# Lindblad Equation

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## I. LINDBLAD MASTER EQUATION

## A. General Markovian Form

For general open quantum evolution, suppose the system and environment are separable initially:  $\rho_T = \rho \otimes \rho_B$ , where we assume  $\rho_B = \sum_{\alpha} \lambda_{\alpha} |\phi_{\alpha}\rangle\langle\phi_{\alpha}|$ . Then the evolution of system-bath is unitary:  $\rho_T(t) = U(t)\rho_T U^{\dagger}(t)$ . Trace out the environment's degrees of freedom, we have the quantum channel expression:

$$\rho(t) = \sum_{\alpha\beta} W_{\alpha\beta} \rho W_{\alpha\beta}^{\dagger}, \quad W_{\alpha\beta} = \sqrt{\lambda_{\beta}} \langle \phi_{\alpha} | U(t) | \phi_{\beta} \rangle. \tag{1}$$

In general, the evolution of an open quantum system has the form  $\rho(t) = \mathcal{L}_t[\rho]$ . The Lindblad equation assumes a semi-group relation:  $\mathcal{L}_t = \lim_{N \to \infty} \mathcal{L}_{t/N} \cdot \mathcal{L}_{t/N} \cdots \mathcal{L}_{t/N}$ . Such time decimation implies that the evolution is Markovian. We will show that Markovian approximation leads directly to the Lindblad equation. First, we choose a complete operator basis  $\{F_i\}$  in N-dimensional Hilbert space, satisfying  $\text{Tr}[F_i^{\dagger}F_j] = \delta_{ij}$ , where we choose  $F_0 = N^{-1/2} \cdot \mathbb{I}$ . For a quantum channel, the channel operator  $K_{\mu}$  can be expanded as  $K_{\mu} = \sum_i \text{Tr}[F_i^{\dagger}K_{\mu}]F_i$ . In general, we have:

$$\mathcal{L}_t[\rho] = \sum_{ij} c_{ij}(t) F_i \rho F_j^{\dagger},$$

where the Hermitian coefficient  $c_{ij}(t)$  is  $c_{ij}(t) = \sum_{\mu} \text{Tr}[F_i^{\dagger}K_{\mu}] \cdot \text{Tr}[F_j^{\dagger}K_{\mu}]^*$ . Our target is to compute the limit

$$\frac{d}{dt}\rho \equiv \lim_{t \to 0} \frac{1}{t} (\mathcal{L}_t[\rho] - \rho).$$

For this purpose, we define the (Hermitian) coefficient  $a_{ij}$  as:

$$a_{00} = \lim_{t \to 0} \frac{c_{00}(t) - N}{t}, \quad a_{ij} = \lim_{t \to 0} \frac{c_{ij}(t)}{t}.$$

The limit is then

$$\frac{d}{dt}\rho = \frac{a_{00}}{N}\rho + \frac{1}{\sqrt{N}} \sum_{i>0} \left( a_{i0}F_i\rho + a_{i0}^*\rho F_i^{\dagger} \right) + \sum_{i,j>0} a_{ij}F_i\rho F_j^{\dagger}.$$

To further simplify the expression, we define

$$F = \frac{1}{\sqrt{N}} \sum_{i=1}^{N^2 - 1} a_{i0} F_i, \quad G = \frac{1}{2N} a_{00} \mathbb{I} + \frac{1}{2} (F^{\dagger} + F), \quad H = \frac{1}{2i} (F^{\dagger} - F).$$

The limit can be expressed by G, H in a compact form:

$$\frac{d\rho}{dt} = -i[H, \rho] + \{G, \rho\} + \sum_{i,j=1}^{N^2 - 1} a_{ij} F_i \rho F_j^{\dagger}.$$
 (2)

Note the  $[H, \rho]$  part is the traceless part and the  $\{G, \rho\}$  is the trace part. Since the quantum channel preserves the trace (for any  $\rho$ ):

$$\operatorname{Tr}\left[\frac{d\rho}{dt}\right] = \operatorname{Tr}\left[\left(2G + \sum_{i,j=1}^{N^2 - 1} a_{ij} F_j^{\dagger} F_i\right) \rho\right] = 0.$$

Therefore  $G = -\frac{1}{2} \sum_{i,j=1}^{N^2-1} a_{ij} F_j^{\dagger} F_i$ . We thus obtain the Lindblad form:

$$\frac{d\rho}{dt} = -i[H,\rho] + \sum_{i,j=1}^{N^2-1} a_{ij} \left( F_i \rho F_j^{\dagger} - \frac{1}{2} \{ F_j^{\dagger} F_i, \rho \} \right).$$

We can further simplify the form by diagonalizing the matrix  $a_{ij}$ . It is a convention to take the norm of  $a_{ij}$  out to indicate the strength of the system-bath coupling, and the diagonalized Lindblad equation is

$$\frac{d\rho}{dt} = -i[H, \rho] + \gamma \sum_{m} \left( L_m \rho L_m^{\dagger} - \frac{1}{2} \{ L_m^{\dagger} L_m, \rho \} \right). \tag{3}$$

# B. First Principal Deduction

In this section, we consider a general system-bath coupling:<sup>1</sup>

$$H_T = H + H_B + V, \quad V = \sum_k A_k \otimes B_k. \tag{4}$$

We will show under certain condition, the dynamics of the system is well approximated by the Lindblad equation. We first assume that initially, the total system is a product state

$$\rho_T(0) = \rho(0) \otimes \rho_B.$$

<sup>&</sup>lt;sup>1</sup> Without loss of generality, we can also assume  $||A_k|| = 1$ ,  $\text{Tr}[\rho_B B_k] = 0$ .

