Masters in Computer Science

Topics in Machine Learning and NN

(COMP-5011)

Group:

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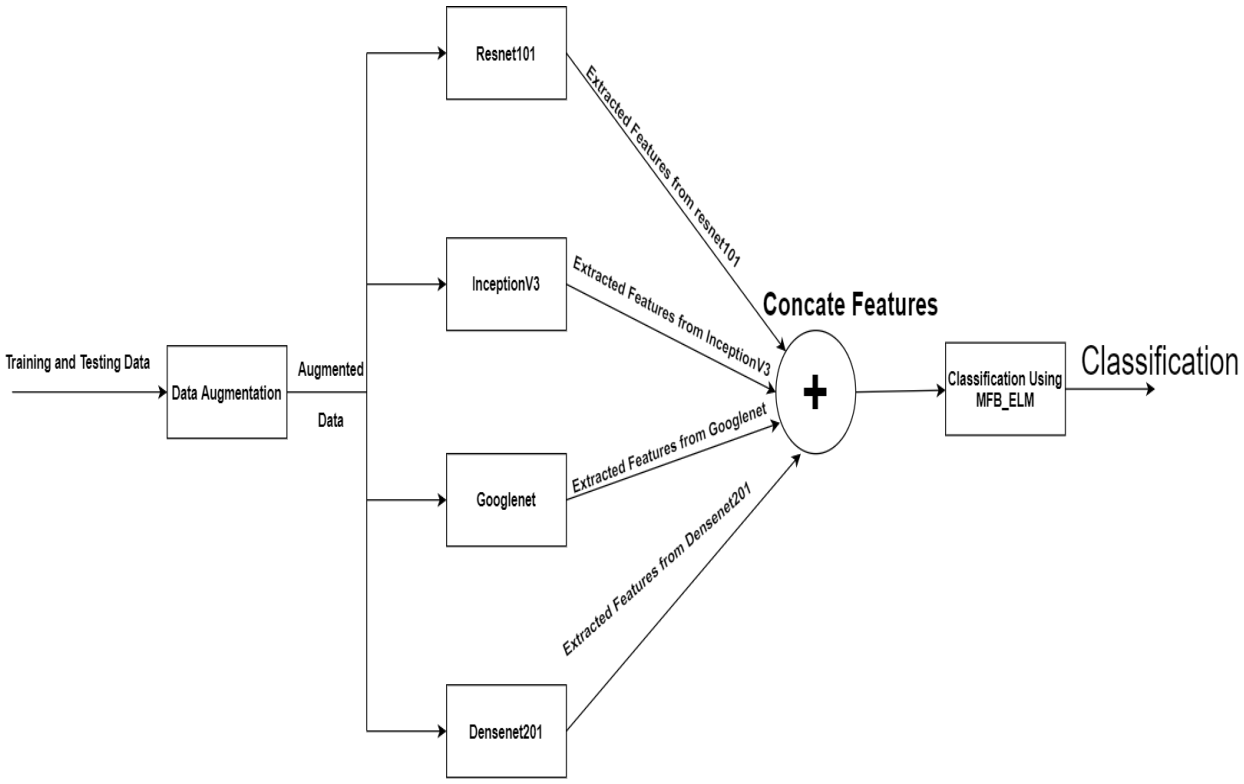
Project:

Task1: Object-centric Image recognition using Caltech101, Caltech256.

Methodology:



The Following structure or Network is used for classification for all three datasets. We obtained deep features from Resnet101, InceptionV3, Googlenet and Densenet201. These Deep Features are then Combined. I used MFB ELM is used as classifier and trained on using data and used for classification. The Output of the class is provided by the MFB_ELM and As per Project requirement I also test on Elm cuda.

