

Short overview quadrature

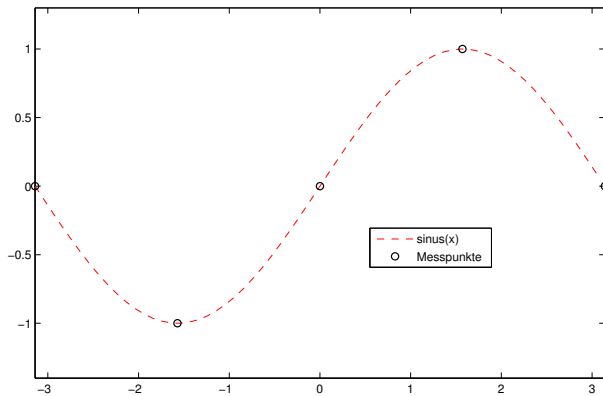
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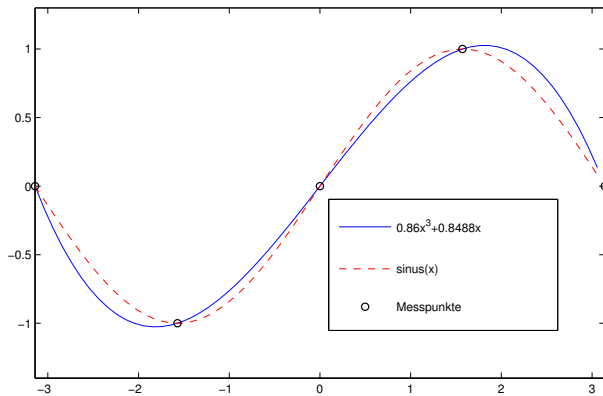
Motivation

$$\int_{-\pi}^{\pi} \sin(x) dx? \quad (1)$$

Motivation



Motivation



Problem setting

Given:

- ▶ points $x_0 < x_1 < \dots < x_n$
- ▶ associated measurements y_0, y_1, \dots, y_n

Goal:

Find a function f with:

$$f(x_i) = y_i \quad i \in \{0, 1, \dots, n\} \quad (2)$$

Questions

- ▶ Does such a polynomial exist ?
- ▶ If yes, is it unique?
- ▶ How well is $p(x)$ approximating original function $f(x)$?

Polynomial Interpolation

Given:

- ▶ points $x_0 < x_1 < \dots < x_n$
- ▶ associated measurements y_0, y_1, \dots, y_n

Goal:

Find a polynomial p of grade n

$$p(x_i) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 \quad (3)$$

with:

$$p(x_i) = y_i \quad i \in \{0, 1, \dots, n\} \quad (4)$$

Example

Given:

- ▶ $(x_0, y_0) = (-1, -3)$
- ▶ $(x_1, y_1) = (0, -1)$
- ▶ $(x_2, y_2) = (1, 5)$

Goal:

Find a polynomial $p(x) = a_2x^2 + a_1x + a_0$ with:

- ▶ $p(-1) = -3$
- ▶ $p(0) = -1$
- ▶ $p(1) = 5$

Example

School:

Find a polynomial $p(x) = a_2x^2 + a_1x + a_0$ with:

$$p(-1) = a_2(-1)^2 + a_1(-1) + a_0 = -3 \quad (5)$$

$$p(0) = a_2 \cdot (0)^2 + a_1 \cdot 0 + a_0 = -1 \quad (6)$$

$$p(1) = a_2 \cdot (1)^2 + a_1 \cdot 1 + a_0 = 5 \quad (7)$$

Example

Solve the system of linear equations:

$$p(-1) = a_2 - a_1 + a_0 = -3 \quad (8)$$

$$p(0) = a_0 = -1 \quad (9)$$

$$p(1) = a_2 + a_1 + a_0 = 5 \quad (10)$$

Example

Solve the system of linear equations:

$$\begin{bmatrix} 1 & -1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a_2 \\ a_1 \\ a_0 \end{bmatrix} = \begin{bmatrix} -3 \\ -1 \\ 5 \end{bmatrix} \quad (11)$$

