

Inference on the Champagne Model using a Gaussian Process

TODO

- Set seed for LHC and stuff
- Change to log discrepancy with custom observation variance
- Change from MLE to cross validation

Setting up the Champagne Model

Imports

```
import pandas as pd
import numpy as np
from typing import Any
import matplotlib.pyplot as plt

from scipy.stats import qmc

import tensorflow as tf
import tensorflow_probability as tfp
tfb = tfp.bijectors
tfd = tfp.distributions
tfk = tfp.math.psd_kernels
```

```
2024-03-07 15:00:31.772942: I external/local_tsl/tsl/cuda/cudart_stub.cc:31] Could not find c
2024-03-07 15:00:31.817782: E external/local_xla/xla/stream_executor/cuda/cuda_dnn.cc:9261] U
2024-03-07 15:00:31.817812: E external/local_xla/xla/stream_executor/cuda/cuda_fft.cc:607] U
```

2024-03-07 15:00:31.819023: E external/local_xla/xla/stream_executor/cuda/cuda_blas.cc:1515]
2024-03-07 15:00:31.825973: I external/local_tsl/tsl/cuda/cudart_stub.cc:31] Could not find c
2024-03-07 15:00:31.827133: I tensorflow/core/platform/cpu_feature_guard.cc:182] This Tensor
To enable the following instructions: AVX2 FMA, in other operations, rebuild TensorFlow with
2024-03-07 15:00:33.162043: W tensorflow/compiler/tf2tensorrt/utils/py_utils.cc:38] TF-TRT W

Model itself

```
np.random.seed(590154)

population = 1000
initial_infecteds = 10
epidemic_length = 1000
number_of_events=15000

pv_champ_alpha = 0.4 # prop of effective care
pv_champ_beta = 0.4 # prop of radical cure
pv_champ_gamma_L = 1 / 223 # liver stage clearance rate
pv_champ_delta = 0.05 # prop of imported cases
pv_champ_lambda = 0.04 # transmission rate
pv_champ_f = 1 / 72 # relapse frequency
pv_champ_r = 1 / 60 # blood stage clearance rate

def champagne_stochastic(
    alpha_,
    beta_,
    gamma_L,
    lambda_,
    f,
    r,
    N=population,
    I_L=initial_infecteds,
    I_0=0,
    S_L=0,
    delta_=0,
    end_time=epidemic_length,
    num_events=number_of_events
):
    if (0 > (alpha_ or beta_)) or (1 < (alpha_ or beta_)):
        return "Alpha or Beta out of bounds"
```

```

if (0 > (gamma_L or lambda_ or f or r)):
    return "Gamma, lambda, f or r out of bounds"

t = 0
S_0 = N - I_L - I_0 - S_L
list_of_outcomes = [{"t": 0, "S_0": S_0, "S_L": S_L, "I_0": I_0, "I_L": I_L}]

for i in range(num_events):
    if S_0 == N:
        break

    S_0_to_I_L = (1 - alpha_) * lambda_ * (I_L + I_0) / N * S_0
    S_0_to_S_L = alpha_ * (1 - beta_) * lambda_ * (I_0 + I_L) / N * S_0
    I_0_to_S_0 = r * I_0 / N
    I_0_to_I_L = lambda_ * (I_L + I_0) / N * I_0
    I_L_to_I_0 = gamma_L * I_L
    I_L_to_S_L = r * I_L
    S_L_to_S_0 = (gamma_L + (f + lambda_ * (I_0 + I_L) / N) * alpha_ * beta_) * S_L
    S_L_to_I_L = (f + lambda_ * (I_0 + I_L) / N) * (1 - alpha_) * S_L

    total_rate = (
        S_0_to_I_L
        + S_0_to_S_L
        + I_0_to_S_0
        + I_0_to_I_L
        + I_L_to_I_0
        + I_L_to_S_L
        + S_L_to_S_0
        + S_L_to_I_L
    )

    t += np.random.exponential(1 / total_rate)
    new_stages_prob = [
        S_0_to_I_L / total_rate,
        S_0_to_S_L / total_rate,
        I_0_to_S_0 / total_rate,
        I_0_to_I_L / total_rate,
        I_L_to_I_0 / total_rate,
        I_L_to_S_L / total_rate,
        S_L_to_S_0 / total_rate,
        S_L_to_I_L / total_rate,
    ]

```

```

new_stages = np.random.choice(
    [
        {"t": t, "S_0": S_0 - 1, "S_L": S_L, "I_0": I_0, "I_L": I_L + 1},
        {"t": t, "S_0": S_0 - 1, "S_L": S_L + 1, "I_0": I_0, "I_L": I_L},
        {"t": t, "S_0": S_0 + 1, "S_L": S_L, "I_0": I_0 - 1, "I_L": I_L},
        {"t": t, "S_0": S_0, "S_L": S_L, "I_0": I_0 - 1, "I_L": I_L + 1},
        {"t": t, "S_0": S_0, "S_L": S_L, "I_0": I_0 + 1, "I_L": I_L - 1},
        {"t": t, "S_0": S_0, "S_L": S_L + 1, "I_0": I_0, "I_L": I_L - 1},
        {"t": t, "S_0": S_0 + 1, "S_L": S_L - 1, "I_0": I_0, "I_L": I_L},
        {"t": t, "S_0": S_0, "S_L": S_L - 1, "I_0": I_0, "I_L": I_L + 1},
    ],
    p=new_stages_prob,
)

list_of_outcomes.append(new_stages)

S_0 = new_stages["S_0"]
I_0 = new_stages["I_0"]
I_L = new_stages["I_L"]
S_L = new_stages["S_L"]

outcome_df = pd.DataFrame(list_of_outcomes)
return outcome_df

champ_samp = champagne_stochastic(
    pv_champ_alpha,
    pv_champ_beta,
    pv_champ_gamma_L,
    pv_champ_lambda,
    pv_champ_f,
    pv_champ_r,
) # .melt(id_vars='t')

