view_frames Result

Recorded at time: 1460448528.617

map

Broadcaster: /amcl
Average rate: 8.845 Hz
Most recent transform: 1460448528.598 (0.020 sec old)
Buffer length: 4.862 sec

odom

Broadcaster: /morse
Average rate: 52.324 Hz
Most recent transform: 1460448528.565 (0.053 sec old)
Buffer length: 4.931 sec

base_footprint

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

base_link

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

base_halo

base_laser_link

head_base_frame

ptu_pan_motor

Broadcaster: /robot/robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1460448528.609 (0.008 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1460448528.609 (0.008 sec old)
Buffer length: 4.900 sec

head_swivel_frame

ptu_tilt_motor

Broadcaster: /robot/robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1460448528.609 (0.008 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1460448528.609 (0.008 sec old)
Buffer length: 4.900 sec

head_frame

ptu_hinge

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

left_eye_base_frame

right_eye_base_frame

ptu_mount

Broadcaster: /robot/robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1460448528.609 (0.008 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1460448528.609 (0.008 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

left_eye_swivel_frame

right_eye_swivel_frame

head_xtion_link

Broadcaster: /robot/robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1460448528.609 (0.008 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1460448528.609 (0.008 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

left_eye_frame

right_eye_frame

head_xtion_depth_frame

head_xtion_rgb_frame

Broadcaster: /robot/robot_state_publisher
Average rate: 50.236 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 4.977 sec

Broadcaster: /robot/robot_state_publisher
Average rate: 61.198 Hz
Most recent transform: 1460448529.110 (-0.493 sec old)
Buffer length: 5.474 sec

head_xtion_depth_optical_frame

head_xtion_rgb_optical_frame

Broadcaster: /morse
Average rate: 17.449 Hz
Most recent transform: 1460448528.565 (0.053 sec old)
Buffer length: 4.929 sec

west_monitor