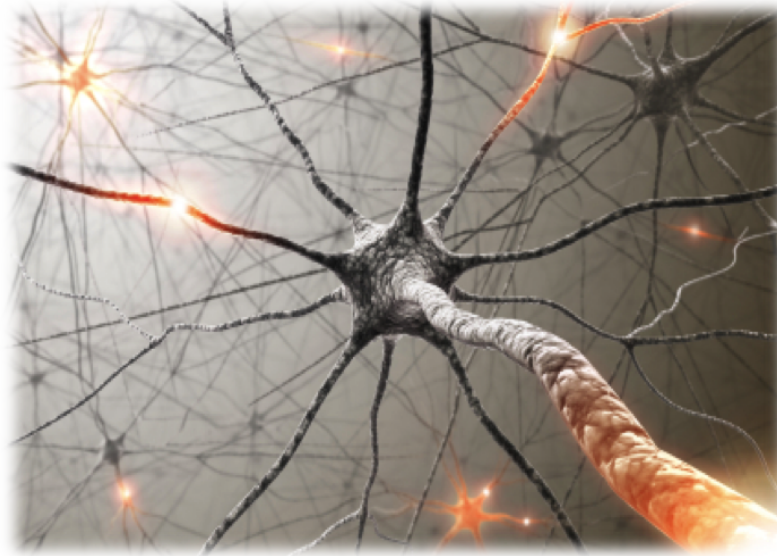
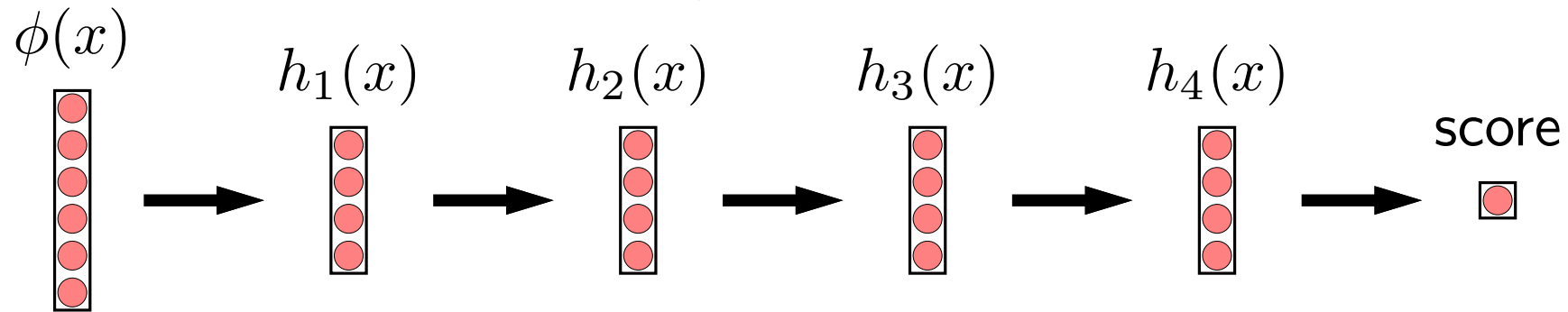




Machine learning: differentiable programming



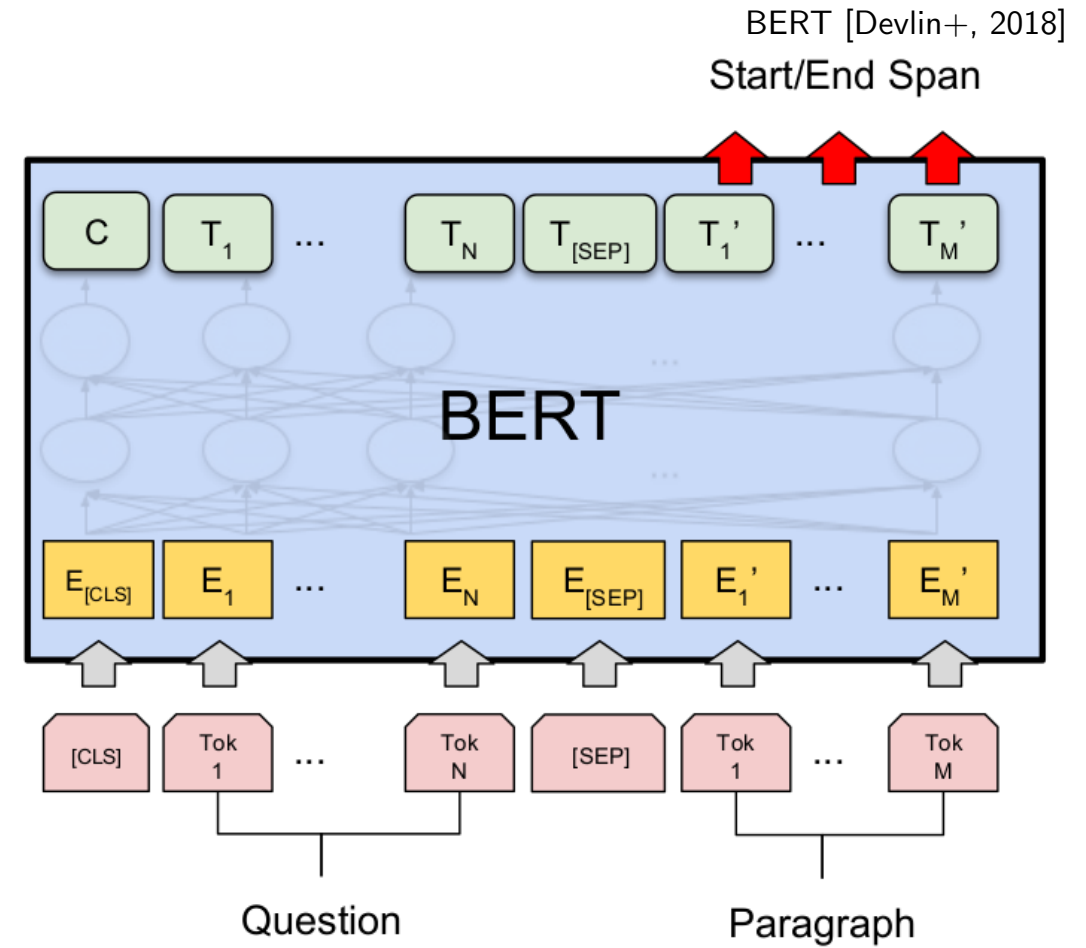
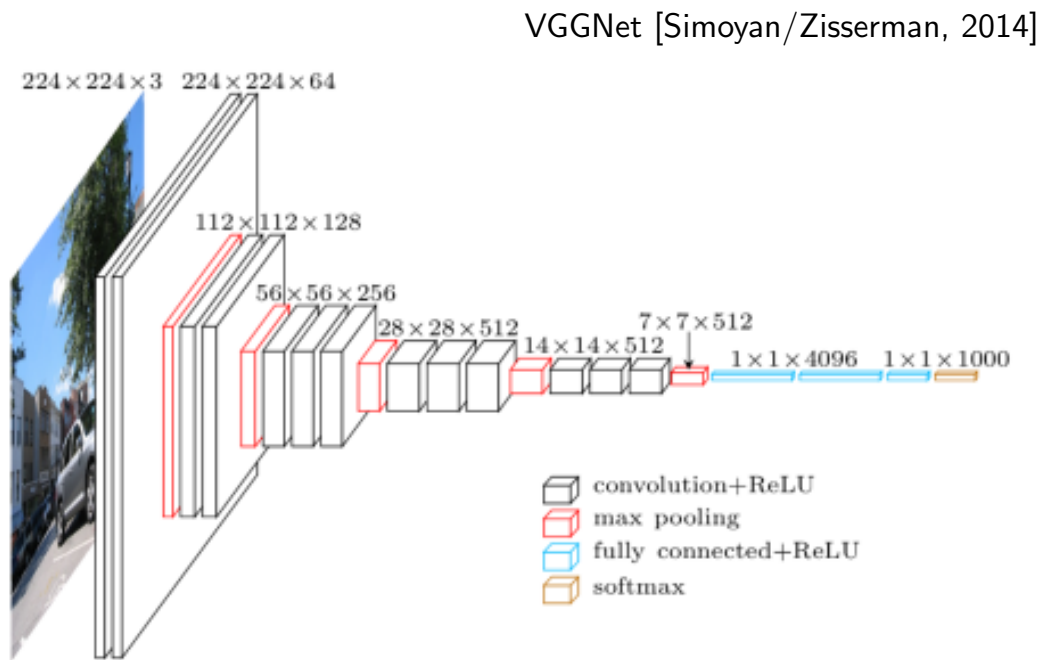
Why depth?



