SNAP board reports monitor information to the key:

```
/mon/snap/<id>
```

The monitor key is intended to be continuously updated on a ~1 second time cadence, and contains low data-volume status information. For example, FPGA temperature, ADC RMS, number of transmitted Ethernet packets, and similar.

2.3.2 Command/Response Protocol

The Command/Response protocol is designed to be a simple interface to the underlying `Snap2FEngine` control class. It will naturally extend as the control class functionality is expanded.

A simple example of a control client is implemented in the `Snap2FEngineEtcdControl` class, which is used for internal testing.

Command Format

Commands sent to the command key are JSON-encoded dictionaries, and should have the following fields:

Field	Type	Description
id	string	A unique string associated with this command, used to identify the command's response
cmd	string	Command name
val	dictionary	A dictionary containing keys: <ul style="list-style-type: none">time (string) The time these statistics were gathered, in ISO 3339 format.block (string): The firmware block name to which this command applies.kwargs (dictionary): Dictionary of arguments required by the <code>block.command</code> method.

Allowed values for ``**block**`` are any of the keys in the `Snap2Fengine.blocks` attribute. I.e.:

```
from lwa_f import snap2_fengine
f = snap2_fengine.Snap2Fengine('snap2-rev2-11')
for block in sorted(f.blocks.keys()): print(block)
adc
autocorr
corr
delay
eq
eq_tvg
eth
input
noise
packetizer
pfb
reorder
sync
```

Allowed values for ``**cmd**`` are any of the methods which can be called against `Snap2Fengine.blocks[block]`. For example, for the `delay` block, allowed commands are:

- `get_max_delay`
- `set_delay`
- `get_delay`
- `initialize`
- `get_status`

All blocks are instances of the generic `Block` class, and thus it is also possible to call parent class methods such as `read_uint` and `write_uint`. These directly manipulate FPGA registers, and should be used with caution.

The ``**kwargs**`` field should contain any arguments required by the command method being called. For example, the `Fengine.delay` block's `set_delay` method requires a `stream` argument (to select which of the 64 SNAP2 data streams is being manipulated) and a `delay` argument (to set the delay for this stream).

As such, in order to set the delay of data stream 5 to 100 adc samples, a command should be issued with:

Field	Value
cmd	"set_delay"
val	{block: "delay", kwargs: {"stream": 5, "delay": 100}}

An example of a valid command JSON string, issued with the above parameters at UNIX time 1618060712.60 and with `id="1"` is:

```
'{"cmd": "set_delay", "val": {"block": "delay", "timestamp": 1618060712.6,
"kwargs": {"stream": 5, "delay": 100}}, "id": "1"}'
```

Consult the `Snap2Fengine` API details for a list of commands and their arguments.

Response Format

Every command sent elicits the writing of JSON-encoded dictionary to the response key. This dictionary has the following fields:

Field	Type	Description
<code>id</code>	string	A string matching the <code>id</code> field of the command string to which this is a response
<code>val</code>	dictionary	<p>A dictionary containing keys:</p> <ul style="list-style-type: none"> <code>timestamp</code> (float): The UNIX time when this response was issued. <code>status</code> (string): The string “normal” if the corresponding command was processed without error, or “error” if it was not. <code>response</code> (dictionary): The response of the command method, as determined by the command API. If a method would usually return a numpy array, when using the <code>etcd</code> interface the response will be a list. In the event that the status field is “error”, The response field will contain an error message string.

Not all `Snap2Fengine` methods return values, in which case the response field is `null`. The previous command example (setting a delay) results in the underlying API call `Snap2Fengine.blocks['delay'].set_delay(5, 100)` which returns `None`. The response to the example command (assuming processing the command took 0.2 milliseconds) is thus:

Field	Value
<code>id</code>	<code>"1"</code>
<code>val</code>	<code>{timestamp: 1618060712.8, status: "normal", response: null}</code>

or, in JSON-encoded form:

```
'{"id": "1", "val": {"timestamp": 1618060712.8, "status": "normal",
"response": null}}'
```

If the response status field is “error”, common response error messages, and their meanings are:

“JSON decode error”	Command string could not be JSON-decoded.
“Sequence ID not string”	Sequence ID was not provided in the command string or decoded to a non-string value.
“Bad command format”	Received command did not comply with formatting specifications. E.g. was missing a required field such as <code>block</code> or <code>cmd</code> .
“Command invalid”	Received command doesn’t exist in the <code>Snap2Engine</code> API, or is prohibited for <code>etcd</code> access.
“Wrong block”	<code>block</code> field of the command decoded to a block which doesn’t exist.
“Command arguments invalid”	<code>kwargs</code> key contained missing, or unexpected keys.
“Command failed”	The underlying <code>Snap2Engine</code> API call raised an exception.