```

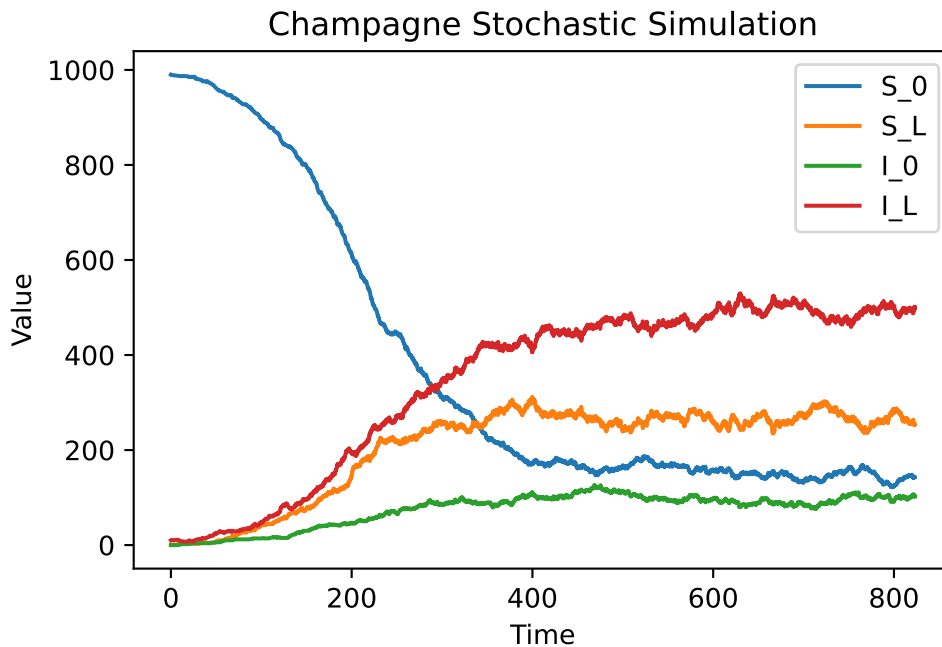
Plotting outcome

```

champ_samp.plot(x = 't', legend=True)
plt.xlabel('Time')
plt.ylabel('Value')

```

```
plt.title('Champagne Stochastic Simulation')
plt.show()
```



Function that Outputs Final Prevalence

```
def champ_prevalence(alpha_, beta_, gamma_L, lambda_, f, r):
    champ_df_ = champagne_stochastic(alpha_, beta_, gamma_L, lambda_, f, r)

    return(champ_df_.iloc[-1]["I_0"] + champ_df_.iloc[-1]["I_L"])

observed_final_prevalence = champ_prevalence(pv_champ_alpha, pv_champ_beta,
pv_champ_gamma_L, pv_champ_lambda, pv_champ_f, pv_champ_r)

def discrepancy_fn(alpha_, beta_, gamma_L, lambda_, f, r):
    x = champ_prevalence(alpha_, beta_, gamma_L, lambda_, f, r)
    return(np.abs(x - observed_final_prevalence))
```

Gaussian Process Regression on Final Prevalence Discrepancy

```
my_seed = np.random.default_rng(seed=1795) # For replicability

num_samples = 50

variables_names = ["alpha", "beta", "gamma_L", "lambda", "f", "r"]

pv_champ_alpha = 0.4 # prop of effective care
pv_champ_beta = 0.4 # prop of radical cure
pv_champ_gamma_L = 1 / 223 # liver stage clearance rate
pv_champ_lambda = 0.04 # transmission rate
pv_champ_f = 1 / 72 # relapse frequency
pv_champ_r = 1 / 60 # blood stage clearance rate

samples = np.concatenate(
    (
        my_seed.uniform(low=0, high=1, size=(num_samples, 1)), # alpha
        my_seed.uniform(low=0, high=1, size=(num_samples, 1)), # beta
        my_seed.exponential(scale=pv_champ_gamma_L, size=(num_samples, 1)), # gamma_L
        my_seed.exponential(scale=pv_champ_lambda, size=(num_samples, 1)), # lambda
        my_seed.exponential(scale=pv_champ_f, size=(num_samples, 1)), # f
        my_seed.exponential(scale=pv_champ_r, size=(num_samples, 1)), # r
    ),
    axis=1,
)

LHC_sampler = qmc.LatinHypercube(d = 6, seed = my_seed)
LHC_samples = LHC_sampler.random(n = num_samples)
LHC_samples[:,2] = -pv_champ_gamma_L*np.log(LHC_samples[:,2])
LHC_samples[:,3] = -pv_champ_lambda*np.log(LHC_samples[:,3])
LHC_samples[:,4] = -pv_champ_f*np.log(LHC_samples[:,4])
LHC_samples[:,5] = -pv_champ_r*np.log(LHC_samples[:,5])

random_indices_df = pd.DataFrame(samples, columns=variables_names)
LHC_indices_df = pd.DataFrame(LHC_samples, columns=variables_names)

print(random_indices_df.head())
print(LHC_indices_df.head())
```

	alpha	beta	gamma_L	lambda	f	r
0	0.201552	0.246202	0.013085	0.051287	0.011657	0.004164
1	0.332324	0.812946	0.000390	0.006251	0.047737	0.018725
2	0.836050	0.343292	0.004725	0.020082	0.004604	0.007983
3	0.566773	0.075311	0.002784	0.007547	0.020959	0.022937
4	0.880603	0.964663	0.004194	0.008378	0.012502	0.009120

	alpha	beta	gamma_L	lambda	f	r
0	0.100008	0.122349	0.005550	0.047169	0.015049	0.023833
1	0.659225	0.590955	0.015422	0.009993	0.026474	0.050003
2	0.503558	0.005003	0.000207	0.024569	0.044514	0.020288
3	0.011840	0.630562	0.001543	0.016033	0.004709	0.010679
4	0.271011	0.942434	0.003873	0.020250	0.006580	0.004226

Generate Discrepancies

```
random_discrepancies = LHC_indices_df.apply(
    lambda x: discrepancy_fn(
        x["alpha"], x["beta"], x["gamma_L"], x["lambda"], x["f"], x["r"]
    ),
    axis=1,
)

print(random_discrepancies.head())
```

```
0    104.0
1    449.0
2     12.0
3      8.0
4    208.0
dtype: float64
```

