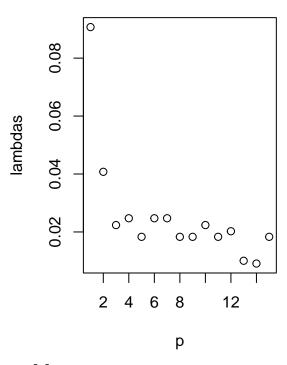
#### **Q2**)

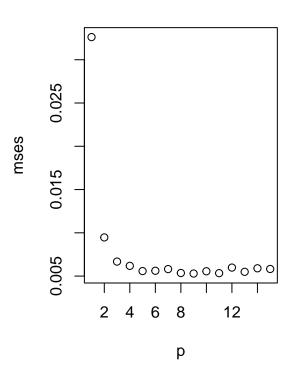
#### Part a)

```
library(glmnet())
## Loading required package: Matrix
## Loaded glmnet 4.1-8
set.seed(42)
data <- read.csv("Quality.csv")</pre>
Y <- ts(data)
t <- as.vector(time(Y))
poly.Time = poly(t, 15)
X <- model.matrix(~ poly.Time) # 180x15
y \leftarrow as.vector(Y) # 180x1
Time.test = c(5, 14, 29, 30, 36, 39, 66, 71, 79, 84, 85, 96, 109,
               112, 135, 136, 139, 146, 156, 171)
Time.train = t[-Time.test]
X.train <- X[Time.train, 2:16]</pre>
X.test <- X[Time.test, 2:16]</pre>
y.train <-y[Time.train]</pre>
y.test <- y[Time.test]</pre>
Log.Lambda.Seq = seq(-7, 3, by = 0.1)
Lambda.Seq = c(0, exp(Log.Lambda.Seq))
for (ALPHA in c(0, 0.5, 1)) {
  lambdas <- c()</pre>
  mses <- c()
  for (p in 1:15){
    # 1) Fit model to training data
    Xmatrix <- X.train[, 1:p]</pre>
    if (p == 1){
      Xmatrix <- cbind(0, Xmatrix)</pre>
    CV = cv.glmnet(Xmatrix, y.train, type.measure="mse", lambda= Lambda.Seq, alpha=ALPHA, family="gaus
    lambdas <- c(lambdas, CV$lambda.1se)</pre>
    mses <- c(mses, CV$cvm[CV$index[2]])</pre>
  p \leftarrow c(1:15)
  par(mfrow=c(1, 2))
  plot(x=p, lambdas, main = sprintf("Lambdas for alpha = %s", ALPHA))
  plot(x=p, mses, main = sprintf("MSEs for alpha = %s", ALPHA))
  print("Chosen p = ")
  print(which.min(mses))
```

# Lambdas for alpha = 0

# MSEs for alpha = 0

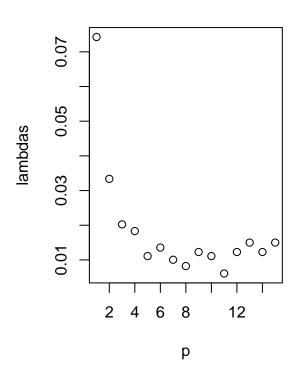


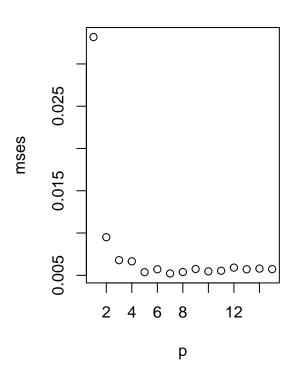


- ## [1] "Chosen p = " ## [1] 9

## Lambdas for alpha = 0.5

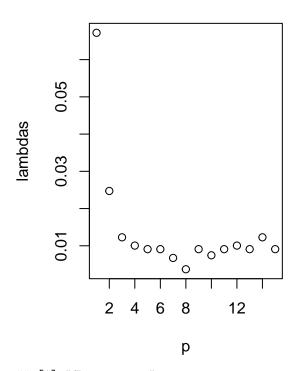
## MSEs for alpha = 0.5

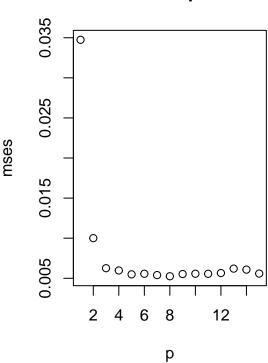




## Lambdas for alpha = 1

### MSEs for alpha = 1





We use the MSE plots to choose the polynomial degree that minimizes the MSE of the regularized model.

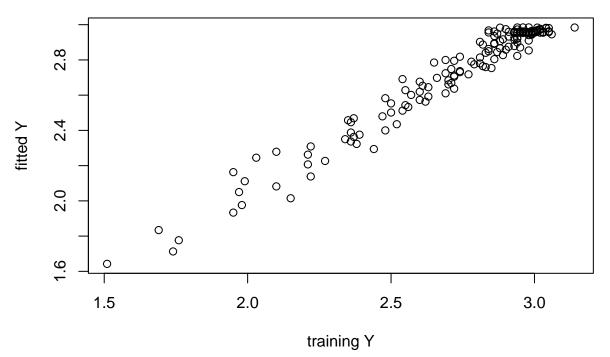
- For ridge  $(\alpha = 0)$  choose p = 9.
- For lasso  $(\alpha = 1)$  choose p = 8
- For elastic net ( $\alpha = 0.5$ ) choose p = 7

Do you think that simpler models compared to what you have chosen here may have similar performances? Comment on your observation.