In the event that a command fails, more information is available in the `Snap2EngineEtcdClient` daemon logs.

Monitoring Interface

The monitor key contains a nested dictionary with the following keys:

Field	Type	Description
timestamp	float	The UNIX timestamp at which the monitor key was last updated.
stats	dictionary	A nested dictionary containing status values, keyed first by block name (eg. <code>delay</code> , <code>eq</code> or <code>corr</code>) and then by status key.
flags	dictionary	A nested dictionary containing status values, keyed first by block name (eg. <code>delay</code> , <code>eq</code> or <code>corr</code>) and then by status key. This dictionary contains a subset of the keys present in the <code>stats</code> field. Where they exist, a value associated with a key indicates whether the corresponding value in the <code>stats</code> dictionary is out of normal range. Values in the <code>flags</code> dictionary are interpreted as in <code>error_levels.py</code> ; i.e.: <ul style="list-style-type: none"> • 0: Value is OK • 1: Value is different from operational normal • 2: Value is outside expected range • 3: Value represents an error condition

Entries in the `stats` dictionary are shown below

Dictionary Key	Dictionary sub-key	type	Description
autocorr	acc_len	int	Accumulation length, in spectra, of the internal autocorrelation module.
corr	acc_len	int	Accumulation length, in spectra, of the internal correlation module.
delay	delay``n``	int	Delay of each of the <code>n</code> data streams.
delay	maxdelay	int	The maximum delay supported by the firmware.
eq	binary_point	int	The position of the EQ coefficient binary point
eq	width	int	The bit width of the EQ coefficients

continues on next page

Table 2.1 – continued from previous page

Dictionary Key	Dictionary sub-key	type	Description
eq	clip_count	int	The number of clips when requantizing spectra to 4-bit. This counter resets every [TODO: when??]
eq	coefficients``n``	list (int)	The currently loaded coefficients, in integer form (i.e., interpreted with all bits above the binary point)
eq_tvg	tv_g_enabled	bool	True if the post- FFT test vector generator is enabled. False otherwise.
eth	tx_ctr	int	Running count of number of packets transmitted.
eth	tx_err	int	Running count of number of packet errors detected.
eth	tx_full	int	Running count of number of transmission buffer overflow events.
eth	tx_vld	int	Running count of number of 256-bit words transmitted.
feng	flash_firmware	string	The current .fpg bitstream file stored in flash memory
feng	flash_firmware_md5	int	The MD5 checksum of the .fpg bitstream stored in flash
feng	host	string	The hostname of the SNAP2 board
feng	programmed	bool	True if the board appears to be running DSP firmware. False otherwise.
feng	serial	string	A notional “serial number” of this hardware. Not yet implemented.
feng	sw_version	string	The software version of the lwa_f python library currently in use
feng	sys_mon	string	“reporting” if the current firmware has a working system monitor module. “not reporting” if no monitoring is available.
feng	temp	float	FPGA junction temperature, in degrees C, reported by system monitor (if available)
feng	vccaux	float	Voltage of the VCCAUX FPGA power rail reported by system monitor (if available)
feng	vccbram	float	Voltage of the VCCBRAM FPGA power rail reported by system monitor (if available)
feng	vccint	float	Voltage of the VCCINT FPGA power rail reported by system monitor (if available)
input	mean``n``	float	Mean of ADC sample values for input ADC <i>n</i> .
input	rms``n``	float	RMS of ADC sample values for input ADC <i>n</i> .
input	power``n``	float	Mean of squares of ADC sample values for input ADC <i>n</i> .
input	switch_position``n``	string	Switch position for input data stream <i>n</i> . <i>noise</i> for internal noise generators, <i>adc</i> for analog inputs, <i>zero</i> for zero.
noise	noise_core00_seed	int	Seed value for internal noise generator 0.