Differing Methods to Iterate Function

```
# import timeit

# def function1():
#     np.vectorize(champ_prevalence)(random_indices_df['alpha'],
#     random_indices_df['beta'], random_indices_df['gamma_L'],
```

```

#     random_indices_df['lambda'], random_indices_df['f'], random_indices_df['r'])
#     pass

# def function2():
#     random_indices_df.apply(
#         lambda x: champ_prevalence(
#             x['alpha'], x['beta'], x['gamma_L'], x['lambda'], x['f'], x['r']),
#             axis = 1)
#     pass

# # Time function1
# time_taken_function1 = timeit.timeit(
#     "function1()", globals=globals(), number=100)

# # Time function2
# time_taken_function2 = timeit.timeit(
#     "function2()", globals=globals(), number=100)

# print("Time taken for function1:", time_taken_function1)
# print("Time taken for function2:", time_taken_function2)

```

Time taken for function1: 187.48960775700016 Time taken for function2: 204.06618941299985

Constrain Variables to be Positive

```

constrain_positive = tfb.Shift(np.finfo(np.float64).tiny)(tfb.Exp())

```

Custom Quadratic Mean Function

```

class quad_mean_fn(tf.Module):
    def __init__(self):
        super(quad_mean_fn, self).__init__()
        self.amp_alpha_mean = tfp.util.TransformedVariable(
            bijector=constrain_positive,
            initial_value=400.0,
            dtype=np.float64,
            name="amp_alpha_mean",
        )

```



```

self.alpha_tp = tf.Variable(pv_champ_alpha, dtype=np.float64, name="alpha_tp")
self.amp_beta_mean = tfp.util.TransformedVariable(
    bijector=constrain_positive,
    initial_value=50.0,
    dtype=np.float64,
    name="amp_beta_mean",
)
self.beta_tp = tf.Variable(pv_champ_beta, dtype=np.float64, name="beta_tp")
self.amp_gamma_L_mean = tfp.util.TransformedVariable(
    bijector=constrain_positive,
    initial_value=500.0,
    dtype=np.float64,
    name="amp_gamma_L_mean",
)
self.gamma_L_tp = tf.Variable(
    pv_champ_gamma_L, dtype=np.float64, name="gamma_L_tp"
)
self.amp_lambda_mean = tfp.util.TransformedVariable(
    bijector=constrain_positive,
    initial_value=16000.0,
    dtype=np.float64,
    name="amp_lambda_mean",
)
self.lambda_tp = tf.Variable(
    pv_champ_lambda, dtype=np.float64, name="lambda_tp"
)
self.amp_f_mean = tfp.util.TransformedVariable(
    bijector=constrain_positive,
    initial_value=15000.0,
    dtype=np.float64,
    name="amp_f_mean",
)
self.f_tp = tf.Variable(pv_champ_f, dtype=np.float64, name="f_tp")
self.amp_r_mean = tfp.util.TransformedVariable(
    bijector=constrain_positive,
    initial_value=13000.0,
    dtype=np.float64,
    name="amp_r_mean",
)
self.r_tp = tf.Variable(pv_champ_r, dtype=np.float64, name="r_tp")
self.bias_mean = tfp.util.TransformedVariable(
    bijector=constrain_positive,

```

```

        initial_value=50.0,
        dtype=np.float64,
        name="bias_mean",
    )

def __call__(self, x):
    return (
        self.amp_alpha_mean * (x[..., 0] - self.alpha_tp) ** 2
        + self.amp_beta_mean * (x[..., 1] - self.beta_tp) ** 2
        + self.amp_gamma_L_mean * (x[..., 2] - self.gamma_L_tp) ** 2
        + self.amp_lambda_mean * (x[..., 3] - self.lambda_tp) ** 2
        + self.amp_f_mean * (x[..., 4] - self.f_tp) ** 2
        + self.amp_r_mean * (x[..., 5] - self.r_tp) ** 2
        + self.bias_mean
    )

```

Making the ARD Kernel

```

index_vals = LHC_indices_df.values
obs_vals = random_discrepancies.values

amplitude_champ = tfp.util.TransformedVariable(
    bijector=constrain_positive,
    initial_value=150.0,
    dtype=np.float64,
    name="amplitude_champ",
)

observation_noise_variance_champ = tfp.util.TransformedVariable(
    bijector=constrain_positive,
    initial_value=1000.0,
    dtype=np.float64,
    name="observation_noise_variance_champ",
)

length_scales_champ = tfp.util.TransformedVariable(
    bijector=constrain_positive,
    initial_value=[0.01, 0.01, 0.35, 0.02, 0.27, 0.2],
    dtype=np.float64,

```

```

    name="length_scales_champ",
)

```

```

kernel_champ = tfk.FeatureScaled(tfk.ExponentiatedQuadratic(
    amplitude=amplitude_champ), scale_diag=length_scales_champ)

```

Define the Gaussian Process with Quadratic Mean Function and ARD Kernel

```

# Define Gaussian Process with the custom kernel
champ_GP = tfd.GaussianProcess(
    kernel=kernel_champ,
    observation_noise_variance=observation_noise_variance_champ,
    index_points=index_vals,
    mean_fn=quad_mean_fn(),
)

print(champ_GP.trainable_variables)

Adam_optim = tf.optimizers.Adam(learning_rate=.01)

```

```

(<tf.Variable 'amplitude_champ:0' shape=() dtype=float64, numpy=5.0106352940962555>, <tf.Variable 'length_scales_champ:0' shape=(5) dtype=float64, numpy=
array([-4.60517019, -4.60517019, -1.04982212, -3.91202301, -1.30933332,
       -1.60943791])>, <tf.Variable 'observation_noise_variance_champ:0' shape=() dtype=float64, numpy=0.001>)

