Recorded at time: 1477565373.395 map Broadcaster: /amcl Average rate: 8.933 Hz Most recent transform: 1477565373.445 ( -0.050 sec old) Buffer length: 4.926 sec odom Broadcaster: /morse Average rate: 53.223 Hz Most recent transform: 1477565373.386 ( 0.009 sec old) Buffer length: 4.904 sec base\_footprint Broadcaster: /robot/robot\_state\_publisher Average rate: 50.203 Hz Most recent transform: 1477565373.865 ( -0.471 sec old) Buffer length: 4.960 sec base link Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 50.203 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Most recent transform: 1477565373.865 (-0.471 sec old) Most recent transform: 1477565373.865 ( -0.471 sec old) Most recent transform: 1477565373.865 ( -0.471 sec old) Most recent transform: 1477565373.865 ( -0.471 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec base\_laser\_link base\_halo head\_base\_frame ptu\_pan\_motor Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1477565373.368 ( 0.027 sec old) Most recent transform: 1477565373.368 ( 0.027 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec head\_swivel\_frame ptu\_tilt\_motor Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1477565373.368 ( 0.027 sec old) Most recent transform: 1477565373.368 ( 0.027 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec head\_frame ptu\_hinge Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 50.203 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Most recent transform: 1477565373.865 (-0.471 sec old) Most recent transform: 1477565373.865 (-0.471 sec old) Most recent transform: 1477565373.865 ( -0.471 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec left\_eye\_base\_frame right\_eye\_base\_frame ptu\_mount Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 50.203 Hz Most recent transform: 1477565373.368 ( 0.027 sec old) Most recent transform: 1477565373.368 ( 0.027 sec old) Most recent transform: 1477565373.865 ( -0.471 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.960 sec left\_eye\_swivel\_frame right\_eye\_swivel\_frame head\_xtion\_link Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Most recent transform: 1477565373.368 ( 0.027 sec old) Most recent transform: 1477565373.368 ( 0.027 sec old) Most recent transform: 1477565373.865 ( -0.471 sec old) Most recent transform: 1477565373.865 ( -0.471 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.960 sec Buffer length: 4.960 sec head\_xtion\_depth\_frame left\_eye\_frame right\_eye\_frame head\_xtion\_rgb\_frame Broadcaster: /robot/robot\_state\_publisher Broadcaster: /morse Average rate: 50.203 Hz Average rate: 62.253 Hz Most recent transform: 1477565373.865 ( -0.471 sec old) Most recent transform: 1477565373.865 ( -0.471 sec old) Buffer length: 4.960 sec Buffer length: 5.381 sec head\_xtion\_depth\_optical\_frame head\_xtion\_rgb\_optical\_frame Broadcaster: /morse Average rate: 8.577 Hz Most recent transform: 1477565373.213 (0.182 sec old) Buffer length: 4.547 sec

monitor.003

view\_frames Result