Intuitions:

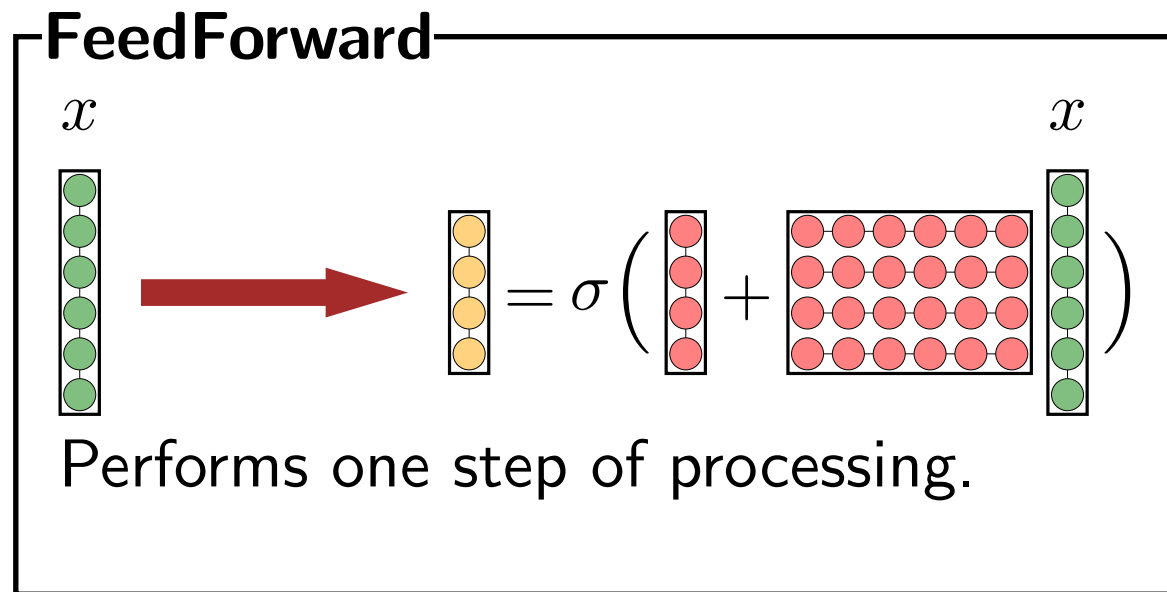
- Multiple levels of abstraction
- Multiple steps of computation
- Empirically works well
- Theory is still incomplete

Deep learning models



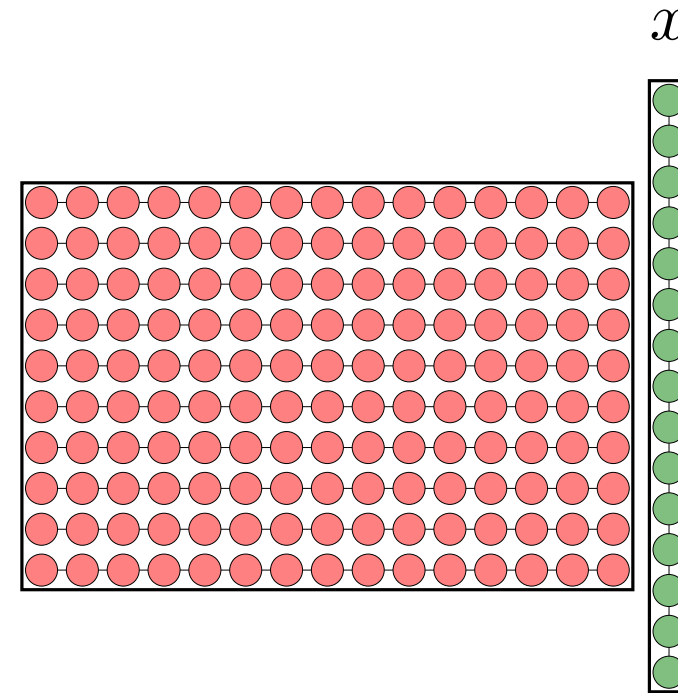
Feedforward neural networks

$$\text{score} = b_3 + \mathbf{V}_3 \sigma \left(b_2 + \mathbf{V}_2 \sigma \left(b_1 + \mathbf{V}_1 \phi(x) \right) \right)$$



$$\text{score} = \text{FeedForward}(\text{FeedForward}(\text{FeedForward}(\phi(x)))) = \text{FeedForward}^3(\phi(x))$$

