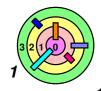
3.4 Linking & Loading

Static Linking & Loading

Shared Libraries



Libraries



- A library is just a collection of .o files
- the linker is used to create libraries



- Two types of libraries
- static library
- dynamic (or shared) library

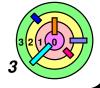


Creating a Static Library

```
% cat subl.c
void sub1() { puts("sub1"); }
% cat sub2.c
void sub2() { puts("sub2"); }
% cat sub3.c
void sub3() { puts("sub3"); }
% qcc -c sub1.c sub2.c sub3.c
% 1s
sub1.c sub2.c sub3.c
sub1.o sub2.o sub3.o
% ar cr libpriv1.a sub1.o sub2.o sub3.o
% ar t libpriv1.a
sub1.o
sub2.o
sub3.o
```



puts() is unresolved in libpriv1.a



Using a Static Library

```
% cat prog.c
int main() {
   sub1();
   sub2();
   sub3();
}
% gcc -o prog prog.c -L. -lpriv1

Where does puts() come from?
% gcc -o prog prog.c -L. -lpriv1 -L/lib -lc
```



will try to resolve references first in the priv1 library (either libpriv1.a or libpriv1.so) and then in the c library (either libc.a or libc.so)



Substitution



Want to use my version of puts () instead of what's in the C library

```
% cat myputs.c
int puts(char *s) {
  write(1, "My puts: ", 9);
  write(1, s, strlen(s));
  write(1, "\n", 1);
  return 1;
}
% gcc -c myputs.c
% ar cr libmyputs.a myputs.o
% gcc -o prog prog.c -L. -lpriv1 -lmyputs
```

will try to resolve puts () first in the priv1 library, then in the myputs library, then in the c library



Shared Libraries



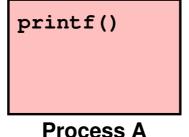
prog must contain everything needed for execution

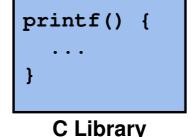
- duplicate code, may be lots of duplicate code, e.g., printf()
 - take up *disk space*
 - take up *memory*

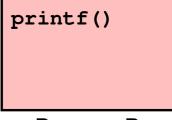


Need a way to share things like printf()

- on disk, and
- in memory







Process B



If printf() required no relocation, then it's easy

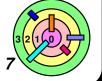
just make sure 1d use the right address consistently



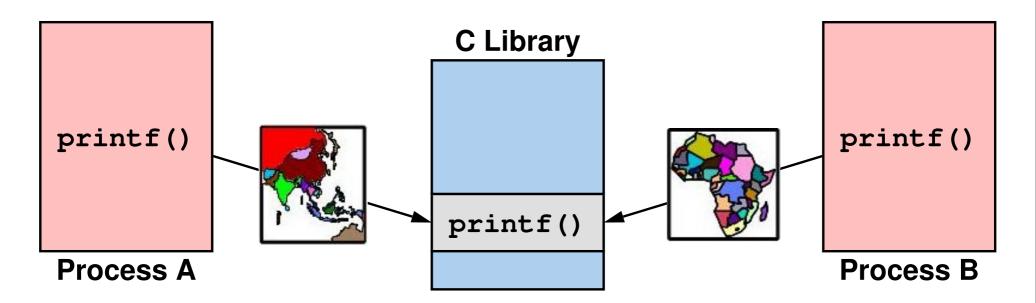
If printf() required relocation, then it's more complicated