```

Train the Hyperparameters

```

@tf.function()
def optimize():
    with tf.GradientTape() as tape:
        loss = -champ_GP.log_prob(obs_vals)
        grads = tape.gradient(loss, champ_GP.trainable_variables)
        Adam_optim.apply_gradients(zip(grads, champ_GP.trainable_variables))
    return loss

num_iters = 1000

lls_ = np.zeros(num_iters, np.float64)
for i in range(num_iters):

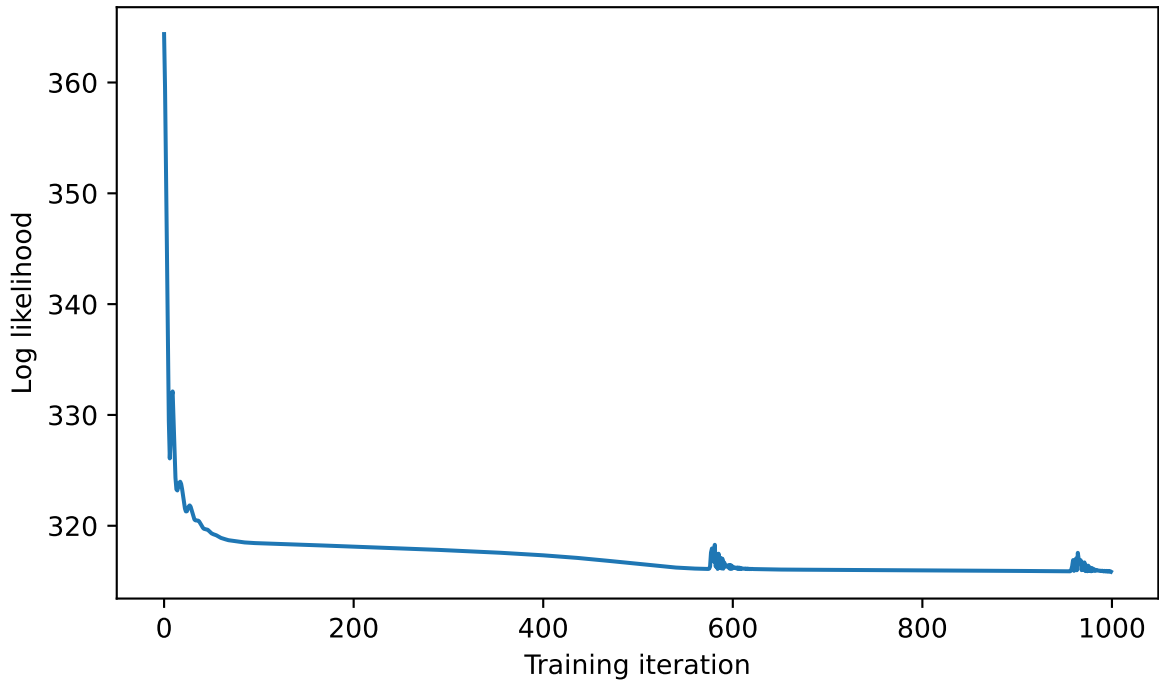
```

```
loss = optimize()
lls_[i] = loss
```

```
print("Trained parameters:")
for var in champ_GP.trainable_variables:
    if "tp" in var.name:
        print("{} is {}".format(var.name, var.numpy().round(3)))
    else:
        print(
            "{} is {}".format(
                var.name, constrain_positive.forward(var).numpy().round(3)
            )
        )
```

```
Trained parameters:
amplitude_champ:0 is 131.251
length_scales_champ:0 is [3.300e-02 1.800e-02 7.440e-01 1.000e-03 1.666e+00 1.255e+00]
observation_noise_variance_champ:0 is 725.188
alpha_tp:0 is 0.207
amp_alpha_mean:0 is 559.783
amp_beta_mean:0 is 34.832
amp_f_mean:0 is 180505.591
amp_gamma_L_mean:0 is 23745.742
amp_lambda_mean:0 is 11231.614
amp_r_mean:0 is 52402.464
beta_tp:0 is -0.462
bias_mean:0 is 24.339
f_tp:0 is 0.029
gamma_L_tp:0 is 0.034
lambda_tp:0 is 0.068
r_tp:0 is 0.004
```

```
plt.figure(figsize=(7, 4))
plt.plot(lls_)
plt.xlabel("Training iteration")
plt.ylabel("Log likelihood")
plt.show()
```



Fitting the GP Regression across alpha

```

plot_samp_no = 21
gp_samp_no = 50

samples = np.concatenate(
    (
        np.linspace(0, 1, plot_samp_no, dtype=np.float64).reshape(-1, 1), # alpha
        np.repeat(pv_champ_beta, plot_samp_no).reshape(-1, 1), # beta
        np.repeat(pv_champ_gamma_L, plot_samp_no).reshape(-1, 1), # gamma_L
        np.repeat(pv_champ_lambda, plot_samp_no).reshape(-1, 1), # lambda
        np.repeat(pv_champ_f, plot_samp_no).reshape(-1, 1), # f
        np.repeat(pv_champ_r, plot_samp_no).reshape(-1, 1), # r
    ),
    axis=1,
)

plot_indices_df = pd.DataFrame(samples, columns=variables_names)

print(plot_indices_df.head())

```

```

plot_discrepancies = plot_indices_df.apply(
    lambda x: discrepancy_fn(
        x["alpha"], x["beta"], x["gamma_L"], x["lambda"], x["f"], x["r"]
    ),
    axis=1,
)

plot_index_vals = plot_indices_df.values

```

	alpha	beta	gamma_L	lambda	f	r
0	0.00	0.4	0.004484	0.04	0.013889	0.016667
1	0.05	0.4	0.004484	0.04	0.013889	0.016667
2	0.10	0.4	0.004484	0.04	0.013889	0.016667
3	0.15	0.4	0.004484	0.04	0.013889	0.016667
4	0.20	0.4	0.004484	0.04	0.013889	0.016667

```

GP_seed = tfp.random.sanitize_seed(
    4362
)

champ_GP_reg = tfd.GaussianProcessRegressionModel(
    kernel=kernel_champ,
    index_points=plot_index_vals,
    observation_index_points=index_vals,
    observations=obs_vals,
    observation_noise_variance=observation_noise_variance_champ,
    predictive_noise_variance=0.,
    mean_fn=quad_mean_fn(),
)

GP_samples = champ_GP_reg.sample(gp_samp_no, seed = GP_seed)