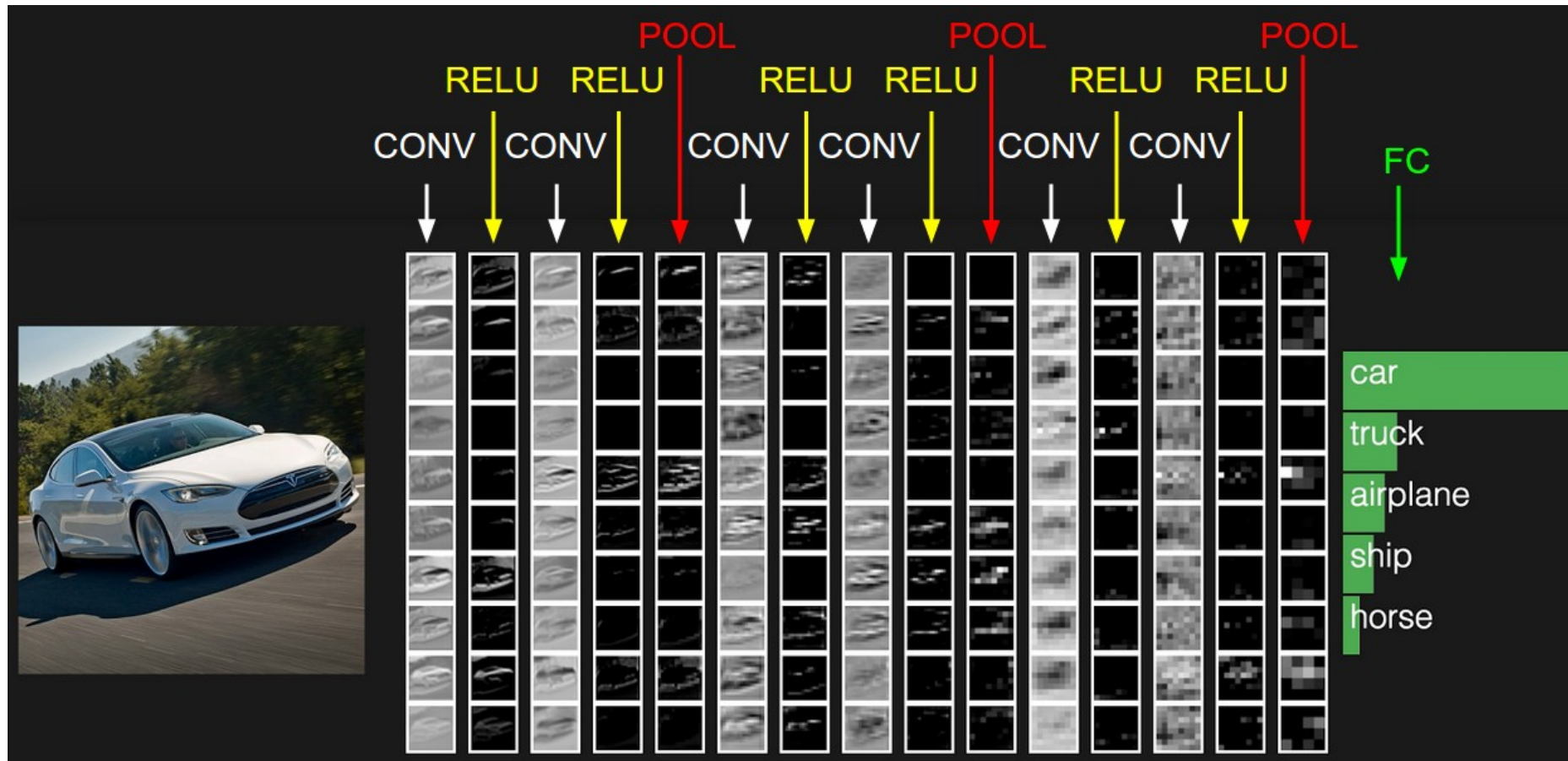
Representing images



Problems:

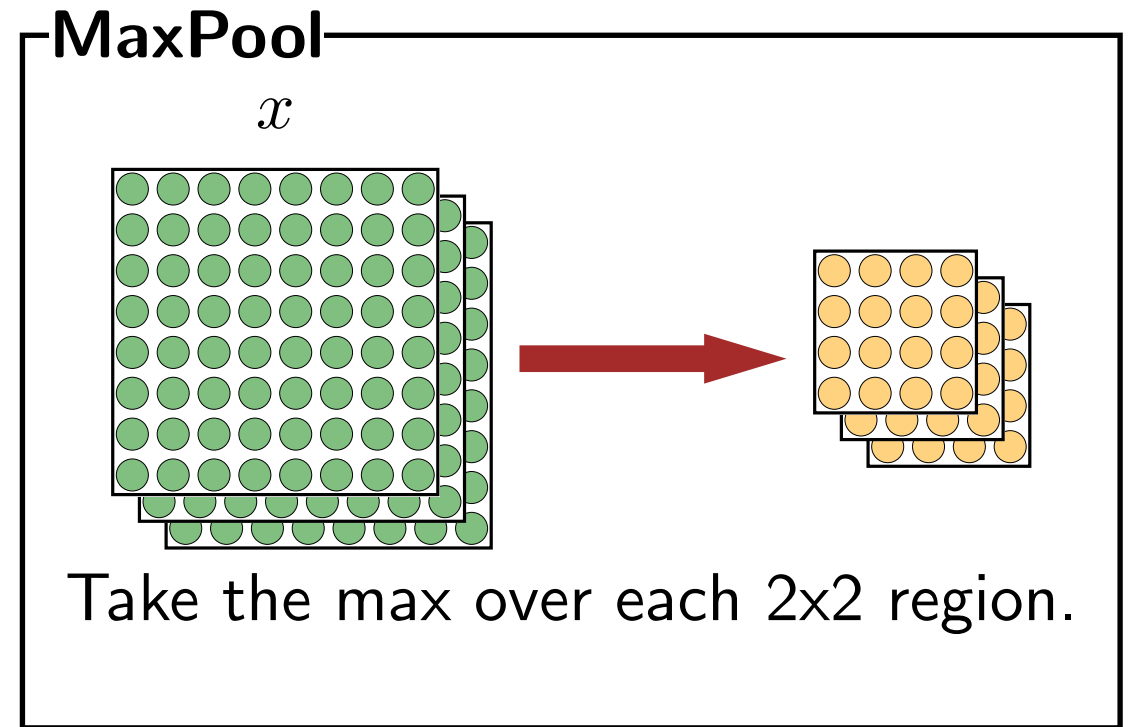
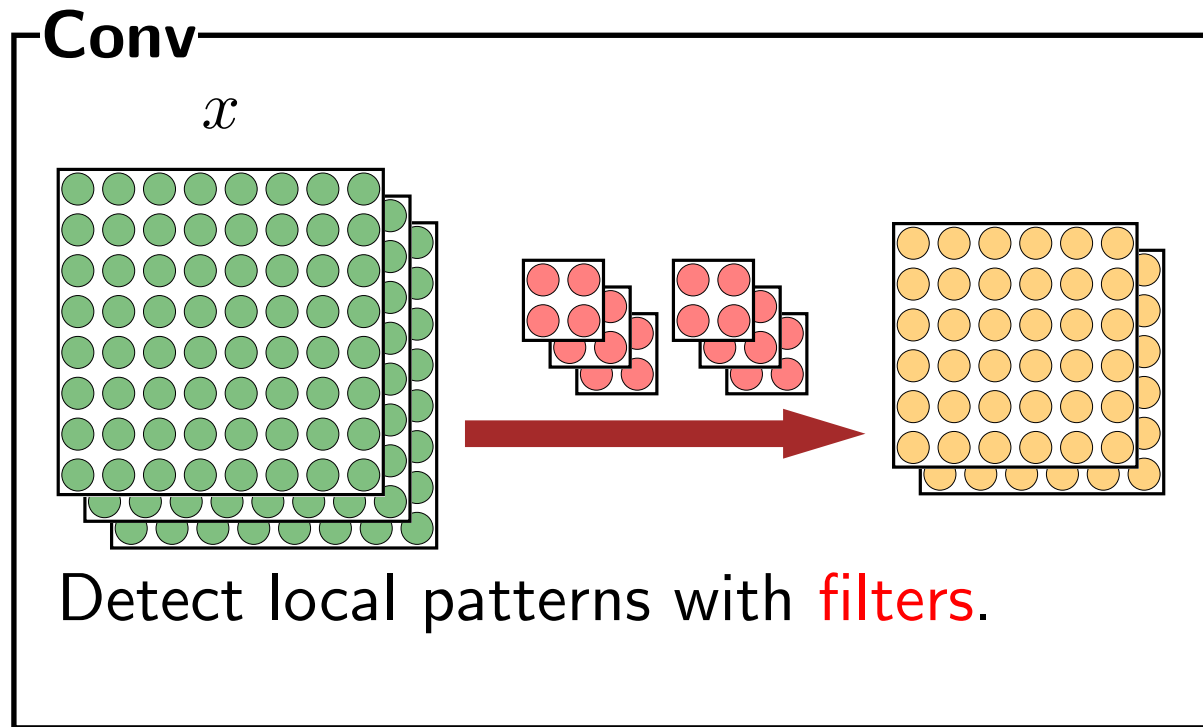
- Matrix is huge (depending on resolution of image)
- Does not capture the spatial structure (locality) of images

Convolutional neural networks



[Andrej Karpathy's demo]