 problem: processes want a shared function to be at different addresses



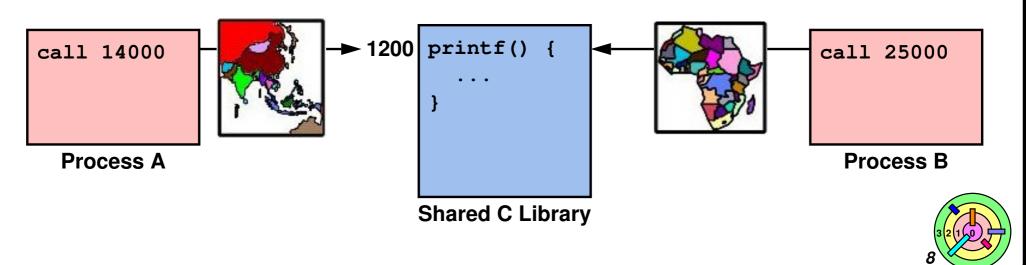


Sharing

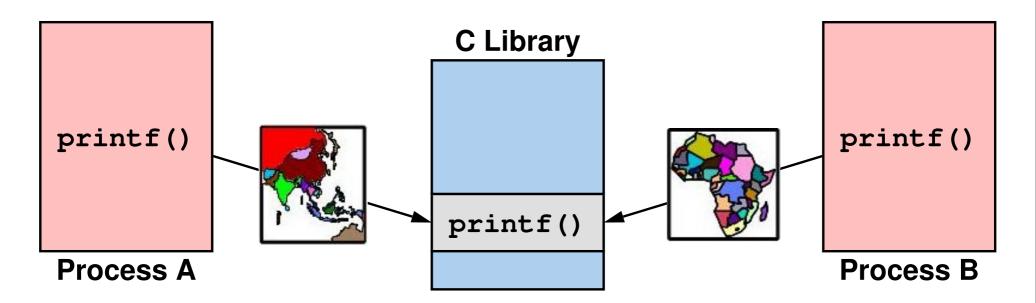




Looks like it can work

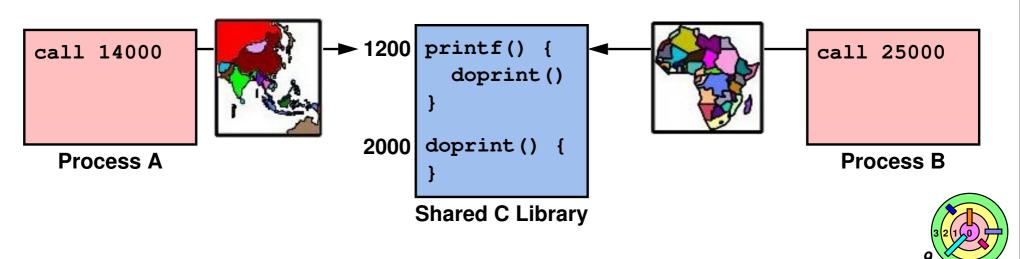


Sharing





What about this?



Relocation and Shared Libraries



Approaches

- Limited sharing: relocate separately for each process
 - have a single copy of printf() on disk
 - as printf() gets copied into memory, perform relocation
 - this would work, but still end up with too many copies of printf() in memory
- Prerelocation: relocate libraries ahead of time
 - difficult to prerelocate all shared functions
 - may need to preform rerelocation

printf()

Process B

- Position-Independent Code: no need for relocation
 - producing code that can be placed anywhere in memory without requiring modification
 - need indirection

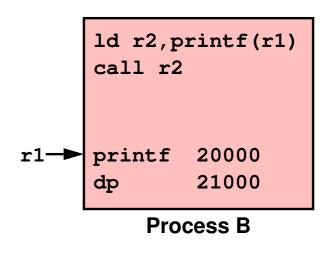
Position-Independent Code

```
ld r2,printf(r1)
call r2

printf 10000
dp 11000

Process A
```

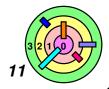
```
0 printf() {
    ld r2,dp(r1)
    call r2
    ...
}
1000 doprint() {
    ...
}
```



- each process maintains a private table, pointed to by register r1
 - table contains addresses of shared routines
- don't call functions directly
 - make a position-independent call (i.e., an indirect call)
 - i.e., call the function located at a fixed index into the table pointed by r1
 - implemented as two instructions in the above example



Please note that 1d is not the same as mov in x86 CPU



Position-Independent Code Details

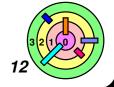


Processor-dependent; x86 32-bit version:



ELF requires 3 data structures for each dynamic executable and shared object

- the procedure linkage table (PLT)
 - read-only executable code, shared by all processes
 - essentially stubs for calling subroutines
- the global offset table (GOT)
 - read-write data, private (to each process)
 - relocated dynamically for each process
- the *dynamic structure*
 - read-only data, shared by all processes
 - contains relocation info and symbol table





Shared Libraries In Practice



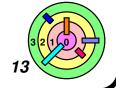
Shared libraries are used extensively in many modern systems

- often implemented with either prerelocation or position-independent code
- in Windows, they are known as *Dynamic-Link Libraries (DLLs)*
- in Unix, they are known as shared objects (.so files)
 - vs. static libraries (.a files)
- they need not be loaded when a program starts up
 - can be loaded when needed, i.e., on-demand
 - this way, the startup time of a program may be reduced



Disadvantages of DLLs and shared objects

- they can have dependencies
- different versions of the same library



Linking and Loading on Linux with ELF



x86 ELF (Excutable and Linking Format)

- used in Unix/Linux systems
 - not used in either MacOS X or Windows



Creating and using a shared library



Substitution



Shared library details



Versioning



Dynamic linking



Interpositioning

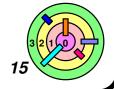


Shared Library Details



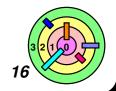
When a program is invoked via the exec system call

- the code that is first given control is 1d. so, the *run-time linker*
- the job of ld.so is to complete the linking and relocation steps, if necessary
 - it does some initial set up of linkages
 - then calls the actual program code
 - it may be called upon later to do some further loading and linking



Creating a Shared Library (1)

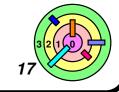
```
% gcc -fPIC -c myputs.c
% ld -shared -o libmyputs.so myputs.o
% gcc -o prog prog.c -L. -lpriv1 -lmyputs
% ./prog
./prog: error while loading shared libraries:
libmyputs.so: cannot open shared object file: No
such file or directory
% ldd prog
libmyputs.so => not found
libc.so.6 => /lib/tls/i686/cmoc/libc.so.6
/lib/ld-linux.so.2 => /lib/ld-linux.so.2
```



Creating a Shared Library (2)

```
% gcc -o prog prog.c -L. -lpriv1 -lmyputs -Wl,-rpath .
% ldd prog
   libmyputs.so => ./libmyputs.so
   libc.so.6 => /lib/tls/i686/cmoc/libc.so.6
   /lib/ld-linux.so.2 => /lib/ld-linux.so.2
% ./prog
My puts: sub1
My puts: sub2
My puts: sub3
```

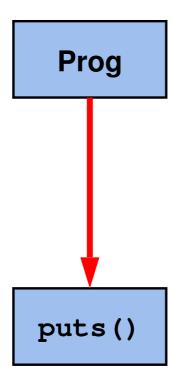
- □ "-₩1, -rpath ." means that what comes after -₩1 are linker options (i.e., pass them to the linker)
 - o in this example, the linker will be invoked with "-rpath ."
- also try "-W1, -rpath, ." if the space character is giving you trouble



Versioning

```
% gcc -fPIC -c myputs.c
% ld -shared -soname libmyputs.so.1 \
      -o libmyputs.so.1.0 myputs.o
% ldconfig -v -n .
% ln -s libmyputs.so.1 libmyputs.so
% gcc -o prog1 prog1.c -L. -lpriv1 -lmyputs \
      -Wl,-rpath .
% vi myputs.c
% gcc -fPIC -c myputs.c
% ld -shared -soname libmyputs.so.2 \
      -o libmyputs.so.2 myputs.o
% rm -f libmyputs.so
% ldconfig -v -n .
% ln -s libmyputs.so.2 libmyputs.so
% gcc -o prog2 prog2.c -L. -lpriv1 -lmyputs \
      -W1,-rpath .
  "libmyputs.so.1" is the soname
  - "libmyputs.so.1.0" is the real name
  - "libmyputs.so" is the linker name
```

