

# ECE-GY 9143 - High Performance Machine Learning

## Homework Assignment 2

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Due Date: Oct 8, 2025

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Max Points: 110

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### Instructions:

This lab is intended to be performed **individually**, great care will be taken in verifying that students are authors of their own submission. Theoretical questions are identified by Q<number> while coding exercises are identified by C<number>.

## Introduction

This assignment will give you experience on how to profile machine learning training and/or inference workloads, which is critical to understanding and improving system performance. To achieve this, we will work with a CNN in PyTorch to classify images. We will use the CIFAR10 dataset, which contains 50K  $32 \times 32$  color images. The reference code is at [pytorch-cifar](#). We will work with the ResNet-18 model, as described in **Deep Residual Learning for Image Recognition**.

## Setup

### Model

Create a ResNet-18 model as defined in [Deep Residual Learning for Image Recognition](#). You can rely on existing open-source implementations. However, your code should define the layers and not just import the model using torch.

Specifically, the first convolutional layer should have 3 input channels, 64 output channels,  $3 \times 3$  kernel, with *stride=1* and *padding=1*.

Followed by 8 basic blocks in 4 sub groups (i.e. 2 basic blocks in each subgroup):

- The first sub-group contains convolutional layer with 64 output channels,  $3 \times 3$  kernel, *stride=1*, *padding=1*.
- The second sub-group contains convolutional layer with 128 output channels,  $3 \times 3$  kernel, *stride=2*, *padding=1*.
- The third sub-group contains convolutional layer with 256 output channels,  $3 \times 3$  kernel, *stride=2*, *padding=1*.
- The forth sub-group contains convolutional layer with 512 output channels,  $3 \times 3$  kernel, *stride=2*, *padding=1*.
- The final linear layer is of 10 output classes.

For all convolutional layers, use ReLU activation functions, and use batch normalization layers to avoid covariant shift. Since batch-norm layers regularize the training, set bias=0

for all convolutional layers. Use SGD optimizer with learning rate 0.1, momentum 0.9, weight decay  $5e^{-4}$ . The loss function is cross entropy.

### DataLoader

Create a PyTorch program with a DataLoader that loads the images and the related labels from the torchvision CIFAR10 dataset. Import CIFAR10 dataset for the torchvision package, with the following sequence of transformations:

1. Random cropping, with size  $32 \times 32$  and padding 4
2. Random horizontal flipping with a probability 0.5
3. Normalize each image's RGB channel with mean (0.4914, 0.4822, 0.4465) and variance (0.2023, 0.1994, 0.2010)

You will only need one data loader to complete this assignment. For your convenience, here are the default settings for the train loader: minibatch size of 128 and 3 IO processes (i.e., `num_workers=2`).

## C1: Training in PyTorch (20 points)

Create a main function that creates the *DataLoaders* for the training set and the neural network, then run 5 epochs with a complete training phase on all the minibatches of the training set. Write the code as device-agnostic, use the *ArgumentParser* to be able to read parameters from input, such as the use of cuda, the *data-path*, the number of dataloader workers and the optimizer (as string, eg: ‘sgd’).

**Calculate the per-batch training loss and the top-1 training accuracy of the predictions, measured on training data.**

*Note:* (i) Typically, we would like to examine test accuracy as well, however, it is sufficient to just measure training loss and training accuracy for this assignment. (ii) You don’t need to submit any outputs for C1. You’ll only need to submit the relevant code for this question. C2–C7 will be based on the code you wrote for C1.

## C2: Time Measurement of code in C1 (10 points)

Report the running time (by using `time.perf_counter()` or other timers you are comfortable with) for the following sections of the code:

- (C2.1) Data-loading time for each epoch
- (C2.2) Training (i.e., mini-batch calculation) time for each epoch
- (C2.3) Total running time for each epoch

*Note:* Data-loading time here is the time it takes to load batches from the generator (exclusive of the time it takes to move those batches to the device).

### **C3: I/O optimization for code in C2 (10 points)**

(C3.1) Report the total time spent for the Dataloader varying the number of workers starting from zero and increment the number of workers by 4 (0,4,8,12,16...) until the I/O time does not decrease anymore. Draw the results in a graph to illustrate the performance you are getting as you increase the number of workers. (C3.2) Report how many workers are needed for the best runtime performance.

### **C4: Profiling starting from code in C3 (10 points)**

Compare data-loading and computing time for runs using 1 worker and the number of workers needed for best performance found in C3 and explain (in a few words) the differences if there is any.

### **C5: Training in GPUs vs CPUs (10 points)**

Report the average running time over 5 epochs using the GPU vs using the CPU (using the number of I/O workers found in C3.2).

### **C6: Experimenting with different optimizers (10 points)**

Run 5 epochs with the GPU-enabled code and the optimal number of I/O workers. For each epoch, report the average training time, training loss and top-1 training accuracy using these Optimizers: SGD, SGD with nesterov, Adagrad, Adadelta, and Adam. Note please use the same default hyperparameters: learning rate 0.1, weight decay  $5e^{-4}$ , and momentum 0.9 (when it applies) for all these optimizers.

### **C7: Experimenting without Batch Norm (10 points)**

With the GPU-enabled code and the optimal number of workers, report the average training loss, top-1 training accuracy for 5 epochs with the default SGD optimizer and its hyperparameters but without batch norm layers.

### **Q1 (4 points)**

How many convolutional layers are in the ResNet-18 model?

### **Q2 (4 points)**

What is the input dimension of the last linear layer?

### **Q3 (8 points)**

How many trainable parameters and how many gradients in the ResNet-18 model that you build (please show both the answer and the code that you use to count them), when using SGD optimizer?

## **Q4 (4 points)**

Same question as Q3, except now using Adam (only the answer is required, not the code).

## **Extra Credit (10 points)**

Use the PyTorch profiler to measure various parts of your code from C1, C2, C3, C4, and C5, generate the trace, and visualize it using Chrome or Tensorboard. There is a known issue with the PyTorch profiler about data loading. If you encounter this issue, use other approaches to measure the time. (Issue: <https://github.com/pytorch/kineto/issues/610>)

## **Appendix - Submission Instructions**

Please submit a .tar.gz archive containing the following files:

- A file named lab2.pdf with a report of the outputs requested in C2-C7 and Q1-Q4. The file should include the terminal screenshots with outputs of executions.
- A file named README.md which explains how to run your code. The course staff should be able to run all experiments with one command. There are many ways to achieve this: you can pass CLI commands to your main python file and use Argparser, you can have a main python function that serves as a driver to each exercise, etc.
- A file named lab2.py containing all the code used, or an equivalent set of files if you split the code amongst files. It should be clear what code is needed for which exercises C2-C7 and Q3.
- Failing to follow the right directory/file name specification is -1 point. Failing to have programs executed in sequence is -1 point.

## **Appendix - How to Run Experiments**

Running jobs

- All jobs that do not require a GPU need to be executed on the CPU-only nodes.
- Please run all jobs in the same computing environment for consistency of results.

## Measuring GPU time

Using `time.time()` (or similar) alone is not accurate to measure GPU times. You will need to use the following to synchronize your code with the CUDA kernel:

```
...
torch.cuda.synchronize() # wait for any running kernels to finish
start = time.time()
<code you want to profile>
torch.cuda.synchronize() # wait for any running kernels to finish
end_epoch = time.time()
...
```

You will learn more about precisely why this is necessary and what this does later in the course.