Convolutional neural networks

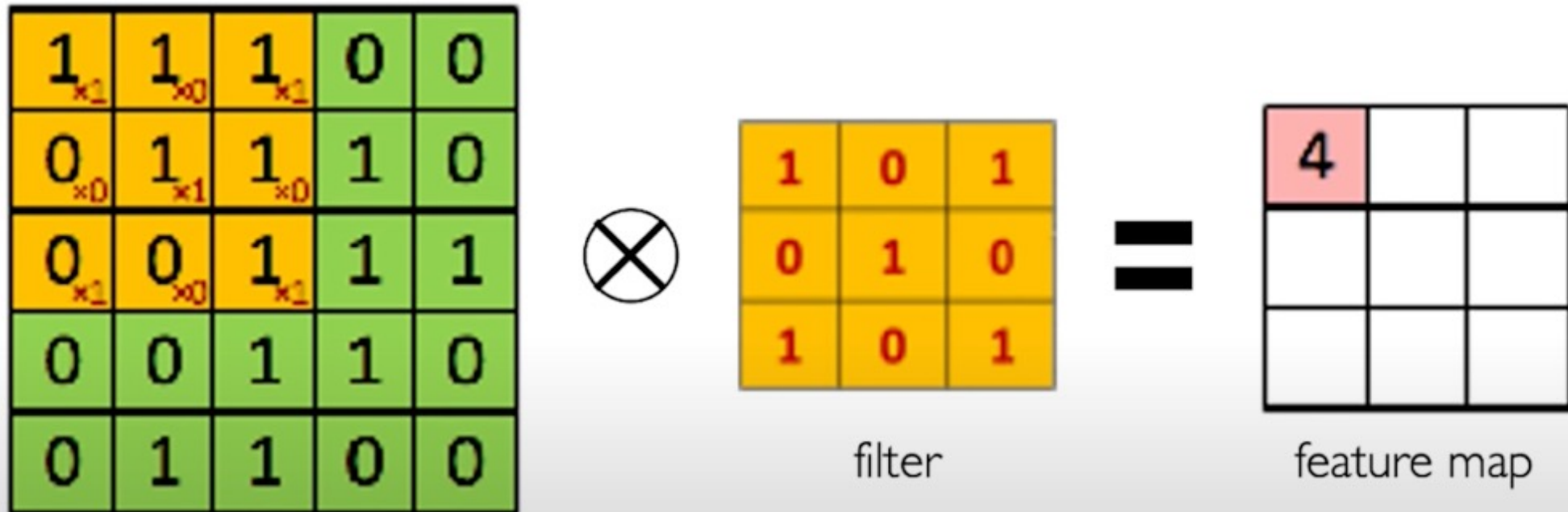


[Andrej Karpathy's demo]

$$\text{AlexNet}(x) = \text{FeedForward}^3(\text{MaxPool}(\text{Conv}^3(\text{MaxPool}(\text{Conv}(\text{MaxPool}(\text{Conv}(x)))))))$$

The Convolution Operation

We slide the 3x3 filter over the input image, element-wise multiply, and add the outputs:



The Convolution Operation

We slide the 3x3 filter over the input image, element-wise multiply, and add the outputs:

1	1	1	0	0
0	1	1	1	0
0	0	1 _{x1}	1 _{x0}	1 _{x1}
0	0	1 _{x0}	1 _{x1}	0 _{x0}
0	1	1 _{x1}	0 _{x0}	0 _{x1}



1	0	1
0	1	0
1	0	1

filter



4	3	4
2	4	3
2	3	4

feature map

Producing Feature Maps



Original



Sharpen

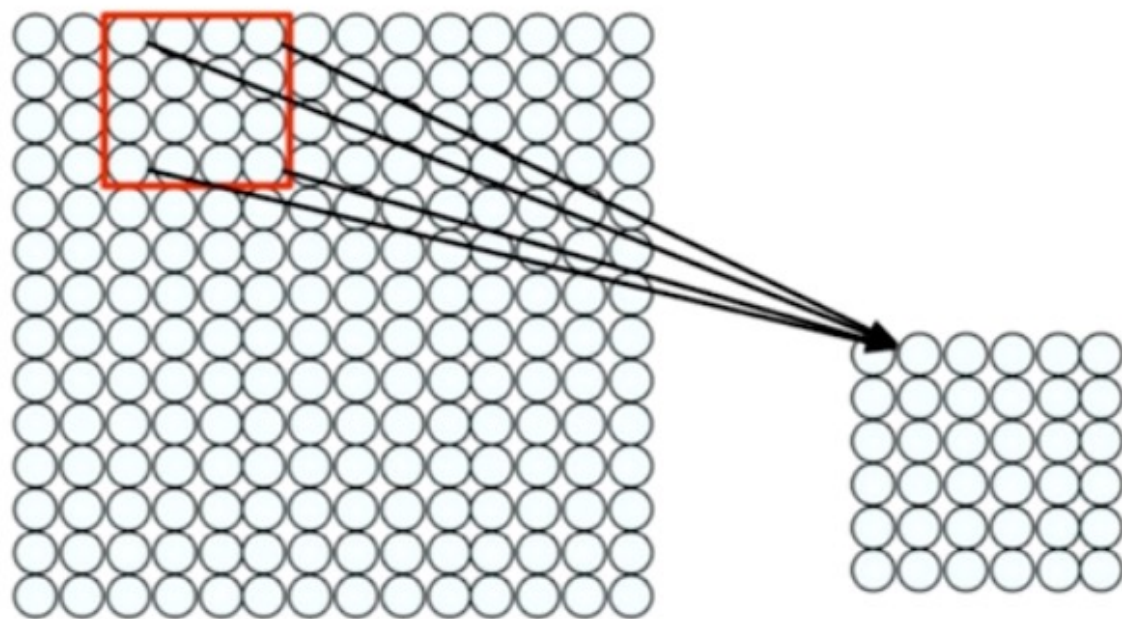


Edge Detect



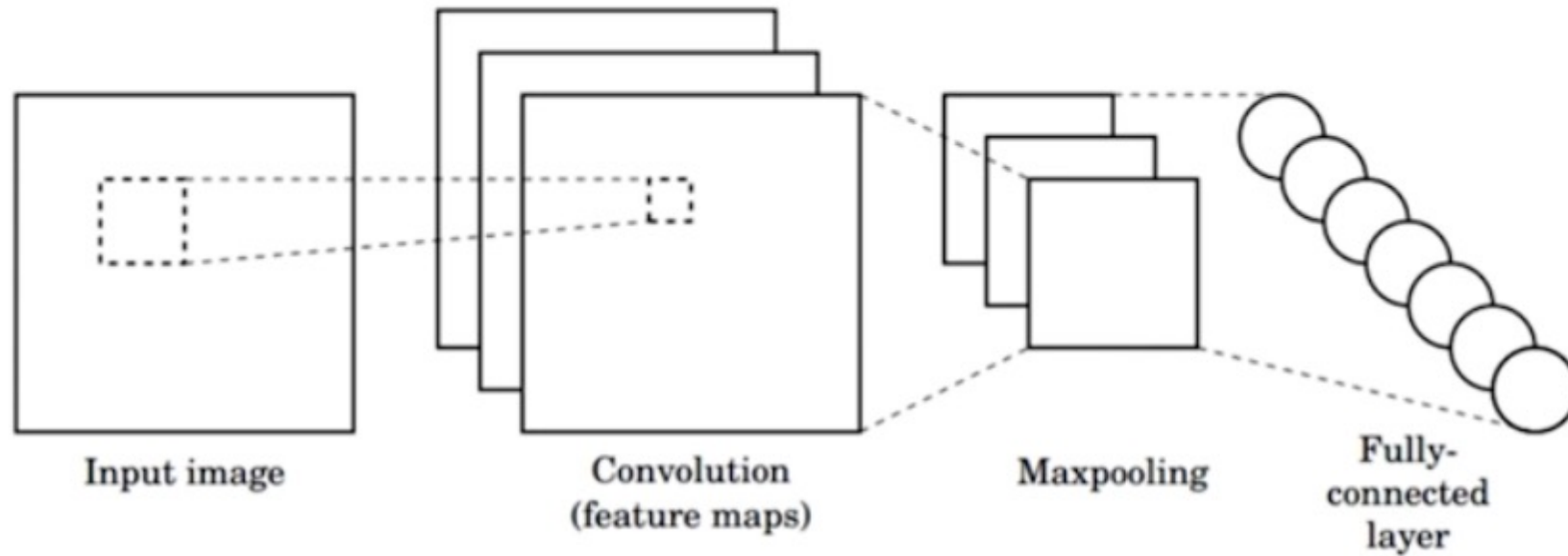
"Strong" Edge
Detect

Feature Extraction with Convolution




- 1) Apply a set of weights – a filter – to extract **local features**
- 2) Use **multiple filters** to extract different features
- 3) **Spatially share** parameters of each filter


CNNs for Classification




1. **Convolution:** Apply filters to generate feature maps.

