#5 SLAM

SLAM Toolbox basic installation

Install with:

```
sudo apt-get install ros-humble-slam-toolbox
```

Reference launch file at:

https://github.com/SteveMacenski/slam_toolbox/blob/ros2/launch/online_sync_launch.py.

install also:

```
sudo apt install ros-humble-navigation2
sudo apt install ros-humble-nav2-bringup
```

Content

The rest of information can be found in the corresponding chapter slides.