

Jay D. Lamb

Computer Engineer

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Education

Montana State University

BS Computer Engineering

2005 – 2009

Bozeman, MT

Experience / Projects

Naval Undersea Warfare Center - Division Keyport

Submarine Undersea Defensive Systems In-Service Engineering Agent (ISEA)

Countermeasure Set, Acoustic MK 2 Lead Engineer

August 2016 – Present

Keyport, WA

- Lead engineer for acoustic submarine countermeasure system for active United States Navy defensive program currently installed on over 30 submarine platforms
- Responsible for lifecycle engineering support including technology refresh, obsolescence management, and new design in order to meet current and future fleet requirements
- Integral part of team comprised of logisticians, contract specialists, and fleet support personnel.
- Coordinate junior engineer support of countermeasure Launch Control Panel (LCP) including design/drawing reviews and operational certification testing prior to delivery to the fleet
- Worked with internal teams to proactively combat system obsolescence issues via lifetime buys, reverse engineering, and redesign

Naval Undersea Warfare Center - Division Keyport

Rapid Prototyping and Fabrication Design

Embedded Systems Engineer - Automated Tracking Analyzer Balancer System (ATABS)

January 2012 – August 2016

Keyport, WA

- Tasked with reverse engineering custom vibration analysis embedded test equipment that corrects rotor balance and tracking on fixed-wing and rotary-wing aircraft
- Designed software functions for conducting vibration analysis, rotor blade imbalance, and tip path tracking testing
- Wrote algorithms to produce adjustment recommendations based on inputs from external sensors (piezoelectric vibration sensor, optical tachometer, line-scan camera)
- Project deployed to a custom printed circuit board (PCB) designed around an Atmel AVR 32-bit microcontroller

Naval Acquisition Intern Program

Systems Planning, Research, Development, and Engineering (SPRDE) - Level 2

July 2009 – January 2012

Keyport, WA

- Completed a Defense Acquisition University program focused on systems acquisition and engineering
- Assisted programs at all stages of the acquisition lifecycle on engineering assignments lasting 3 to 6 months

Projects

Automated Tracking Analyzer Balancer System (ATABS)

- Project objective was to re-create a set of test equipment for correcting rotor balance and tracking on fixed-wing and rotary-wing aircraft

- Designed software to produce adjustment recommendations based upon inputs from external sensors (piezoelectric vibration sensor, optical tachometer, line-scan camera)
- Project deployed to a custom printed circuit board (PCB) based around an Atmel AVR 32-bit microcontroller
- Software written primarily in C, leveraging the Atmel Studio IDE and Atmel Software Framework

Countermeasure Launch Control Panel (LCP) Technology Refresh

- Engineer overseeing the upgrade of a submarine defensive system with a form, fit, function replacement
- Worked with internal teams to proactively combat system component obsolescence issues
- Conducted/coordinated testing of new equipment prior to delivery to the fleet

Skills

Embedded Hardware Analog and digital circuit design, schematic creation, PCB layout, PCB parts library creation, logical analysis, test hardware design

Programming Languages and Tools Assembly, C, C++, Arduino, VHDL, CMake, \LaTeX , Git, GCC, Vim, GMock, GTest, Google Protocol Buffers

Currently holds a Secret clearance. Previously held a Top Secret clearance with access to Sensitive Compartmented Information based on an Office of Personnel Management Single Scope Background Investigation/Periodic Review completed on 11/22/3333.