

# Stability of a collisionless plasma in a solid torus

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Joint work with Walter Strauss

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- The dynamics of ions / electrons:  $f^\pm(t, x, v) \geq 0$  solves [Vlasov](#)

$$f_t^\pm + \hat{v} \cdot \nabla_x f^\pm \pm \left( E + \hat{v} \times B \right) \cdot \nabla_v f^\pm = 0$$

on  $\Omega \times \mathbb{R}^3$  (ignore collisions), with the fields  $E, B$  solving the [Maxwell](#) equations. In term of potentials (Coulomb gauge  $\nabla \cdot A = 0$ ):

$$-\Delta \phi = \rho, \quad \partial_t^2 A - \Delta A = j - \partial_t \nabla \phi.$$

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- [Relativistic VM](#): particle velocity  $\hat{v} = \frac{v}{\langle v \rangle}$ , with  $\langle v \rangle = \sqrt{1 + |v|^2}$ .
- Wellposedness is a big open problem ( $\Omega$  with or without a boundary)! I focus on the issue of the [stability theory](#) of equilibria.

When  $\Omega$  has a boundary, we impose

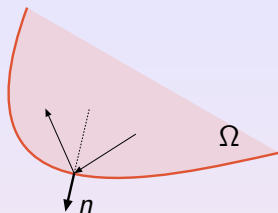
- **Specular** boundary condition on  $f^\pm$ :

$$f^\pm(t, x, v) = f^\pm(t, x, v - 2(v \cdot n)n)$$

for  $n \cdot v < 0$  and  $x \in \partial\Omega$ .

- **Perfect conductor** boundary conditions on  $E, B$ :

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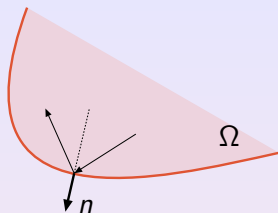
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- Specular BC assures casimirs' invariants:  $\frac{d}{dt} \iint_{\Omega \times \mathbb{R}^3} \Phi(f^\pm) dx dv = 0$ .
- Perfect conductor BC (in fact,  $(E \times B) \cdot n = 0$ ) assures the conservation of energy:

$$\iint_{\Omega \times \mathbb{R}^3} \langle v \rangle (f^+ + f^-) dv dx + \frac{1}{2} \int_{\Omega} (|E|^2 + |B|^2) dx = E_0.$$



- **Equilibria:** infinitely many (e.g., Rein '92), including

$$f^+ = \mu^+(e^+), \quad f^- = \mu^-(e^-)$$

for arbitrary  $\mu^\pm(\cdot)$ , where  $e^\pm := \langle v \rangle \pm \phi(x)$  denote the particle energy (invariant), together with Maxwell equations:  $j = 0$ ,  $B = 0$ , and

$$-\Delta\phi = \int_{\mathbb{R}^3} (\mu^+ - \mu^-) dv, \quad \phi|_{\partial\Omega} = \text{const.}$$

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- In a domain with **symmetry:** additional conservations. **Equilibria:**

$$f^+ = \mu^+(e^+, p^+), \quad f^- = \mu^-(e^-, p^-).$$

- Guo '99:  $\Omega$  is  $x_3$ -translation invariant.  $p^\pm := v_3 \pm A_3(x_1, x_2)$
- Guo'99, Lin-Strauss '07-08:  $\Omega$  is rotational invariant.  
 $p^\pm := r(v_\theta \pm A_\theta(r, z))$
- Maxwell becomes a semi-linear elliptic system for  $(\phi, A_3)$ .

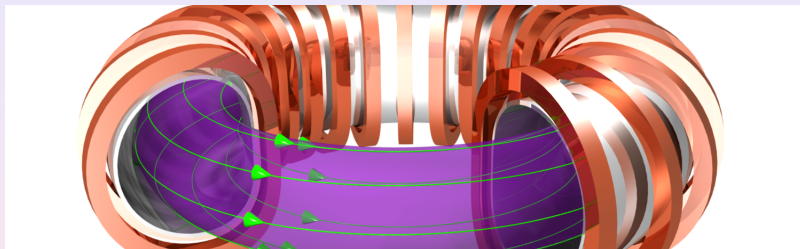


Figure : *Illustrated is a tokamak! Figure credit: internet.*



- $\Omega$  is a solid torus (N-Strauss, ARMA '14, Fig 1.1):

$\Omega =$

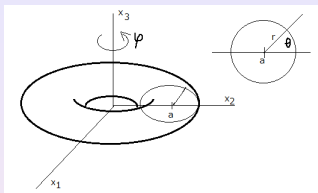


Figure : Shown are toroidal coordinates  $(r, \theta, \varphi)$ . Set  $\beta := a + r \cos \theta$ .

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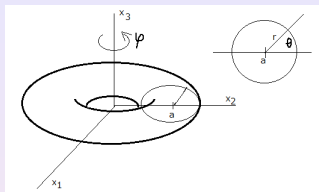


Figure : Shown are toroidal coordinates  $(r, \theta, \varphi)$ . Set  $\beta := a + r \cos \theta$ .