1. Caltech101

Code:

```
tic
% define  folder
Folder = fullfile('C:\Users\Neel\Desktop\DLProject\data', 'caltech101');
disp('steps to output')

% Create ImageDatastore of the dataset for processing in Matlab.
rootFolder = fullfile(Folder, '101_ObjectCategories');
imds = imageDatastore(fullfile(rootFolder), 'LabelSource',
'foldernames','IncludeSubfolders',true);
clear Folder rootFolder;

% Split each label Using 30 images for training and rest for testing
[trainingSet, testingSet] = splitEachLabel(imds, 30);

% Load resnet
disp('1. Loading Pretrained Resnet');
 net = resnet101;

 %set imageSize according to DCNN first input layer
 imageSize = net.Layers(1).InputSize;


%Store Augmented training image into Imagedatastore
augImdstraining = augmentedImageDatastore(imageSize,trainingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%Store Augmented testing image into Imagedatastore
augImdstesting = augmentedImageDatastore(imageSize,testingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);
%resetgpu
gpuDevice(1)
```

```
% Get features from resnet
 disp('3. Loading Resnet train features');
 %Extract training features from resnet101 DCNN
 resnet_features_train =
activations(net,augImdstraining,'fc1000','MiniBatchSize',200);

 disp('4. Loading Resnet test features');
 %Extract testing features from resnet101 DCNN
 resnet_features_test =
activations(net,augImdstesting,'fc1000','MiniBatchSize',200);

 %Reshape training and testing features from resnet101
 resnet_features_train =
reshape(resnet_features_train,[1*1*1000,size(resnet_features_train,4)])' ;
 resnet_features_test =
reshape(resnet_features_test,[1*1*1000,size(resnet_features_test,4)])';

 disp('5. Loading Pretrained inceptionv3');
% Load inceptionv3
net = inceptionv3;

%set imageSize according to DCNN first input layer
imageSize = net.Layers(1).InputSize;

%Store Augmented training image into Imagedatastore
augImdstraining = augmentedImageDatastore(imageSize,trainingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%Store Augmented testing image into Imagedatastore
augImdstesting = augmentedImageDatastore(imageSize,testingSet, ...
   'ColorPreprocessing','gray2rgb' ,'DataAugmentation',imageAugmenter);

%resetgpu
gpuDevice(1)

disp('6. Loading inceptionv3 train features');
 %Extract training features from inceptionv3 DCNN
inceptionv3_features_train =
activations(net,augImdstraining,'avg_pool','MiniBatchSize',200);

disp('7. Loading inceptionv3 test features');
 %Extract testing features from inceptionv3 DCNN
inceptionv3_features_test =
activations(net,augImdstesting,'avg_pool','MiniBatchSize',200);

%Reshape training and testing features from inceptionv3
inceptionv3_features_train =
reshape(inceptionv3_features_train,[1*1*2048,size(inceptionv3_features_train,
4)])' ;
inceptionv3_features_test =
reshape(inceptionv3_features_test,[1*1*2048,size(inceptionv3_features_test,4)
])';

disp('8. Loading Pretrained googlenet');
% Load inceptionv3
```

```
% Load inceptionv3
net = googlenet;

%set imageSize according to DCNN first input layer
imageSize = net.Layers(1).InputSize;

%Store Augmented training image into Imagedatastore
augImdstraining = augmentedImageDatastore(imageSize,trainingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%Store Augmented testing image into Imagedatastore
augImdstesting = augmentedImageDatastore(imageSize,testingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);
%resetgpu
gpuDevice(1)

 disp('9. Loading googlenet train features');
 %Extract training features from googlenet DCNN
  googlenet_features_train = activations(net,augImdstraining,'loss3-
classifier','MiniBatchSize',200);

  disp('10. Loading googlenet test features');
  %Extract testing features from googlenet DCNN
googlenet_features_test = activations(net,augImdstesting,'loss3-
classifier','MiniBatchSize',200);

%Reshape training and testing features from googlenet
googlenet_features_train =
reshape(googlenet_features_train,[1*1*1000,size(googlenet_features_train,4)])
' ;
googlenet_features_test =
reshape(googlenet_features_test,[1*1*1000,size(googlenet_features_test,4)])';

disp('11. Loading Pretrained densenet201');
% Load densenet201
net = densenet201;

%set imageSize according to DCNN first input layer
imageSize = net.Layers(1).InputSize;

%Store Augmented training image into Imagedatastore
augImdstraining = augmentedImageDatastore(imageSize,trainingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%Store Augmented testing image into Imagedatastore
augImdstesting = augmentedImageDatastore(imageSize,testingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%resetgpu
gpuDevice(1)

 disp('12. Loading densenet train features');
 %Extract training features from densenet DCNN
```

```
densenet_features_train =
activations(net,augImdstraining,'fc1000','MiniBatchSize',200);

  disp('13. Loading densenet test features');
  %Extract testing features from densenet DCNN
densenet_features_test =
activations(net,augImdstesting,'fc1000','MiniBatchSize',200);

%Reshape training and testing features from densenet
densenet_features_train =
reshape(densenet_features_train,[1*1*1000,size(densenet_features_train,4)])'
;
densenet_features_test =
reshape(densenet_features_test,[1*1*1000,size(densenet_features_test,4)])';


disp('14. Combining the training features from All DCNN');
% Merge Resnet and googlenet deep features for training
x = horzcat(resnet_features_train,googlenet_features_train);
% Merge densenet and inceptionv3 deep features for training
w = horzcat(inceptionv3_features_train, densenet_features_train);
% Merge all deep features for training
new_F_train = horzcat(x,w);

disp('15. Combining the testing features from All DCNN');
% Merge Resnet and googlenet deep features for testing
y = horzcat(resnet_features_test,googlenet_features_test);
% Merge inceptionv3 and densenet deep features for testing
z = horzcat(inceptionv3_features_test, densenet_features_test);
% Merge all deep features for testing
new_F_test = horzcat(y,z);


%Get Train Label from training dataset
train_labels = grp2idx(trainingSet.Labels);

%Get Test Label from testing dataset
test_labels = grp2idx(testingSet.Labels);

disp('16. creating training and testing dataset for elm');
%Give labels to training and testing features
 training = horzcat(train_labels,new_F_train);
 testing = horzcat( test_labels,new_F_test);


C = 2^-10;
%disp('17. Classification using ELM');
%[TrainingTime, TestingTime, TrainingAccuracy, TestingAccuracy] =
ELM(training, testing, 1, 10000, 'sig', C);

%define Number subnetworknode for MFB_ELM
number_subnetwork_node =10;
```

```
disp('18. Classification using MFB_ELM')
[train_time,
train_accuracy,test_accuracy]=MFB_ELM(training,testing,1,1,'sig',number_subne
twork_node,C);
fprintf('Training Time = %f\n',train_time);
fprintf('Training Accuracy = %f\n',train_accuracy);
fprintf('Testing Accuracy = %f\n',test_accuracy);



timeElapsed = toc;
```

