

Let $\dot{\vec{r}}$ denote derivative wrt. s and \vec{r}' denote derivative wrt. t . Let \vec{u} , \vec{p} and \vec{b} denote the tangent, normal and binormal vectors respectively. Firstly, note that

$$\vec{u} = \frac{\{\vec{r}'\}}{|\vec{r}'|} = \frac{\dot{\vec{r}} s'}{|\dot{\vec{r}}| s'}$$

Further, by the definition of the arclength s ,

$$\frac{ds}{dt} = \left| \frac{d\vec{r}}{dt} \right|$$

Instead of arbitrary t , put $t = s$:

$$\left| \frac{d\vec{r}}{ds} \right| = |\dot{\vec{r}}| = \frac{ds}{ds} = 1$$

So,

$\vec{u} = \dot{\vec{r}}$. This greatly simplifies things.

Now,

$$\begin{aligned}\vec{r}' &= s' \dot{\vec{r}} = s' \vec{u} \\ \vec{r}'' &= s'' \vec{u} + s'^2 \dot{\vec{u}}\end{aligned}\quad (1)$$

Also,

$$\kappa = |\dot{\vec{u}}| \quad \text{and} \quad \vec{p} = \frac{\dot{\vec{u}}}{|\dot{\vec{u}}|} = \frac{\dot{\vec{u}}}{\kappa}$$

So,

$$\vec{r}'' = s'' \vec{u} + \kappa s'^2 \vec{p} \quad (2)$$

Crossing (1) \times (2),

$$\vec{r}' \times \vec{r}'' = \underbrace{s' \vec{u} \times s'' \vec{u}}_0 + s' \kappa s'^2 \vec{u} \times \vec{p}$$

But,

$$\vec{b} = \vec{u} \times \vec{p} \quad \text{by definition.}$$

$$\Rightarrow \vec{r}' \times \vec{r}'' = \kappa s'^3 \vec{b}$$

$$\Rightarrow |\vec{r}' \times \vec{r}''| = \kappa s'^3$$

$$\kappa = \frac{|\vec{r}' \times \vec{r}''|}{|\vec{r}'|^3}$$

Now, \vec{b} is a vector of constant unit length. Hence, $\dot{\vec{b}}$ is perpendicular to \vec{b} . Using $\vec{b} = \vec{u} \times \vec{p}$, $\vec{b} \cdot \vec{u} = 0$ and $\vec{b} \cdot \vec{p} = \vec{b} \cdot \dot{\vec{u}} = 0$.

$$\begin{aligned}\Rightarrow (\vec{b} \cdot \vec{u})' &= 0 \\ \vec{b} \cdot \dot{\vec{u}} + \underbrace{\dot{\vec{b}} \cdot \vec{u}}_0 &= 0\end{aligned}$$

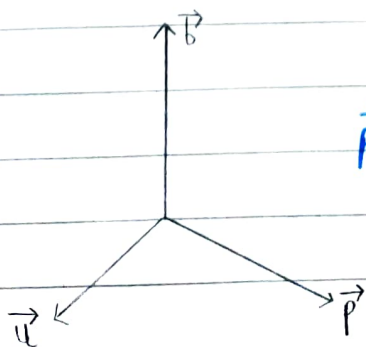
$$\Rightarrow \vec{b} \cdot \dot{\vec{u}} = 0$$

So, $\dot{\vec{b}}$ is perpendicular to both \vec{b} and \vec{u} , and hence

$$\dot{\vec{b}} = \lambda \vec{p}$$

By convention,

$$\dot{\vec{b}} = -\tau \vec{p}, \quad \text{where } \tau \text{ is the torsion.}$$



$\vec{p}, \vec{u}, \vec{b}$ form a right-handed system.

$$\begin{aligned}
 \text{Now, } \vec{p}' &= (\vec{b} \times \vec{u})' \\
 \vec{p}' &= \vec{b} \times \vec{u}' + (-\vec{u} \times \vec{b}') \\
 &= -\tau \vec{p} \times \vec{u} + \vec{b} \times \kappa \vec{p} \\
 \vec{p}' &= -\kappa \vec{u} + \tau \vec{b}
 \end{aligned}$$

The above three relations

$$\begin{aligned}
 \vec{u}' &= \kappa \vec{p} \\
 \vec{p}' &= -\kappa \vec{u} + \tau \vec{b} \\
 \vec{b}' &= -\tau \vec{p}
 \end{aligned}$$

are called the Frenet formulas. In the differential geometry, it is shown that the whole differential-geometric theory of curves is obtained from the Frenet formulas, whose solution shows that the "natural equations" $\kappa = \kappa(s)$, $\tau = \tau(s)$ determine a curve uniquely, except for its position in space.

$$\begin{aligned}
 \text{Now, } \tau &= -(\vec{u} \times \vec{p})' \cdot \vec{p} \\
 &= -\vec{p} \cdot (\underbrace{\vec{u}' \times \vec{p}}_0 + \vec{u} \times \vec{p}') \\
 &= -\vec{p} \cdot (\vec{u} \times \vec{p}')
 \end{aligned}$$

$$\tau = \begin{vmatrix} \vec{u} & \vec{p} & \vec{p}' \end{vmatrix}$$

$$\text{And } \vec{u} = \frac{\vec{r}'}{|\vec{r}'|}, \quad \vec{p} = \frac{\vec{u}'}{\kappa} = \frac{1}{\kappa} \vec{r}''$$

$$\Rightarrow \vec{p}' = \frac{1}{\kappa} \vec{r}''' + \left(\frac{1}{\kappa}\right)' \vec{r}''$$

$$\begin{aligned}
 \text{So, } \tau &= \begin{vmatrix} \vec{u} & \vec{p} & \vec{p}' \end{vmatrix} = \begin{vmatrix} \vec{r}' & \frac{1}{\kappa} \vec{r}'' & \frac{1}{\kappa} \vec{r}''' + \left(\frac{1}{\kappa}\right)' \vec{r}'' \end{vmatrix} \\
 &= \frac{1}{\kappa^2} \begin{vmatrix} \vec{r}' & \vec{r}'' & \vec{r}''' \end{vmatrix} + \begin{vmatrix} \vec{r}' & \frac{1}{\kappa} \vec{r}'' & \left(\frac{1}{\kappa}\right)' \vec{r}'' \end{vmatrix}
 \end{aligned}$$

The second term is zero as \vec{r}'' makes up two rows of the determinant.

$$\Rightarrow \tau = \frac{1}{k^2} (\vec{r} \cdot \vec{r} \cdot \vec{r}) = \tau(s)$$

To convert this to an arbitrary parameter 't', note that

$$\dot{\vec{r}} = \frac{1}{s'} \vec{r}'$$

$$\ddot{\vec{r}} = \frac{1}{s'} \left(\frac{\vec{r}''}{s'} - \frac{\vec{r}'}{s'^2} \right)$$

something that makes two rows of a det. equal, hence discarded.

Similarly, $\ddot{\vec{r}} = \frac{\vec{r}'''}{s'^3} + \dots$

$$\text{So, } \tau = \frac{1}{k^2} \left(\frac{1}{s'} \vec{r}' \quad \frac{1}{s'^2} \vec{r}'' \quad \frac{1}{s'^3} \vec{r}''' \right)$$

$$= \frac{1}{k^2 s^6} (\vec{r}' \cdot \vec{r}'' \cdot \vec{r}''')$$

$$\tau(t) = \frac{(\vec{r}' \cdot \vec{r}'' \cdot \vec{r}''')}{|\vec{r}' \times \vec{r}''|^2}$$