Example

Solve the system of linear equations:

$$\begin{bmatrix} 1 & -1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a_2 \\ a_1 \\ a_0 \end{bmatrix} = \begin{bmatrix} -3 \\ -1 \\ 5 \end{bmatrix} \quad (12)$$

$$\rightarrow \begin{bmatrix} a_2 \\ a_1 \\ a_0 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ -1 \end{bmatrix} \quad (13)$$

Example

Solve the system of linear equations:

$$\begin{bmatrix} 1 & -1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a_2 \\ a_1 \\ a_0 \end{bmatrix} = \begin{bmatrix} -3 \\ -1 \\ 5 \end{bmatrix} \quad (12)$$

$$\rightarrow \begin{bmatrix} a_2 \\ a_1 \\ a_0 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ -1 \end{bmatrix} \quad (13)$$

$$\rightarrow p(x) = 2x^2 + 4x - 1 \quad (14)$$

More general

Solve the system of linear equations:

Find a polynomial $p(x) = a_n x^n + \cdots + a_1 x + a_0$ with:

$$p(x_0) = a_n (x_0)^n + \cdots + a_1 x_0 + a_0 = y_0$$

$$p(x_1) = a_n (x_1)^n + \cdots + a_1 x_1 + a_0 = y_1$$

$$\vdots$$

$$p(x_n) = a_n (x_n)^n + \cdots + a_1 x_n + a_0 = y_n$$

More general

Solve the system of linear equations:

Find a polynomial $p(x) = a_n x^n + \cdots + a_1 x + a_0$ with:

$$\begin{bmatrix} (x_0)^n & \cdots & x_0 & 1 \\ (x_1)^n & \cdots & x_1 & 1 \\ \vdots & \cdots & \vdots & 1 \\ (x_n)^n & \cdots & x_n & 1 \end{bmatrix} \begin{bmatrix} a_n \\ a_{n-1} \\ \vdots \\ a_0 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{bmatrix} \quad (15)$$

More general

Solve the system of linear equations:

Find a polynomial $p(x) = a_n x^n + \dots + a_1 x + a_0$ with:

$$\begin{bmatrix} (x_0)^n & \dots & x_0 & 1 \\ (x_1)^n & \dots & x_1 & 1 \\ \vdots & \dots & \vdots & 1 \\ (x_n)^n & \dots & x_n & 1 \end{bmatrix} \begin{bmatrix} a_n \\ a_{n-1} \\ \vdots \\ a_0 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{bmatrix} \quad (15)$$

→ Gauss-Approach

Linear Algebra

Vector space

$$\mathbf{R}_{\leq n}[x] \in \mathbf{R}^{n+1} \quad (16)$$

Kanonical Basis

$$B = \{1, x, x^2, x^3, \dots, x^n\} \quad (17)$$

Element

$$P_n(x) = \sum_{i=0}^n a_i x^i \quad (18)$$

Linear Algebra

Vector space

$$\mathbf{R}_{\leq n}[x] \in \mathbf{R}^{n+1} \quad (19)$$

Lagrange Basis

Given:

$$x_0 < x_1 < \cdots < x_n \quad (20)$$

$$L = \{l_0(x), l_1(x), \dots, l_n(x)\} \quad (21)$$

with

$$l_i(x) := \prod_{\substack{k=0, \\ i \neq k}}^n \frac{x - x_k}{x_i - x_k} \quad (22)$$

Element

$$P_n(x) = \sum_{i=0}^n b_i l_i(x) \quad (23)$$

Example

Given:

- ▶ $x_0 = -1$
- ▶ $x_1 = 0$
- ▶ $x_2 = 1$

$$l_0(x) = \frac{x - 0}{-1 - 0} \cdot \frac{x - 1}{-1 - 1} \quad (24)$$

$$l_1(x) = \frac{x + 1}{0 + 1} \cdot \frac{x - 1}{0 - 1}$$

$$l_2(x) = \frac{x + 1}{1 + 1} \cdot \frac{x - 0}{1 - 0}$$

Lagrange-Polynomial

$$l_i(x) := \prod_{\substack{k=0, \\ i \neq k}}^n \frac{x - x_k}{x_i - x_k} \quad (25)$$

with

$$x_0 < x_1 < \cdots < x_n \quad (26)$$

is basis of \mathbf{R}^n , d.h.,

$$P_n(x) = \sum_{i=0}^n b_i l_i(x) \quad (27)$$

Properties of the Lagrange-Polynomials

$$l_i(x_j) := \begin{cases} 1 & \text{für } x_j = x_i \\ 0 & \text{für } x_j \neq x_i \end{cases} \quad (28)$$