Results:

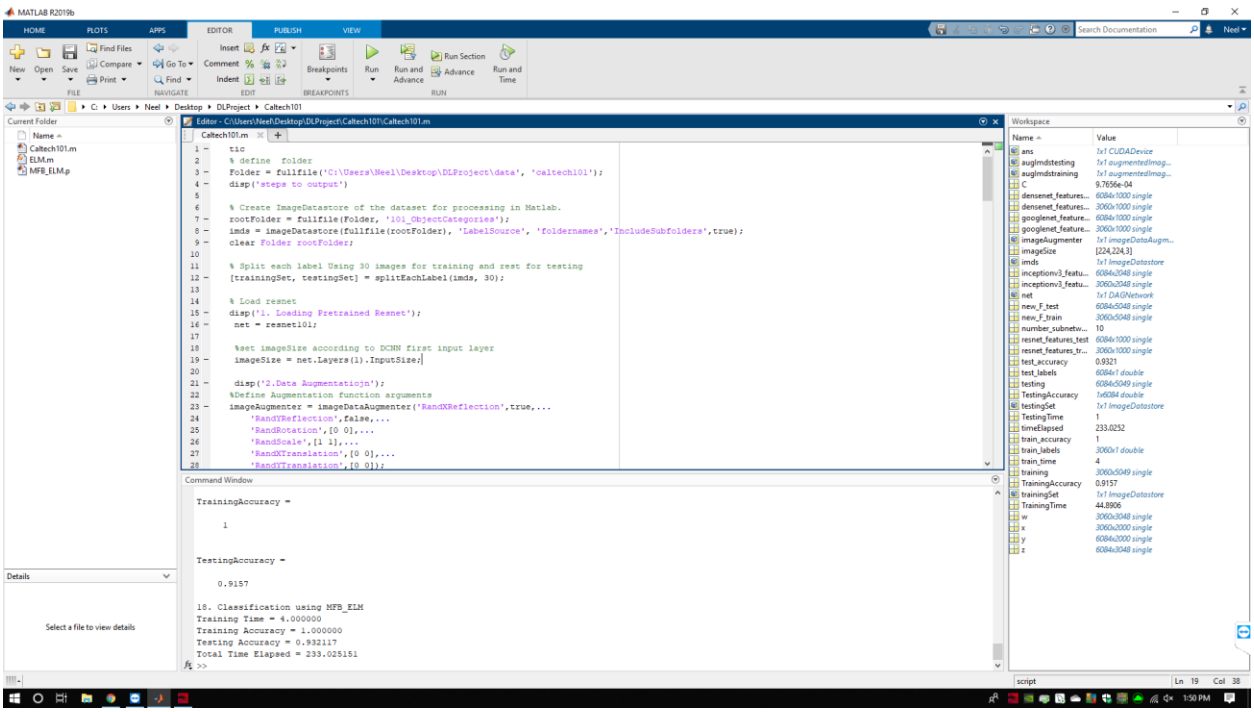
- **Top 1-Accuracy: 93.23%**
- **Accuracy in each Trial:**

Classifier	Run 1	Run 2	Run 3	Avg
ELM(Cuda)	0.9124	0.9159	0.9265	0.9265
ELM(CPU)	0.9157	0.9065	0.9246	0.9246
MFB_ELM	0.9321	0.9323	0.9330	0.9323

- **GPU: NVIDIA QUADRO RTX 8000 48GB**
- **Total time: = 22.1547minutes each run**

Outputs:

1.Run (Testing Acc: - 93.2117%)



1.Run (Testing Acc: - 91.2420%)

