SCATTERING HIDDEN MARKOV TREE

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ABSTRACT

A Scattering Convolutional Hidden Markov Tree (SCHMT) proposes a new inference mechanism for high-dimensional signals by combining the interesting signal representation created by the Scattering Transform (ST) to a powerful Probabilistic Graphical Model (PGM).

A wavelet scattering network computes a signal translation invariant and stable to deformations representation that still preserves the informative content of the signal. Such properties are acquired by cascading wavelet transform convolutions with nonlinear modulus and averaging operators.

The network's structure and its distributions are described using a Hidden Markov Tree (HMT). This yield a generative model for high-dimensional inference. It offers a mean for performing several inference tasks among which are predictions. The scattering convolutional hidden Markov tree displays promising results on both classification and segmentation tasks of complex images.

Index Terms— Scattering network, Deep network, Hidden Markov Model, Classification

1 Introduction

The standard approach when working with high dimensional signals can be expressed as a two step procedure. First the data are projected in a feature space where the task at hand (classification, regression...) is simplified. Then prediction is done using a simple predictor in this new representational space. Predictors such as logistic regression or linear Support vector Machine are common choices. The mapping can either be hand-build —e.g. Fourier transform, wavelet transform— or learned. In the last decade methods for learning the projection have drastically improved under the impulsion of the so called deep learning. Deep neural networks (sometime enriched by convolutional architecture) have been able to learn very effective representations for a given dataset and a given task. Such method have achieved state of the art on many standard problems as well as real world applications. And this despite using a very simple prediction mechanism —on top of a very clever projection method.

We proposes a method combining a recently proposed deterministic analytically tractable transformation inspired by

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deep convolutional to a probabilistic graphical model in order to create a powerful probabilistic tool to handle high dimensional prediction problems. In a similar fashion to the work done by Crouse on wavelet trees [?], we propose to describe Mallat's scattering convolutional scattering transform [?] using a hidden Markov tree. Doing so we develop a new framework to model high-dimensional inputs. As opposed to the commonly used simple classification method, once trained our model can tackle prediction problems but also other inference tasks —e.g. generation, sensitivity analysis...

In Section 2 we present the requisite background of high dimensional signal classification. Section ?? introduces the Scattering Transform and some of its properties. We fuse these to an hidden Markov Tree concepts in Section 4, propose our Scattering Hidden Markov Tree (SCHMT), and describe the inferential machinery. In Section 5 we perform classification on a selection of standard datasets. We draw conclusions in Section ??

2 Background

3 The Scattering transform

Introduction of SCN

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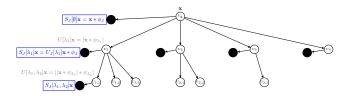


Fig. 1. Frequency decreasing scattering convolution network with J=4, L=1 and M=2. A node i at scale j_i generates $(j_i-1)\times L$ nodes.

4 The Scattering hidden Markov tree:

? introduced the use of scattering networks combined with a support vector machine classifier to achieve competitive classification performance on some problems. However this method only provides a boolean label for each class. Some methods to express the output of an SVM as a probability exists? but they are just a rescaling of the output and not a true probabilistic approach. If one is interested in a true probabilistic model to describe the scattering coefficients, it is quite natural to try expressing them as a probabilistic graphical model. Furthermore generative models are known to be better for inference tasks when the number of training example is low?.

4.1 Hidden Markov tree model

We propose an adaptation of those models to create a scattering convolutional hidden Markov tree composed of a set of visible nodes $\{S_i\}_{i\in\mathcal{T}}$ and a set of hidden node $\{\mathbf{H}_i\}_{i\in\mathcal{T}}$. Both sets are organized in a tree structure such that for any index i of the tree, $S_i \in \mathbb{R}$ and $H_i \in [1, K]$ where K is the number of possible hidden states. The initial state is drawn from a discrete non uniform distribution π_0 such that, $\forall k \in [1, K] \pi_0(k) = P(H_0 = k)$. For any index i of the tree, the emission distribution describes the probability of the visible node S_i conditional to the hidden state H_i such that, $\forall i \in \mathcal{T}, \forall k \in [1, K]$ and $\forall s \in \mathbb{R}$ $P(S_i = s_i|H_i = k) = P_{\theta_{k,i}}(s)$, where $P_{\theta_{k,i}}$ belongs to a parametric distribution family and $\theta_{k,i}$ is the vector of emission parameters for the state k and node i. In the remainder of the paper the emission distribution is Gaussian so that $P(S_i = s|H_i = k) = \mathcal{N}(\mu_{k,i}, \sigma_{k,i})$, where $\theta_{k,i} = (\mu_{k,i}, \sigma_{k,i})$ with $\mu_{k,i}$ and $\sigma_{k,i}$ being respectively the mean and the variance of the Gaussian for the k-th value of the mixture and the node i. Finally the probability for the hidden node H_i to be in a state k given its father's state g is characterized by a transition probability such that $\forall i \in \mathcal{T} \backslash \{0\} \ \forall g,k \in [\![1,K]\!]^2 \ \epsilon_i^{(gk)} = P(H_i = k|H_{\rho(i)} = g)$ where ϵ_i defines a transition probability matrix such that $P(H_i = k) = \sum_{g=1}^K \epsilon_i^{(gk)} P(H_{\rho(i)} = g)$.