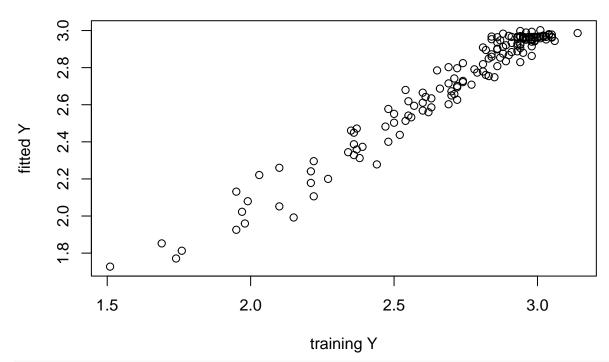
• Yes. I think a square root model  $Y_t = \alpha \sqrt{t}$  can have a better fit than polynomial models.

#### Part b)

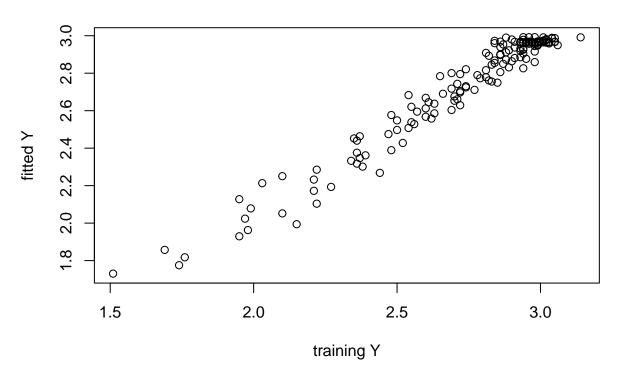
#### Alpha = 0



### Alpha = 0.5



Alpha = 1

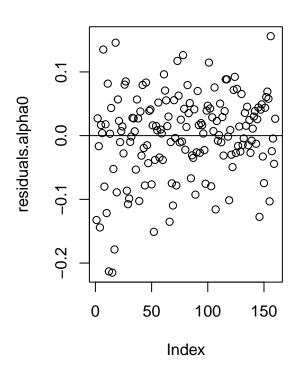


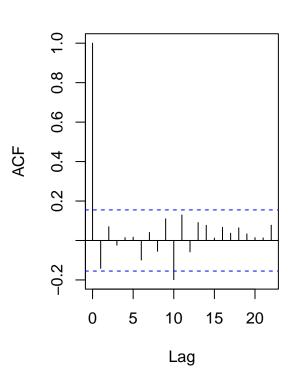
### Part c)

```
plot of residuals for \alpha = 0
residuals.alpha0 = y.train- fitted.alpha0
par(mfrow=c(1, 2))
plot(residuals.alpha0, main = "Residuals for alpha = 0")
abline(h=0)
acf(residuals.alpha0)
```

## Residuals for alpha = 0

## Series residuals.alpha0



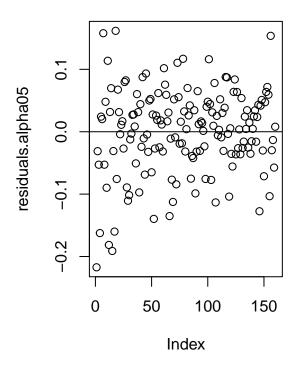


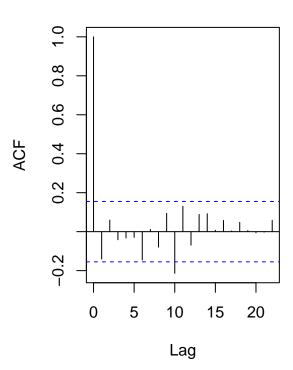
plot of residuals for  $\alpha = 0.5$ 

```
residuals.alpha05 = y.train- fitted.alpha05
par(mfrow=c(1, 2))
plot(residuals.alpha05, main = "Residuals for alpha = 0.5")
abline(h=0)
acf(residuals.alpha05)
```

## Residuals for alpha = 0.5

### Series residuals.alpha05



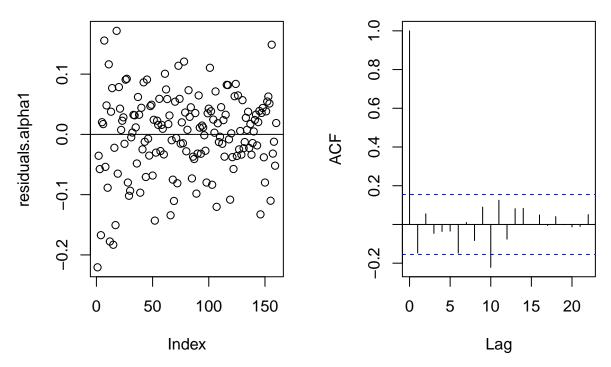


plot of residuals for  $\alpha=1$ 

```
residuals.alpha1 = y.train- fitted.alpha1
par(mfrow=c(1, 2))
plot(residuals.alpha1, main = "Residuals for alpha = 1")
abline(h=0)
acf(residuals.alpha1)
```

### Residuals for alpha = 1

## Series residuals.alpha1



All ACF's have: - Only a small amount of peaks outside the blue lines - No slow decreasing trend that could indicate a trend in the residuals - No period.

All plots of residuals look randomly spread around zero, so we conclude the residuals from all three models represent iid noise.