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Table 2.1 – continued from previous page

Dictionary Key	Dictionary sub-key	type	Description
noise	noise_core01_seed	int	Seed value for internal noise generator 1.
noise	noise_core02_seed	int	Seed value for internal noise generator 2.
noise	output_assignment`n`	int	Noise source (0 - 5) currently assigned to data stream n.
pfb	fft_shift	int	Currently loaded FFT shift schedule.
pfb	overflow_count	int	Running count of FFT overflow events.
sync	ext_count	int	Running count of number of external sync pulses received since FPGA was programmed.
sync	int_count	int	Running count of number of internal sync pulses received since FPGA was programmed.
sync	period_fpga_clks	int	Detected period of external sync pulses in units of FPGA clock cycles.
sync	uptime_fpga_clks	int	Number of FPGA clock ticks since the FPGA was last programmed

F-ENGINE REGISTER DEFINITIONS

F-Engine firmware is designed to be manipulated using the provided `Snap2FEngine` class, or its higher level `etcd`-based control interface.

However, individual F-engine registers and their purposes are described below.

3.1 Register Descriptions

Register Name	Size (Bytes)	Permission	Description
ADC Registers			
<code>ads5296_controller_<i>_<j></code>	128	r/w	ADS5296 board control register for the <i>j</i> th ADC card in FMC <i>i</i> . Should be manipulated using the <code>ADS5296</code> class of the <code>casperfpga</code> python library.
<code>ads5296_spi_controller<i></code>	16	r/w	ADS5296 SPI controller register for ADC cards on FMC slot <i>i</i> . Should be manipulated using the <code>ADS5296</code> class of the <code>casperfpga</code> python library.
<code>ads5296_wb_ram<i>_<j>_<k></code>	4096	r/w	ADC snapshot RAM for ADC chip <i>k</i> on board <i>j</i> of FMC port <i>i</i> . Should be manipulated using the <code>ADS5296</code> class of the <code>casperfpga</code> python library.
<code>adc_rst</code>	4	r/w	Set to 1 to assert the ADC reset. This flushes the ADC output FIFOs. Data will not begin flowing again until the ADC <code>sync</code> input transitions from 0 to 1.
<code>adc_snapshot_trigger</code>	4	r/w	When this register transitions from 0 to 1, all ADC channels will simultaneously capture a burst of ADC samples.
<code>adc_sync</code>	4	r/w	Write 1 to this register to assert the ADC's <code>sync</code> input. This input is edge sensitive.
Auto-Correlator Registers			
<code>autocorr_acc_cnt</code>	4	r	32-bit wrapping accumulation counter, which increments each time a new accumulation is recorded to RAM. There is no buffer locking when correlation data are read, so this counter can be used to ensure that data have not changed during a read.
<code>autocorr_acc_len</code>	4	r/w	Accumulation length, in spectra.

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Table 3.1 – continued from previous page

Register Name	Size (Bytes)	Permission	Description
autocorr_common_dout0_bram	262144	r/w	For memory name suffix <n>_bram, stores the autocorrelation powers for frequency channels $8n$ of 16 consecutive F-engine inputs. Data are stored in [input_number, freq_channel] order.
autocorr_common_dout1_bram	262144	r/w	For memory name suffix <n>_bram, stores the autocorrelation powers for frequency channels $8n$ of 16 consecutive F-engine inputs. Data are stored in [input_number, freq_channel] order.
autocorr_common_dout2_bram	262144	r/w	For memory name suffix <n>_bram, stores the autocorrelation powers for frequency channels $8n$ of 16 consecutive F-engine inputs. Data are stored in [input_number, freq_channel] order.
autocorr_common_dout3_bram	262144	r/w	For memory name suffix <n>_bram, stores the autocorrelation powers for frequency channels $8n$ of 16 consecutive F-engine inputs. Data are stored in [input_number, freq_channel] order.
autocorr_common_dout4_bram	262144	r/w	For memory name suffix <n>_bram, stores the autocorrelation powers for frequency channels $8n$ of 16 consecutive F-engine inputs. Data are stored in [input_number, freq_channel] order.
autocorr_common_dout5_bram	262144	r/w	For memory name suffix <n>_bram, stores the autocorrelation powers for frequency channels $8n$ of 16 consecutive F-engine inputs. Data are stored in [input_number, freq_channel] order.
autocorr_common_dout6_bram	262144	r/w	For memory name suffix <n>_bram, stores the autocorrelation powers for frequency channels $8n$ of 16 consecutive F-engine inputs. Data are stored in [input_number, freq_channel] order.
autocorr_common_dout7_bram	262144	r/w	For memory name suffix <n>_bram, stores the autocorrelation powers for frequency channels $8n$ of 16 consecutive F-engine inputs. Data are stored in [input_number, freq_channel] order.
autocorr_mux_sel	4	r/w	Input selection controller. Set bits [1:0] to n to compute the autocorrelations of F-engine inputs $16n..16(n+1)-1$.
Channel Reorder Registers			
chan_reorder_dynamic_map1	16384	r/w	Determines the remapping of input samples to output samples. I.e., if the first entry is 5, then the first sample into the reorder will come out 5th
Correlation Registers			
corr_0_acc_cnt	4	r	32-bit wrapping accumulation counter, which increments each time a new accumulation is recorded to RAM. There is no buffer locking when correlation data are read, so this counter can be used to ensure that data have not changed during a read.