In the following, we will adopt the interacting picture, where the density operator evolves as

$$\partial_t \rho_T(t) = -i[V(t), \rho_T(t)] \equiv -i\mathcal{V}(t)|\rho_T(t)\rangle.$$

Note that in the last equality,  $\rho_T$  is expressed as a ket in the Hilbert space of linear operator, and the commutator with V is expressed as a superoperator  $\mathcal{V}$ . This notation can simplify the expression. For example, the inner product in the operator space is the trace, so the partial trace operation can be denoted as  $|\rho\rangle = \langle \mathbb{I}_B | \rho_T \rangle$ . The evolution of the system is then

$$\frac{d}{dt}|\rho(t)\rangle = -i\langle \mathbb{I}_B|\mathcal{V}(t)|\rho_T(t)\rangle = -i\langle \mathbb{I}_B|\mathcal{V}(t)|\rho_T(0)\rangle - \int_0^t \langle \mathbb{I}_B|\mathcal{V}(t)\mathcal{V}(\tau)|\rho_T(\tau)\rangle d\tau 
= -\int_0^t \langle \mathbb{I}_B|\mathcal{V}(t)\mathcal{V}(\tau)|\rho_T(\tau)\rangle d\tau.$$

Now we are taking the **Born approximation**, which states when the coupling is weak enough compared with the energy scale of the system and the bath, the total density matrix is approximated by the product state  $|\rho_T(t)\rangle \approx |\rho(t)\rangle \otimes |\rho_B\rangle$ . The evolution is now

$$\frac{d}{dt}\rho(t) \approx \int_0^t \operatorname{Tr}_B\left[V(t)\rho_T(\tau)V(\tau) - \rho_T(\tau)V(\tau)V(t)\right] d\tau + h.c.$$

$$= \sum_{kl} \int_0^t d\tau \ C_{lk}(\tau - t) \left[A_k(t)\rho(\tau)A_l(\tau) - \rho(\tau)A_l(\tau)A_k(t)\right] + h.c..$$

where  $C_{kl}(t) \equiv \text{Tr}_B[\rho_B B_k(t) B_l]$  is the correlation function of  $B_k$ 's. We then take the **Markovian approximation** which assumes that the correlations of the bath decay fast in time. We can thus make the substitution  $\rho(\tau) \to \rho(t)$ , the result equation of motion is Markovian:

$$\frac{d}{dt}\rho(t) \approx \sum_{kl} \int_{0}^{t} dt' C_{lk}(-t') \left[ A_{k}(t)\rho(t) A_{l}(t-t') - \rho(t) A_{l}(t-t') A_{k}(t) \right] + h.c.$$

$$= \sum_{k} \int_{0}^{t} dt \left[ A_{k}\rho B_{k} - \rho B_{k} A_{k} + h.c. \right],$$

where we have defined  $B_k(t) = \sum_l \int_0^\infty dt' A_l(t-t') C_{lk}(-t')$ . Now we switch to the frequency domain,

$$A_k(t) = \sum_{\omega} A_k(\omega) e^{-i\omega t}, \quad B_k(t) = \sum_{l,\omega} e^{-i\omega t} A_l(\omega) \Gamma_{lk}(\omega), \quad \Gamma_{kl}(\omega) = \int_0^\infty dt \ e^{i\omega t} C_{kl}(t).$$

We then take the **rotating wave approximation**, where we only keep the contributions from canceling frequency of operator A and B,

$$\frac{d}{dt}\rho(t) = \sum_{\omega} \left[ \Gamma_{lk}(\omega) A_k(\omega) \rho A_l(\omega) - \Gamma_{lk}(\omega) \rho A_l(\omega) A_k(\omega) + h.c. \right] 
= \sum_{\omega} \gamma_{kl}(\omega) (A_{l,\omega} \rho A_{k,\omega}^{\dagger} - \frac{1}{2} \{ \rho, A_{k,\omega}^{\dagger} A_{l,\omega} \} ) - i \left[ \sum_{\omega} S_{kl}(\omega) A_{k,\omega}^{\dagger} A_{l,\omega}, \rho \right],$$
(5)

where we defined

$$\gamma_{kl}(\omega) = \Gamma_{kl}(\omega) + \Gamma_{lk}^*(\omega), \quad S_{kl}(\omega) = \frac{\Gamma_{kl}(\omega) - \Gamma_{lk}^*(\omega)}{2i}.$$

The matrices  $\gamma(\omega)$  are positive, we can then take the square root of them. The jump operator is then

$$L_{i,\omega} = \sum_{j} \sqrt{\gamma_{ij}(\omega)} A_{j,\omega}.$$

The evolution is then in the Lindblad form.

## C. Stochastic Schrödinger Equation

The Lindblad form Eq. (3) is equivalent to the stochastic Schrödinger equation (SSE):

$$d|\psi\rangle = -iH|\psi\rangle + A[\psi]dt + B[\psi]dW,\tag{6}$$

where dW is a stochastic infinitesimal element. The expectation value is then the average over all possible evolution path (trajectory):  $\langle O(t) \rangle = \overline{\langle \psi(t) | O | \psi(t) \rangle}$ .