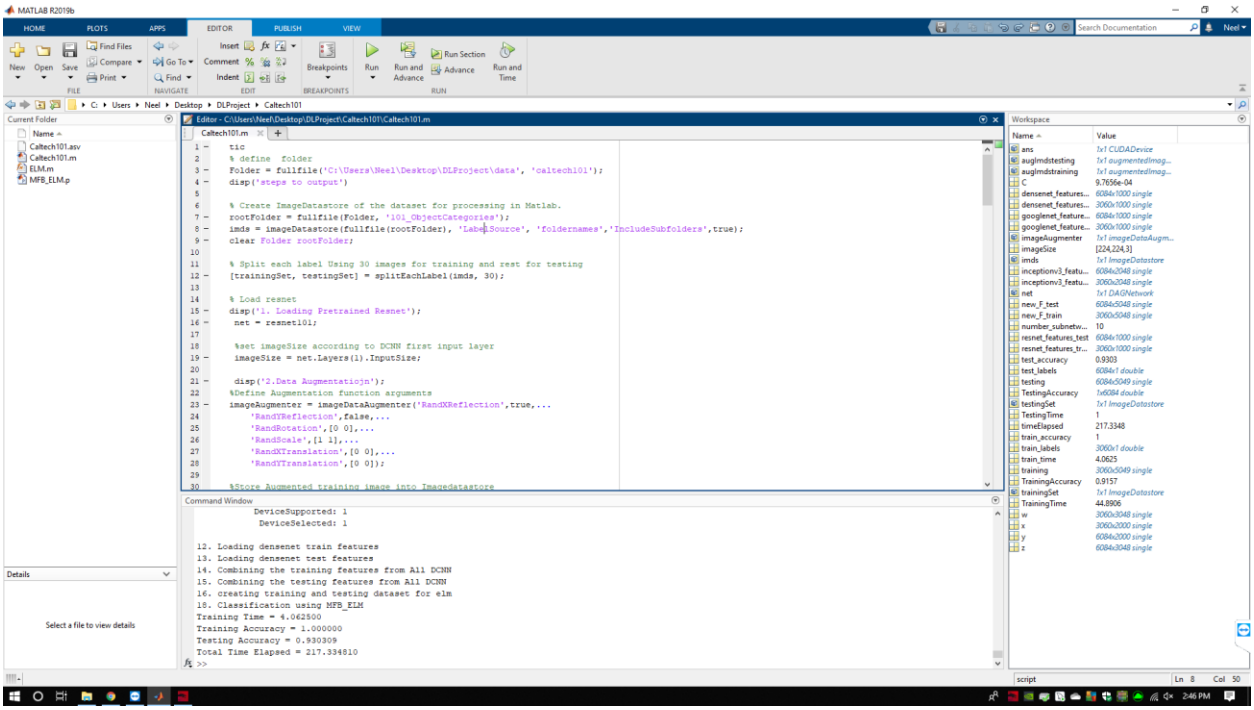
```
C:\Windows\System32\cmd.exe

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>nvcc Caltech101ELM.cu
Caltech101ELM.cu
MatAdd.cu
MatMul.cu
Matrixprint.cu
RandomGPU.cu
ReadCSV.cu
Pinv.cu
   Creating library Caltech101ELM.lib and object Caltech101ELM.exp

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>Caltech101ELM.exe
Training Accuracy is : 0.996847
Testing Accuracy is : 0.912420

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>
```

2.Run (Testing Acc: - 93.0309%)



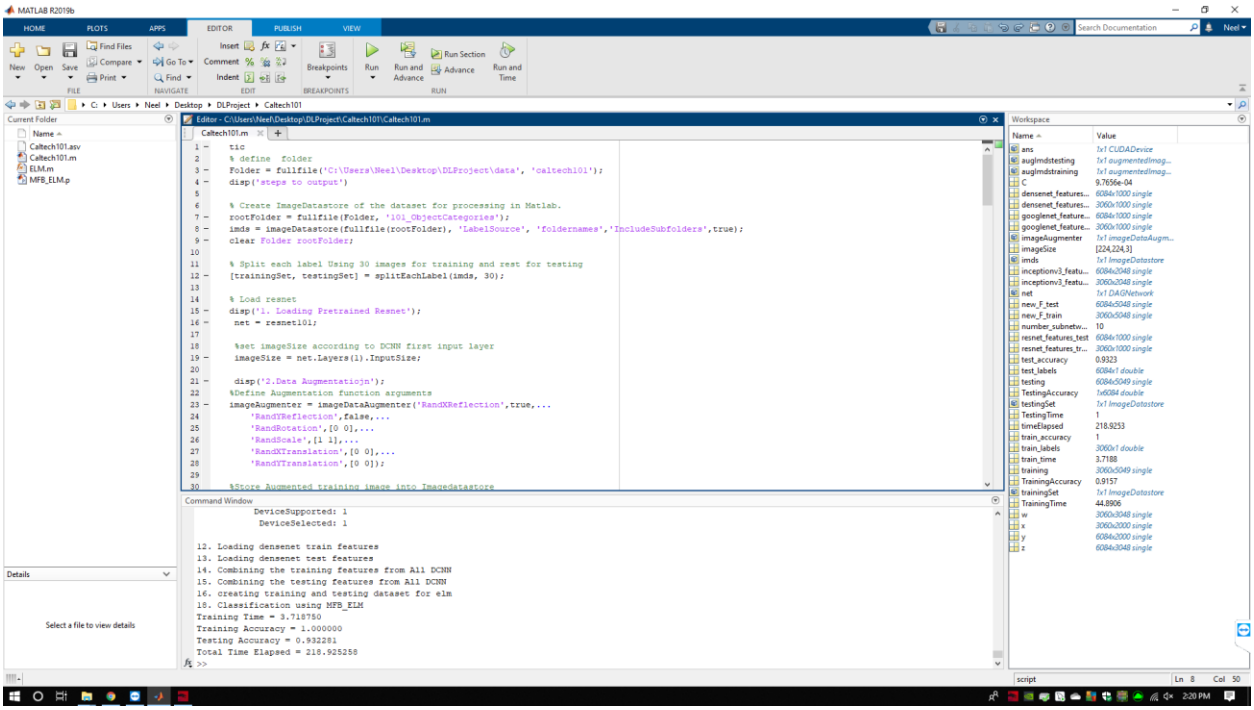
2.Run (Testing Acc: - 91.5896%)

```
C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>nvcc Caltech101ELM.cu MatA
Caltech101ELM.cu
MatAdd.cu
MatMul.cu
Matrixprint.cu
RandomGPU.cu
ReadCSV.cu
Pinv.cu
   Creating library Caltech101ELM.lib and object Caltech101ELM.exp

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>1
^C
C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>Caltech101ELM.exe
Training Accuracy is : 0.999557
Testing Accuracy is : 0.915896

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>
```