Polynomial interpolation

Geben:

- ▶ Points $x_0 < x_1 < \dots < x_n$
- ▶ measurements y_0, y_1, \dots, y_n

Goal:

Find a polynomial p of grade n

$$p(x) = b_n l_n(x) + \dots + b_1 l_1(x) + b_0 l_0(x) \quad (29)$$

with

$$p(x_i) = y_i \quad i \in \{0, 1, \dots, n\} \quad (30)$$

Solve the system of linear equations:

Find a polynomial $p(x) = b_n l_n(x) + \dots + b_1 l_1(x) + b_0 l_0(x)$ with:

$$\begin{bmatrix} l_n(x_n) & \dots & l_0(x_n) \\ l_n(x_{n-1}) & \dots & l_0(x_{n-1}) \\ \vdots & \dots & \vdots \\ l_n(x_0) & \dots & l_0(x_0) \end{bmatrix} \begin{bmatrix} b_n \\ b_{n-1} \\ \vdots \\ b_0 \end{bmatrix} = \begin{bmatrix} y_n \\ y_{n-1} \\ \vdots \\ y_0 \end{bmatrix} \quad (31)$$

Lagrange-Interpolation

$$l_i(x_j) := \begin{cases} 1 & \text{für } x_j = x_i \\ 0 & \text{für } x_j \neq x_i \end{cases} \quad (32)$$

Lagrange-Interpolation

$$\begin{bmatrix} l_n(x_n) & \dots & l_0(x_n) \\ l_n(x_{n-1}) & \dots & l_0(x_{n-1}) \\ \vdots & \dots & \vdots \\ l_n(x_0) & \dots & l_0(x_0) \end{bmatrix} \begin{bmatrix} b_n \\ b_{n-1} \\ \vdots \\ b_0 \end{bmatrix} = \begin{bmatrix} y_n \\ y_{n-1} \\ \vdots \\ y_0 \end{bmatrix} \quad (33)$$

Lagrange-Interpolation

$$\begin{bmatrix} 1 & \dots & 0 \\ 0 & 1 & 0 \\ \vdots & \dots & \vdots \\ 0 & \dots & 1 \end{bmatrix} \begin{bmatrix} b_n \\ b_{n-1} \\ \vdots \\ b_0 \end{bmatrix} = \begin{bmatrix} y_n \\ y_{n-1} \\ \vdots \\ y_0 \end{bmatrix} \quad (34)$$

Existence and uniqueness

Proposition For fixed points $x_0 < x_1 < \dots < x_n$ and arbitrary points y_0, y_1, \dots, y_n there is a unique polynomial P_n of grade n with

$$p(x_i) = y_i \quad i \in \{0, 1, \dots, n\} \quad (35)$$

Motivation

Setting: Error of the polynomial interpolation

$$|\epsilon_n(x)| = |f(x) - P_n(x)| \leq \max_{x \in [a,b]} \left| \frac{1}{(n+1)!} f^{(n+1)}(x) \right| \max_{x \in [a,b]} \left| \prod_{i=0}^n (x - x_i) \right|$$

Goal: small error

Motivation

Setting: Error of the polynomial interpolation

$$|\epsilon_n(x)| = |f(x) - P_n(x)| \leq \max_{x \in [a,b]} \left| \frac{1}{(n+1)!} f^{(n+1)}(x) \right| \max_{x \in [a,b]} \left| \prod_{i=0}^n (x - x_i) \right|$$

Motivation

Setting: Error of the polynomial interpolation

$$|\epsilon_n(x)| = |f(x) - P_n(x)| \leq \max_{x \in [a,b]} \left| \frac{1}{(n+1)!} f^{(n+1)}(x) \right| \max_{x \in [a,b]} \left| \prod_{i=0}^n (x - x_i) \right|$$

More concrete goal: want

$$\max_{x \in [a,b]} \left| \prod_{i=0}^n (x - x_i) \right|$$

to be small

How?