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Table 3.1 – continued from previous page

Register Name	Size (Bytes)	Permission	Description
corr_0_acc_len	4	r/w	Accumulation length, in FPGA clock cycles. To specify an accumulation length as a number of spectra this register should be written with $\text{number_of_spectra} \times \text{frequency_channels_per_spectra}$. Here the number of frequency channels per spectra is the number <i>output</i> by the correlation subsystem. Glitches may occur (resulting in the no new accumulations for a few seconds) if the value in this register is reduced without re-applying a sync to the correlation module.
corr_0_dout	32768	r/w	Correlation data buffer. Word $[2n]$ is the real part of the correlation of frequency channel n (after any channel averaging). Word $[2n+1]$ is the imaginary part of this correlation.
corr_0_input_sel	4	r/w	Input selector control register. Bits $[5:0]$ select the unconjugated correlation input. Bits $[13:8]$ select the conjugated correlation input.
Delay Registers			
delay_<n>_delay	4	r/w	The delay applied to stream n . Any value entered in this 32-bit register will be interpreted modulo the maximum supported delay.
delay_max_delay	4	r	Interpretted as a uint32 value, contains the maximum allowed delay, in ADC samples, which may be applied to a data stream.
Equalization Registers			
eq_core<n>_clip_cnt	4	r	A count of the number of times a sample has been clipped, for any of F-engine inputs $16n \dots 16(n+1) - 1$. This counter is reset only by a global system reset.
eq_core<n>_coeffs	131072	r/w	This memory holds coefficients for F-engine streams $16n \dots 16(n+1) - 1$. Coefficients are stored as a $[16, \text{n_fft_channels} / 8]$ array, where the first axis (over input number) varies <i>slowest</i> . Coefficients are shared over 8 consecutive frequency channels, with coefficient m being applied to frequency channel $m \dots 8(m+1) - 1$. Coefficients are interpreted with 5 bits below the binary point.
40GbE Registers			
eth_ctrl	4	r/w	40GbE control register. Bit 0 is an active high reset of the 40GbE interface core. Bit 1 is an active high transmission enable for the core, which takes effect either after the next packet is sent, or when the <i>force</i> flag is asserted. Bit 18 is an active high reset for statistics provided by the Ethernet core. Bit 19 is an active high <i>force</i> signal, which causes the current transmission enable flag to immediately take effect.
eth_forty_gbe_txctr	4	r	Counter which increments each time a valid end-of-frame is seen on a packet to be transmitted

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Table 3.1 – continued from previous page