3.Run (Testing Acc: - 93.2281%)



3.Run (Testing Acc: - 92.6476%)

```
C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>nvcc Caltech101ELM
Caltech101ELM.cu
MatAdd.cu
MatMul.cu
Matrixprint.cu
RandomGPU.cu
ReadCSV.cu
Pinv.cu
   Creating library Caltech101ELM.lib and object Caltech101ELM.exp

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>Caltech101ELM.exe
Training Accuracy is : 0.998437
Testing Accuracy is : 0.926476

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech101>
```

2. Caltech256

Code:

```
tic
% define  folder
Folder = fullfile('C:\Users\Neel\Desktop\DLProject\data', 'caltech256');
disp('steps to output')

% Create ImageDatastore of the dataset for processing in Matlab.
rootFolder = fullfile(Folder, '256_ObjectCategories');
imds = imageDatastore(fullfile(rootFolder), 'LabelSource',
'foldernames','IncludeSubfolders',true);
clear Folder rootFolder;

% Split each label Using 30 images for training and rest for testing
[trainingSet, testingSet] = splitEachLabel(imds, 30);

% Load resnet
disp('1. Loading Pretrained Resnet');
 net = resnet101;

 %set imageSize according to DCNN first input layer
 imageSize = net.Layers(1).InputSize;


%Store Augmented training image into Imagedatastore
augImdstraining = augmentedImageDatastore(imageSize,trainingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%Store Augmented testing image into Imagedatastore
augImdstesting = augmentedImageDatastore(imageSize,testingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);
%resetgpu
gpuDevice(1)
```

```
% Get features from resnet
 disp('3. Loading Resnet train features');
 %Extract training features from resnet101 DCNN
 resnet_features_train =
activations(net,augImdstraining,'fc1000','MiniBatchSize',200);

 disp('4. Loading Resnet test features');
 %Extract testing features from resnet101 DCNN
 resnet_features_test =
activations(net,augImdstesting,'fc1000','MiniBatchSize',200);

 %Reshape training and testing features from resnet101
 resnet_features_train =
reshape(resnet_features_train,[1*1*1000,size(resnet_features_train,4)])' ;
 resnet_features_test =
reshape(resnet_features_test,[1*1*1000,size(resnet_features_test,4)])';

 disp('5. Loading Pretrained inceptionv3');
% Load inceptionv3
net = inceptionv3;

%set imageSize according to DCNN first input layer
imageSize = net.Layers(1).InputSize;

%Store Augmented training image into Imagedatastore
augImdstraining = augmentedImageDatastore(imageSize,trainingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%Store Augmented testing image into Imagedatastore
augImdstesting = augmentedImageDatastore(imageSize,testingSet, ...
   'ColorPreprocessing','gray2rgb' ,'DataAugmentation',imageAugmenter);

%resetgpu
gpuDevice(1)

disp('6. Loading inceptionv3 train features');
 %Extract training features from inceptionv3 DCNN
inceptionv3_features_train =
activations(net,augImdstraining,'avg_pool','MiniBatchSize',200);

disp('7. Loading inceptionv3 test features');
 %Extract testing features from inceptionv3 DCNN
inceptionv3_features_test =
activations(net,augImdstesting,'avg_pool','MiniBatchSize',200);

%Reshape training and testing features from inceptionv3
inceptionv3_features_train =
reshape(inceptionv3_features_train,[1*1*2048,size(inceptionv3_features_train,
4)])' ;
inceptionv3_features_test =
reshape(inceptionv3_features_test,[1*1*2048,size(inceptionv3_features_test,4)
])';

disp('8. Loading Pretrained googlenet');
```

```
% Load inceptionv3
net = googlenet;

%set imageSize according to DCNN first input layer
imageSize = net.Layers(1).InputSize;

%Store Augmented training image into Imagedatastore
augImdstraining = augmentedImageDatastore(imageSize,trainingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%Store Augmented testing image into Imagedatastore
augImdstesting = augmentedImageDatastore(imageSize,testingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);
%resetgpu
gpuDevice(1)

 disp('9. Loading googlenet train features');
 %Extract training features from googlenet DCNN
  googlenet_features_train = activations(net,augImdstraining,'loss3-
classifier','MiniBatchSize',200);

  disp('10. Loading googlenet test features');
  %Extract testing features from googlenet DCNN
googlenet_features_test = activations(net,augImdstesting,'loss3-
classifier','MiniBatchSize',200);

%Reshape training and testing features from googlenet
googlenet_features_train =
reshape(googlenet_features_train,[1*1*1000,size(googlenet_features_train,4)])
' ;
googlenet_features_test =
reshape(googlenet_features_test,[1*1*1000,size(googlenet_features_test,4)])';

disp('11. Loading Pretrained densenet201');
% Load densenet201
net = densenet201;

%set imageSize according to DCNN first input layer
imageSize = net.Layers(1).InputSize;

%Store Augmented training image into Imagedatastore
augImdstraining = augmentedImageDatastore(imageSize,trainingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%Store Augmented testing image into Imagedatastore
augImdstesting = augmentedImageDatastore(imageSize,testingSet, ...
   'ColorPreprocessing','gray2rgb','DataAugmentation',imageAugmenter);

%resetgpu
gpuDevice(1)

 disp('12. Loading densenet train features');
```

```
%Extract training features from densenet DCNN
  densenet_features_train =
activations(net,augImdstraining,'fc1000','MiniBatchSize',200);

  disp('13. Loading densenet test features');
  %Extract testing features from densenet DCNN
densenet_features_test =
activations(net,augImdstesting,'fc1000','MiniBatchSize',200);

%Reshape training and testing features from densenet
densenet_features_train =
reshape(densenet_features_train,[1*1*1000,size(densenet_features_train,4)])'
;
densenet_features_test =
reshape(densenet_features_test,[1*1*1000,size(densenet_features_test,4)])';


disp('14. Combining the training features from All DCNN');
% Merge Resnet and googlenet deep features for training
x = horzcat(resnet_features_train,googlenet_features_train);
% Merge densenet and inceptionv3 deep features for training
w = horzcat(inceptionv3_features_train, densenet_features_train);
% Merge all deep features for training
new_F_train = horzcat(x,w);

disp('15. Combining the testing features from All DCNN');
% Merge Resnet and googlenet deep features for testing
y = horzcat(resnet_features_test,googlenet_features_test);
% Merge inceptionv3 and densenet deep features for testing
z = horzcat(inceptionv3_features_test, densenet_features_test);
% Merge all deep features for testing
new_F_test = horzcat(y,z);


%Get Train Label from training dataset
train_labels = grp2idx(trainingSet.Labels);

%Get Test Label from testing dataset
test_labels = grp2idx(testingSet.Labels);

disp('16. creating training and testing dataset for elm');
%Give labels to training and testing features
 training = horzcat(train_labels,new_F_train);
 testing = horzcat( test_labels,new_F_test);


C = 2^-10;
% disp('17. Classification using ELM');
% [TrainingTime, TestingTime, TrainingAccuracy, TestingAccuracy] =
ELM(training, testing, 1, 10000, 'sig', C);

%define Number subnetworknode for MFB_ELM
number_subnetwork_node =10;
```

```
disp('18. Classification using MFB_ELM')
[train_time,
train_accuracy,test_accuracy]=MFB_ELM(training,testing,1,1,'sig',number_subne
twork_node,C);
fprintf('Training Time = %f\n',train_time);
fprintf('Training Accuracy = %f\n',train_accuracy);
fprintf('Testing Accuracy = %f\n',test_accuracy);



timeElapsed = toc;
```