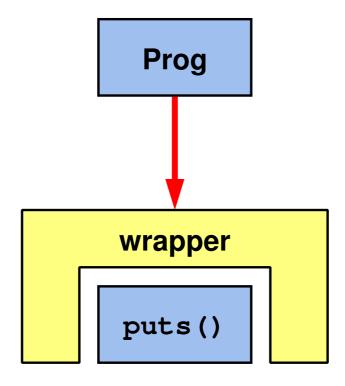
Interpositioning



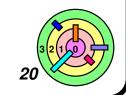
prog thinks it's calling puts()



Interpositioning



- prog thinks it's calling puts()
- interpose your puts()
 - you can call the original puts () that prog thought it was calling
 - security problem?!
 - "DLL injection" if you pick up a DLL unknowningly



How To ...

```
% cat myputs.c
#include <dlfcn.h>

int puts(const char *s) {
   int (*pptr) (const char *);

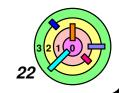
   pptr = (int(*) (const char*))dlsym(RTLD_NEXT, "puts");

   write(2, "calling myputs: ", 16);
   return (*pptr)(s);
}
```

- dlsym() returns a function pointer for the named function
- RTLD_NEXT asks for the next occurrence of the named function
 - O RTLD_DEFAULT will get you the first occurrence of the named function using the default library search order

Compiling/Linking It

- -D_GNU_SOURCE is needed or won't recognize RTLD_NEXT
- ldconfig may be in /sbin



What's Going On ...



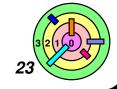
gcc/ld

- compiles code
- does static linking
- searches list of libraries
- adds references to shared objects



runtime

- program invokes ld.so (or ld-linux.so) to finish linking
- maps in shared objects
- does relocation and procedure linking as required
- dlsym() invokes ld.so to do more linking



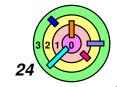
Delayed Wrapping



LD PRELOAD

- environment variable checked by ld.so
- specifies additional shared objects to search (first) when program is started

```
% gcc -o tputs tputs.c
% ./tputs
This is a boring message.
% setenv LD_PRELOAD ./libmyputs.so.1
% ./tputs
calling myputs: This is a boring message.
%
```



Extra Slides



Position-Independent Code Details

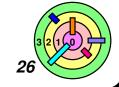


Processor-dependent; x86 32-bit version:



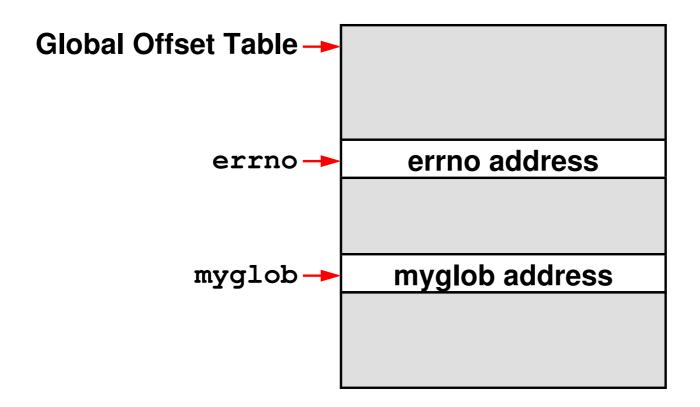
ELF requires 3 data structures for each dynamic executable and shared object

- the procedure linkage table (PLT)
 - read-only executable code, shared by all processes
 - essentially stubs for calling subroutines
- the global offset table (GOT)
 - read-write data, private (to each process)
 - relocated dynamically for each process
- the *dynamic structure*
 - read-only data, shared by all processes
 - contains relocation info and symbol table





Global-Offset Table: Data References



- Modules refer to global variables indirectly by looking up their addresses in this table
 - a registger contains the address of the table
 - modules refer to entries via their offsets
- When a module is loaded into memory
 - 1d.so puts the actual addresses into the GOT





