# CP1 for NPRE 501

Jin Whan Bae

2017-11-01

## 1 Problem Definition

Table 1 lists the constants used in the problem.

Parameter	Value	[Unit]
Diamater	6	[cm]
Radius	3	[cm]
Geometry	Sphere	
k	15	$[rac{W}{mK}] \ [rac{kg}{m_{_{_{I}}}^{3}}]$
Density	8000	$\left[\frac{kg}{m^3}\right]$
Specific Heat	500	$\left[\frac{m_J}{kqK}\right]$
$\alpha$	3.75e-6	$egin{aligned} \left[rac{J}{kgK} ight] \ \left[rac{m^2}{s} ight] \end{aligned}$

Table 1: Problem Constants. Derived constants are in bold.

Differential Equation:

$$\frac{1}{\alpha} \cdot \frac{dT}{dt} = \frac{1}{r^2} \frac{d}{dr} r^2 \frac{dT}{dr}$$

**Boundary Conditions:** 

$$T(0,t) = finite \quad OR \quad \frac{dT}{dr}(r=0,t) = 0$$
 
$$\frac{dT}{dr}(r=R) = 0$$

**Initial Condition:** 

$$T(r,0) = \frac{T_0}{2} (1 - \cos\left(\frac{\pi \cdot r}{R}\right))$$

## 1.1 Finding Steady State

Since there is no heat generation or leakage (r=R is insulated), the steady state temperature is a constant throughout the sphere.

Expressing mathematically,

 $T_{ss}$  is when  $\frac{dT}{dt} = 0$ :

$$0 = \frac{1}{r^2} \frac{d}{dr} r^2 \left(\frac{dT_{ss}}{dr}\right)$$

$$\frac{C_1}{r^2} = \frac{dT_{ss}}{dr}$$

$$-\frac{C_1}{r} + C_2 = T_{ss}$$

applying BC:

at r = 0, finite, makes  $C_1 = 0$ 

$$T_{ss} = C_2$$

the numerical value of this constant can be found doing an energy balance of the system.

$$\int_0^R \frac{T_0}{2} (1 - \cos(\frac{\pi r}{R})) r^2 dr = \int_0^R C r^2 dr$$

$$\frac{T_0}{2} \int_0^R (r^2 - r^2 \cos(\frac{\pi r}{R})) dr = C \frac{R^3}{3}$$

using separation of variables:

$$\frac{T_0}{2} \left( \frac{R^3}{3} - \left( \frac{r^2 R}{\pi} \sin(\frac{\pi r}{R}) \right) \right)_0^R - \frac{2R}{\pi} \int_0^R r \sin(\frac{\pi r}{R}) dr = C \frac{R^3}{3}$$

Solving this:

$$\frac{T_0}{2}(\frac{R^3}{3} + \frac{2R^3}{\pi^2}) = C\frac{R^3}{3}$$

$$C = T_{ss} = \frac{3T_0}{2} (\frac{\pi^2 + 6}{3\pi^2}) \approx 0.804T_0$$

#### 2 **Numerical Solution**

$$\frac{1}{\alpha} \cdot \frac{dT}{dt} = \frac{2}{r} \frac{dT}{dr} + \frac{d^2T}{dr^2}$$

Applying the finite difference method, central for r and explicit for t:

$$\frac{1}{\alpha} \cdot \frac{T_k^u - T_k^{u-1}}{\Delta t} = \frac{2}{r_k} \left( \frac{T_{k+1}^{u-1} - T_{k-1}^{u-1}}{2\Delta r} \right) + \frac{T_{k-1}^{u-1} - 2T_k^{u-1} + T_{k+1}^{u-1}}{\Delta r^2}$$

where u is the temporal step and k is the spacial step.