Results:

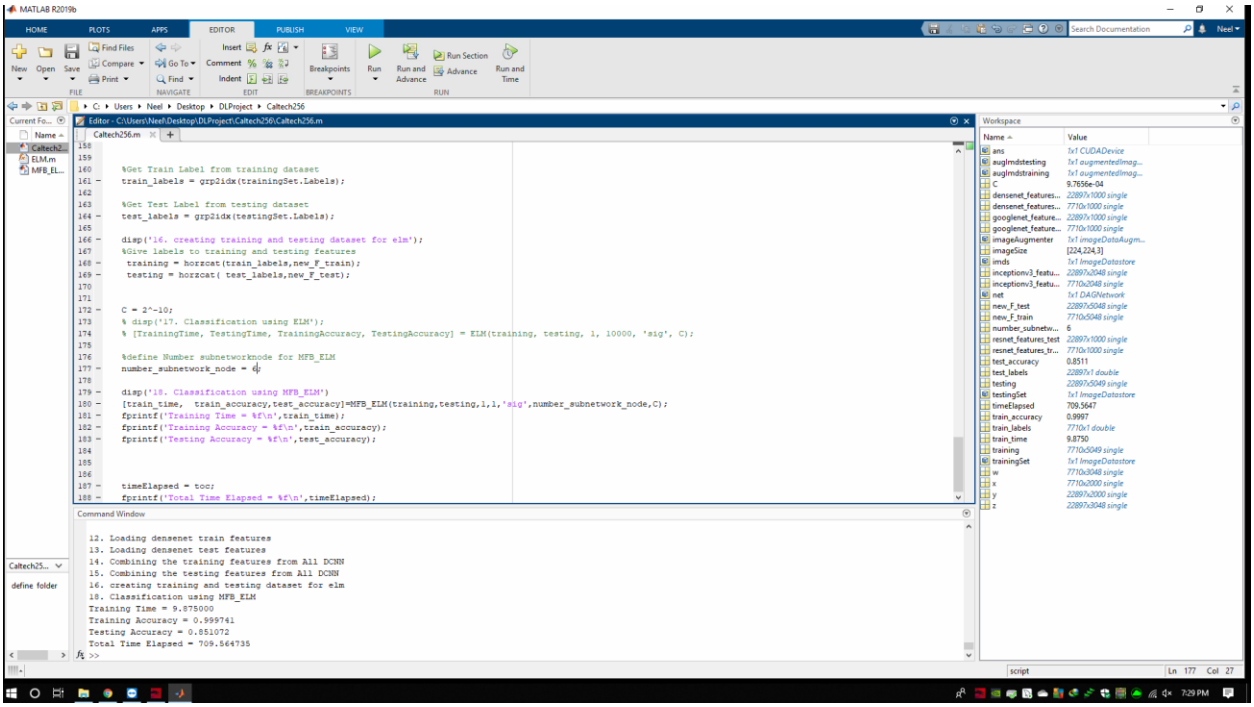
- **Top 1-Accuracy: 85.14%**
- **Accuracy in each Trial:**