- Particle energy and angular momentum invariants:

$$e^{\pm}(x, v) := \langle v \rangle \pm \phi^0(r, \theta), \quad p^{\pm}(x, v) := \beta(v_{\varphi} \pm A_{\varphi}^0(r, \theta)).$$

- Equilibria:  $f^{\pm} = \mu^{\pm}(e^{\pm}, p^{\pm})$ . Elliptic problem for scalar potentials:

$$-\Delta \phi^0 = \rho^0, \quad \left(-\Delta + \frac{1}{\beta^2}\right) A_{\varphi}^0 = j_{\varphi}^0, \quad (\phi, \beta A_{\varphi})|_{\partial\Omega} = \text{const.}$$

- Quick theorem: if  $\|\mu^{\pm}\|_{\text{Lip}_{\omega}} \ll 1$ , equilibria exist:  $\phi^0, A_{\varphi}^0 \in C^{2+\alpha}(\Omega)$ .

- **Equilibria:**  $f^\pm = \mu^\pm(e^\pm, p^\pm)$ . Current density  $j_r^0 = j_\theta^0 = 0$  and

$$\left(-\Delta + \frac{1}{\beta^2}\right)B_\varphi^0 = 0, \quad B_{\varphi|_{\partial\Omega}}^0 = \text{arbitrary}.$$

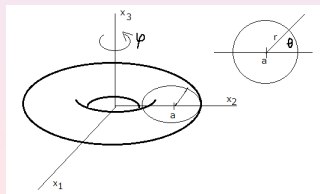
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- **Objective:** a linear stability theory for “monotonic” equilibria ( $\mu_e^\pm < 0$ )

$$E^0 = -\nabla\phi^0 = \partial_r\phi^0 \mathbf{e}_r + \frac{1}{r}\partial_\theta\phi^0 \mathbf{e}_\theta \in \text{span}\{\mathbf{e}_r, \mathbf{e}_\theta\}$$

$$B_\varphi^0 = 0, \quad B^0 = \nabla \times A_\varphi^0 \mathbf{e}_\varphi \in \text{span}\{\mathbf{e}_r, \mathbf{e}_\theta\}.$$



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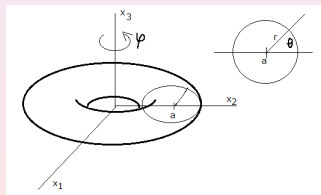
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- **Boundary conditions:**

$$E_\theta^0|_{\partial\Omega} = 0, \quad B_r^0|_{\partial\Omega} = 0.$$



Particle trajectories (for ion particle):

$$\dot{X} = \hat{V}, \quad \dot{V} = E^0 + \hat{V} \times B^0, \quad (X, V)|_{t=0} = (x, v),$$

following the rule of specular condition, when it hits  $\partial\Omega$ .

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Proof.

The map  $\Phi_{t(\cdot)}(\cdot)$  is  $\sigma$ -measure preserving on  $\partial\Omega \times \mathbb{R}^3$ . The Poincaré recurrence theorem asserts that

$$Z := \left\{ (x, v) \in \partial\Omega \times \mathbb{R}^3 : \sum_{k \geq 0} t_k(\Phi_{t_k(x, v)}(x, v)) < \infty \right\}$$

must have  $\sigma$ -measure zero!





Linearization under the toroidal symmetry ( $f = f^+$ ):

$$\begin{aligned}
 D_t f &= -(E + \hat{v} \times B) \cdot \nabla_v \mu(e, p) \\
 &= -\mu_e \hat{v} \cdot E - \beta \mu_p e_\varphi \cdot (E + \hat{v} \times (\nabla \times A_\varphi^0 e_\varphi)) \\
 &= -\mu_e \hat{v} \cdot E + \beta \mu_p \partial_t A_\varphi + \mu_p \hat{v} \cdot \nabla (\beta A_\varphi).
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Linearization under the toroidal symmetry ( $f = f^+$ ):

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Lemma (Energy conservation)

Set  $F := f - \beta \mu_p A_\varphi$ . The energy functional

$$\mathcal{I}(f^\pm, E, B) := \sum_{\pm} \iint \left[ \frac{1}{|\mu_e^\pm|} |F^\pm|^2 - \beta \hat{v}_\varphi \mu_p^\pm |A_\varphi|^2 \right] + \int \left[ |E|^2 + |B|^2 \right]$$

is independent of time. *Stable equilibria:*  $\mu_p = 0$  and  $\mu_e < 0$ .