#### 1. Poisson SSE

Consider a small time interval  $\Delta t$ , the Lindblad equation is equivalent to the quantum channel  $\rho(t + \Delta t) = M_0 \rho(t) M_0^{\dagger} + \sum_m M_m \rho M_m^{\dagger}$ , where

$$M_0 = 1 - i \left( H - i \frac{\gamma}{2} \sum_m L_m^{\dagger} L_m \right) \Delta t, \quad M_m = \sqrt{\gamma \Delta t} L_m.$$

A quantum channel can be simulated by a stochastic evolution of pure states:

$$|\psi(t+\Delta t)\rangle \propto \begin{cases} L_m|\psi(t)\rangle & p = p_m(t)\gamma\Delta t\\ \exp(-iH_{\text{eff}}\Delta t)|\psi(t)\rangle & p = 1 - \sum_m p_m(t) \end{cases}, \text{ where } p_m(t) = \langle \psi(t)|L_m^{\dagger}L_m|\psi(t)\rangle. \tag{7}$$

Here the effective (non-Hermitian) Hamiltonian is

$$H_{\text{eff}} = H - i\frac{\gamma}{2} \sum_{m} L_{m}^{\dagger} L_{m}. \tag{8}$$

We can introduce a Poisson variable  $dW_m$  satisfying

$$dW_m dW_n = \delta_{mn} dW_m, \quad \overline{dW_m} = \langle L_m^{\dagger} L_m \rangle \gamma dt$$

and the evolution can be cast into the stochastic differential equation

$$d|\psi\rangle = -iHdt|\psi\rangle + \sum_{m} \left[ \left( \frac{L_m}{\langle L_m^{\dagger} L_m \rangle^{\frac{1}{2}}} - 1 \right) dW_m - \frac{\gamma}{2} \left( L_m^{\dagger} L_m - \langle L_m^{\dagger} L_m \rangle \right) dt \right] |\psi\rangle. \tag{9}$$

Note that the  $-\langle L_m^{\dagger} L_m \rangle dt | \psi \rangle$  comes from the renormalization. For numerical simulation, we can ignore it.

# 2. Gaussian SSE

We can also use the Wiener processes  $dW_m$  satisfying

$$\overline{dW_m} = 0, \quad \overline{dW_m dW_n} = \delta_{mn} \gamma dt.$$

The Gaussian SSE is

$$d|\psi\rangle = -iHdt|\psi\rangle + \sum_{m} \left[ (L_m - \langle L_m \rangle) dW_m - \frac{\gamma}{2} \left( L_m^{\dagger} - \langle L_m \rangle \right) (L_m - \langle L_m \rangle) dt \right] |\psi\rangle.$$
 (10)

To retain the Lindblad, note that  $d\rho = \overline{|d\psi\rangle\langle\psi|} + \overline{|\psi\rangle\langle d\psi|} + \overline{|d\psi\rangle\langle d\psi|}$ . Without going into the detail, we note that  $L_m dW_m$  term in  $\overline{|d\psi\rangle\langle d\psi|}$  will contribute a term  $\gamma L_m \rho L_m^{\dagger} dt$ ;  $-\frac{\gamma}{2} L_m^{\dagger} L_m dt$  term in  $\overline{|d\psi\rangle\langle\psi|} + \overline{|\psi\rangle\langle d\psi|}$  contribute a term  $-\frac{\gamma}{2} \{L_m^{\dagger} L_m, \rho\}$  term. All terms involving expectation value can be regarded as coming from the renormalization.

#### II. QUADRATIC LINDBLADIAN

Consider the Lindblad in the Heisenberg picture:

$$\frac{d}{dt}\hat{O} = i[\hat{H}, \hat{O}] + \sum_{\mu} \hat{L}^{\dagger}_{\mu} \hat{O} \hat{L}_{\mu} - \frac{1}{2} \sum_{\mu} \{\hat{L}^{\dagger}_{\mu} \hat{L}_{\mu}, \hat{O}\}, \tag{11}$$

where we choose  $\hat{O}_{ij} = \omega_i \omega_j$  satisfying the relation  $\hat{O}^T = 2\mathbb{I} - \hat{O}$ . The covariance matrix is then  $\Gamma_{ij} = i\langle \hat{O} \rangle - i\delta_{ij}$ .

We assume that the jump operator has up to quadratic Majorana terms. In particular, we denote the linear terms and the Hermitian quadratic terms as

$$\hat{L}_r = \sum_{j=1}^{2N} L_j^r \omega_j, \quad \hat{L}_s = \sum_{j,k=1}^{2N} M_{jk}^s \omega_j \omega_k.$$

When the **jump operator**  $\hat{L}_{\mu}$  contains only the linear Majorana operator, the Lindblad equation preserves Gaussianity. For jump operators containing up to quadratic Majorana terms, the evolution will break the Gaussian form, however, the 2n-point correlation is still solvable for free fermion systems.

