

# Robust Principal Component Analysis\*

Algorithm Optimization and Big Data

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**Abstract:** Paper is about detailed discussion and derived results on how to recover a low-rank matrix and sparse component of exactly by solving a larger matrix by Principle Component Pursuit. Initially a corrupted image with low rank matrix which does not contain all entries of matrix. The low rank matrix is converted to convex convenient matrix by minimizing weighted combination of nuclear norm and l1 norm. Paper discusses about different norms and their implication in resolving the exact matrix using Robust PCA method. Method has higher accuracy than conventional PCA method. there is comparison between different existing approaches and their applications in real life problems involving larger matrix like video surveillance, face recognition, Latent Semantic Indexing, Ranking and Collaborative Filters, etc.

## 1. Introduction

Principally, we used technique of Principle Component Analysis for reducing the dimensionality of a larger matrix. Where we define a large data matrix  $M$ , and know that it may be decomposed as

$$M = L_o + S_o$$

where  $L_o$  has low rank and  $S_o$  is sparse. Here we are unaware of low-dimensional column and row space of  $L_o$ . Also we don't know the location of non-zero entries of  $S_o$ . Results aim to generate low rank and sparse component of given data matrix efficiently and accurately. A provable and scalable solution to this question would surely boost the optimization and analysis of big data.

$$\begin{aligned} &\text{Minimize } \|M - L\| \\ &\text{subject to } \text{rank}(L) \leq k \end{aligned}$$

The singular value decomposition (SVD) given the fact that  $N_o$  is small and independent and identically distributed Gaussian

Some of the applications where data can be modeled into to separate low rank and sparse component are as follows

- Video Surveillance : Given a sequence of surveillance video frames, we often need to identify activities that stand out from the background.
- Face Recognition : Images of a convex, Lambertian surface under varying illuminations span a low-dimensional subspace.

- Latent Semantic Indexing : - Web search engines often analyze and index the content of an enormous corpus of document.
- Ranking and Collaborative Filter : - A document-versus-term matrix  $M$  whose entries typically encode the relevance of a term to a document such as the frequency it appears in the document. This idea is known as TFIDF (Term Frequency Inverse Document Frequency).

## 2. Approach to Robust PCA

The equation has two unknown and one known entity. To solve this equation we assume that  $\|M\|_* = \sum_i \sigma_i(M)$  denote the nuclear norm of matrix  $M$ . The equation becomes

$$\begin{aligned} &\text{minimize } \|L\| + \lambda \|S\| \\ &\text{subject to } L + S = M \end{aligned}$$

This will exactly recover low rank  $L_o$  and the sparse  $S_o$ . Also for linear increase in dimension  $L_o$  and with error up to constant fraction for all entries of  $S_o$ .

### 2.1. Separation of components

We need to impose that the low rank component is not sparse and the sparse matrix is not low rank. Otherwise it would be extremely difficult to recover the components. We consider  $L_o$  as  $L_o = U \Sigma V'$ . Then the incoherence condition with parameter  $\mu$  will be as follows:

$$\begin{aligned} \max_i \|U * e_i\|^2 &\leq \frac{\mu r}{n_1}, & \max_i \|V * e_i\|^2 &\leq \frac{\mu r}{n_2} \\ \|UV * \|_\infty &\leq \sqrt{\frac{\mu r}{n_1 n_2}} \end{aligned}$$

The above condition asserts that  $L_o$  and  $S_o$  are not orthogonal. Thus, for small values of  $\mu$ , the singular vectors are not sparse.

**Theorem - 1:** Suppose  $L_o$  is  $n \times n$  matrix. Fix any  $n \times n$  matrix  $\Sigma$  of signs. Suppose that the support set of  $\Omega S_o$  is uniformly distributed among all sets of cardinality  $m$ , and that  $\text{sgn}([S_o]_{ij}) = \Sigma_{i,j}$  for all  $(i, j) \in \Omega$ . Then, there is a numerical constant  $c$  such that with probability at least  $1 - cn^{-10}$ , Principle Component Pursuit with  $\lambda = \frac{1}{\sqrt{n}}$  is exact, i.e.  $L' = L_o$   $S' = S_o$  provided that.

$$\text{rank}(L_o) \leq \rho_r n \mu^{-1} (\log)^{-2} \text{ and } m \leq \rho_s n^2$$

$\sigma_r$  and  $\sigma_s$  are numerical constant and so  $L$  and  $S$  can be recovered with probability almost 1. It also works for large rank i.e.

order of  $n/(\log n)^2$ . The piece of randomness in our assumptions are locations of non zero entries of  $S_o$ , everything else is deterministic. Also the choice of  $\lambda = \frac{1}{\sqrt{n(1)}}$  is universal for  $n(1) = \max(n_1, n_2)$