```

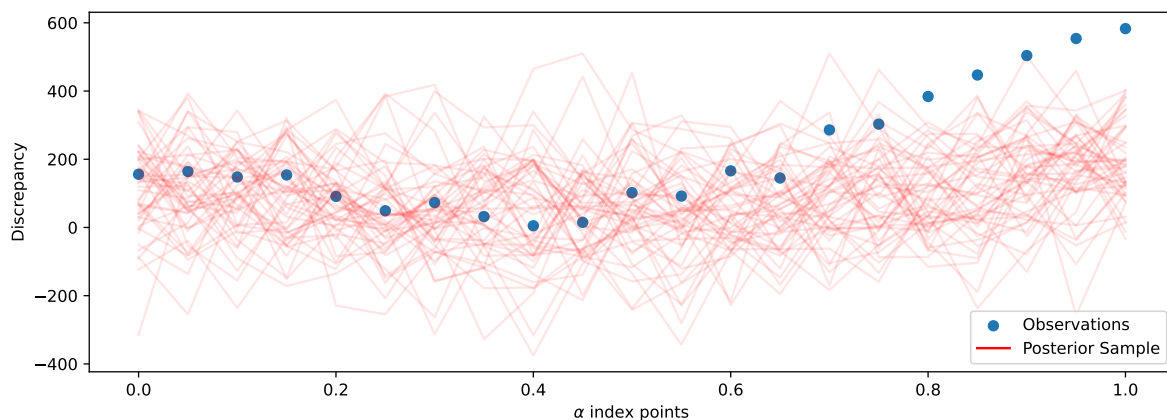
```

plt.figure(figsize=(12, 4))
plt.scatter(plot_index_vals[:, 0], plot_discrepancies,
            label='Observations')
for i in range(gp_samp_no):
    plt.plot(plot_index_vals[:, 0], GP_samples[i, :], c='r', alpha=.1,
            label='Posterior Sample' if i == 0 else None)
leg = plt.legend(loc='lower right')
for lh in leg.legendHandles:
    lh.set_alpha(1)

```

```
plt.xlabel(r"$\alpha$ index points")
plt.ylabel("Discrepancy")
plt.show()
```

/tmp/ipykernel_9471/3006156578.py:8: MatplotlibDeprecationWarning: The legendHandles attribute for lh in leg.legendHandles:



Fitting the GP Regression across beta

```
samples = np.concatenate(
    (
        np.repeat(pv_champ_alpha, plot_samp_no).reshape(-1, 1), # alpha
        np.linspace(0, 1, plot_samp_no, dtype=np.float64).reshape(-1, 1), # beta
        np.repeat(pv_champ_gamma_L, plot_samp_no).reshape(-1, 1), # gamma_L
        np.repeat(pv_champ_lambda, plot_samp_no).reshape(-1, 1), # lambda
        np.repeat(pv_champ_f, plot_samp_no).reshape(-1, 1), # f
        np.repeat(pv_champ_r, plot_samp_no).reshape(-1, 1), # r
    ),
    axis=1,
)

plot_indices_df = pd.DataFrame(samples, columns=variables_names)

print(plot_indices_df.head())

plot_discrepancies = plot_indices_df.apply(
```

```

    lambda x: discrepancy_fn(
        x["alpha"], x["beta"], x["gamma_L"], x["lambda"], x["f"], x["r"]
    ),
    axis=1,
)

plot_index_vals = plot_indices_df.values

```

	alpha	beta	gamma_L	lambda	f	r
0	0.4	0.00	0.004484	0.04	0.013889	0.016667
1	0.4	0.05	0.004484	0.04	0.013889	0.016667
2	0.4	0.10	0.004484	0.04	0.013889	0.016667
3	0.4	0.15	0.004484	0.04	0.013889	0.016667
4	0.4	0.20	0.004484	0.04	0.013889	0.016667

```

champ_GP_reg = tfd.GaussianProcessRegressionModel(
    kernel=kernel_champ,
    index_points=plot_index_vals,
    observation_index_points=index_vals,
    observations=obs_vals,
    observation_noise_variance=observation_noise_variance_champ,
    predictive_noise_variance=0.,
    mean_fn=quad_mean_fn(),
)

GP_samples = champ_GP_reg.sample(gp_samp_no, seed = GP_seed)

```

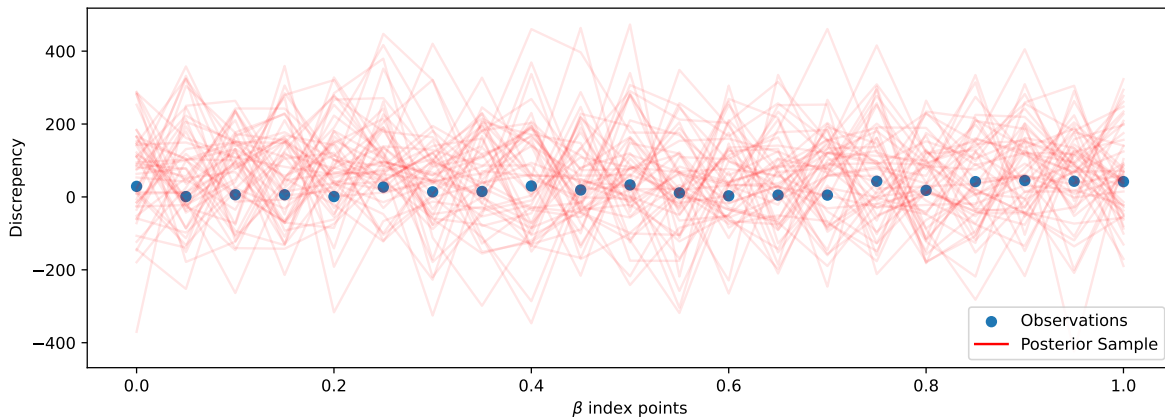
```

plt.figure(figsize=(12, 4))
plt.scatter(plot_index_vals[:, 1], plot_discrepancies,
            label='Observations')
for i in range(gp_samp_no):
    plt.plot(plot_index_vals[:, 1], GP_samples[i, :], c='r', alpha=.1,
            label='Posterior Sample' if i == 0 else None)
leg = plt.legend(loc='lower right')
for lh in leg.legendHandles:
    lh.set_alpha(1)
plt.xlabel(r"$\beta$ index points")
plt.ylabel("Discrepancy")
plt.show()

