

Theoretical Limits in Constraining Tidal Quality Factors of Binary Stars

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ABSTRACT

1. INTRODUCTION

We aim to place theoretical limits on the constraints we can get on Q and τ using tidal equilibrium models, and disentangle different sources of uncertainty:

- **Observational:** To what degree is the limitation on the uncertainty of Q and τ due to a limitation of observational (e.g. ability to observe a parameter, data precision, sample size), which might be improved by better data? That is, how does the accuracy and precision of our observations affect the derived uncertainty of Q and τ and which observational constraints matter most when it comes to inferring Q and τ ? What types of systems are most promising for constraining Q and τ ? Limitation of sample size or limitation of constraints? How do constraints from synchronization (rotation period + eccentricity + orbital period) compare to constraints from circularization (eccentricity + orbital period)? Smaller sample/more constraints vs. larger sample/less constraints
- **Model:** To what degree to inherent degeneracies/pathologies in the model formulation contribute to uncertainty? Is this a problem that is *well posed* for (Bayesian) inference—are the observables sensitive enough to your parameters of interest?
- **Hypothesis:** To what degree does our hypothesis fail to reproduce reality? (comparison between simulated data uncertainties and real data uncertainties; model comparison between CTL, CPL). Can theoretical limits to the uncertainties on Q and τ derived on *simulated data* give us context to interpret uncertainties on *real data*? Given enough free parameters, it can become possible for a model to reproduce any range of outcomes. How in this situation, can a model be invalidated?

2. METHODS

2.1. Tidal Evolution Model

2.2. Stellar Evolution + Magnetic Braking Model

2.3. Global Sensitivity Analysis

2.4. Markov Chain Monte Carlo

2.5. Observational Constraints

Model initial conditions and observational constraints:

	Model Input	Prior	Observational Constraint	Good Unc
M_1	primary mass [M_\odot]	$\mathcal{N}(m, s)$	kepler solution (lc eclipse + rvs)	0.001
M_2	secondary mass [M_\odot]	$\mathcal{N}(m, s)$	kepler solution (lc eclipse + rvs)	0.001
$P_{\text{rot1},i}$	pri init rotation period [days]	$\log\mathcal{N}(m, s)$	dist in young open clusters	
$P_{\text{rot2},i}$	sec init rotation period [days]	$\log\mathcal{N}(m, s)$	dist in young open clusters	
$P_{\text{orb},i}$	init orbital period [days]	$\mathcal{U}(4.0, 10.0)$	uninformed	
e_i	init eccentricity	$\mathcal{U}(0, 0.5)$	uninformed	
age	system age [yr]	$\mathcal{N}(m, s)$	open cluster age	10%
$\varepsilon_{1,i}$	pri init obliquity [deg]	$\mathcal{U}(0, 30)$	uninformed	
$\varepsilon_{2,i}$	sec init obliquity [deg]	$\mathcal{U}(0, 30)$	uninformed	
\mathcal{Q}_1	pri tidal phase lag	$\mathcal{U}(4, 9)$	uninformed	
\mathcal{Q}_2	sec tidal phase lag	$\mathcal{U}(4, 9)$	uninformed	
τ_1	pri tidal time lag [log(s)]	$\mathcal{U}(-4, 2)$	uninformed	
τ_2	sec tidal time lag [log(s)]	$\mathcal{U}(-4, 2)$	uninformed	

Model final conditions and observational constraints:

	Model Output	Likelihood	Observational Constraint	Good Unc
$P_{\text{rot1},f}$	pri final rotation period [days]	$\mathcal{N}(m, s)$	lc autocorrelation function	0.1
$P_{\text{rot2},f}$	sec final rotation period [days]	$\mathcal{N}(m, s)$	spectroscopic $v \sin i$	0.1
$P_{\text{orb},f}$	final orbital period [days]	$\mathcal{N}(m, s)$	lc lomb scargle	10^{-5}
e_f	final eccentricity	$\mathcal{N}(m, s)$	lc eclipse + rvs	0.001
$R_{1,f}$	pri final radius [R_\odot]	$\mathcal{N}(m, s)$	stellar models + photometry	0.01
$R_{2,f}$	sec final radius [R_\odot]	$\mathcal{N}(m, s)$	eclipse shape + pri radius	0.01
$L_{1,f}$	pri final luminosity [L_\odot]	$\mathcal{N}(m, s)$	stellar models + photometry	0.1
$L_{2,f}$	sec final luminosity [L_\odot]	$\mathcal{N}(m, s)$	stellar models + photometry	0.1
$T_{\text{eff1},f}$	pri final temperature [K]	$\mathcal{N}(m, s)$	stellar models + spectra	
$T_{\text{eff2},f}$	sec final temperature [K]	$\mathcal{N}(m, s)$	stellar models + spectra	

