view\_frames Result Recorded at time: 1462589655.508 map Broadcaster: /amcl Average rate: 9.813 Hz Most recent transform: 1462589655.497 (0.011 sec old) Buffer length: 4.790 sec odom Broadcaster: /morse Average rate: 57.950 Hz Most recent transform: 1462589655.506 (0.001 sec old) Buffer length: 4.901 sec base\_footprint Broadcaster: /robot/robot\_state\_publisher Average rate: 50.203 Hz Most recent transform: 1462589655.991 (-0.483 sec old) Buffer length: 4.960 sec base link Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 50.203 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Most recent transform: 1462589655.991 (-0.483 sec old) Most recent transform: 1462589655.991 (-0.483 sec old) Most recent transform: 1462589655.991 ( -0.483 sec old) Most recent transform: 1462589655.991 (-0.483 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec base\_laser\_link base\_halo head\_base\_frame ptu\_pan\_motor Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 1462589655.410 ( 0.097 sec old) Most recent transform: 1462589655.410 (0.097 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec head\_swivel\_frame ptu\_tilt\_motor Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 1462589655.410 ( 0.097 sec old) Most recent transform: 1462589655.410 ( 0.097 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec head\_frame ptu\_hinge Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 50.203 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Most recent transform: 1462589655.991 (-0.483 sec old) Most recent transform: 1462589655.991 (-0.483 sec old) Most recent transform: 1462589655.991 ( -0.483 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec left\_eye\_base\_frame right\_eye\_base\_frame ptu\_mount Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Average rate: 50.203 Hz Most recent transform: 1462589655.410 ( 0.097 sec old) Most recent transform: 1462589655.410 ( 0.097 sec old) Most recent transform: 1462589655.991 ( -0.483 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.960 sec left\_eye\_swivel\_frame head\_xtion\_link right\_eye\_swivel\_frame Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Broadcaster: /robot/robot\_state\_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Average rate: 50.203 Hz Average rate: 50.203 Hz Most recent transform: 1462589655.410 ( 0.097 sec old) Most recent transform: 1462589655.410 ( 0.097 sec old) Most recent transform: 1462589655.991 ( -0.483 sec old) Most recent transform: 1462589655.991 (-0.483 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.960 sec Buffer length: 4.960 sec left\_eye\_frame right\_eye\_frame head\_xtion\_depth\_frame head\_xtion\_rgb\_frame Broadcaster: /robot/robot\_state\_publisher Broadcaster: /morse Average rate: 50.203 Hz Average rate: 63.207 Hz Most recent transform: 1462589655.991 (-0.483 sec old) Most recent transform: 1462589655.991 ( -0.483 sec old) Buffer length: 4.960 sec Buffer length: 5.442 sec head\_xtion\_depth\_optical\_frame head\_xtion\_rgb\_optical\_frame