 `tf.keras.layers.Conv2D`

2. **Non-linearity:** Often ReLU.

 `tf.keras.activations.*`

3. **Pooling:** Downsampling operation on each feature map.

 `tf.keras.layers.MaxPool2D`

Train model with image data.
Learn weights of filters in convolutional layers.

Pooling

x ↑

1	1	2	4
5	6	7	8
3	2	1	0
1	2	3	4

→ y

max pool with 2x2 filters
and stride 2

```
tf.keras.layers.MaxPool2D(  
    pool_size=(2,2),  
    strides=2  
)
```

6	8
3	4

- 1) Reduced dimensionality
- 2) Spatial invariance

Representing natural language

In meteorology, precipitation is any product of the condensation of atmospheric water vapor that falls under **gravity**. The main forms of precipitation include drizzle, rain, sleet, snow, **graupel** and hail... Precipitation forms as smaller droplets coalesce via collision with other rain drops or ice crystals **within a cloud**. Short, intense periods of rain in scattered locations are called “showers”.

What causes precipitation to fall?

gravity

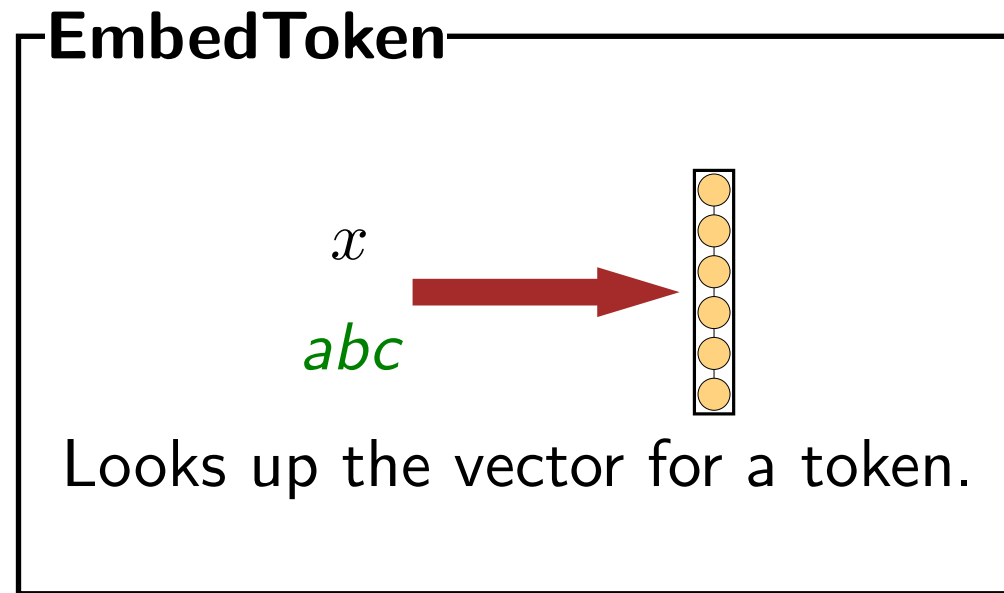
What is another main form of precipitation besides drizzle, rain, snow, sleet and hail?

graupel

Where do water droplets collide with ice crystals to form precipitation?

within a cloud

Embedding tokens



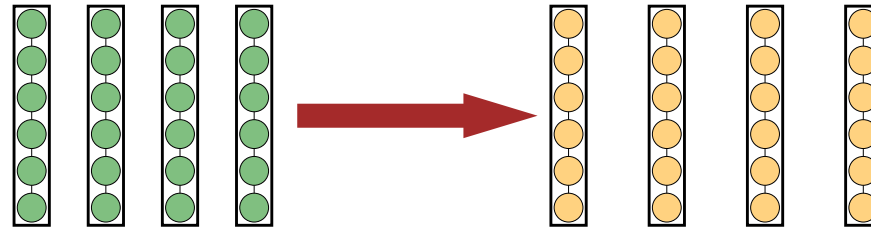
In meteorology, precipitation is any product of the condensation of atmospheric water vapor that falls under gravity.

Meaning of words/tokens depends on context...

Representing sequences

SequenceModel

x_1 x_2 x_3 x_4



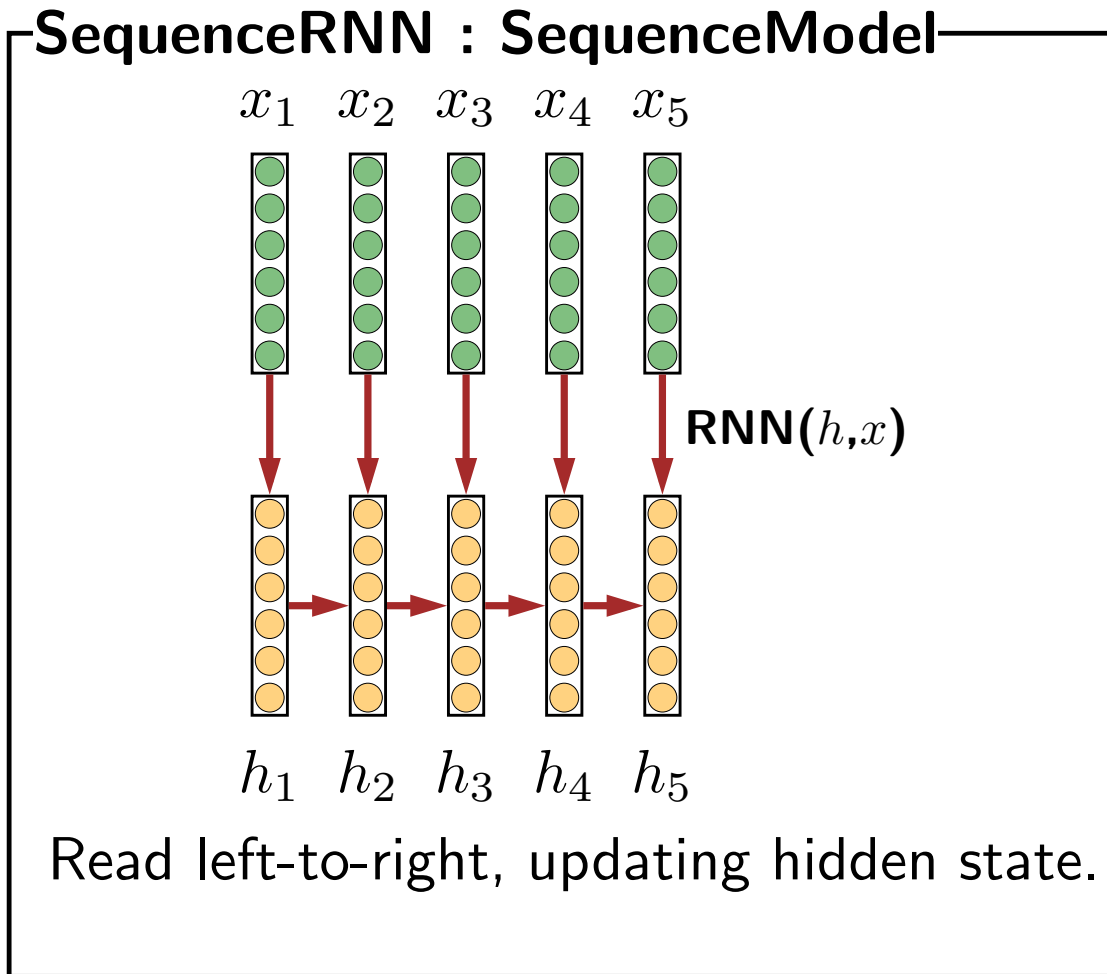
Process each element of a sequence with respect to other elements.

