

# VBD-MODE

## Interview Exercise

Dr. Peter Fransson, Dr. Michael Opata, Dr. Stella Dafka

## 1 Instructions

As preparatory work for your interview, we ask that you write code covering all tasks listed below (see Subsection 1.1). The source code should be written in *Python*, *R*, or *Julia*. Additionally, please create a public repository on *GitHub* and upload your files. A link to the repository should be sent to us at **peter.fransson@iwr.uni-heidelberg.de** no later than **Monday, December 1, 14:00 CET**. If you have any questions, please contact us at **peter.fransson@iwr.uni-heidelberg.de**.

### 1.1 Tasks

- Implement Algorithms 1 and 2 (see Section 2).
- Declare the variables:  $\beta = 24$ ,  $\delta_E = 0.6$ ,  $\mu_E = 0.15$ ,  $\delta_J = 0.08$ ,  $\mu_J = 0.05$ ,  $\alpha = 0.003$ ,  $\omega = 0.5$ ,  $\mu_A = 0.1$ ,  $t_0 = 0$ ,  $t_{\text{end}} = 365$ ,  $h = 0.01$ , and the vector  $y_0 = [10, 0, 0]$ .
- Create a vector  $T$  where the elements follow the pattern  $t_0 + h(i - 1)$ , where  $i$  denotes the position of the element in  $T$ . Thus,  $t_0$  is the first element in  $T$ , and  $t_{\text{end}}$  should be the last.
- Create a **for**-loop which iterates over the integers 1 to  $t_{\text{end}}/h$ , where:
  1. In the first iteration, call the function *RK4* (Algorithm 1) with the function  $f$  (Algorithm 2),  $y_0$ , the first element of  $T$ , and  $h$  as input.
  2. In the second iteration, call the function *RK4* with the function  $f$ , the output from *RK4* in the first iteration, the second element of  $T$ , and  $h$  as input.
  3. The remaining iterations follow the same pattern.
- Save  $y_0$  together with the *RK4* outputs from the **for**-loop in a new variable  $Y$ .
- Create a plot with three subplots with the following specifications:

1. The first subplot should plot a curve where the x-axis values are given by  $T$  and the y-axis values are given by the corresponding first elements of  $y_0$  and the  $RK4$  outputs. The x- and y-axes should be labeled “T” and “E”, respectively.
2. The second subplot should plot a curve where the x-axis values are given by  $T$  and the y-axis values are given by the corresponding second elements of  $y_0$  and the  $RK4$  outputs. The x- and y-axes should be labeled “T” and “J”, respectively.
3. The third subplot should plot a curve where the x-axis values are given by  $T$  and the y-axis values are given by the corresponding third elements of  $y_0$  and the  $RK4$  outputs. The x- and y-axes should be labeled “T” and “A”, respectively.

## 2 Algorithms

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### Algorithm 1 RK4 Function

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1: function RK4( $f,y_n,t_n,h$ )
2:    $k_1 \leftarrow f(t_n, y_n)$                                       $\triangleright f$  is a function of  $t_n$  and  $y_t$ 
3:    $k_2 \leftarrow f(t_n + \frac{1}{2}h, y_n + \frac{1}{2}hk_1)$ 
4:    $k_3 \leftarrow f(t_n + \frac{1}{2}h, y_n + \frac{1}{2}hk_2)$ 
5:    $k_4 \leftarrow f(t_n + h, y_n + hk_3)$ 
6:    $y_{n+1} \leftarrow y_n + \frac{1}{6}h(k_1 + 2k_2 + 2k_3 + k_4)$ 
7:   return  $y_{n+1}$ 
8: end function

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### Algorithm 2 $f$ Function

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1: function  $f(t_n, y_n, \beta, \delta_E, \mu_E, \delta_J, \mu_J, \alpha, \omega, \mu_A)$ 
2:    $E \leftarrow y_n[1]$                                           $\triangleright$  First element of  $y_t$ 
3:    $J \leftarrow y_n[2]$ 
4:    $A \leftarrow y_n[3]$ 
5:    $dE \leftarrow \beta A - \delta_E E - \mu_E E$ 
6:    $dJ \leftarrow \delta_E E - \delta_J J - \alpha J^2 - \mu_J J$ 
7:    $dA \leftarrow \omega \delta_J J - \mu_A A$ 
8:    $dy \leftarrow [dE, dJ, dA]$                                       $\triangleright dy$  is a vector
9:   return  $dy$ 
10: end function

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