view_frames Result

Recorded at time: 1462554571.340

map

Broadcaster: /amcl
Average rate: 8.502 Hz
Most recent transform: 1462554571.384 ( -0.044 sec old)
Buffer length: 4.940 sec

odom

Broadcaster: /morse
Average rate: 50.719 Hz
Most recent transform: 1462554571.327 ( 0.013 sec old)
Buffer length: 4.909 sec

base_footprint

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

base_link

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

base_halo

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

base_laser_link

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

head_base_frame

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

ptu_pan_motor

Broadcaster: /robot/robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1462554571.239 ( 0.101 sec old)
Buffer length: 4.800 sec

head_swivel_frame

Broadcaster: /robot/robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1462554571.239 ( 0.101 sec old)
Buffer length: 4.800 sec

ptu_tilt_motor

Broadcaster: /robot/robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1462554571.239 ( 0.101 sec old)
Buffer length: 4.800 sec

head_frame

Broadcaster: /robot/robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1462554571.239 ( 0.101 sec old)
Buffer length: 4.800 sec

ptu_hinge

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

left_eye_base_frame

right_eye_base_frame

ptu_mount

Broadcaster: /robot/robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1462554571.239 ( 0.101 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1462554571.239 ( 0.101 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

left_eye_swivel_frame

right_eye_swivel_frame

head_xtion_link

Broadcaster: /robot/robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1462554571.239 ( 0.101 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1462554571.239 ( 0.101 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

left_eye_frame

right_eye_frame

head_xtion_depth_frame

head_xtion_rgb_frame

Broadcaster: /robot/robot_state_publisher
Average rate: 50.207 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 4.940 sec

Broadcaster: /morse
Average rate: 60.625 Hz
Most recent transform: 1462554571.804 ( -0.464 sec old)
Buffer length: 5.460 sec

head_xtion_depth_optical_frame

head_xtion_rgb_optical_frame

Broadcaster: /morse
Average rate: 16.802 Hz
Most recent transform: 1462554571.284 ( 0.056 sec old)
Buffer length: 4.940 sec

monitor.003