## 2.2. Grossly Corrupted Data

We assume that  $P_\Omega$  will be the orthogonal projection onto the linear space of matrices supported on  $P_\Omega \subset [n_1] \times [n_2]$

$$P_\Omega = \begin{cases} X_{i,j}, & (i,j) \in \Omega. \\ 0, & (i,j) \notin \Omega. \end{cases} \quad (1)$$

As we have only few entries of  $L_o + S_o$  which can be written as  $Y = P_{\Omega_{obs}}(L_o + S_o) = P_{\Omega_{obs}}L_o + S'_o$ . We have very few entries that are corrupted. Recovering  $L_o$  and  $S$  is only possible if we undersample but otherwise perfect data  $P_{\Omega_{obs}}L_o$

minimize  $\|L\|_* + \lambda \|S\|_1$   
 subjec to  $P_{\Omega_{obs}}L_o = (L + S) = Y$

**Theorem - 2:** Suppose  $L_o$  in  $n \times n$ , obeys the incoherence conditions that  $\Omega_{obs}$  is uniformly distributed among all sets of cardinality  $m$  obeying  $m = 0 : 1n^2$ . Suppose for simplicity, that each observed entry is corrupted with probability  $\tau$  independently of the others. Then, there is a numerical constant  $c$  such that with probability at least  $1 - cn^{-1}$ , Principle Component Pursuit with  $\lambda = \frac{1}{\sqrt{0.1n}}$  is exact, that is  $L' = L_o$  provided that

$$\text{rank}(L_o) \leq \sigma_r n(2)\mu^{-1}(\log n)^{-2}, \text{ and } \tau \leq \tau_s$$

So, perfect recovery from incomplete and corrupted entries is possible by convex programming. Here,  $\sigma_r$  and  $\sigma_s$  are positive numerical constants. For  $n_1 \times n_2$  matrices we take  $\lambda = \frac{1}{\sqrt{0.1n_1}}$  succeeds from  $m = 0.1 * n_1 * n_2$  corrupted entries with probability at least  $1 - cn^{-1}$  provided that  $\text{rank}(L_o) \leq \sigma_r n(2)\mu^{-1}(\log n(1))^{-2}$ . For  $\tau = 0$  we have pure matrix completion problem.

## 3. ARCHITECTURE OF THE PROOF

In this section, we provide the key steps for the proof of the above mentioned theorem.

### 3.1. An elimination theorem

Suppose the solution with input data  $M_0 = L_0 + S_0$  is unique and exact, and consider  $M_0^1 = L_0 + S_0^1$  where  $S_0^1$  is a trimmed version  $S_0$ . Then, the solution with input  $M_0^1$  is exact as well.

### 3.2. De-randomization

Suppose  $L_o$  obeys the conditions of Theorem 1 and that the locations of the nonzero entries of  $S_0$  follow the Bernoulli model, and the signs of  $S_0$  are independent and identically distributed. Then, if the PCP solution is exact with high probability, then it is also exact with at least the same probability for the model in which the signs are fixed and the locations are sampled from the Bernoulli model with

parameter  $\rho_s$

This theorem is convenient because to prove our main result, we only need to show that it is true in the case where the signs of the sparse component are random.

## 3.3. Dual Certificates

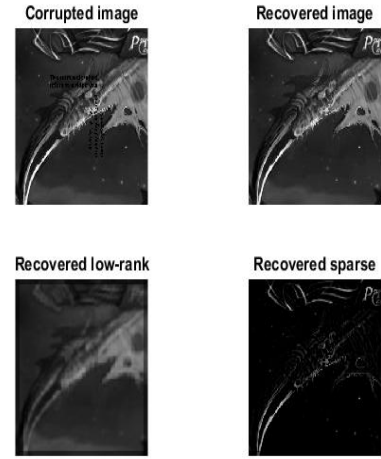
Assume that  $|P_\Omega P| < 1$ . With the standard notations,  $(L_0, S_0)$  is the unique solution if there is a pair  $(W, F)$  obeying

$$UV + W = \lambda(\text{sgn}(S_0) + F)$$

Assume  $|P_\Omega P| < 1/2$  and  $\lambda < 1$ . Then with the same notation,  $(L_0, S_0)$  is the unique solution if there is a pair  $(W, F)$  obeying

$$UV + W = \lambda(\text{sgn}(S_0) + F + P_\Omega D)$$

## 4. Simulation Output



## 5. Conclusion

For the available larger matrix with corrupted data we can deduce a complete matrix using convex optimization technique of Principal Component Pursuit. Robust PCA is now widely used in field of video surveillance, face recognition due to its higher accuracy to recover a corrupted matrix by weighted combination of nuclear norm and L1 norm. Thus, by results obtained it can be substantiated that Robust PCA is better technique for matrix recovery.

## References

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- [2] <http://perception.csl.illinois.edu/matrix-rank/samplecode.html>
- [3] <https://github.com/dlaptev/RobustPCA>
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