Expanding  $B$ , a sufficient condition for stability:

$$\int_{\Omega} |B|^2 \, dx = \int_{\Omega} \left[ |\nabla A_{\varphi}|^2 + \frac{1}{\beta^2} |A_{\varphi}|^2 + |B_{\varphi}|^2 \right] dx \geq \iint \beta \hat{v}_{\varphi} \mu_p^{\pm} |A_{\varphi}|^2$$

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or equivalently (similar to Guo '99),

$$\mathcal{L}_{\text{Guo}} := \left( -\Delta + \frac{1}{\beta^2} \right) - \int \beta \hat{v}_{\varphi} \mu_p^{\pm} \, dv \geq 0.$$

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Theorem (N.-Strauss, ARMA 2014)

- *Stable equilibria:*  $p\mu_p^{\pm} \leq 0$  and  $\|A_{\varphi}^0\|_{L^{\infty}} \ll 1$ .
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Next, to analyze the role of  $|F|^2$  and  $|\nabla\phi|^2$  in the energy, we write

$$D_t F = -\mu_e \hat{v} \cdot E = \mu_e \hat{v} \cdot (\nabla\phi + \partial_t A)$$

The linearization now reads

$$\partial_t (F - \mu_e \hat{v} \cdot A) + D(F - \mu_e \phi) = 0. \quad (1)$$

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**Classical idea:** minimizing the energy functional under the orthogonality constraint (e.g., Lin '04, Lin-Strauss '07). By (1), minimizer  $(f, \phi)$  satisfies

$$F - \mu_e \phi \in \ker(D).$$

- Hence,  $F = \mu_e(1 - \mathbb{P})\phi + \mu_e\mathbb{P}(\hat{v} \cdot A)$ , with  $\mathbb{P} = \mathbb{P}_{\ker(D)}$ .

At the minimizer:  $F = \mu_e(1 - \mathbb{P})\phi + \mu_e\mathbb{P}(\hat{v} \cdot A)$ , we compute

$$-\Delta\phi = \int F \, dv + \int \beta\mu_p A_\varphi \, dv \quad \Leftrightarrow \quad \phi = -(\mathcal{A}_1^0)^{-1}(\mathcal{B}^0)^* A_\varphi$$

$$\iint \frac{1}{|\mu_e|} |F|^2 = \|(1 - \mathbb{P})\phi\|_{L^2_{|\mu_e|}}^2 + \|\mathbb{P}(\hat{v} \cdot A)\|_{L^2_{|\mu_e|}}^2$$

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Theorem (Lin-Strauss '07 (no boundary); N.-Strauss, ARMA 2014)

*Sufficient condition for stability:  $\mathcal{I}(f^\pm, E, B) \geq 0$ , or equivalently,*

$$\mathcal{L}_{\text{LinStr}} := \mathcal{L}_{\text{Guo}} - \mathcal{B}^0(\mathcal{A}_1^0)^{-1}(\mathcal{B}^0)^* - \int \hat{v}_\varphi \mu_e \mathbb{P}(\hat{v}_\varphi(\cdot)) \, dv \geq 0$$

*Last two terms are nonnegative (and no contribution from boundary).*

Much **striking and delicate**:  $\mathcal{L}_{LinStr} \geq 0$  is also necessary for stability (see also our **very next** talk!)

Theorem (Lin-Strauss '08 (no boundary); N.-Strauss, ARMA 2014)

*Let  $\Omega$  be a solid torus. Under toroidally symmetric perturbations*

- *Equilibrium is linearly stable if and only if*

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- *Stable equilibria:  $|\mu_p^\pm| \ll 1$ .*
- *Unstable equilibria:  $\mu^+(e, p) = \mu^-(e, -p)$  and  $p\mu_p^-(e, p) \geq c_0 p^2 \nu(e)$ , with  $c_0 \gg 1$ .*

- A nonlinear stability theory?
  - Guo '99: sufficiency of  $\mathcal{L}_{\text{Guo}} \geq 0$  for nonlinear stability (under  $x_3$ -translation or rotation symmetry; only study for 3D case). Should also apply to the torus!
  - Lin-Strauss' 07:  $\mathcal{L}_{\text{LinStr}} \geq 0$  implies nonlinear stability for purely magnetic equilibria of  $1\frac{1}{2}D$  systems. **Open** for the torus.

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- Linear implies nonlinear instability.
  - A series of Guo-Strauss '95-'00 for homogenous and weakly inhomogenous equilibria, and periodic BGK waves.
  - Lin '04 (for VP) and Lin-Strauss' 07 (for  $1\frac{1}{2}DVM$ ):  $\mathcal{L}_{\text{LinStr}} \geq 0$  is also necessary for nonlinear stability.
  - **Open** for the torus or even 3D cases without a boundary!

Let us sign off with the following **nonlinear instability of 3D RVM!**

**Theorem (Instability in the classical limit; Han-Kwan & N., 2015)**

Let  $\mu(v)$  be smooth unstable equilibrium (in the sense of Penrose). Let  $c \gg 1$  be the speed of light. There are smooth solutions  $(f^c, E^c, B^c)$  to RVM so that

$$\|\langle v \rangle^m (f^c_{|t=0} - \mu)\|_{H^s} \leq c^{-N} \rightarrow 0,$$

but at time  $t_c \approx \log c$ ,

$$\liminf_{c \rightarrow \infty} \|f^c_{|t=t_c} - \mu\|_{H^{-s'}} > 0,$$

for arbitrary fixed  $m, s, s', N$ .

**Classical limit of VM  $\rightarrow$  VP:** Asano-Ukai '86, Degond '86, and Schaeffer '86, within a finite interval of time.