Solving for 
$$T_k^{u+1}$$
: 
$$T_k^{u+1} = T_k^u + \alpha \frac{\Delta t}{\Delta r \cdot r} (T_{k+1}^u + T_{k-1}^u) + \alpha * \frac{\Delta t}{(\Delta r)^2} (T_{k+1}^u - 2T_k^u + T_{k-1}^u)$$

Applying neuman boundary condition at r=0:

$$\frac{dT(0,t)}{dr} = 0$$

$$\frac{T_1^u - T_{-1}^u}{2\Delta r} = 0$$

$$T_1^u = T_{-1}^u$$

This gives: 
$$T_0^{u+1} = T_0^u + \alpha * \frac{\Delta t}{(\Delta r)^2} (2T_1^u - 2T_0^u)$$

Applying neuman boundary condition at r=R (k=K at r=R):

$$-k\frac{dT(R,t)}{dr} = 0$$

$$\frac{T_{K+1}^u - T_{K-1}^u}{2\Delta r} = 0$$

$$T_{K+1}^u = T_{K-1}^u$$

This gives:

$$T_K^{u+1} = T_K^u + \alpha * \frac{\Delta t}{(\Delta r)^2} (2T_{K-1}^u - 2T_K^u)$$

## 3 Appendix A

## 3.1 a. Final Temperature Distribution in the Sphere

The final temperature distribution will be a cosine curve with the highest point at r = 0, gradually going down to the minimum value at r = R.

## 4 Appendix B

### 4.1 Analytical solution for solving T(r,t) directly

$$\frac{1}{\alpha} \cdot \frac{dT}{dt} = \frac{1}{r^2} \frac{d}{dr} r^2 \frac{dT}{dr}$$

**Boundary Conditions:** 

$$T(0,t) = finite$$

$$\frac{dT}{dr}(r=R) = 0$$

**Initial Condition:** 

$$T(r,0) = \frac{T_0}{2} (1 - \cos\left(\frac{\pi \cdot r}{R}\right))$$

set:

$$T(r,t) = \frac{\overline{T}(r,t)}{r} + T_s s$$

$$\overline{T}(r,t) = T(r,t)r + T_s s r$$

plugging this back into the differential equation:

$$\frac{1}{\alpha} \cdot \frac{d\overline{T}}{dt} \frac{1}{r} = \frac{1}{r^2} \frac{d}{dr} r^2 \left( \frac{d\overline{T}}{dr} \frac{1}{r} - \frac{1}{r^2} \overline{T} \right)$$

$$\frac{1}{\alpha} \cdot \frac{d\overline{T}}{dt} = \frac{1}{r} \frac{d}{dr} (\frac{d\overline{T}}{dr} r - \overline{T})$$

$$\frac{1}{\alpha} \cdot \frac{d\overline{T}}{dt} = \frac{1}{r} \left( \frac{d^2 \overline{T}}{dr^2} r + \frac{d\overline{T}}{dr} - \frac{d\overline{T}}{dr} \right)$$

$$\frac{1}{\alpha} \cdot \frac{d\overline{T}}{dt} = \frac{d^2\overline{T}}{dr^2}$$

where

$$\overline{T}(0,t) = 0$$

$$\frac{d\overline{T}}{dr} = \frac{\overline{T}}{R}$$

and initial condition

$$\overline{T}(r,0) = r \frac{T_0}{2} (1 - \cos(\frac{\pi r}{R})) - T_{ss}r$$

This turns into a cartesian problem.

Applying Separation of Variables:

$$\overline{T}(r,t) = \Gamma(t) \Psi(r)$$

Applying the new variables, dividing both sides by  $\Gamma(t)\Psi(r)$ , and setting it to a new variable  $-\beta^2$ :

$$\frac{1}{\alpha\Gamma} \cdot \frac{d\Gamma}{dt} = \frac{d^2\Psi}{dr^2} \frac{1}{\Psi} = -\beta^2$$

Solving for  $\Psi$  first:

$$\frac{d^2\Psi}{dr^2}\frac{1}{\Psi} = -\beta^2$$

$$\frac{d^2\Psi}{dr^2} + \beta^2\Psi = 0$$

$$\Psi(r) = C_1 sin(\beta r) + C_2 cos(\beta r)$$

**Boundary Conditions:** 

Since:

$$\frac{dT}{dr} = -\frac{\overline{T}}{r^2} + \frac{1}{r}\frac{d\overline{T}}{dr}$$

