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# The Multi-Stencil Language

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Abstract Insert your abstract here.

Keywords First keyword  $\cdot$  Second keyword  $\cdot$  More

### 1 Introduction

### Contributions:

- Formalism of a multi-stencil program and its parallelization
- The Multi-stencil Language: agnostic from the type of mesh and of the choosen implementation
- A first implementation of the MSL compiler (static scheduling + fusion + dump to SkelGIS/components)
- Evaluation of the different types of parallelism introduced + compiler + fusion

# 2 Computational model of Multi-Stencil Programs

### Formalism:

- mesh / mesh entities and groups / computations domains
- data and scalars
- computations : stencil, local and reduction
- Multi-Stencil Program

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# 3 Parallelization of Multi-Stencil Programs

Parallelization formalism:

- Data parallelism (introduction of synchronizations)
- Task parallelism (computation of the dependency graph)

# 4 The Multi-Stencil Language

The parallel empty skeleton of the application can be computed automatically from the language :

- grammar
- example from the language to the dependency graph

### 5 Static Scheduling

From the dependency graph we study a first dump: static scheduling

- description of the algorithm to get the binary tree decomposition of a minimal serie-parallel graph
- use of the serie-parallel tree decomposition to detect fusions of kernels
- example (the same one) from the dependency graph to the binary tree

### 6 Evaluation

- short description of the implementation (compiler in Python, DDS = Skel-GIS, Components)
- evaluation of the compiler (execution times of the different steps)
- evaluation of the data parallelism (weak/strong scaling)
- evaluation of the fusion
- evaluation of the hybrid parallelism
- analytic model for the results

### 7 Related work

- Lizst, Pochoir, PATUS for optimizations/parallelization of a single stencil kernel + mesh dependent
- Halide for pipeline of stencil computations = mesh dependent
- Reuse of external solutions as SkelGIS, GA, Lizst, Pochoir etc.

## 8 Conclusion

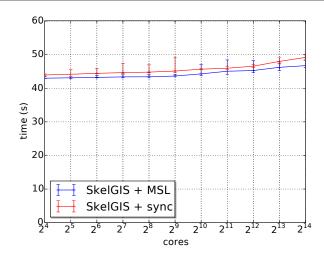


Fig. 1: weak-scaling 400 x 400 blocks.

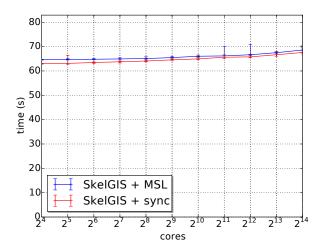


Fig. 2: weak-scaling  $800 \times 800$  blocks

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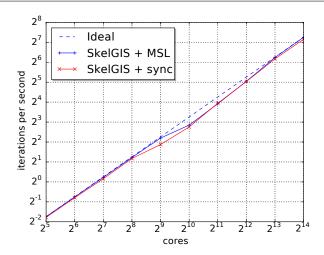


Fig. 3: strong-scaling 10kx10k, 1k iterations

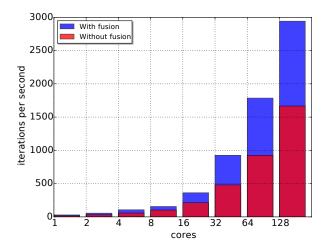


Fig. 4: strong scaling 500x500, 200 iterations, with and without fusion

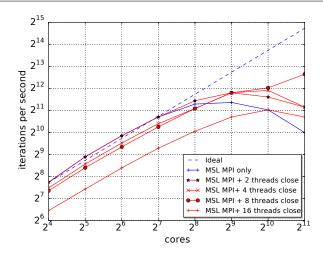


Fig. 5: MPI only vs MPI+threads with close scheduling policy (OpenMP)

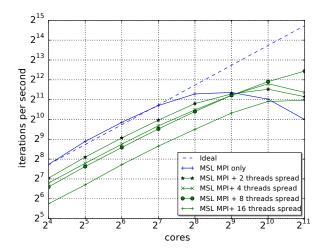


Fig. 6: MPI only vs MPI+threads with  $\mathit{spread}$  scheduling policy (OpenMP)

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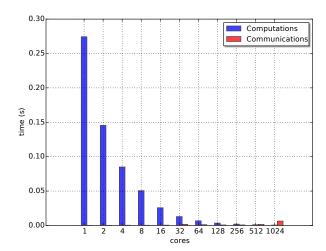


Fig. 7: Computation vs communication times in the MPI only application