view_frames Result Recorded at time: 1462397813.837 map Broadcaster: /amcl Average rate: 9.187 Hz Most recent transform: 1462397813.853 (-0.016 sec old) Buffer length: 4.898 sec odom Broadcaster: /morse Average rate: 54.475 Hz Most recent transform: 1462397813.792 (0.045 sec old) Buffer length: 4.938 sec base_footprint Broadcaster: /robot/robot_state_publisher Average rate: 50.204 Hz Most recent transform: 1462397814.307 (-0.470 sec old) Buffer length: 4.960 sec base link Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Average rate: 50.204 Hz Average rate: 50.204 Hz Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 1462397814.307 (-0.470 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec base_halo base_laser_link head_base_frame ptu_pan_motor Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1462397813.765 (0.072 sec old) Most recent transform: 1462397813.765 (0.072 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec head_swivel_frame ptu_tilt_motor Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1462397813.765 (0.072 sec old) Most recent transform: 1462397813.765 (0.072 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec head_frame ptu_hinge Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Average rate: 50.204 Hz Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 1462397814.307 (-0.470 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec left_eye_base_frame right_eye_base_frame ptu_mount Broadcaster: /robot/robot state publisher Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 50.204 Hz Most recent transform: 1462397813.765 (0.072 sec old) Most recent transform: 1462397813.765 (0.072 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.960 sec left_eye_swivel_frame right_eye_swivel_frame head_xtion_link Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 1462397813.765 (0.072 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Most recent transform: 1462397813.765 (0.072 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.960 sec Buffer length: 4.960 sec left_eye_frame right_eye_frame head_xtion_depth_frame head_xtion_rgb_frame Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Average rate: 50.204 Hz Average rate: 61.991 Hz Most recent transform: 1462397814.307 (-0.470 sec old) Most recent transform: 1462397814.307 (-0.470 sec old) Buffer length: 4.960 sec Buffer length: 5.452 sec head_xtion_depth_optical_frame head_xtion_rgb_optical_frame