Motivation

Setting: Error of the polynomial interpolation

$$|\epsilon_n(x)| = |f(x) - P_n(x)| \leq \max_{x \in [a,b]} \left| \frac{1}{(n+1)!} f^{(n+1)}(x) \right| \max_{x \in [a,b]} \left| \prod_{i=0}^n (x - x_i) \right|$$

More concrete goal: want

$$\max_{x \in [a,b]} \left| \prod_{i=0}^n (x - x_i) \right|$$

to be small

How?: smart choice of points x_i

Equidistant supporting points

Proposition:

For equidistant supporting points in the interval $[a, b]$ i.e.,

$$x_i = a + i \frac{(b-a)}{n} \quad i \in \{0, \dots, n\} \quad (36)$$

the interpolation error has the following upper bound:

$$|\epsilon_n(x)| \leq \left(\frac{b-a}{n}\right)^{n+1} \frac{1}{4(n+1)} \max_{x \in [a,b]} |f^{(n+1)}(x)| \quad (37)$$

Tschebyscheff-Polynomials

Definition

The Tschebyscheff-Polynomials of first order are defined as follows for $n \in \mathbb{N}$:

$$T_n : [-1, 1] \rightarrow \mathbb{R}, \quad T_n(x) = \cos(n \arccos x)$$

Tschebyscheff-Polynomials

Rekursiv formular

$$T_{n+1}(t) = 2t \cdot T_n(t) - T_{n-1}(t) \text{ für } t \in [-1, 1] \quad (38)$$

with

$$T_0(t) = 1, \quad T_1(t) = t \quad (39)$$

Roots

$T_n(t)$ has n roots $t_k^{(n)}$ on $[-1, 1]$: with

$$t_k^{(n)} := \cos\left(\frac{(2k-1)\pi}{2n}\right) \quad \text{für } k \in \{1, \dots, n\} \quad (40)$$

for all $n \in \mathbb{N}$

Extrem points

$T_n(t)$ has $n + 1$ **extrem points** $s_k^{(n+1)}$ on $[-1, 1]$: with

$$s_k^{(n+1)} := \cos\left(\frac{k\pi}{n}\right) \quad \text{für } k \in \{0, \dots, n\} \quad (41)$$

and it holds that

$$T_n(s_k^{(n)}) = (-1)^k \quad \text{für } k \in \{0, \dots, n\} \quad (42)$$

for all $n \in \mathbb{N}$

Tschebyscheff- supporting points

Definition

The roots $\{t_0^{(n+1)}, \dots, t_n^{(n+1)}\}$ of the $n + 1$ -Tschebyscheff Polynomial $T_{n+1}(t)$ are the so called
Tschebyscheff-Supporting-Points.

Optimality on $[-1, 1]$

Optimality on $[-1, 1]$:

$$\max_{x \in [a, b]} \left| \prod_{i=0}^n (x - x_i) \right|$$

is minimal for the Tschebyscheff-Supporting-Points

Error

For **Tschebyscheff-Supporting Points** on the Intervall $[-1, 1]$ the interpolation error has the following upper bound:

$$|f(x) - P_n(x)| \leq \frac{1}{2^n} \max_{x \in [-1, 1]} \left| \frac{1}{(n+1)!} f^{(n+1)}(x) \right|$$

Optimality on $[a, b]$

Optimality on $[a, b]$:

$$\max_{x \in [a, b]} \left| \prod_{i=0}^n (x - x_i) \right|$$

is minimal for

$$\Phi : [-1, 1] \rightarrow [a, b] \tag{43}$$

shifted Tschebyscheff-Supporting Points $\Phi(t_k^{(n+1)})$.