Such a model is pictured in Figure 2 and for a given scattering architecture —i.e. fixed $M,\ J$ and L— the SCHMT model is fully parametrized by,

$$\Theta = (\pi_0, \{\epsilon_i, \{\theta_{k,i}\}_{k \in \llbracket 1, K \rrbracket}\}_{i \in \mathcal{T}}). \tag{1}$$

This model implies to do two assumptions on the scattering transform. First one need to assume — K-populations— that a signal's scattering coefficients can be described by K clusters. This is a common assumptions for standard wavelets [?] and hence it can be extended to the scattering transform. The SCHMT also assumed —persistence— that the informative character of a coefficients is propagated across layers. This assumption is sound since ...

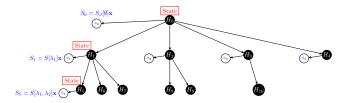


Fig. 2. Scattering convolutional hidden Markov tree.

4.2 Learning the tree parameters

The SCHMT is trained using the smoothed version of the Expectation-Maximisation algorithm (?) for hidden Markov trees proposed by [?] and adapted to non-homogeneous and non-binary trees.

```
Meta-parameters:
 K
Initialization:
// P_{\theta_{k,i}}(s_i):
 for All the nodes i of the tree T do
          P_{\theta_{k,i}}(s_i) = \mathcal{N}(s_i|\mu_{k,i},\sigma_{k,i})
// Loop over the leaves i of the tree :
 for All the leaves i of the tree T do
         \beta_{i}(k) = \frac{P_{\theta_{i,i}}(s_{i})P(H_{i}=k)}{\sum_{g=1}^{K} P_{\theta_{g,i}}(s_{i})P(H_{i}=g)}
\beta_{i,\rho(i)}(k) = \sum_{g=1}^{K} \frac{\beta_{i}(g)\epsilon_{i}^{(kg)}}{P(H_{i}=g)}.P(H_{\rho(i)}=k)
         l_i = 0
end
Induction:
// Bottom-Up loop over the nodes of the tree :
for All non-leaf nodes i of the tree \mathcal{T} do
M_{i} = \sum_{k=1}^{K} P_{\theta_{k,i}}(s_{i}) \prod_{j \in c(i)} \frac{\beta_{j,i}(k)}{P(H_{i}=k)^{n_{i}-1}}
l_{i} = \log(M_{i}) + \sum_{j \in c(i)} l_{j}
\beta_{i}(k) = \frac{P_{\theta_{k,i}(s_{i})} \prod_{j \in c(i)} (\beta_{j,i}(k))}{P(H_{i}=k)^{n_{i}-1} M_{i}}
         for All the children nodes j of node i do
                \beta_{i \setminus c(i)}(k) = \frac{\beta_i(k)}{\beta_{i,j}(k)}
         \beta_{i,\rho(i)}(k) = \sum_{g=1}^{K} \frac{\beta_{i}(g)\epsilon_{i}^{(kg)}}{P(H_{i}=g)} . P(H_{\rho(i)}=k)
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Algorithm 1: Smoothed upward algorithm.

5 Classification results

6 Conclusion

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\begin{aligned} & \textbf{Meta-parameters:} \\ & K \\ & \textbf{Initialization:} \\ & \alpha_0(k) = 1 \\ & \textbf{Induction:} \\ & \text{/ Top-Down loop over the nodes of the tree:} \\ & \textbf{for } All \ nodes \ i \ of \ the \ tree \ \mathcal{T} \backslash \{0\} \ \textbf{do} \\ & & | \ \alpha_i(k) = \\ & & \frac{1}{P(H_i = k)} \sum_{g=1}^K \alpha_{\rho(i)}(g) \epsilon_i^{(gk)} \beta_{\rho(i)\backslash i}(g) P(H_{\rho(i)} = g) \\ & \textbf{end} \end{aligned}
```

Algorithm 2: Smoothed downward algorithm.

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\begin{aligned} &\textbf{Meta-parameters:} \\ &K, \\ &\text{Distribution family for } P_{\theta} \;; \qquad \text{// Here Gaussian} \\ &N \;; \qquad \text{// Number of observed realizations of the signal} \\ &\textbf{Initialization:} \\ &\pi_0(k) = \frac{1}{N} \sum_{n=1}^N P(H_0^n = m | s_0^n, \Theta^l) \\ &\textbf{Induction:} \\ &\text{// Loop over the nodes of the tree:} \\ &\textbf{for } All \ nodes \ i \ of the \ tree \ \mathcal{T} \backslash \{0\} \ \textbf{do} \\ & & P(H_i = k) = \frac{1}{N} \sum_{n=1}^N P(H_i^n = k | \bar{s}_0^n, \Theta^l), \\ &\epsilon_i^{gk} = \frac{\sum_{n=1}^N P(H_i^n = k, H_{\rho(i)}^n = g | \bar{s}_0^n, \Theta^l)}{NP(H_{\rho(i)} = k)}, \\ & & \mu_{k,i} = \frac{\sum_{n=1}^N s_i^n P(H_i^n = k | \bar{s}_0^n, \Theta^l)}{NP(H_i = k)}, \\ & & \sigma_{k,i}^2 = \frac{\sum_{n=1}^N (s_i^n - \mu_{k,i})^2 P(H_i^n = k | \bar{s}_0^n, \Theta^l)}{NP(H_i = k)}. \\ & \textbf{end} \end{aligned}
```

Algorithm 3: M-step of the EM algorithm.

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8 REFERENCES