Register Name	Size (Bytes)	Permission	Description
eth_forty_gbe_txfullctr	4	r	Counter which increments every time the transmission buffer is full
eth_forty_gbe_txofctr	4	r	Counter which increments on every transmission overflow event
eth_forty_gbe_txvldctr	4	r	Counter which increments with every valid word of data input to the core
Input Control Registers			
input_bit_stats_histogram_output	32768	r/w	BRAM storing histogram data. Word n in the bottom half of the RAM stores the number of occurrences of ADC sample code n in <code>_even_</code> numbered ADC samples. Word n in the <code>_top_</code> half of the RAM stores the number of occurrences of ADC sample code n in <code>_odd_</code> numbered ADC samples.
input_bit_stats_input_sel	4	r/w	Input selection. The least significant 6 bits should be set to n to compute the histogram for input n .
input_rms_enable	4	r/w	Enable statistics recording. If the least-significant bit is 1, statistics will be recorded to RAM.
input_rms_levels	32768	r/w	Multi-channel statistics. For the n th 64-bit word, the least significant 32 bits represent the accumulated ADC power, accumulated over 65536 samples and stored as an unsigned 32-bit integer. The most significant 32 bits represent the sum of 65536 ADC samples stored as a signed 32-bit integer.
input_source_sel0	4	r/w	Selector control to determine if signal streams carry ADC samples, digital noise samples, or zeros. Streams $n=0..15$ is controlled by register bits $[2n+1:2n]$. Value 0 selects noise; 1 selects ADC; 2 selects zeros.
input_source_sel1	4	r/w	Selector control to determine if signal streams carry ADC samples, digital noise samples, or zeros. Streams $n=16..31$ is controlled by register bits $[2(n-16)+1:2(n-16)]$. Value 0 selects noise; 1 selects ADC; 2 selects zeros.
input_source_sel2	4	r/w	Selector control to determine if signal streams carry ADC samples, digital noise samples, or zeros. Streams $n=32..47$ is controlled by register bits $[2(n-32)+1:2(n-32)]$. Value 0 selects noise; 1 selects ADC; 2 selects zeros.
input_source_sel3	4	r/w	Selector control to determine if signal streams carry ADC samples, digital noise samples, or zeros. Streams $n=48..63$ is controlled by register bits $[2(n-48)+1:2(n-48)]$. Value 0 selects noise; 1 selects ADC; 2 selects zeros.
Noise Generator Registers			
noise_octal_mux0_sel	4	r/w	The lower 2 bits define the select signal for the noise multiplexor. If this register has value v , then noise generator v is selected.

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Table 3.1 – continued from previous page

Register Name	Size (Bytes)	Permission	Description
noise_octal_mux1_sel	4	r/w	The lower 2 bits define the select signal for the noise multiplexor. If this register has value v , then noise generator v is selected.
noise_octal_mux2_sel	4	r/w	The lower 2 bits define the select signal for the noise multiplexor. If this register has value v , then noise generator v is selected.
noise_octal_mux3_sel	4	r/w	The lower 2 bits define the select signal for the noise multiplexor. If this register has value v , then noise generator v is selected.
noise_octal_mux4_sel	4	r/w	The lower 2 bits define the select signal for the noise multiplexor. If this register has value v , then noise generator v is selected.
noise_octal_mux5_sel	4	r/w	The lower 2 bits define the select signal for the noise multiplexor. If this register has value v , then noise generator v is selected.
noise_octal_mux6_sel	4	r/w	The lower 2 bits define the select signal for the noise multiplexor. If this register has value v , then noise generator v is selected.
noise_octal_mux7_sel	4	r/w	The lower 2 bits define the select signal for the noise multiplexor. If this register has value v , then noise generator v is selected.
noise_seeds0	4	r/w	Noise generator seed values. If the 32-bit value in this register is v , the seed for the first noise generator is (using Verilog syntax) $\{8'h5c, v[7:0], v[0:7], 8'ha3\}$. The seed for the second noise generator is $\{8'h5c, v[15:8], v[8:15], 8'ha3\}$. The seed for the third noise generator is $\{8'h5c, v[23:16], v[16:23], 8'ha3\}$. The seed for the fourth noise generator is $\{8'h5c, v[31:24], v[24:31], 8'ha3\}$.
Packetizer Registers			
packetizer_ants	262144	r/w	Antenna header entry map. Word n contains the header antenna ID field for sample n in a transmission period. This field is only relevant for samples accompanied by valid and header flags.
packetizer_chans	262144	r/w	Channel ID header entry map. Bits [23:0] of word n contain the header channel ID field for sample n in a transmission period. This header field should hold the index of the first channel in a packet. Bits [31:24] contain the header channel block index field for this sample. These field is only relevant for samples accompanied by valid and header flags.
packetizer_flags	262144	r/w	Packet flags. For word n , bit 0 is an active high flag which indicates that sample n in a transmission period is a packet header. Bit 8 is an active high flag which indicates that this word is valid and should be transmitted. Bit 16 is an active high flag indicating that this word is the last in a packet.