Classifier	Run 1	Run 2	Run 3	Avg
ELM(Cuda)	0.8394	0.8457	0.8346	0.8457
ELM(CPU)	0.8248	0.8496	0.8392	0.8496
MFB_ELM	0.8511	0.8514	0.8505	0.8514

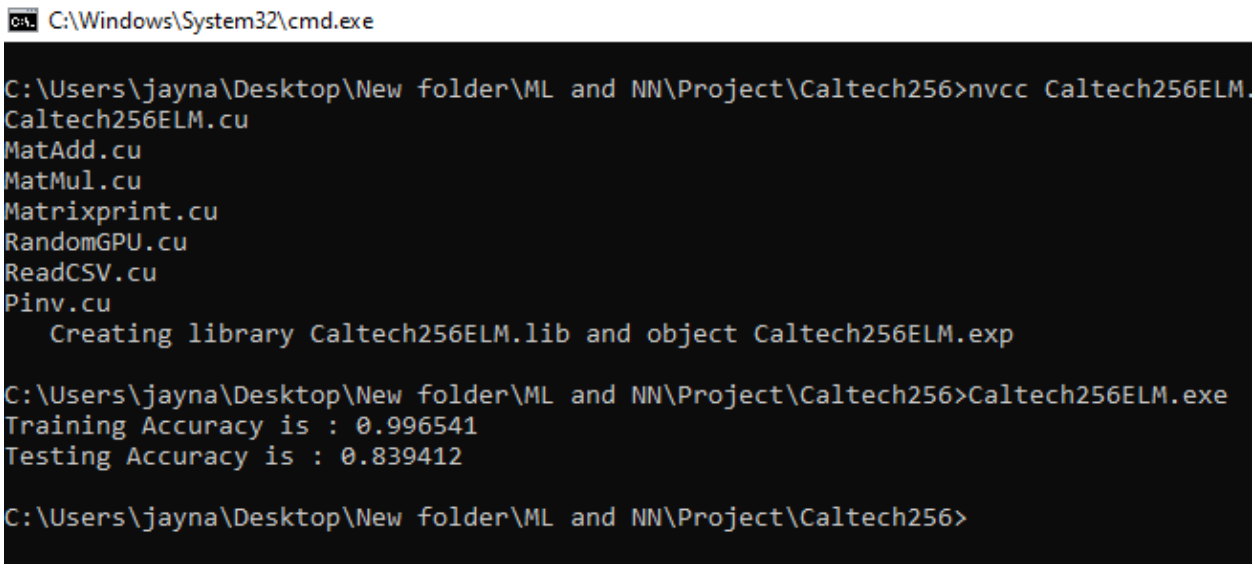
- **GPU: NVIDIA QUADRO RTX 8000 48GB**
- **Total time: 60.421minutes**

Outputs:

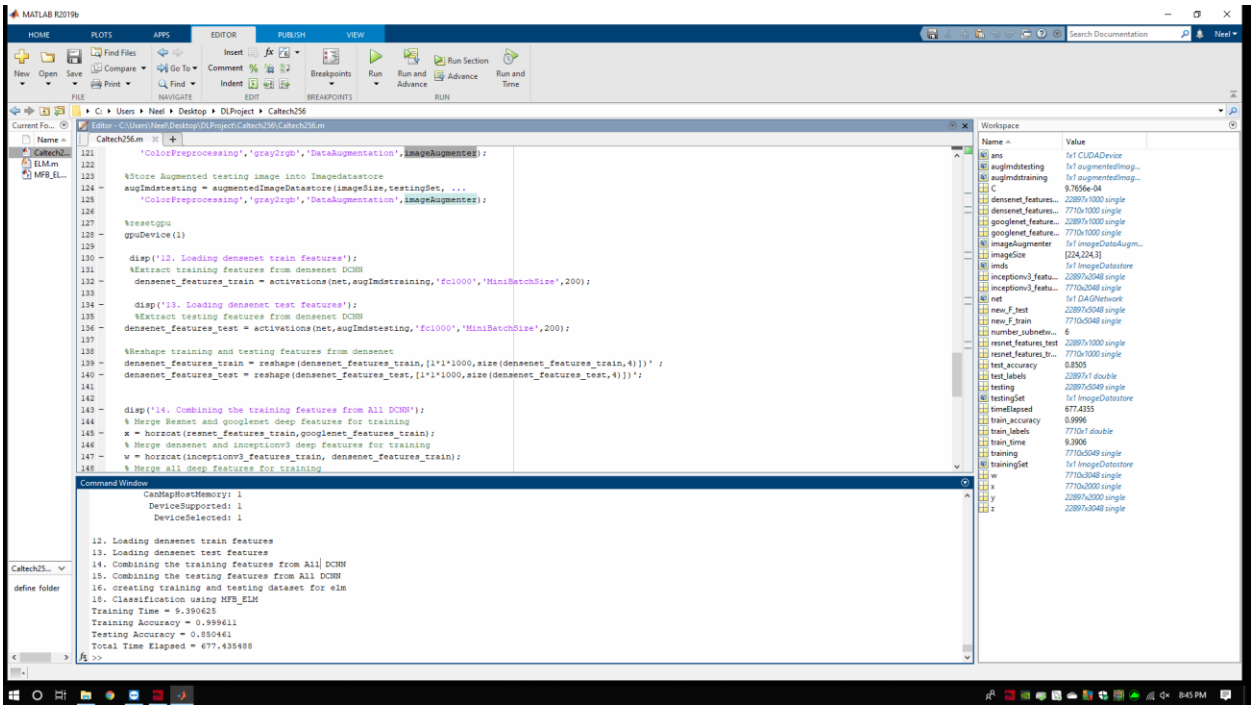
1.Run (Testing Acc: - 85.10%)