```

/tmp/ipykernel_9471/1440423062.py:8: MatplotlibDeprecationWarning: The legendHandles attribute


```
for lh in leg.legendHandles:
```



Acquiring the next datapoint to test

Proof that .variance returns what we need in acquisition function

```
new_guess = np.array([0.4, 0.4, 0.004, 0.04, 0.01, 0.17])
mean_t = champ_GP_reg.mean_fn(new_guess)
variance_t = champ_GP_reg.variance(index_points=[new_guess])

kernel_self = kernel_champ.apply(new_guess, new_guess)
kernel_others = kernel_champ.apply(new_guess, index_vals)
K = kernel_champ.matrix(
    index_vals, index_vals
) + observation_noise_variance_champ * np.identity(index_vals.shape[0])
inv_K = np.linalg.inv(K)
print("Self Kernel is {}".format(kernel_self.numpy().round(3)))
print("Others Kernel is {}".format(kernel_others.numpy().round(3)))
print(inv_K)
my_var_t = kernel_self - kernel_others.numpy() @ inv_K @ kernel_others.numpy()

print("Variance function is {}".format(variance_t.numpy().round(3)))
print("Variance function is {}".format(my_var_t.numpy().round(3)))
```

Self Kernel is 17226.707

Others Kernel is [0. 0.]

```

0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
0. 0.]
[[ 5.57044227e-005 -6.56596010e-243 -2.06129350e-170 ... 5.76222720e-153
 3.94182883e-280 2.90854769e-086]
 [-6.56596010e-243 5.57044227e-005 6.73797555e-165 ... -3.67941981e-150
 -2.29065230e-120 -1.53150862e-201]
 [-2.06129350e-170 6.73797555e-165 5.57044227e-005 ... -5.76556313e-059
 -2.68421228e-116 -3.94778349e-089]
 ...
 [ 5.76222720e-153 -3.67941981e-150 -5.76556313e-059 ... 5.57044227e-005
 2.77823458e-170 -1.57790746e-143]
 [ 3.94182883e-280 -2.29065230e-120 -2.68421228e-116 ... 2.77823458e-170
 5.57044227e-005 7.54937937e-199]
 [ 2.90854769e-086 -1.53150862e-201 -3.94778349e-089 ... -1.57790746e-143
 7.54937937e-199 5.57044227e-005]]
Variance function is [17226.707]
Variance function is 17226.707

```

Loss function

```

next_alpha = tfp.util.TransformedVariable(
    initial_value=0.4,
    bijector = tfb.Sigmoid(),
    dtype=np.float64,
    name="next_alpha",
)

next_beta = tfp.util.TransformedVariable(
    initial_value=0.4,
    bijector = tfb.Sigmoid(),
    dtype=np.float64,
    name="next_beta",
)

next_gamma_L = tfp.util.TransformedVariable(
    initial_value=0.004,
    bijector = constrain_positive,
    dtype=np.float64,
    name="next_gamma_L",
)

```

```

next_lambda = tfp.util.TransformedVariable(
    initial_value=0.04,
    bijector = constrain_positive,
    dtype=np.float64,
    name="next_lambda",
)

next_f = tfp.util.TransformedVariable(
    initial_value=0.01,
    bijector = constrain_positive,
    dtype=np.float64,
    name="next_f",
)

next_r = tfp.util.TransformedVariable(
    initial_value=0.17,
    bijector = constrain_positive,
    dtype=np.float64,
    name="next_r",
)

next_vars = [
    v.trainable_variables[0]
    for v in [next_alpha, next_beta, next_gamma_L, next_lambda, next_f, next_r]
]

```

```

Adam_optim = tf.optimizers.Adam(learning_rate=0.1)

```

```

@tf.function(autograph=False, jit_compile=False)
def optimize():
    with tf.GradientTape() as tape:
        next_guess = tf.reshape(
            [
                tfb.Sigmoid().forward(next_vars[0]),
                tfb.Sigmoid().forward(next_vars[1]),
                tfb.Sigmoid().forward(next_vars[2]),
                tfb.Sigmoid().forward(next_vars[3]),
                tfb.Sigmoid().forward(next_vars[4]),
                tfb.Sigmoid().forward(next_vars[5]),
            ],
            [1, 6],

```

```

    )
    mean_t = champ_GP_reg.mean_fn(next_guess)
    std_t = champ_GP_reg.stddev(index_points=next_guess)
    loss = tf.squeeze(mean_t - 1.7 * std_t)
    grads = tape.gradient(loss, next_vars)
    Adam_optim.apply_gradients(zip(grads, next_vars))
    return loss

num_iters = 1000

lls_ = np.zeros(num_iters, np.float64)
for i in range(num_iters):
    loss = optimize()
    lls_[i] = loss

print("Trained parameters:")
for var in next_vars:
    if ("alpha" in var.name) | ("beta" in var.name):
        print(
            "{} is {}".format(var.name, (tfb.Sigmoid()).forward(var).numpy().round(3)))
    else:
        print(
            "{} is {}".format(
                var.name, constrain_positive.forward(var).numpy().round(3)
            )
        )