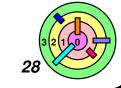
Procedure References













```
.PLT0:
 pushl 4(%ebx)
 imp 8 (%ebx)
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 push1 $name1RelOffset
      PLTO
 qmŗ
.PLT2:
  jmp name2(%ebx)
.PLT2next.
 push1 $name2RelOffset
 jmp .PLT0
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long .PLT1next
name2:
    .long .PLT2next
```

```
Relocation info:

GOT_offset(name1), symx(name1)

GOT_offset(name2), symx(name2)

_DYNAMIC
```



Before the first call to name1

- the actual address of the name1 procedure is not in the GOT
- first call to name1 invokes ld.so with indication of the above fact
- Id.so finds name1 and update the GOT





```
.PLT0:
 pushl 4(%ebx)
       8 (%ebx)
 qmp
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 push1 $name1RelOffset
      .PLTO
 qmŗ
PLT2:
 jmp name2(%ebx)
.PLT2next.
 push1 $name2RelOffset
     .PLTO
 qmŗ
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long .PLT1next
name2:
    .long .PLT2next
```

```
Relocation info:

GOT_offset(name1), symx(name1)

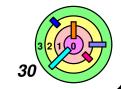
GOT_offset(name2), symx(name2)

_DYNAMIC
```



How did this work?

- references from module to name1 are statically linke to entry .PLT1 in the procedure-linkage table
 - the index into the symbol table in _DYNAMIC tells use where to start (in this example, it's 0 for name1)





```
.PLT0:
 pushl 4(%ebx)
       8 (%ebx)
 qmp
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 push1 $name1RelOffset
        .PLTO
 qmŗ
.PLT2:
       name2 (%ebx)
 dmĖ
PLT2next
 push1 $name2RelOffset
        .PLTO
 qmŗ
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long .PLT1next
name2:
    .long .PLT2next
```

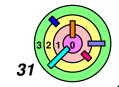
```
Relocation info:

GOT_offset (name1), symx (name1)

GOT_offset (name2), symx (name2)

_DYNAMIC
```

unconditional jump to the address contained in the name1 offset of the GOT (pointed to by the register ebx)



```
.PLT0:
 pushl 4(%ebx)
       8 (%ebx)
 qmp
 nop; nop
 nop; nop
.PLT1:
       name1 (%ebx)
 qmp
.PLT1next:
 push1 $name1RelOffset
        .PLTO
 qmŗ
.PLT2:
 jmp name2(%ebx)
PLT2next
 pushl $name2RelOffset
        .PLTO
 qmŗ
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long .PLT1next
name2:
    .long .PLT2next
```

```
Relocation info:

GOT_offset(name1), symx(name1)

GOT_offset(name2), symx(name2)

_DYNAMIC
```

- unconditional jump to the address contained in the name1 offset of the GOT (pointed to by the register ebx)
 - initially, this address is of the instruction following the jump instruction



```
.PLT0:
 pushl 4(%ebx)
 imp 8 (%ebx)
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 pushl $name1RelOffset
      .PLTO
 qmŗ
.PLT2:
 jmp name2(%ebx)
PLT2next
 push1 $name2RelOffset
       .PLTO
 qmŗ
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long .PLT1next
name2:
    .long .PLT2next
```

```
Relocation info:

GOT_offset (name1), symx (name1)

GOT_offset (name2), symx (name2)

_DYNAMIC
```

- pushd onto the stack the offset of the name1 entry in the relocation table
 - in the above example, this is 12 (if name1 is the 4th entry in the GOT)



```
.PLT0:
 pushl 4(%ebx)
       8 (%ebx)
 qmp
 nop; nop
 nop; nop
.PLT1:
  qmŗ
        name1(%ebx)
.PLT1next:
 push1 $name1RelOffset
        .PLTO
 qmŗ
.PLT2:
       name2 (%ebx)
  dmĖ
.PLT2next
 push1 $name2RelOffset
        .PLTO
 qmŗ
 Procedure-Linkage Table
```

```
Relocation info:

GOT_offset(name1), symx(name1)

GOT_offset(name2), symx(name2)

_DYNAMIC
```