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Register Name	Size (Bytes)	Permission	Description
packetizer_ips	262144	r/w	IP Destination address map. Word n contains the IP address to which sample n in a transmission period should be sent. Only entries accompanied by <code>valid</code> and <code>end of frame</code> flags result in a packet's destination being set from this register.
packetizer_n_chans	4	r/w	32-bit <code>n_chans</code> header field for F-engine output data packets, indicating the number of frequency channels per packet.
packetizer_n_pols	4	r/w	32-bit <code>n_pols</code> header field for F-engine output data packets, indicating the number of antenna-polarizations present in a packet.
packetizer_ports	262144	r/w	UDP Destination port map. For word n , bits $[15:0]$ contain the UDP port to which sample n in a transmission period should be sent. Only samples accompanied by <code>valid</code> and <code>end of frame</code> flags result in a packet's destination being set from this register.
PFB Registers			
pfb_ctrl	4	r/w	PFB control register. Bit 18 is an active-high reset for overflow statistics counters. Bits $15:0$ hold the FFT shift schedule for the PFB processing pipeline, with bit n an active high shift signal for the n th FFT stage.
pfb_pfb16x_<n>_status	4	r	A 32-bit counter which, for register name suffix <code><n>_status</code> increments every time an FFT overflow event is detected in any of FFT channels $16n \dots 16(n+1) - 1$. Resets only when commanded via the PFB control register, and will wrap once the maximum value is reached.
Post-EQ Test Vector Generator Registers			
post_eq_tvg_core<n>_tv	524288	r/w	This memory holds 4+4 bit complex test vector streams for F-engine streams $16n \dots 16(n+1) - 1$. Test vectors are stored as a $[16, n_fft_channels]$ array, where the first axis (over input number) varies <i>slowest</i> , and vectors are stored in order of increasing FFT channel. An 8-bit word in location $[m, c]$ is interpreted as a 4+4 bit complex value for channel c of F-engine stream $16n + m$. The most significant 4 bits are interpreted as the real part of the complex value.
post_eq_tvg_tvg_en	4	r/w	Test vector multiplexor control. If the least significant bit is 1, ADC data will be replaced with software-controllable test vectors.
Synchronization Registers			

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Table 3.1 – continued from previous page

Register Name	Size (Bytes)	Permission	Description
sync_ctrl	4	r/w	Timing control register. Bit 0: active high enable allowing telescope time counter to be loaded from telescope time load registers on next synchronization pulse. Bit 1: When transitioned from 0 to 1, forces telescope time counter to be loaded from telescope time load registers immediately. Bit 2: active high telescope time counter reset. Bit 3: active high reset for error counters. Bit 4: active high arm signal, which causes a global system reset, released on the next synchronization pulse; a system sync on the next synchronization pulse. Bit 5: When transitioned from 0 to 1, emulates the arrival of an external sync pulse. Bit 6: When transitioned from 0 to 1, arms noise generator seed loaders.
sync_ext_sync_count	4	r	Number of external synchronization pulses received.
sync_ext_sync_period	4	r	Measured number of FPGA clock ticks between previous two external synchronization pulses.
sync_ext_sync_tt_lsb	4	r	Least significant 32 bits of the telescope time counter, at the point of the last external synchronization pulse.
sync_ext_sync_tt_msb	4	r	Most significant 32 bits of the telescope time counter, at the point of the last external synchronization pulse.
sync_int_sync_count	4	r	Number of synchronization pulses emitted via GPIO.
sync_latency	4	r	Measured latency, in FPGA clock ticks, between transmitting a synchronization pulse and receiving it from the timing distribution system.
sync_sync_div_bits	4	r	Holds the log2 value of the sync period – i.e. the rate at which sync pulses are emitted from the board via GPIO – in FPGA clock ticks.
sync_tt_load_lsb	4	r/w	Telescope time load register. Least significant 32 bits to load to the telescope time counter.
sync_tt_load_msb	4	r/w	Telescope time load register. Most significant 32 bits to load to the telescope time counter.
sync_tt_lsb	4	r	Least significant 32 bits of the telescope time counter.
sync_tt_msb	4	r	Most significant 32 bits of the telescope time counter.
sync_uptime_msb	4	r	Board uptime, in units of 2^{32} FPGA clock ticks.
Version Registers			
version_timestamp	4	r	Unix timestamp, in integer seconds, when firmware was last compiled.
version_version	4	r	Version register. Bits [31:24]: major version. Bits [23:16]: minor version. Bits [15:8]: revision. Bits [7:0]: buxfix.

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