Two implementations:

- Recurrent neural networks
- Transformers

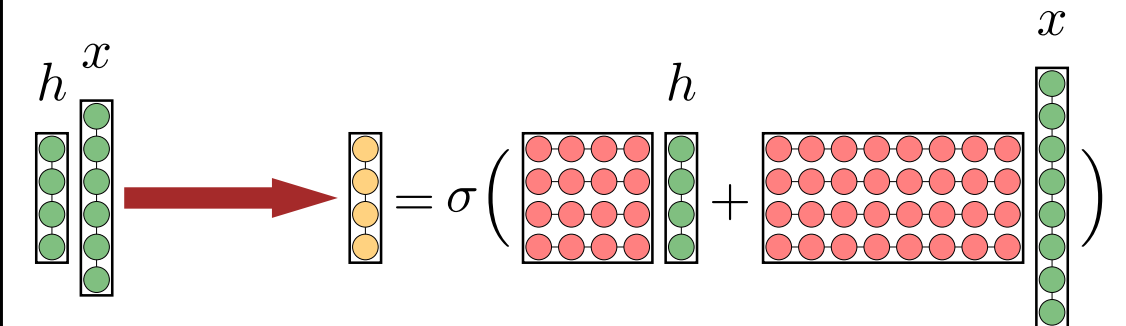
Recurrent neural networks

In meteorology, precipitation is any product of the condensation of atmospheric water vapor that falls under gravity.



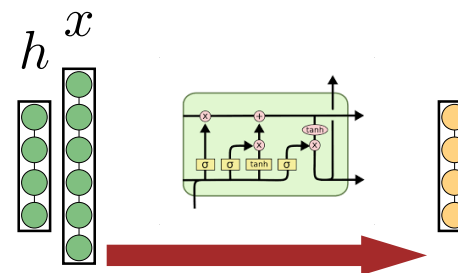
Recurrent neural networks

SimpleRNN : RNN



Update hidden state given a new input.

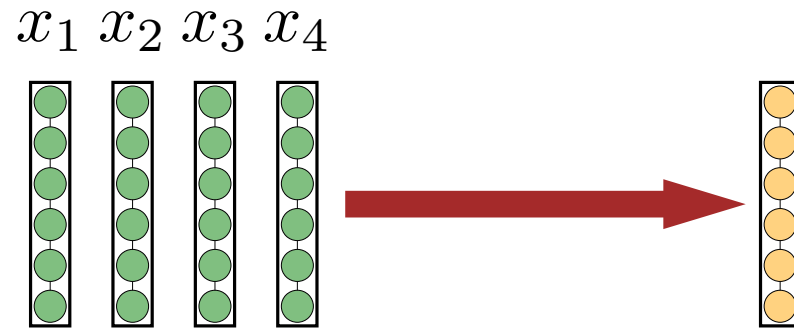
LSTM : RNN



Update hidden state given a new input without forgetting the past.

Collapsing to a single vector

Collapse



Summarize using one vector (first, last, or average).

Example text classification model:

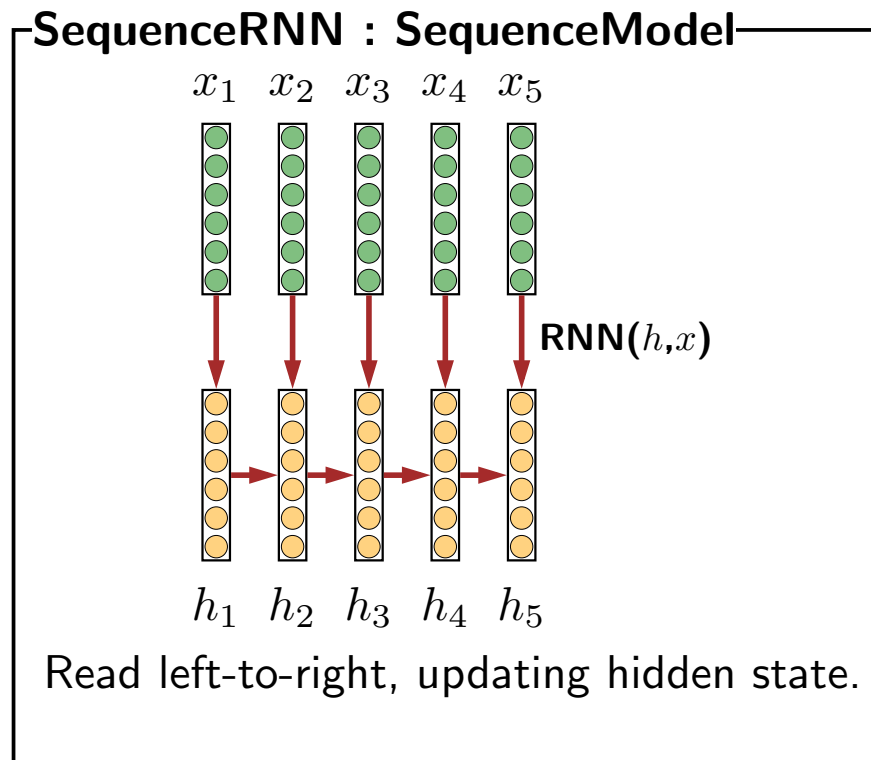
In meteorology, precipitation is any product of the condensation of atmospheric water vapor that falls under gravity.

$$\text{score} = \mathbf{w} \cdot \mathbf{Collapse}(\mathbf{SequenceModel}^3(\mathbf{EmbedToken}(\mathbf{x})))$$

