

# Matrix Condition & Introducing the Temperature Problem

**CS 111: Introduction to Computational Science**

Spring 2019      Lecture #6

Ziad Matni, Ph.D.

# Administrative

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- Homework #3 due next Monday

# Lecture Outline

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- More on Numerical Stability
  - The Matrix Condition Number
- The Temperature Problem and Sparse Matrices

# Numerical Stability

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- Forward and backward error are related by the **condition number**
  - We'll examine its calculation another time
  - You can use **numpy** to calculate it!
- Large condition number = the matrix is not numerically stable
  - Or, “ill-conditioned”
- Small condition number (closer to 1) = the matrix **is** numerically stable
  - Or, “well-conditioned”
- Usually, symmetrical and/or is normal matrices are “well-conditioned”

# Condition Number

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The condition number of matrix  $M$  is defined as:

$$\|M\| \times \|M^{-1}\|$$

*i.e. norm of  $M$  multiplied by the norm of the inverse of  $M$*

In Python, you can use the `.cond()` function in `linalg`:

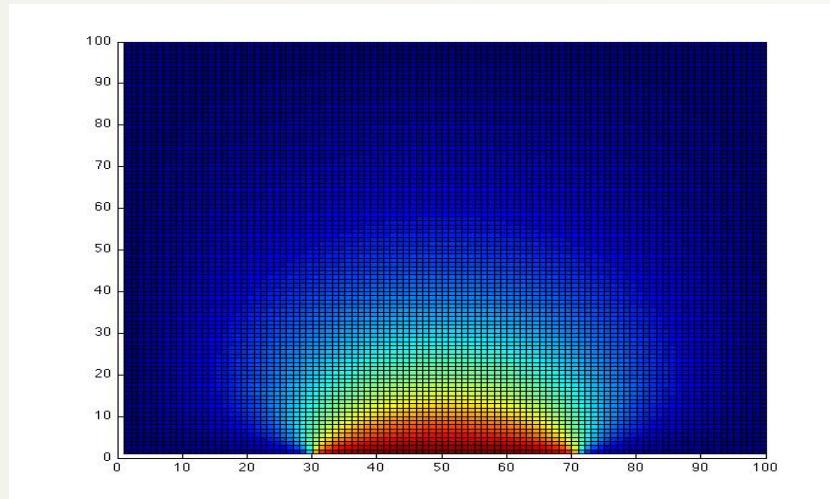
```
numpy.linalg.cond(M, 'fro')
```

Where '`fro`' indicates the Frobenius Norm, that is the norm defined as the square root of the sum of the absolute squares of its elements.



# The Temperature Problem

- A cabin in the snow
- Wall temperature is  $0^\circ$ , except for a radiator at  $100^\circ$
- What is the temperature at every point in the interior?



Matni,

# The Physics behind the Problem: Poisson's Equation

$$\nabla^2 u(x, y) \equiv \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y) = f(x, y)$$