# A. Third Quantization

Assume only linear terms in jump operators.

$$\partial_t \hat{O} = \left[ i \hat{H}, \hat{O} \right] + \mathcal{D}_r[\hat{O}] = \left[ i \hat{H} - \frac{1}{2} \sum_r \hat{L}_r^{\dagger} L_r, \hat{O} \right] + \sum_r \left[ \hat{L}_r^{\dagger}, \hat{O} \right] \hat{L}_r.$$

Define  $B \equiv \sum_{r} L_{i}^{r} L_{i}^{r*}$ , the first term of EOM is:<sup>2</sup>

$$\begin{split} \left[ i\hat{H} - \frac{1}{2} \sum_{r} \hat{L}_{r}^{\dagger} L_{r}, \hat{O}_{ij} \right] &= \sum_{kl} \left( \frac{1}{4} H - \frac{1}{2} B \right)_{kl} \left[ \omega_{k} \omega_{l}, \omega_{i} \omega_{j} \right] \\ &= \sum_{kl} \left( \frac{1}{2} H - B \right)_{kl} \left( \delta_{ki} \omega_{j} \omega_{l} - \delta_{kj} \omega_{i} \omega_{l} + \delta_{li} \omega_{k} \omega_{j} - \delta_{lj} \omega_{k} \omega_{i} \right) \\ &= \left[ \left( \frac{1}{2} H - B \right) \cdot \hat{O}^{T} + \left( \frac{1}{2} H - B \right)^{T} \cdot \hat{O} - \hat{O} \cdot \left( \frac{1}{2} H - B \right)^{T} - \hat{O}^{T} \cdot \left( \frac{1}{2} H - B \right) \right]_{ij} \\ &= \left[ \left( -H + 2B^{I} \right) \cdot \hat{O} + \hat{O} \cdot \left( H - 2B^{I} \right) \right]_{ij} \end{split}$$

The second term is

$$\sum_{r} \left[ L_r^{\dagger}, \hat{O}_{ij} \right] \hat{L}_r = \sum_{kl} B_{kl} [\omega_k, \omega_i \omega_j] \omega_l = 2 \sum_{kl} B_{kl} \left( \delta_{ki} \omega_j \omega_l - \delta_{kj} \omega_i \omega_l \right)$$
$$= \left[ 2B \cdot \hat{O}^T - 2\hat{O} \cdot B^T \right]_{ij} = \left[ -2B \cdot \hat{O} - 2\hat{O} \cdot B^* + 4B \right]_{ij}$$

Therefore

$$\partial_t \hat{O}_{ij} = \left[ (-H - 2B^R) \cdot \hat{O} + \hat{O} \cdot (H - 2B^R) + 4B \right]_{ij}$$

The EOM of the covariance matrix is then

$$\partial_t \Gamma = X^T \cdot \Gamma + \Gamma \cdot X + Y,\tag{12}$$

<sup>&</sup>lt;sup>2</sup> Use the commutation relation  $\{\omega_i, \omega_j\} = 2\delta_{ij}$ , we have the relation  $[\omega_k, \omega_i \omega_j] = 2(\delta_{ki}\omega_j - \delta_{kj}\omega_i)$  and  $[\omega_k\omega_l, \omega_i\omega_j] = 2(\delta_{ki}\omega_j\omega_l - \delta_{kj}\omega_i\omega_l + \delta_{li}\omega_k\omega_j - \delta_{lj}\omega_k\omega_i)$ .

where  $X = H - 2B^R$ ,  $Y = 4B^I$ . Note that the constant part is replaced by its anti-symmetric part.

The steady state of the system is solved by the Lyapunov equation

$$X^T \cdot \Gamma + \Gamma \cdot X = -Y. \tag{13}$$

## B. Quadratic Jump Operators

Now include the Hermitian quadratic quantum jumps:

$$\partial_t \hat{O} = i[\hat{H}, \hat{O}] + \mathcal{D}_r[\hat{O}] + \mathcal{D}_s[\hat{O}],$$

$$\mathcal{D}_s[\hat{O}] = \sum_s \hat{L}_s \hat{O} \hat{L}_s - \frac{1}{2} \sum_r \{\hat{L}_s^2, \hat{O}\} = -\frac{1}{2} \sum_s [\hat{L}_s, [\hat{L}_s, \hat{O}]].$$
(14)

1. Majorana Case

A direct calculation gives

$$\begin{split} D_s[\hat{O}] &= -\frac{1}{2} \sum_s \sum_{kl} M_{kl}^s \langle [\hat{L}_s, [\omega_k \omega_l, \omega_i \omega_j]] \\ &= 2 \sum_s \sum_k \left\{ M_{ik}^s [\hat{L}_s, \omega_k \omega_j] - [\hat{L}_s, \omega_i \omega_k] M_{kj}^s \right\} \\ &= 8 \sum_{s,kl} \left[ M_{ik}^s (-M_{kl}^s \omega_l \omega_j + \omega_k \omega_l M_{lj}^s) + (M_{il}^s \omega_l \omega_k - \omega_i \omega_l M_{lk}^s) M_{kj}^s \right] \\ &= 8 \sum_s \left[ 2M^s \cdot \hat{O} \cdot M^s - (M^s)^2 \cdot \hat{O} - \hat{O} \cdot (M^s)^2 \right]_{ij}. \end{split}$$

Together, we get the EOM of the variance matrix  $\Gamma_{ij}$ :

$$\partial_t \Gamma = X^T \cdot \Gamma + \Gamma \cdot X + \sum_s (Z^s)^T \cdot \Gamma \cdot Z^s + Y, \tag{15}$$

where

$$X = H - 2B^R + 8\sum_{s} (\text{Im}M^s)^2, \quad Y = 4B^I, \quad Z = 4M^s.$$
 (16)

2. Dirac Fermion Case

In this section, we consider the free fermion system preserving the U(1) charge. The jump operators are assumed to be quadratic:  $\hat{L}_s = \sum_{jk} M_{jk}^s c_j^{\dagger} c_k$  where  $\{M^s\}$  are Hermitian matrices.

For the fermion case, we choose  $\hat{O}_{ij} = c_i^{\dagger} c_j$ , and consider the Lindbladian

$$\partial_t \hat{O} = i[\hat{H}, \hat{O}] + \mathcal{D}_s[\hat{O}] = i[\hat{H}, \hat{O}] - \frac{1}{2} \sum_s [\hat{L}_s, [\hat{L}_s, \hat{O}]],$$

where each  $\hat{L}_s = M_{ij}^s c_i^{\dagger} c_j$  is a Hermitian fermion bilinear.

The Hamiltonian part is:<sup>3</sup>

$$i\sum_{kl}H_{kl}[c_k^{\dagger}c_l,c_i^{\dagger}c_j]=i\sum_{kl}H_{kl}(\delta_{il}c_k^{\dagger}c_j-\delta_{jk}c_i^{\dagger}c_l)=i[H^T\cdot\hat{O}-\hat{O}\cdot H^T]_{ij}.$$

<sup>&</sup>lt;sup>3</sup> Using the fact  $[c_k^{\dagger}c_l,c_i^{\dagger}c_j]=c_k^{\dagger}[c_l,c_i^{\dagger}c_j]+[c_k^{\dagger},c_i^{\dagger}c_j]c_l=\delta_{il}c_k^{\dagger}c_j-\delta_{jk}c_i^{\dagger}c_l$ , we know that for a quadratic form  $\hat{A}=\sum_{ij}A_{ij}c_i^{\dagger}c_j$ ,  $[\hat{A},\hat{O}_{ij}]=[A^T,\hat{O}]_{ij}$ .

Similarly, the double commutation in the second term is:

$$\mathcal{D}_s[\hat{O}] = -\frac{1}{2} \sum_{s} [(M^{s*})^2 \cdot \hat{O} + \hat{O} \cdot (M^{s*})^2 - 2M^{s*} \cdot \hat{O} \cdot M^{s*}].$$

Together, the EOM of correlation  $G_{ij} = \langle c_i^{\dagger} c_j \rangle$  is

$$\partial_t G = X^{\dagger} \cdot G + G \cdot X + \sum_s M^{s*} \cdot G \cdot M^{s*}, \tag{17}$$

where  $X = -iH^* - \frac{1}{2} \sum_{s} (M^{s*})^2$ .

#### III. FERMIONIC GAUSSIAN STATES

In this section, we discuss the general fermionic Gaussian state, in the framework of the Grassmann representation. We will closely follow Ref. [1].

# A. Grassmann Representation

The Majorana operators are defined as  $\hat{\omega}_j^a = \hat{c}_i + \hat{c}_i^{\dagger}$ ,  $\hat{\omega}_j^b = i(\hat{c}_i - \hat{c}_i^{\dagger})$ . A general operator in Fermionic Fock space can be expanded on the Majorana basis:

$$\hat{X} = \alpha \hat{I} + \sum_{p=1}^{2n} \sum_{1 \le a_1 < \dots < a_p \le 2n} \alpha_{a_1 \dots a_p} \hat{\omega}_{a_1} \dots \hat{\omega}_{a_p}.$$

$$\tag{18}$$

Define a linear map from Fermionic operator space to Grassmann algebra:

$$\hat{X} \mapsto X(\theta) = \alpha + \sum_{1 \le a_1 < \dots < a_p \le 2n} \alpha_{a_1 \dots a_p} \theta_{a_1} \dots \theta_{a_p}. \tag{19}$$

This mapping is called the Grassmann representation of  $\hat{X}$ .

One can formally define calculus on Grassmann algebra:

$$\frac{\partial}{\partial \theta_i} \theta_j = \int d\theta_i \theta_j = \delta_{ij}, \quad \frac{\partial}{\partial \theta_i} 1 = \int d\theta_i 1 = 0. \tag{20}$$

The Gaussian integral of Grassmann algebra is

$$\int D\theta \exp\left(\eta^T \theta + \frac{i}{2} \theta^T M \theta\right) = i^n \operatorname{Pf}(M) \exp\left(-\frac{i}{2} \eta^T M^{-1} \eta\right). \tag{21}$$

One useful result concerning the expectation value is

**Theorem 1.** For two operator  $\hat{X}$  and  $\hat{Y}$ , we have the following identity

$$\operatorname{Tr}\left(\hat{X}\hat{Y}\right) = (-2)^n \int D[\theta, \mu] e^{\theta^T \cdot \mu} X(\theta) Y(\mu).$$

where  $\int D\theta = \int d\theta_{2n} \cdots \int d\theta_1$ ,  $\int D\mu = \int d\mu_{2n} \cdots \int d\mu_1$ .

*Proof.* We prove the statement by considering only m-th order monomial. On the one hand

LHS = Tr[
$$\hat{\omega}_1 \cdots \hat{\omega}_m \hat{\omega}_1 \cdots \hat{\omega}_m$$
] =  $2^n (-1)^{m(m-1)/2}$ .

On the other hand,

RHS = 
$$(-2)^n \int D[\theta, \mu] \ \theta_1 \cdots \theta_m (\theta_{m+1}\mu_{m+1} \cdots \theta_{2n}\mu_{2n}) \mu_1 \cdots \mu_m$$
  
=  $(-2)^n (-1)^{(4n-m)m+(m+1+2n)(2n-m)/2}$   
=  $2^n (-1)^{-m(m+3)/2} = 2^n (-1)^{m(m-1)/2}$ .

We therefore proved the statement.

#### 1. Gaussian States

**Definition 1.** A quantum state  $\hat{\rho}$  is Gaussian if it has Gaussian Grassmann representation:

$$\rho(\theta) = \frac{1}{2^n} \exp\left(\frac{i}{2}\theta^T M \theta\right),\,$$

where the antisymmetric matrix  $M_{ab} = \frac{i}{2} \operatorname{Tr}(\hat{\rho}[\hat{\omega}_a, \hat{\omega}_b])$  is the **covariance matrix**.

All higher correlations of a Gaussian state are determined by the Wick theorem, namely

$$\operatorname{Tr}(i^p \hat{\rho} \hat{\omega}_{a_1} \cdots \hat{\omega}_{a_p}) = \operatorname{Pf}(M|_{a_1, \dots, a_p}).$$

The canonical form of antisymmetric matrix M is:

$$M = R \begin{bmatrix} 0 & \operatorname{diag}(\lambda_1, \dots, \lambda_n) \\ -\operatorname{diag}(\lambda_1, \dots, \lambda_n) & 0 \end{bmatrix} R^T, \quad R \in SO(2n).$$

Under the new Grassmann variance  $\mu = R\theta$ ,  $\rho$  has the form

$$\rho(\mu) = \frac{1}{2^n} \prod_j \exp(i\lambda_j \mu_j \mu_{j+n}) = \frac{1}{2^n} \prod_j (1 + i\lambda_j \mu_j \mu_{j+n}).$$
 (22)

We can then obtain the operator form:

$$\hat{\rho} = 2^{-n} \prod_{j=1}^{n} (1 + i\lambda_j \hat{\gamma}_j \hat{\gamma}_{j+n})$$
(23)

where  $\hat{\gamma}$ 's are a new set of Majorana operators. In the fermion basis

$$\hat{d}_j = \frac{\hat{\gamma}_j - i\hat{\gamma}_{j+n}}{2}, \quad \hat{d}_j^{\dagger} = \frac{\hat{\gamma}_j + i\hat{\gamma}_{j+n}}{2}, \tag{24}$$

the density matrix has the form

$$\hat{\rho} = \prod_{j} \left( \frac{1 + \lambda_j}{2} - \lambda_j d_j^{\dagger} d_j \right) = \bigotimes_{j} \begin{bmatrix} \frac{1 + \lambda_j}{2} & 0\\ 0 & \frac{1 - \lambda_j}{2} \end{bmatrix}_{j}. \tag{25}$$

Without loss of generality, we assume  $\lambda_i \geq 0$ . For pure state,  $\lambda_i = 1$ ,  $\forall i$ . For mixed state, the entropy of  $\rho$  is just

$$S(\hat{\rho}) = \sum_{j} H\left(\frac{1+\lambda_{j}}{2}\right) = -\sum_{j} \left[ \left(\frac{1+\lambda_{j}}{2}\right) \log\left(\frac{1+\lambda_{j}}{2}\right) + \left(\frac{1-\lambda_{j}}{2}\right) \log\left(\frac{1-\lambda_{j}}{2}\right) \right]. \tag{26}$$

2. Gaussian Operators

**Definition 2.** An operator  $\hat{X}$  (with nonzero trace) is Gaussian if

$$X(\theta) = C \exp\left(\frac{i}{2}\theta^T M \theta\right)$$

for some complex number C and some **complex antisymmetric** matrix M. M is called a correlation matrix of  $\hat{X}$ . If  $\hat{X}$  is traceless, it should be thought of as a limit  $\hat{X} = \lim_{m \to \infty} \hat{X}_m$  for some converging sequence of Gaussian operators with nonzero trace.

Note that for traceless  $\hat{X}$ , the explicit form of  $X(\theta)$  is

$$X(\theta) = C\left(\prod_{a=1}^{2k} \mu_a\right) \exp\left(\frac{i}{2} \sum_{a,b=2k+1}^{2n} M_{ab} \mu_a \mu_b\right),\tag{27}$$

where  $\mu_a = \sum_b T_{ab}\theta_b$  for some invertible complex matrix T. The factor is a limiting point of the sequence:

$$\prod_{a=1}^{2k} \mu_a = \lim_{t \to \infty} \prod_{a=1}^k \left( \mu_{2a-1} \mu_{2a} + \frac{1}{t} \right) = \lim_{t \to \infty} \frac{1}{t^k} \exp\left( t \sum_{a=1}^k \mu_{2a-1} \mu_{2a} \right).$$

Introducing the operator  $\hat{\Lambda} \equiv \sum_{a=1}^{2n} \hat{\omega}_a \otimes \hat{\omega}_a$ , we have the following theorem:

**Theorem 2.** An operator  $\hat{X}$  is Gaussian iff  $\hat{X}$  is even and satisfies

$$[\hat{\Lambda}, \hat{X} \otimes \hat{X}] = 0.$$

*Proof.* The adjoint action of  $\hat{\Lambda}$  in the Grassmann representation has the form:

$$\Lambda_{\rm ad} = 2\sum_{a} \left( \theta_a \otimes \frac{\partial}{\partial \theta_a} + \frac{\partial}{\partial \theta_a} \otimes \theta_a \right) \equiv \sum_{a} \Delta_a. \tag{28}$$

That is,  $[\hat{\omega}_a \otimes \hat{\omega}_a, Y \otimes Z](\theta) = \Delta_a \cdot Y(\theta) \otimes Z(\theta)$  for any operators Y, Z having the same parity. Without loss of generality, both Y and Z are monomials in  $\hat{\omega}$ 's. In this case each of them either commutes or anticommutes with  $\hat{\omega}_a$ . Consider two cases:

- 1. Both Y and Z contain  $\hat{\omega}_a$ , or both Y and Z do not contain  $\hat{\omega}_a$ . Then the commutator  $[\hat{\omega}_a \otimes \hat{\omega}_a, Y \otimes Z]$  is zero since both factors yield the same sign. The right-hand side is also zero, since either  $\theta_a$  or  $\partial/\partial\theta_a$  annihilates both Y and Z.
- 2. Y contains  $\hat{\omega}_a$  while Z does not contain  $\hat{\omega}_a$  (or vice verse). In this case  $\hat{\omega}_a \otimes \hat{\omega}_a$  anticommutes with  $Y \otimes Z$ . Let us write  $Y = \hat{\omega}_a \tilde{Y}$ , where  $\tilde{Y}$  is a monomial which does not contain  $\hat{\omega}_a$ . We have:

$$[\hat{\omega}_a \otimes \hat{\omega}_a, Y \otimes Z] = 2(\hat{\omega}_a \otimes \hat{\omega}_a)(Y \otimes Z) = 2\tilde{Y} \otimes (\hat{\omega}_a Z).$$

On the other hand,

$$\theta_a \otimes \frac{\partial}{\partial \theta_a} \cdot Y \otimes Z = 0, \quad \frac{\partial}{\partial \theta_a} \otimes \theta_a \cdot Y \otimes Z = \tilde{Y} \otimes \theta_a Z.$$

We again get equality.

**Necessity:** Note that  $\Lambda_{ad}$  is invariant under change of variables since

$$\mu_a = \sum_b T_{ab}\theta_b, \quad \frac{\partial}{\partial \mu_a} = \sum_b (T^{-1})_{ab} \frac{\partial}{\partial \theta_b} \implies \sum_a \theta_a \otimes \frac{\partial}{\partial \theta_a} = \sum_a \mu_a \otimes \frac{\partial}{\partial \mu_a}.$$

Direct application of the operator to the general Gaussian form will prove the necessity.

Sufficiency: Denote  $C = 2^{-n} \operatorname{tr}(X) \equiv X(0)$  and represent  $X(\theta)$  as

$$X(\theta) = C \cdot 1 + \frac{iC}{2} \sum_{a,b=1}^{2n} M_{ab} \,\theta_a \theta_b + \text{higher order terms.}$$

Applying a differential operator  $1 \otimes \frac{\partial}{\partial \theta_b}$  to both sides:

$$\sum_{a=1}^{2n} \left( \theta_a X \otimes \frac{\partial^2}{\partial \theta_b \partial \theta_a} X - \frac{\partial}{\partial \theta_a} X \otimes \theta_a \frac{\partial}{\partial \theta_b} X \right) + \frac{\partial}{\partial \theta_b} X \otimes X = 0.$$

Now let us put  $\theta \equiv 0$  in the second factor:

$$\frac{\partial}{\partial \theta_b} X = i \sum_{a=1}^{2n} M_{ba} \theta_a X.$$

This differential equation can be easily solved by  $X(\theta) = C \exp\left(\frac{i}{2} \theta^T M \theta\right)$ .

For general cases, we denote  $\mathcal{K} \subseteq \mathcal{M}_1$  a subspace spanned by linear functions which annihilate  $\hat{X}$ , i.e.

$$\mathcal{K} = \{ f \in \mathcal{M}_1 : f(\theta)X(\theta) = 0 \}.$$

Let us perform a linear change of variables  $\mu_a = \sum_b T_{ab}\theta_b$ , with T being an invertible complex matrix chosen such that the first k variables  $\mu$  span the subspace  $\mathcal{K}$ , i.e.  $\mathcal{K} = \mathrm{span}\left[\mu_1,\ldots,\mu_{2k}\right]$ . From equalities  $\mu_j X = 0,\ j \in [1,2k]$  it follows that

$$X(\theta(\mu)) = \left(\prod_{a} \mu_{a}\right) \tilde{X}(\mu),$$

where  $\tilde{X}(\mu)$  depends only upon  $\mu_{2k+1}, \ldots, \mu_{2n}$ . The function  $\tilde{X}(\mu)$  satisfies the equation

$$\sum_{a=2k+1}^{2n} \left( \mu_a \otimes \frac{\partial}{\partial \mu_a} + \frac{\partial}{\partial \mu_a} \otimes \mu_a \right) \tilde{X} \otimes \tilde{X} = 0.$$

Therefore we get the general Gaussian form.

3. Gaussian Linear Maps

We define linear maps that preserve Gaussian states as the following:

**Definition 3.** A linear map  $\mathcal{E}$  is Gaussian iff it admits an integral representation

$$\mathcal{E}(X)(\theta) = C \int D[\eta, \mu] \exp\left[S(\theta, \eta) + i\eta^T \mu\right] X(\mu), \tag{29}$$

where

$$S(\theta, \eta) = \frac{i}{2} (\theta^T, \eta^T) \begin{pmatrix} A & B \\ -B^T & D \end{pmatrix} \begin{pmatrix} \theta \\ \eta \end{pmatrix}$$
(30)

for some complex  $2n \times 2n$  matrices A, B, D, and some complex number C.

Consider a Gaussian operator  $\hat{X}$  which can be described by a correlation matrix M and a Gaussian map  $\mathcal{E}$ . Applying the Gaussian integration, one can show that  $\mathcal{E}(X)$  has a correlation matrix

$$\mathcal{E}(M) = A + B \left( M^{-1} + D \right)^{-1} B^{T} = A + B \left( I + MD \right)^{-1} MB^{T},$$

while a pre-exponential factor of the operator  $\mathcal{E}(X)$  can be found from an identity

$$\operatorname{tr}(\mathcal{E}(X)) = C(-1)^n \operatorname{Pf}(M) \operatorname{Pf}(M^{-1} + D) \operatorname{tr}(X).$$

The value of  $\operatorname{tr}(\mathcal{E}(X))$  can be found up to a factor  $\pm 1$  using a regularized version:

$$\operatorname{tr}(\mathcal{E}(X))^2 = C^2 \det(I + MD) \operatorname{tr}(X)^2.$$

# B. Operator Form

1. Dirac Fermion Case

For particle number conserving systems, the Gaussian state can be represented as a matrix:

$$|B\rangle \equiv \prod_{i=1}^{N} \sum_{i} B_{ij} c_i^{\dagger} |0\rangle \equiv \bigotimes_{i=1}^{N} |B_j\rangle.$$
(31)

Note that the matrix B representing the Gaussian state has the unitary degree of freedom

$$|B\rangle = |B'\rangle, \quad B'_{ij} = \sum_{k} B_{ik} U_{kj},$$

where  $U_{kj}$  is an  $N \times N$  unitary matrix. It means that the Gaussian state is determined by the linear subspace that columns of B span. The columns of B need not to orthogonal, while the canonical form can be obtained by the QR decomposition:  $B_{L\times N} = Q_{L\times N} \cdot R_{N\times N}$ , where the Q matrix is orthonormal and we can set B' = Q.

A free fermion state maintains its structure when applied to a quasi-particle creation/annihilation operator. Consider a general quasi-particle  $b^{\dagger} = \sum_{i} b_{i} c_{i}^{\dagger}$ , creating a quasiparticle is simply adding a column to B, since

$$b^{\dagger}|B\rangle = \sum_{k} b_{k} c_{k}^{\dagger} \prod_{j=1}^{N} \sum_{i} c_{i}^{\dagger} B_{ij}|0\rangle = \prod_{j=1}^{N+1} \sum_{i} c_{i}^{\dagger} [b|B]_{ij}|0\rangle$$
 (32)

In general, the new column b is not orthogonal to linear space B, therefore orthogonalization procedure is needed to obtain canonical form.

Using the Baker-Campbell-Hausdorff formula  $e^X Y e^{-X} = \exp(\operatorname{ad} X) Y$ ,

$$e^{-iHt}c_j^{\dagger}e^{iHt} = c_k^{\dagger}[e^{-iHt}]_{kj} \implies e^{-iHt}|B\rangle = \prod_{j=1}^N \sum_i [e^{-iHt}]_{ki}B_{ij}c_k^{\dagger}|0\rangle = |e^{-iHt} \cdot B\rangle. \tag{33}$$

For the quasiparticle annihilation operator b,

$$b|B\rangle = \sum_{k} b_{k}^{*} c_{k} \prod_{j} \sum_{i} c_{i}^{\dagger} B_{ij} |0\rangle = \sum_{j} \langle b|B_{j}\rangle \bigotimes_{l\neq j} |B_{l}\rangle.$$
(34)

We can use the gauge freedom to restrict  $\langle b|B'_j\rangle=0$  for j>1. Such matrix B' always exists since we can always find a column j that  $\langle b|B_j\rangle\neq 0$  (otherwise  $p_m=0$  and the jump is impossible). We then move the column to the first and define the column as

$$|B_j'\rangle = |B_j\rangle - \frac{\langle a|B_j\rangle}{\langle a|B_1\rangle}|B_1\rangle, \quad j > 1.$$
 (35)

Such column transformations do not alter the linear space B spans, while the orthogonality and the normalization might be affected.

2. Majorana Case

For the Majorana case, the canonical form (25) for a Gaussian pure state  $|\psi\rangle$  can be reformulated as

$$|\psi\rangle\langle\psi| = \prod_{i=1}^{n} \hat{d}_{j}^{\dagger} \hat{d}_{j}, \quad \hat{d}_{j}^{\dagger} = \frac{\hat{\gamma}_{j} + i\hat{\gamma}_{j+n}}{2} = \sum_{i=1}^{n} \left(\frac{R_{i,j} + iR_{i,j+n}}{2}\right) \hat{c}_{i} + \left(\frac{R_{i+n,j} + iR_{i+n,j+n}}{2}\right) \hat{c}_{i}^{\dagger}. \tag{36}$$

Note that the state is annihilated by  $\{\hat{d}_i^{\dagger}\}$ . We can store the information of  $|\psi\rangle$  into a  $2n \times n$  complex matrix

$$|\psi\rangle \Longleftrightarrow B = \frac{1}{2} \begin{bmatrix} R_{11} + iR_{12} \\ R_{21} + iR_{22} \end{bmatrix}. \tag{37}$$

The rest of the procedures are parallel to those of the Dirac fermion case.

[1] S. Bravyi, Lagrangian representation for fermionic linear optics (2004), quant-ph/0404180.