Long-range dependencies

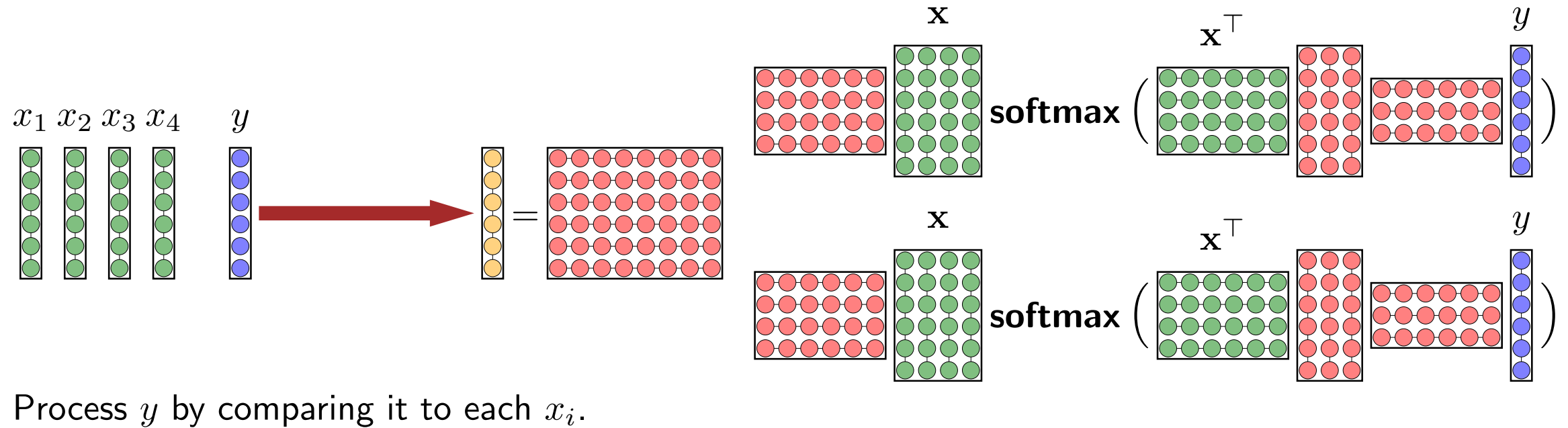
[CLS] What causes precipitation to fall? [SEP] In meteorology, precipitation is any product of the condensation of atmospheric water vapor that falls under gravity.