The boundary conditions become:

$$-\Psi(r=0) = 0$$

$$-k(\frac{\Psi}{R^2} + \frac{d\Psi}{dr}\frac{1}{R}) = 0$$

Applying the first boundary condition, interpreting as  $\Psi(r=0)=0, C_2=0$  Applying the second boundary condition,

$$-\frac{C_1\sin(\beta R)}{R^2} + C_1\cos(\beta r)\beta = 0$$

$$-\sin(\beta R) + R\beta\cos\beta R = 0$$

$$\tan(\beta R) = R\beta$$

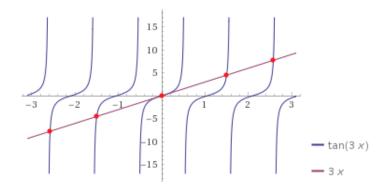


Figure 1: Plot of tan(3x) = 3x.

 $\beta$  is the zeros of that equation (illustrated in fig. 1)

Solving for  $\Gamma(t)$ :

$$\frac{1}{\alpha \Gamma} \cdot \frac{d\Gamma}{dt} = -\beta_n^2$$

$$\frac{1}{\alpha\Gamma}\cdot\frac{d\Gamma}{dt} = -\beta_n^2\alpha\Gamma$$

$$\Gamma(t) = A_1 e^{-\alpha \beta_n^2 t}$$

This makes  $\overline{T}(r,t)$ :

$$\overline{T}(r,t) = \sum_{n=1}^{\infty} A_n e^{-\alpha \beta_n^2 t} sin(\beta_n r)$$

Applying initial condition and orthogonality:

$$T\sum_{n=1}^{\infty} A_n \sin(\beta_n r) = r \frac{T_0}{2} (1 - \cos(\frac{\pi r}{R})) - T_{ss}r$$

$$A_n = \frac{\int_0^R (r \frac{T_0}{2} (1 - \cos(\frac{\pi r}{R})) - T_{ss} r) \sin(\beta_n r) dr}{\int_0^R (\sin(\beta_n r))^2 dr}$$
 Plugging all this into  $T(r, t)$ :

$$T(r,t) = \sum_{n=1}^{\infty} A_n \frac{\sin(\beta_n r)}{r} e^{-\beta_n^2 \alpha t} + T_{ss}$$

#### 4.2 Analytical solution by defining new temperature

$$T'(r,t) = T(r,t) - T_{ss}$$

$$T'(r,t) + T_{ss} = T(r,t)$$

where  $T_{ss}$  is:

$$0 = \frac{1}{r^2} \frac{d}{dr} r^2 \left(\frac{dT_{ss}}{dr}\right)$$

$$\frac{C_1}{r^2} = \frac{dT_{ss}}{dr}$$

$$-\frac{C_1}{r} + C_2 = T_{ss}$$

applying BC: at r = 0, finite, makes  $C_1 = 0$ 

$$T_{ss} = C_2$$

Plugging the new definition into the original differential equation: differential equation becomes:

$$\frac{1}{\alpha}\left(\frac{dT'}{dt} + \frac{dT_{ss}}{dt}\right) = \frac{1}{r^2}\frac{d}{dr}r^2\left(\frac{dT'}{dr} + \frac{dT_{ss}}{dr}\right)$$

Considering  $\frac{dT_{ss}}{dt} = \frac{dT_{ss}}{dr} = 0$ ,

$$\frac{1}{\alpha} \cdot \frac{dT'}{dt} = \frac{1}{r^2} \frac{d}{dr} r^2 \cdot \frac{dT'}{dr}$$

**Boundary Conditions:** 

$$T'(0,t) = finite$$

$$\frac{dT'}{dr}(r=R) = 0$$

**Initial Condition:** 

$$T'(r,0) = \frac{T_0}{2}(1 - \cos(\frac{\pi \cdot r}{R})) - C_2$$

set:

$$T'(r,t) = \frac{\overline{T'}}{r}$$

$$\frac{1}{\alpha} \cdot \frac{d\overline{T'}}{dt} \frac{1}{r} = \frac{1}{r^2} \frac{d}{dr} r^2 (\frac{d\overline{T'}}{dr} \frac{1}{r} - \frac{1}{r^2} \overline{T'})$$