1.Run (Testing Acc: - 83.94%)



2.Run (Testing Acc: - 85.04%)



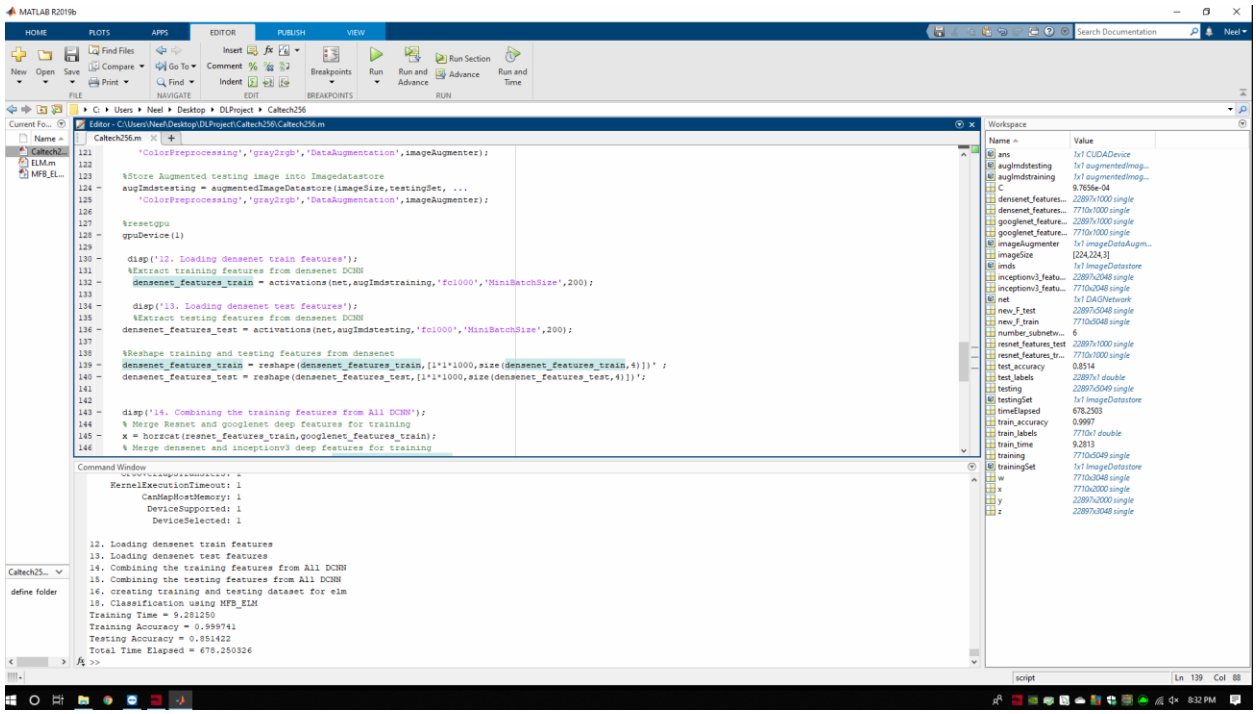
2.Run (Testing Acc: - 84.06%)

```
C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech256>nvcc Caltech256ELM.c
Caltech256ELM.cu
MatAdd.cu
MatMul.cu
Matrixprint.cu
RandomGPU.cu
ReadCSV.cu
Pinv.cu
   Creating library Caltech256ELM.lib and object Caltech256ELM.exp

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech256>Caltech256ELM.exe
Training Accuracy is : 0.982952
Testing Accuracy is : 0.840567

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech256>
```

3.Run (Testing Acc: - 85.14%)



3.Run (Testing Acc: - 83.46%)

```
C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech256>nvcc Caltech256ELM
Caltech256ELM.cu
MatAdd.cu
MatMul.cu
Matrixprint.cu
RandomGPU.cu
ReadCSV.cu
Pinv.cu
   Creating library Caltech256ELM.lib and object Caltech256ELM.exp

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech256>Caltech256ELM.exe
Training Accuracy is : 0.994236
Testing Accuracy is : 0.834598

C:\Users\jayna\Desktop\New folder\ML and NN\Project\Caltech256>
```

Average Accuracy:

- **Caltech101+Caltech256 /2 =**

  (93.23+85.14)/2 ≈ 90

Reference:

- **Yimin Yang, Q.M.Jonathan Wu. Autoencoder with invertible functions for dimension reduction and image reconstruction. IEEE Transactions on Neural Networks and Learning Systems. 2018.- MFB_ELM**
- http://www.yiminyang.com/code.html
- **All Together Now! The Benefits of Adaptively Fusing Pre-trained Deep Representations. Yehezkel S. Resheff1, Itay Lieder2 and Tom Hope2.**