Problem: RNN (and ConvNets) are very local

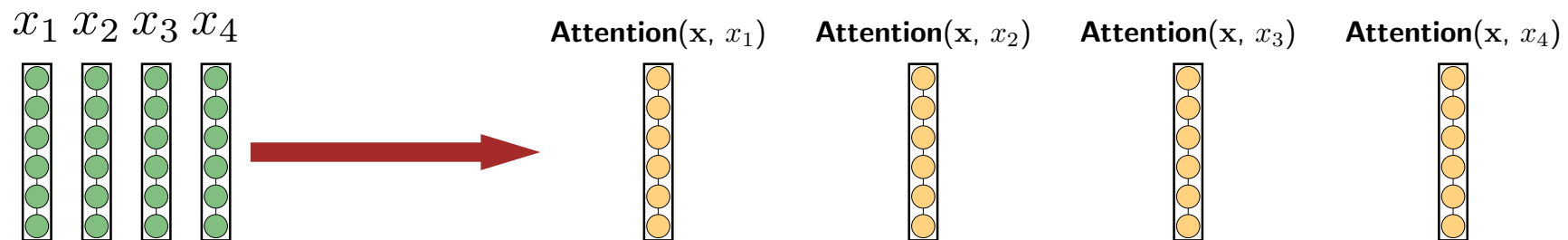


Attention mechanism

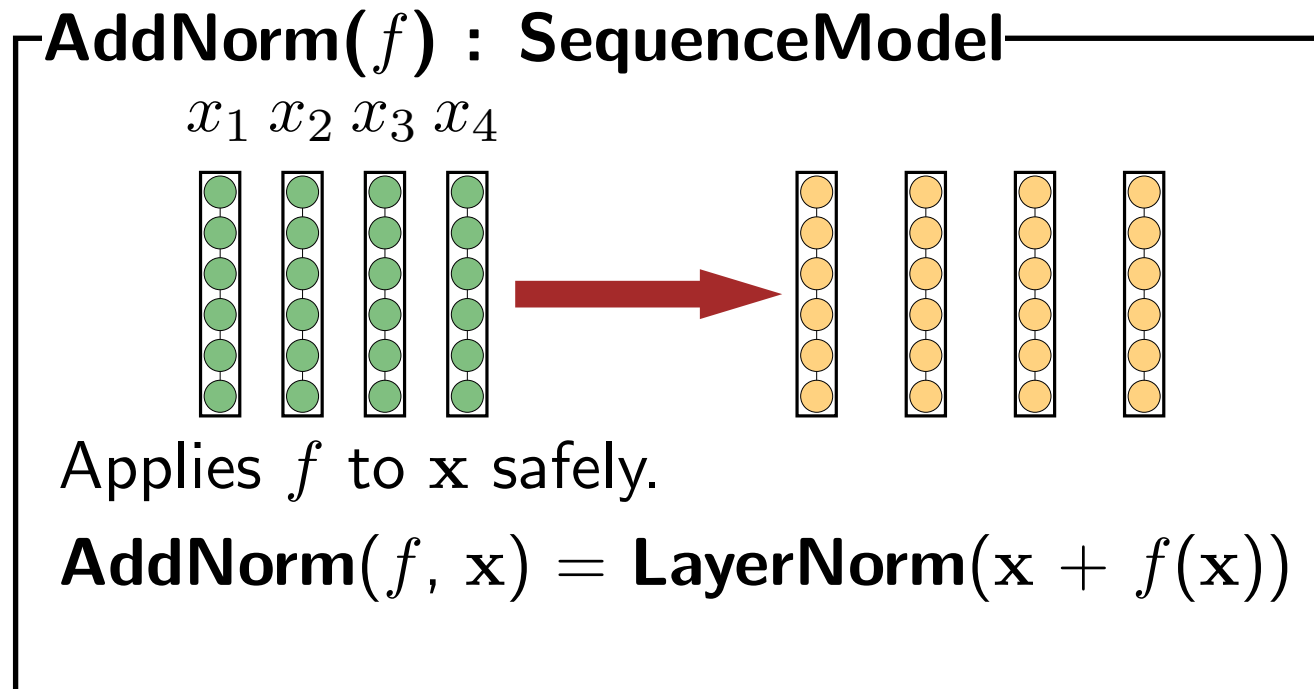
Attention



Attention : SequenceModel

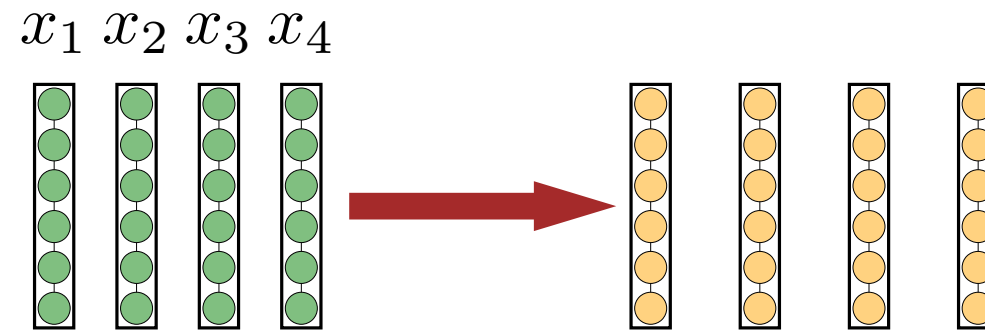


Layer normalization and residual connections



Transformer

TransformerBlock : SequenceModel

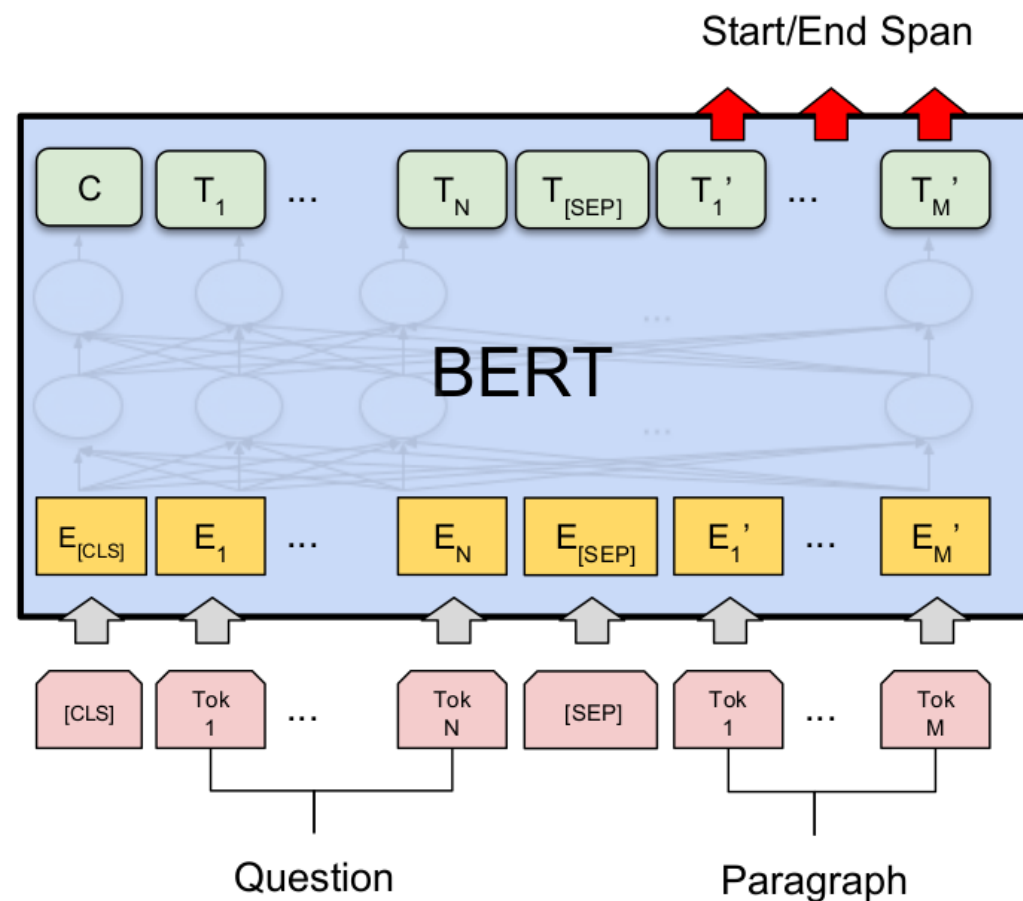


Processes each object x_i in context.

$$\mathbf{TransformerBlock}(\mathbf{x}) = \mathbf{AddNorm}(\mathbf{FeedForward}, \mathbf{AddNorm}(\mathbf{Attention}, \mathbf{x}))$$



BERT

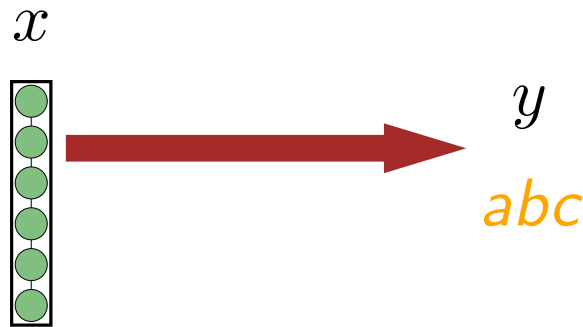


[CLS] What causes precipitation to fall? [SEP] In meteorology, precipitation is any product of the condensation of atmospheric water vapor that falls under gravity.

$$\text{BERT}(\mathbf{x}) = \text{TransformerBlock}^{24}(\text{EmbedToken}(\mathbf{x}))$$

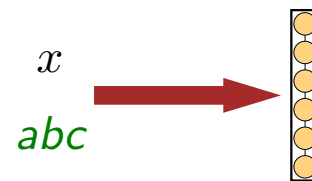
Generating tokens

GenerateToken



Generate token y based on x . **EmbedToken**(y).

EmbedToken



Looks up the vector for a token.

Generating sequences

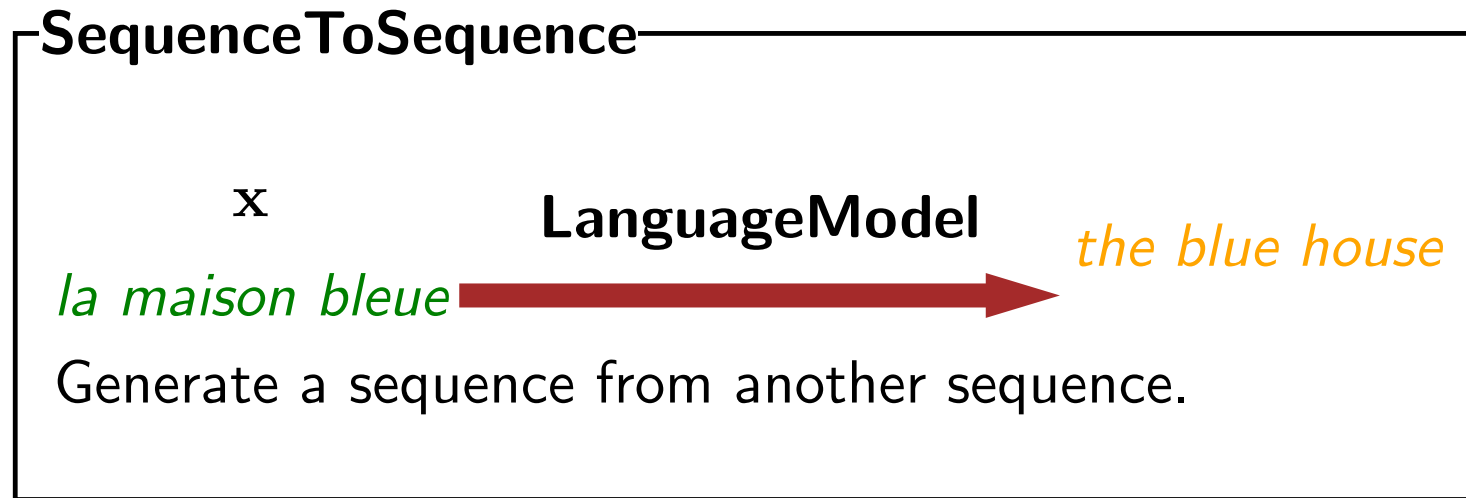
LanguageModel

x
the quick brown  *fox*

Generate next token in the sequence.

LanguageModel(x) = **GenerateToken**(**Collapse**(**SequenceModel**(**EmbedToken**(x))))

Sequence-to-sequence models



Applications:

- Machine translation: sentence to translation
- Document summarization: document to summary
- Semantic parsing: sentence to code



Summary

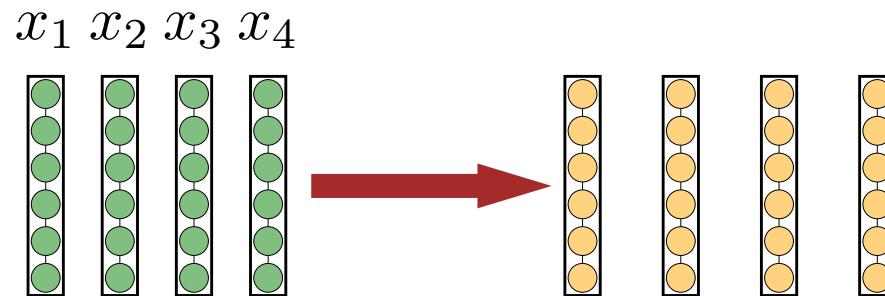
FeedForward Conv MaxPool

EmbedToken SequenceRNN SimpleRNN LSTM

Attention AddNorm TransformerBlock BERT

Collapse GenerateToken LanguageModel SequenceToSequence

SequenceModel



Process each element of a sequence with respect to other elements.