- pushd onto the stack the offset of the name1 entry in the relocation table
 - in the above example, this would be 12 (if name1 is the 4th entry in the GOT)

```
.PLT0:
 pushl 4(%ebx)
 imp 8 (%ebx)
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 pushl $name1RelOffset
       .PLTO
  qmŗ
.PLT2:
       name2 (%ebx)
  dmĖ
.PLT2next
 push1 $name2RelOffset
        .PLTO
 qmŗ
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long .PLT1next
name2:
    .long .PLT2next
```

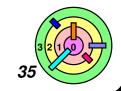
```
Relocation info:

GOT_offset(name1), symx(name1)

GOT_offset(name2), symx(name2)

_DYNAMIC
```

unconditional jump to the beginning of the procedure-linkage table, .PLT0



```
.PLT0:
 pushl 4(%ebx)
 imp 8 (%ebx)
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 push1 $name1RelOffset
      .PLTO
 qmŗ
.PLT2:
  jmp name2(%ebx)
.PLT2next.
 push1 $name2RelOffset
 jmp .PLT0
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
.long _DYNAMIC
.long identification
.long ld.so

name1:
.long .PLT1next
name2:
.long .PLT2next
```

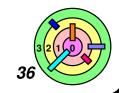
```
Relocation info:

GOT_offset(name1), symx(name1)

GOT_offset(name2), symx(name2)

_DYNAMIC
```

 pushd the "identification" of the current executing module on to the stack



```
.PLT0:
 pushl 4(%ebx)
  imp 8 (%ebx)
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 push1 $name1RelOffset
      .PLTO
 qmŗ
PLT2:
  jmp name2(%ebx)
PLT2next
 pushl $name2RelOffset
        .PLTO
 qmŗ
 Procedure-Linkage Table
```

```
cbx
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long .PLT1next
name2:
    .long .PLT2next
```

```
Relocation info:

GOT_offset(name1), symx(name1)

GOT_offset(name2), symx(name2)

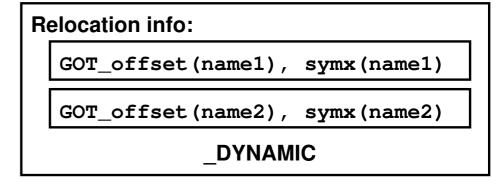
_DYNAMIC
```

- unconditional jump to ld.so
 - 1d. so can figure out who was making the request (TOS)
 - TOS-4 contains the GOT offset (12 in our example) of where to write the result into
 - **TOS-8 contains index into symbol table in _DYNAMIC**

```
.PLT0:
 pushl 4(%ebx)
 imp 8 (%ebx)
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 push1 $name1RelOffset
      .PLTO
 qmŗ
PLT2:
  jmp name2(%ebx)
.PLT2next.
 push1 $name2RelOffset
 jmp .PLT0
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long name1
name2:
    .long .PLT2next
```





- ld. so writes the actual address of the name1 procedure into the name1 entry of the GOT
- unwinds the stack a bit and then passes control to name1



After Calling name1

```
.PLT0:
 pushl 4(%ebx)
 imp 8 (%ebx)
 nop; nop
 nop; nop
.PLT1:
 qmp
       name1(%ebx)
.PLT1next:
 pushl $name1RelOffset
      .PLTO
 qmŗ
.PLT2:
  jmp name2(%ebx)
.PLT2next
 push1 $name2RelOffset
 jmp .PLT0
 Procedure-Linkage Table
```

```
__GLOBAL_OFFSET_TABLE:
    .long _DYNAMIC
    .long identification
    .long ld.so

name1:
    .long name1
name2:
    .long .PLT2next
```

```
Relocation info:

GOT_offset (name1), symx (name1)

GOT_offset (name2), symx (name2)

_DYNAMIC
```



Subsequent call to name1 invokes more directly

