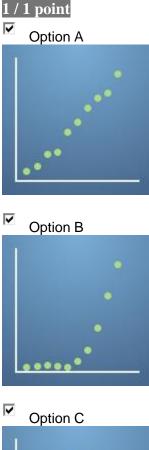
# Fitting a non-linear function

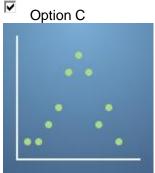
## **TOTAL POINTS 5**

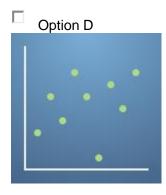
#### 1.Question 1

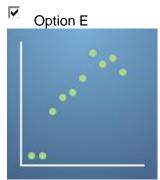
The previous quiz tested our knowledge of linear regression, and how we can begin to model sets of data. In the last video, we developed on this idea further, looking at the case for data that cannot be effectively modelled by linear approximations. As such, we were introduced to the nonlinear least squares method, as a way of fitting nonlinear curves to data.

In this question, we have a set of graphs highlighting different distributions of data. Select the appropriate graphs where the nonlinear least squares method can be adapted to provide an effective fit to this data.









### 2.Question 2

In the previous lecture, you were taken through the example of  $\chi^2$  and how it is important in utilising the sum of the differences and the least squares method. We were also introduced to the expression  $\chi^2 = \sum_{i=1}^{\infty} [y_i - y(x_i;a_k)]^2$ . For the parameter  $\chi^2$ , select all the statements below that are true.

## 1 / 1 point

The parameter  $\chi_2$  is the uncertainty value of our variables.

Taking the gradient of  $\chi^2$  and setting this to zero allows us to determine effective fitting parameters.

The parameter  $\chi$  is squared so that the effect of bad uncertainties are minimised.

When  $\chi_2$  is large, we have a good fit to our data.

#### 3. Question 3

In the previous lecture, we took the derivative of  $\chi^2\chi^2$  with respect to our fitting parameters, the form of which is shown below.

 $\partial a_j \partial \chi_2 = -2i = 1 \sum_n \sigma_i 2y_i - f(x_i,a) \partial a_j \partial f(x_i,a) for j = 1.....n$ Here we will define the matrix  $[\mathbf{Z}_j] = [\mathbf{Z}_j] = \partial a_j \partial f(x_i,a)$ 

Assuming  $f(x_i,a)=a_1x^3-a_2x^2+e^{-a_3x}$ , select the option that correctly shows the partial differentiation for this function.

# 1 / 1 point

 $\partial f / \partial a_1 = x^3, \, \partial f / \partial a_2 = -x^2, \, \partial f / \partial a_3 = -xe^{-a_3x}$ 

#### 4.Question 4

In this question, we want to put our working knowledge of the partial differentiation of our functions and arrange this into the Jacobian. As a reminder, the Jacobian for the nonlinear least squares method will take the form:

$$J = [\partial ak\partial(\chi^2)] = [\partial(\chi^2)/\partial a_1, \partial(\chi^2)/\partial a_2].$$

For the equation  $y(x_i;a)=a_1(1-e^{\Lambda}-a_2x_{i2})$  and assuming  $\sigma^{\Lambda}2=1$ , select the correct Jacobian that should be evaluated for our fit function.

### 1 / 1 point

$$\partial(\chi^{\wedge}2) / \partial a_{1} = -2\sum_{i=1, n} [y_{i} - a_{1}(1 - e^{\wedge} - a_{2}x^{\wedge}_{i2})](1 - e^{\wedge} - a_{2}x^{\wedge}_{i2})$$
$$\partial(\chi^{2}) / \partial a_{2} = -2\sum_{i=1, n} [y_{i} - a_{1}(1 - e^{\wedge} - a_{2}x^{\wedge}_{i2})](a_{1}x_{i}^{\wedge}2e^{\wedge} - a_{2}x_{i}^{\wedge}2)$$

#### 5. Question 5

In this question, we will develop our idea of building the Jacobian further by looking at a function with more fitting parameters. The function below is of a Gaussian distribution with 4 fitting parameters  $(\sigma, x_p, I, b)$  which are to be used in the nonlinear least squares method.

$$y(x;\sigma,x_p,I,b)=b+\sigma 2\pi I \exp\{2\sigma_2-(x-x_p)_2\}$$

In the lectures, we also showed how to find  $\chi^2$  and how this forms the Jacobian shown below:

$$J=[\partial ak\partial(\chi_2)]=[\partial\sigma\partial(\chi_2),\partial x_p\partial(\chi_2),\partial I\partial(\chi_2),\partial b\partial(\chi_2)].$$
 where

$$\partial a_j \partial \chi_2 = -2_{i=1} \sum_n \sigma_{i2} y_i - y(x_i;a) \partial a_j \partial y(x_i;a)$$
 for  $j=1$ ..... $n$ 

For the Gaussian function above, determine the partial differential  $\partial y / \partial x_p$ 

### 1 / 1 point

$$\partial y / \partial x_p = (I\sigma^3(x-x_p)\exp\{-(x-x_p)^2/2\sigma^2\}) / \operatorname{sqrt}(2) \pi$$