for  $(x, y) \in R = \{ (x, y) \mid a < x < b, c < y < d \}$ , and

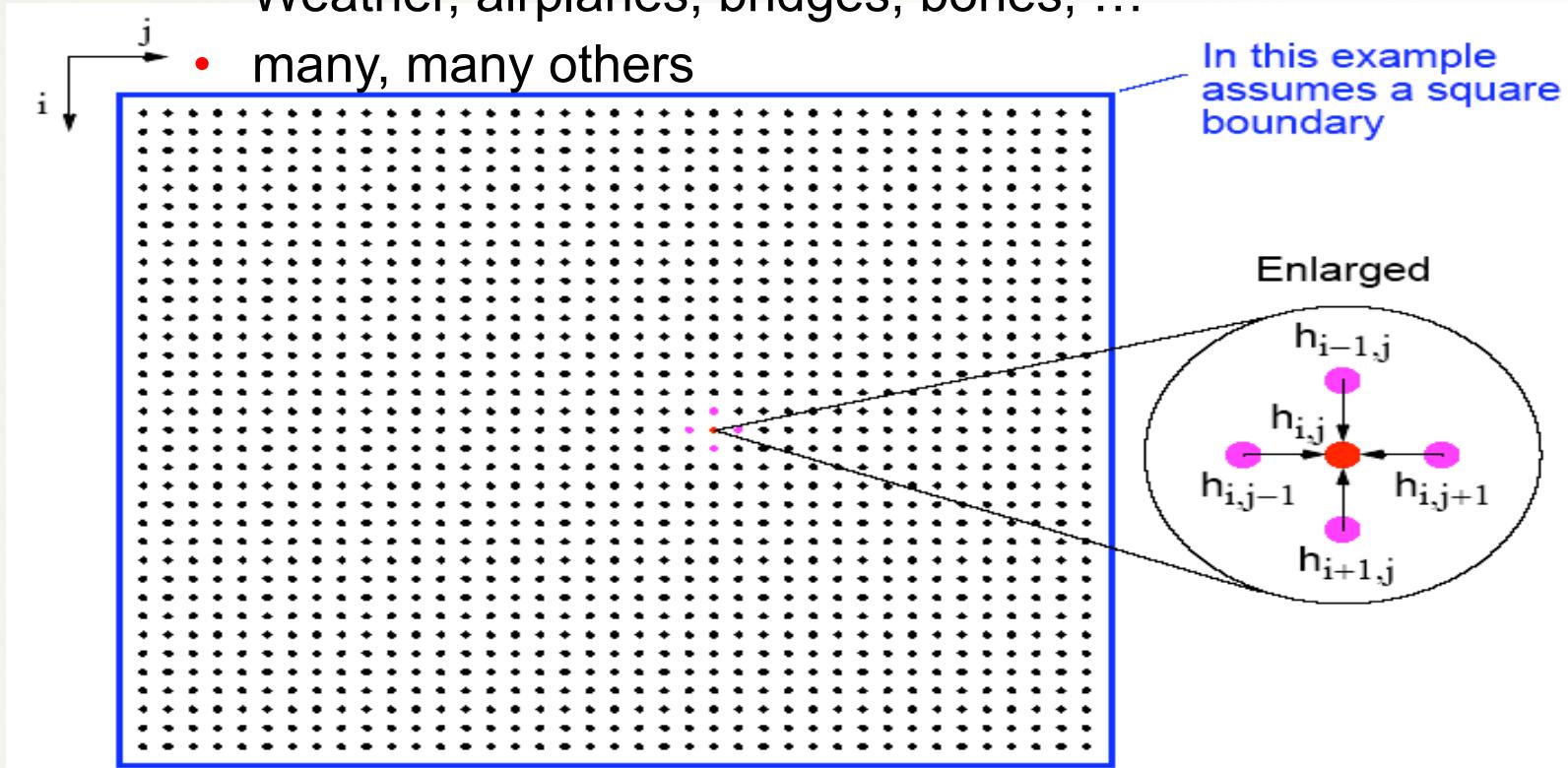
$$u(x, y) = g(x, y)$$

for  $(x, y)$  on the boundary of  $R$ .

But, this is a continuous math (Calculus)  
problem – how can we “translate” it into  
discrete math (Computation)?

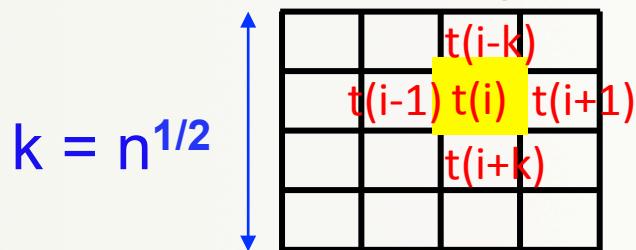
## Many Physical Models Use Stencil Computations

- PDE models of heat, fluids, structures, ...
- Weather, airplanes, bridges, bones, ...
- many, many others



# Model Problem: Solving Poisson's equation for temperature

- Discrete approximation to Poisson's equation (without going into details):

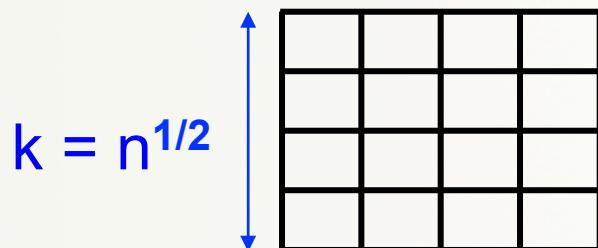


$$t(i) = \frac{1}{4} ( t(i-k) + t(i-1) + t(i+1) + t(i+k) )$$

- Intuitively:

Temperature at any point is  
the average of the temperatures at its surrounding points

# Model Problem: Solving Poisson's equation for temperature



- For each  $i$  from 1 to  $n$ , except on the boundaries:  
$$-t(i-k) - t(i-1) + 4*t(i) - t(i+1) - t(i+k) = 0$$
- $n$  equations in  $n$  unknowns:  $A*t = b$
- Each row of  $A$  has at most 5 non-zeros (the rest are zeros!)
- In three dimensions,  $k = n^{1/3}$  and each row has at most 7 non-zeros

## A Stencil Computation Solves a System of Linear Equations

- Solve  $\mathbf{Ax} = \mathbf{b}$  for  $\mathbf{x}$
- Matrix  $\mathbf{A}$ , right-hand side vector  $\mathbf{b}$ , unknown vector  $\mathbf{x}$
- $\mathbf{A}$  is *sparse*: most of the entries are 0

$\mathbf{A}$

Those equations with a boundary point on diagonal unnecessary for solution

*i*th equation

$a_{i,i-n} \quad a_{i,i-1} \quad a_{i,i} \quad a_{i,i+1} \quad a_{i,i+n}$

$$\mathbf{x} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{N-1} \\ x_N \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 0 \end{bmatrix}$$

*b* is where we would express boundary conditions

**Note for later use:**

This temperature matrix is a SPD type!

# To Python We Go!

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- Sparse vs Dense Matrix Representation
- Solving the temperature problem!
- Graphing it too!!

# Your To-Dos

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- Homework #3 – due **Monday, April 22<sup>nd</sup>**

</LECTURE>