```

```

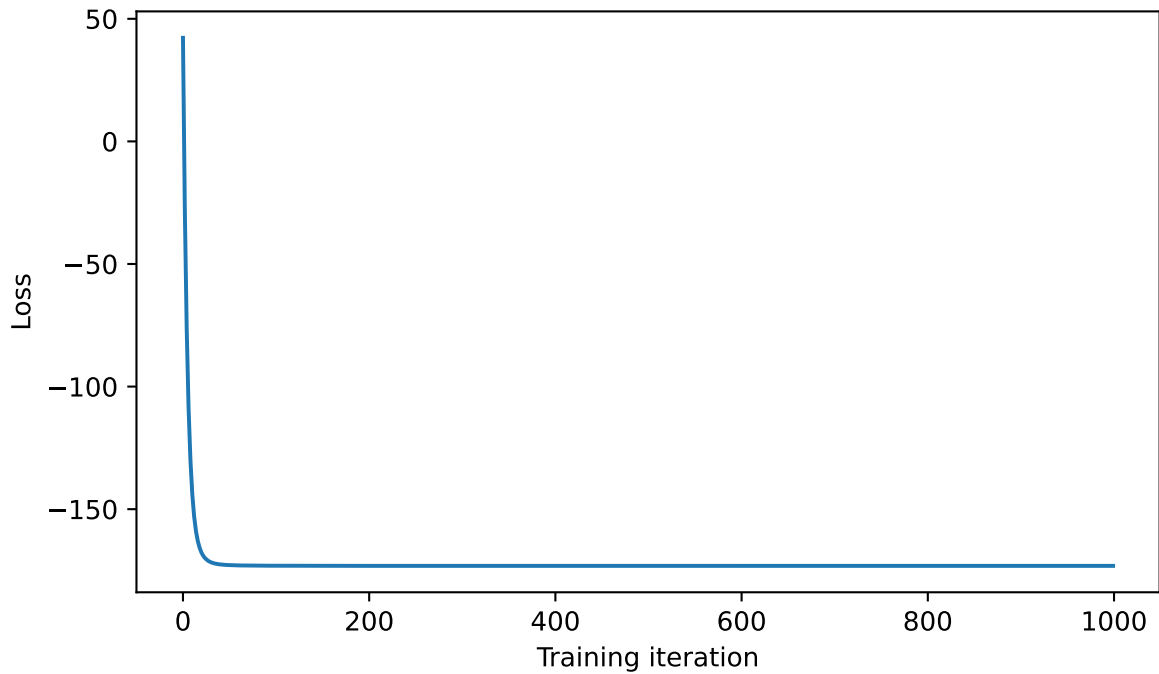
Trained parameters:
next_alpha:0 is 0.4
next_beta:0 is 0.4
next_gamma_L:0 is 0.005
next_lambda:0 is 0.042
next_f:0 is 0.014
next_r:0 is 0.017

```

```

plt.figure(figsize=(7, 4))
plt.plot(lls_)
plt.xlabel("Training iteration")
plt.ylabel("Loss")
plt.show()

```



```
for t in range(100):  
    # print(t)  
    new_discrepancy = discrepancy_fn(  
        next_alpha.numpy(),  
        next_beta.numpy(),  
        next_gamma_L.numpy(),  
        next_lambda.numpy(),  
        next_f.numpy(),  
        next_r.numpy(),  
    )  
  
    index_vals = np.append(  
        index_vals,  
        np.array(  
            [  
                next_alpha.numpy(),  
                next_beta.numpy(),  
                next_gamma_L.numpy(),  
                next_lambda.numpy(),  
                next_f.numpy(),  
                next_r.numpy(),  
            ]  
        )  
    )
```

```

        ).reshape(1, -1),
        axis=0,
    )
    obs_vals = np.append(obs_vals, new_discrepancy)

    champ_GP = tfd.GaussianProcess(
        kernel=kernel_champ,
        observation_noise_variance=observation_noise_variance_champ,
        index_points=index_vals,
        mean_fn=quad_mean_fn(),
    )

    Adam_optim = tf.optimizers.Adam(learning_rate=0.1)

    @tf.function()
    def optimize():
        with tf.GradientTape() as tape:
            loss = -champ_GP.log_prob(obs_vals)
            grads = tape.gradient(loss, champ_GP.trainable_variables)
            Adam_optim.apply_gradients(zip(grads, champ_GP.trainable_variables))
        return loss

    num_iters = 500

    lls_ = np.zeros(num_iters, np.float64)
    for i in range(num_iters):
        loss = optimize()
        lls_[i] = loss

    champ_GP_reg = tfd.GaussianProcessRegressionModel(
        kernel=kernel_champ,
        index_points=plot_index_vals,
        observation_index_points=index_vals,
        observations=obs_vals,
        observation_noise_variance=observation_noise_variance_champ,
        predictive_noise_variance=0.0,
        mean_fn=quad_mean_fn(),
    )

    Adam_optim = tf.optimizers.Adam(learning_rate=0.1)

    @tf.function(autograph=False, jit_compile=False)

```

```

def optimize():
    with tf.GradientTape() as tape:
        next_guess = tf.reshape(
            [
                tfb.Sigmoid().forward(next_vars[0]),
                tfb.Sigmoid().forward(next_vars[1]),
                tfb.Sigmoid().forward(next_vars[2]),
                tfb.Sigmoid().forward(next_vars[3]),
                tfb.Sigmoid().forward(next_vars[4]),
                tfb.Sigmoid().forward(next_vars[5]),
            ],
            [1, 6],
        )
        mean_t = champ_GP_reg.mean_fn(next_guess)
        std_t = champ_GP_reg.stddev(index_points=next_guess)
        loss = tf.squeeze(mean_t - 1.7 * std_t)
        grads = tape.gradient(loss, next_vars)
        Adam_optim.apply_gradients(zip(grads, next_vars))
    return loss

num_iters = 200

lls_ = np.zeros(num_iters, np.float64)
for i in range(num_iters):
    loss = optimize()
    lls_[i] = loss

```

Fitting the GP Regression across alpha

```

plot_samp_no = 21
gp_samp_no = 50

```

```

samples = np.concatenate(
    (
        np.linspace(0, 1, plot_samp_no, dtype=np.float64).reshape(-1, 1), # alpha
        np.repeat(pv_champ_beta, plot_samp_no).reshape(-1, 1), # beta
        np.repeat(pv_champ_gamma_L, plot_samp_no).reshape(-1, 1), # gamma_L
        np.repeat(pv_champ_lambda, plot_samp_no).reshape(-1, 1), # lambda
        np.repeat(pv_champ_f, plot_samp_no).reshape(-1, 1), # f
        np.repeat(pv_champ_r, plot_samp_no).reshape(-1, 1), # r
    )
)

```

```

    ),
    axis=1,
)

plot_indices_df = pd.DataFrame(samples, columns=variables_names)

print(plot_indices_df.head())

plot_discrepancies = plot_indices_df.apply(
    lambda x: discrepancy_fn(
        x["alpha"], x["beta"], x["gamma_L"], x["lambda"], x["f"], x["r"]
    ),
    axis=1,
)

plot_index_vals = plot_indices_df.values