$$\frac{1}{\alpha} \cdot \frac{d\overline{T'}}{dt} = \frac{1}{r} \frac{d}{dr} (\frac{d\overline{T'}}{dr}r - \overline{T'})$$

$$\frac{1}{\alpha} \cdot \frac{d\overline{T'}}{dt} = \frac{1}{r} \left( \frac{d^2 \overline{T'}}{dr^2} r + \frac{d\overline{T'}}{dr} - \frac{d\overline{T'}}{dr} \right)$$

$$\frac{1}{\alpha} \cdot \frac{d\overline{T'}}{dt} = \frac{d^2\overline{T'}}{dr^2}$$

turns into a cartesian problem.

Applying Separation of Variables:

$$\overline{T'}(r,t) = \Gamma(t)\Psi(r)$$

**Boundary Conditions:** 

$$\Psi(r=0) = finite$$

$$\frac{d\Psi}{dr}(r=R) = 0$$

Applying the new variables, dividing both sides by  $\Gamma(t)\Psi(r)$ , and setting it to a new variable  $-\beta^2$ :

$$\frac{1}{\alpha\Gamma} \cdot \frac{d\Gamma}{dt} = \frac{d^2\Psi}{dr^2} \frac{1}{\Psi} = -\beta^2$$

Solving for  $\Psi$  first:

$$\frac{d^2\Psi}{dr^2}\frac{1}{\Psi} = -\beta^2$$

$$\frac{d^2\Psi}{dr^2} + \beta^2\Psi = 0$$

$$\Psi(r) = C_1 sin(\beta r) + C_2 cos(\beta r)$$

Applying the first boundary condition, interpreting as  $\Psi(r=0)=0, C_2=0$ Applying the second boundary condition,

$$-\frac{C_1 \sin(\beta R)}{R^2} + C_1 \cos(\beta r)\beta = 0$$
$$-\sin(\beta R) + R\beta \cos \beta R = 0$$
$$\tan(\beta R) = R\beta$$

 $\beta$  is the zeros of that equation.

Solving for  $\Gamma(t)$ :

$$\frac{1}{\alpha\Gamma} \cdot \frac{d\Gamma}{dt} = -\beta_n^2$$

$$\frac{1}{\alpha\Gamma} \cdot \frac{d\Gamma}{dt} = -\beta_n^2 \alpha\Gamma$$

$$\Gamma(t) = A_1 e^{-\alpha \beta_n^2 t}$$

This makes  $\overline{T'}(r,t)$ :

$$\overline{T'}(r,t) = A_n e^{-\alpha \beta_n^2 t} sin(\beta_n r)$$

Solving back for T'(r, t):

$$T'(r,t) = \frac{A_n}{r} e^{-\alpha \beta_n^2 t} sin(\beta_n r)$$

Applying initial condition and orthogonality:

$$T'(r,0) = \frac{A_n}{r} sin(\beta_n r) = \frac{T_0}{2} (1 - \cos(\frac{\pi \cdot r}{R})) + C_2$$

$$A_n = \frac{\int_0^R r^3 \sin(\beta_n r) (\frac{T_0}{2} \cdot (1 - \cos\frac{\pi r}{R}) + C_2) dr}{\int_0^R r^2 \sin^2 \beta_n r dr}$$

The analytical solution is:

$$T'(r,t) = \frac{\int_0^R r^3 \sin(\beta_n r) (\frac{T_0}{2} \cdot (1 - \cos\frac{\pi r}{R}) + T_{ss}) dr}{\int_0^R r^2 \sin^2 \beta_n r dr} e^{-\alpha \beta_n^2 t} \sin(\beta_n r)$$

$$T = \frac{\int_0^R r^3 \sin(\beta_n r) (\frac{T_0}{2} \cdot (1 - \cos\frac{\pi r}{R}) + T_{ss}) dr}{\int_0^R r^2 \sin^2 \beta_n r dr} e^{-\alpha \beta_n^2 t} \sin(\beta_n r) + T_{ss}$$

Since the solution from section 4.1 with n = 0 covers the steady state case, this problem is redundant and provides no new insight into the problem from section 4.1.

#### 4.3 Code1