Quadratur

Problem: determine Integral

$$I[f] = \int_a^b f(x) \, dx \quad (44)$$

Quadraturformel

$$I[f] \approx I_n[f] = \sum_{i=0}^n g_i f(x_i) \, dx \quad (45)$$

with

- ▶ knots $x_i \in [a, b]$ für $i=0, \dots, n$
- ▶ weights g_i für $i=0, \dots, n$

Newton-Cotes Formular

Idea: Determine Interpolation polynomial for $(x_i, f(x_i))$
 $i = 0, 1, \dots, n$

$$P_n(x) = \sum_{i=0}^n l_i(x) f(x_i) \quad \text{mit } l_i(x) := \prod_{\substack{k=0, \\ i \neq k}}^n \frac{x - x_k}{x_i - x_k}$$

to approximate $f(x)$

Solution: Quadratur formulae

$$I[f] \approx I_n[f] = \int_a^b P_n(x) \, dx = \sum_{i=0}^n \int_a^b l_i(x) \, dx \, f(x_i) = \sum_{i=0}^n g_i f(x_i)$$

Newton-Cotes formulare

Simplification: Use equidistant supporting points

$$x_i = a + i \frac{(b-a)}{n} \quad i \in \{0, \dots, n\}$$

Ergebnis: Newton-Cotes formulare

$$I[f] \approx I_n[f] = \int_a^b P_n(x) \, dx = (b-a) \sum_{i=0}^n \alpha_i^n f(x_i)$$

with

$$\alpha_i^n = \frac{1}{n} \int_0^n \prod_{\substack{j=0, \\ i \neq j}}^n \frac{x-j}{i-j} \, dx$$

Newton-Cotes formulare

Trapez rule: $n = 1$

$$I[f] \approx I_1[f] = (b - a) \frac{f(a) + f(b)}{2} \quad (46)$$

Simpson rule: $n = 2$

$$I[f] \approx I_2[f] = \frac{(b - a)}{6} \left(f(a) + 4f\left(\frac{b + a}{2}\right) + f(b) \right) \quad (47)$$

Newton-Cotes formulare

Satz

The Newton-Cotes formulare $I_n[f]$ integrates polynomials of grade $\leq n$ exactly.

Idea Gauß-Quadratur: Use different points x_0, \dots, x_n to be able to exactly integrate polynomials of higher order

Error of the Newton-Cotes formulare

$\epsilon_n[f] = I_n[f] - I[f]$ is called **Error** of the Quadratur formulare

Reminder: Representation of the Interpolation error

$$f(x) - p_n(x) = \frac{1}{n+1!} f^{(n+1)}(\xi) \cdot \prod_{i=1}^n (x - x_i) \quad (48)$$

Example: For the Quadratur error of the Trapez rule ($n = 1$) the following holds

$$\epsilon_1[f] = |I_1[f] - I[f]| \leq \frac{1}{12} \|f^{(2)}\|_{\infty} \cdot h^3 \quad (49)$$

Gauß-Quadratur

Ziel:

Approximate for a fixed positive weight function:

$$\mu : (a, b) \rightarrow (0, \infty) \quad (50)$$

Integrals of the form

$$I[f] = \int_a^b f(x) \mu(x) \, dx \quad (51)$$

via a Quadratur rule of the form:

$$I[f] \approx \sum_{i=0}^n f(x_i) \mu_i \quad (52)$$

with a special choice of the supporting points x_i and positive weights μ_i

Construction of Gauß-Quadratur formular

- Find orthogonal Polynomials $\{p_0, p_1, \dots, p_{n+1}\}$ with respect to

$$\langle p_k, p_j \rangle_\mu = \int_a^b p_k(x) p_j(x) \mu(x) \, dx \quad (53)$$

mit $p_k \in \mathcal{P}_k$ und $\langle p_k, p_j \rangle = \delta_{kj}$

- use roots of p_{n+1} as knots
- determine weights

$$\mu_i = \int_a^b \mu(x) \prod_{\substack{k=0, \\ i \neq k}}^n \frac{x - x_k}{x_i - x_k} \, dx \quad \text{für } 0 \leq i \leq n \quad (54)$$

Gauß-Quadraturformeln

Solution: Gauß-Quadratur Formulare

$$I_n[f] = \sum_{i=0}^n \mu_i f(x_i) \approx I[f] = \int_a^b f(x) \mu(x) \, dx \quad (55)$$

with

$$I_n[p] = I[p] \quad \forall p \in \mathcal{P}_{2n+1} \quad (56)$$