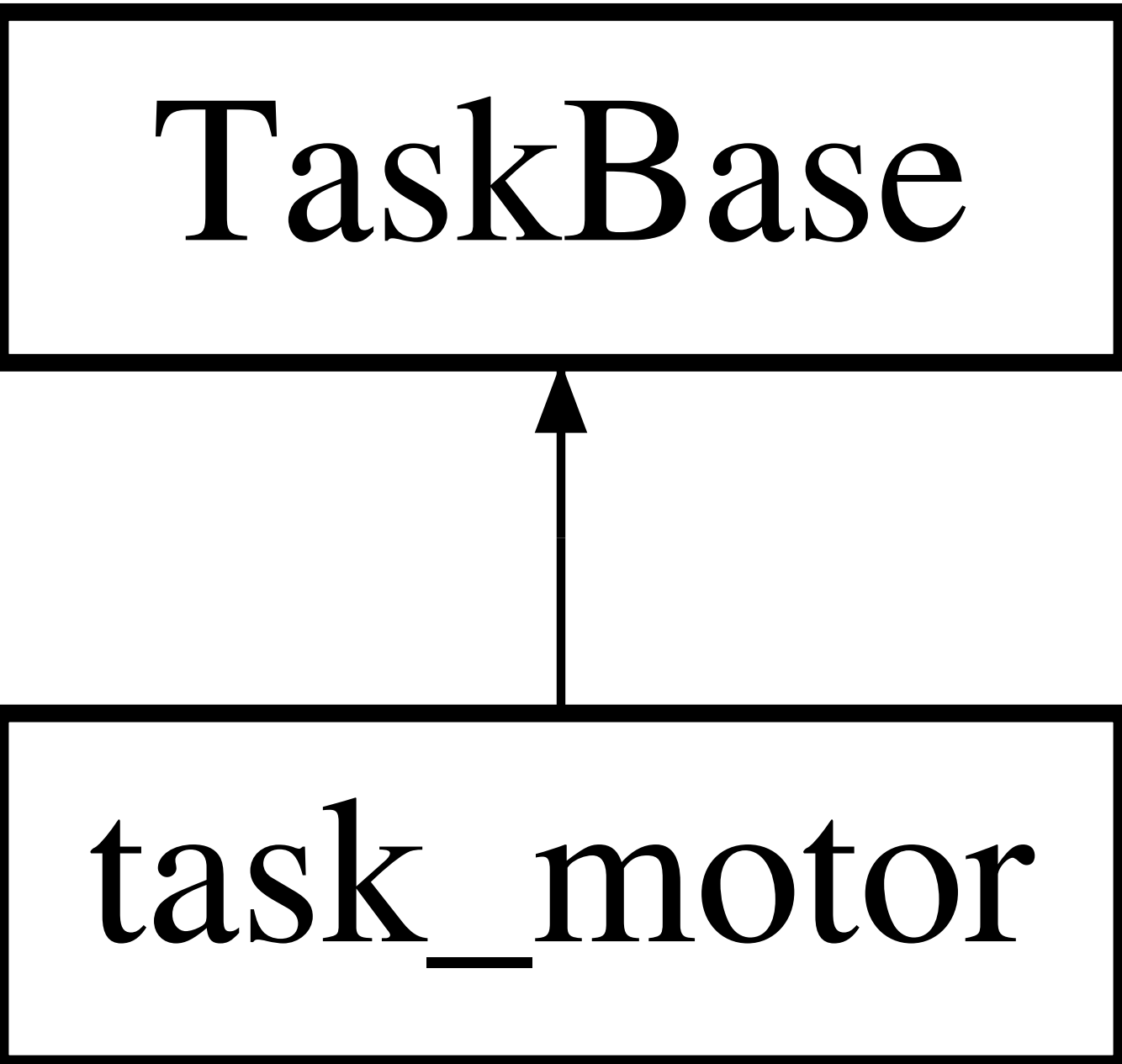
TaskBase
task_motor