```

	alpha	beta	gamma_L	lambda	f	r
0	0.00	0.4	0.004484	0.04	0.013889	0.016667
1	0.05	0.4	0.004484	0.04	0.013889	0.016667
2	0.10	0.4	0.004484	0.04	0.013889	0.016667
3	0.15	0.4	0.004484	0.04	0.013889	0.016667
4	0.20	0.4	0.004484	0.04	0.013889	0.016667

```

GP_seed = tfp.random.sanitize_seed(
    4362
)

champ_GP_reg = tfd.GaussianProcessRegressionModel(
    kernel=kernel_champ,
    index_points=plot_index_vals,
    observation_index_points=index_vals,
    observations=obs_vals,
    observation_noise_variance=observation_noise_variance_champ,
    predictive_noise_variance=0.,
    mean_fn=quad_mean_fn(),
)

GP_samples = champ_GP_reg.sample(gp_samp_no, seed = GP_seed)

```

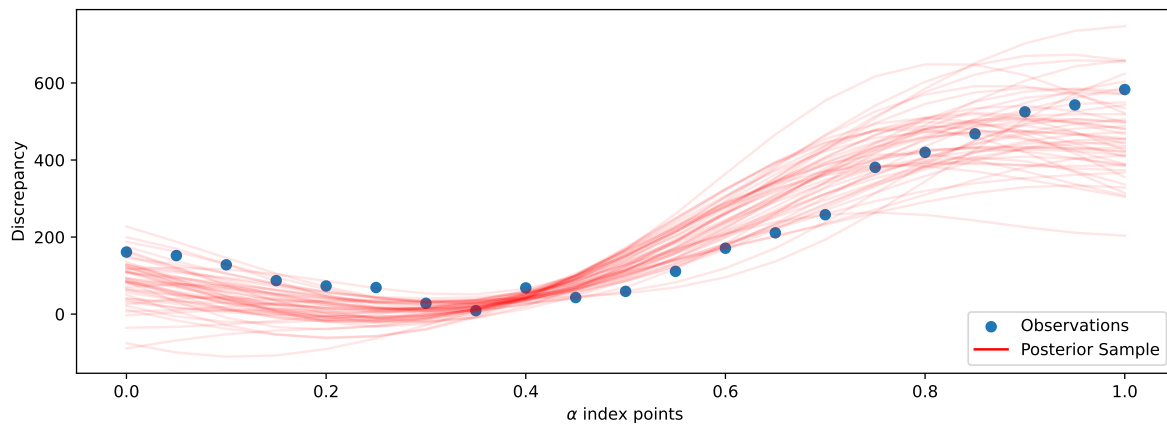


```

plt.figure(figsize=(12, 4))
plt.scatter(plot_index_vals[:, 0], plot_discrepancies,
            label='Observations')
for i in range(gp_samp_no):
    plt.plot(plot_index_vals[:, 0], GP_samples[i, :], c='r', alpha=.1,
            label='Posterior Sample' if i == 0 else None)
leg = plt.legend(loc='lower right')
for lh in leg.legendHandles:
    lh.set_alpha(1)
plt.xlabel(r"$\alpha$ index points")
plt.ylabel("Discrepancy")
plt.show()

```

/tmp/ipykernel_9471/3006156578.py:8: MatplotlibDeprecationWarning: The legendHandles attribute for lh in leg.legendHandles:



Fitting the GP Regression across beta

```

samples = np.concatenate(
    (
        np.repeat(pv_champ_alpha, plot_samp_no).reshape(-1, 1), # alpha
        np.linspace(0, 1, plot_samp_no, dtype=np.float64).reshape(-1, 1), # beta
        np.repeat(pv_champ_gamma_L, plot_samp_no).reshape(-1, 1), # gamma_L
        np.repeat(pv_champ_lambda, plot_samp_no).reshape(-1, 1), # lambda
        np.repeat(pv_champ_f, plot_samp_no).reshape(-1, 1), # f
        np.repeat(pv_champ_r, plot_samp_no).reshape(-1, 1), # r
    )
)

```

```

    ),
    axis=1,
)

plot_indices_df = pd.DataFrame(samples, columns=variables_names)

print(plot_indices_df.head())

plot_discrepancies = plot_indices_df.apply(
    lambda x: discrepancy_fn(
        x["alpha"], x["beta"], x["gamma_L"], x["lambda"], x["f"], x["r"]
    ),
    axis=1,
)

plot_index_vals = plot_indices_df.values

```

	alpha	beta	gamma_L	lambda	f	r
0	0.4	0.00	0.004484	0.04	0.013889	0.016667
1	0.4	0.05	0.004484	0.04	0.013889	0.016667
2	0.4	0.10	0.004484	0.04	0.013889	0.016667
3	0.4	0.15	0.004484	0.04	0.013889	0.016667
4	0.4	0.20	0.004484	0.04	0.013889	0.016667

```

champ_GP_reg = tfd.GaussianProcessRegressionModel(
    kernel=kernel_champ,
    index_points=plot_index_vals,
    observation_index_points=index_vals,
    observations=obs_vals,
    observation_noise_variance=observation_noise_variance_champ,
    predictive_noise_variance=0.,
    mean_fn=quad_mean_fn(),
)

GP_samples = champ_GP_reg.sample(gp_samp_no, seed = GP_seed)

```

```

plt.figure(figsize=(12, 4))
plt.scatter(plot_index_vals[:, 1], plot_discrepancies,
            label='Observations')
for i in range(gp_samp_no):
    plt.plot(plot_index_vals[:, 1], GP_samples[i, :], c='r', alpha=.1,

```

```

        label='Posterior Sample' if i == 0 else None)
leg = plt.legend(loc='lower right')
for lh in leg.legendHandles:
    lh.set_alpha(1)
plt.xlabel(r"$\beta$ index points")
plt.ylabel("Discrepancy")
plt.show()

```

/tmp/ipykernel_9471/1440423062.py:8: MatplotlibDeprecationWarning: The legendHandles attribute
for lh in leg.legendHandles:

