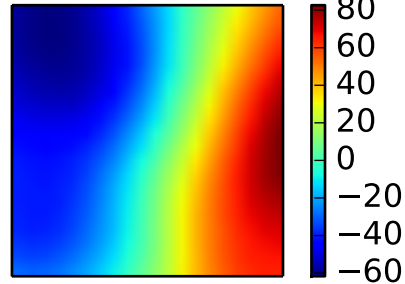
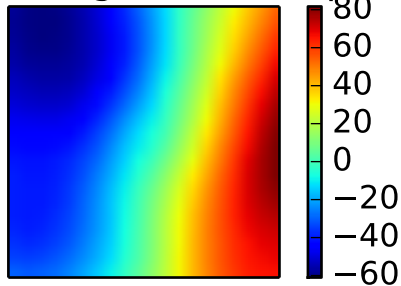


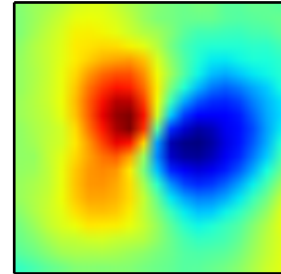
observed CMB map



filtered gradient map



filtered lensing map



reconstructed lensing convergence