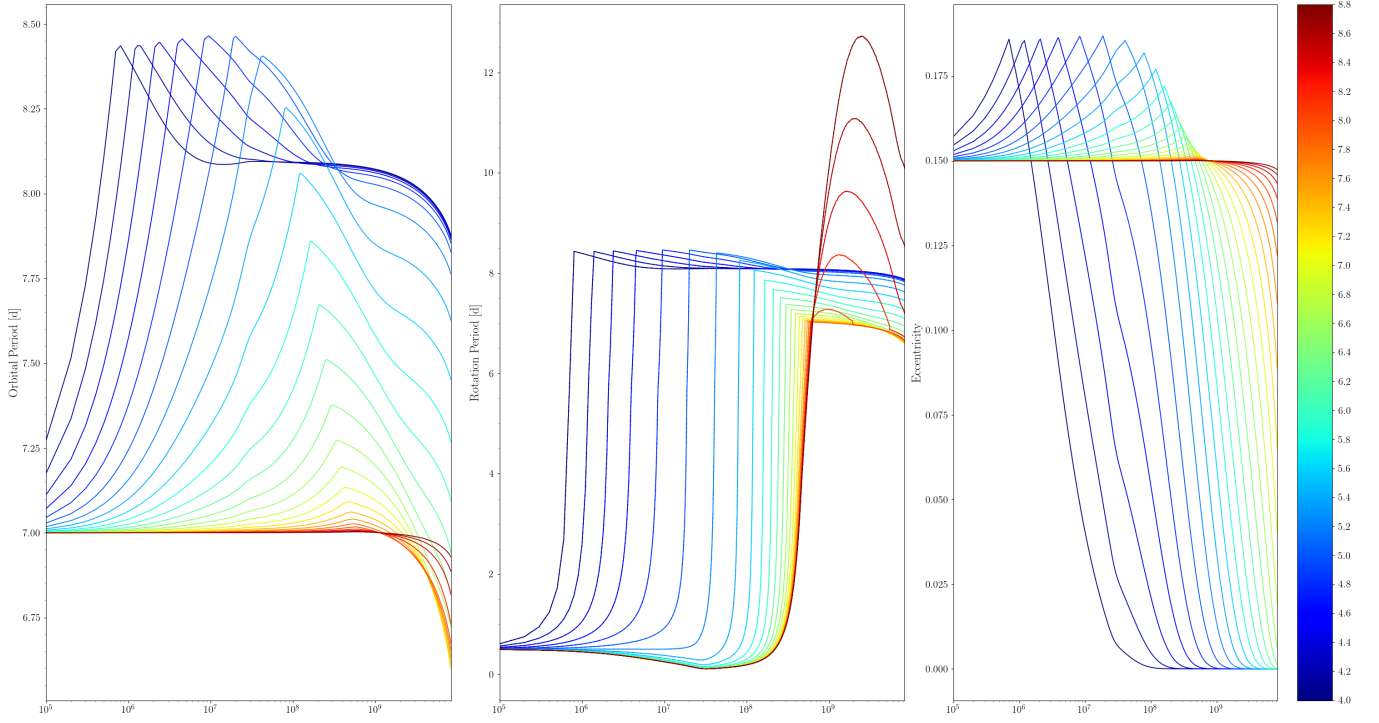
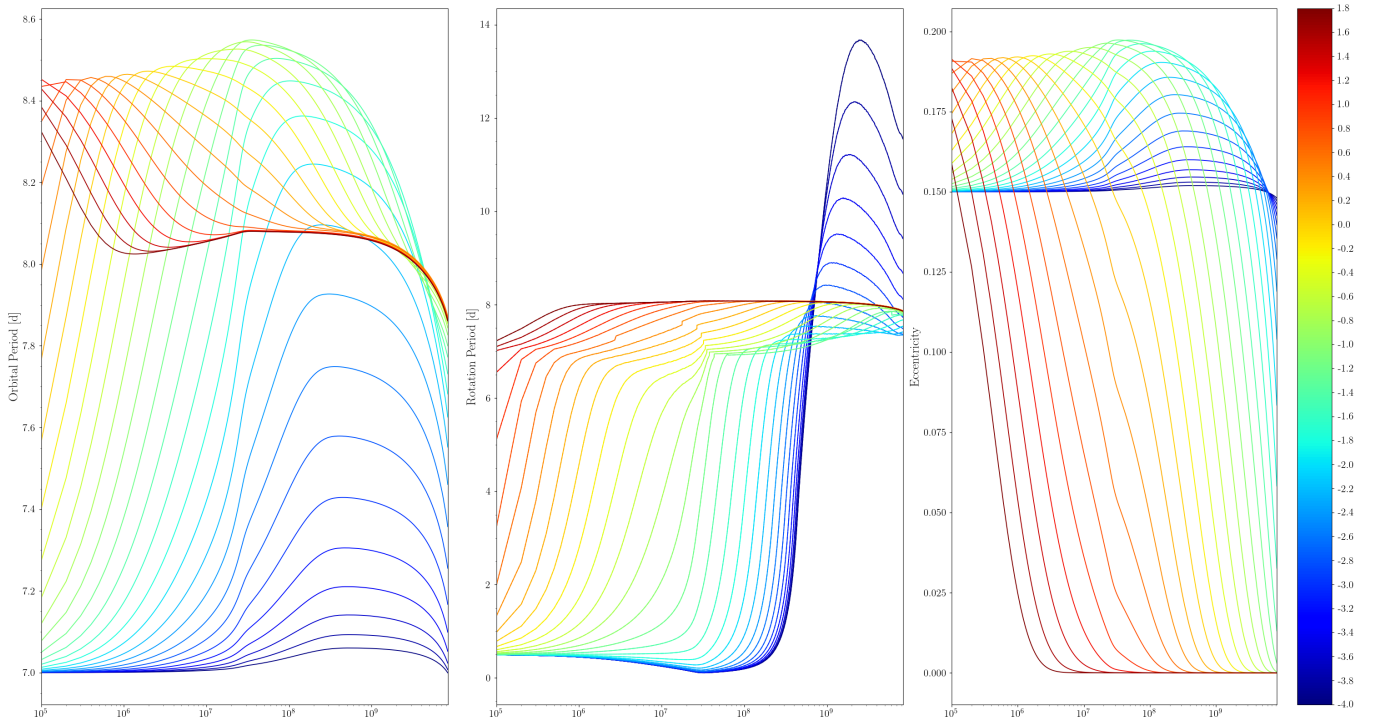
3. RESULTS

- sensitivity analysis (full 9 parameters + age) - CTL, CPL, CTL + STELLAR, CPL + STELLAR
 free parameters: $M_1, M_2, \varepsilon_{1,i}, \varepsilon_{2,i}, P_{\text{rot1},i}, P_{\text{rot2},i}, e_i, P_{\text{orb},i}, \mathcal{Q}$
 computation time: ~ 30 min eqtide only, ~ 1 day for eqtide + stellar
- sensitivity analysis (6 parameters + age) - CTL, CPL, CTL + STELLAR, CPL + STELLAR
 free parameters: $M_1, M_2, P_{\text{rot1},i}, P_{\text{rot2},i}, e_i, \mathcal{Q}$ (without obliquity, prior for porb based on final porb, ecc)
 computation time: ~ 30 min eqtide only, ~ 1 day for eqtide + stellar
- MCMC recovery test on synthetic data (4 parameters + age)
 free parameters: $P_{\text{rot1},i}, P_{\text{rot2},i}, e_i, \mathcal{Q}$ (fix masses, without obliquity, prior for porb based on final porb, ecc)
 computation time (per MCMC run): \sim few hours for eqtide only, \sim few weeks for eqtide + stellar
- 1D likelihood tests
 free parameters: \mathcal{Q}

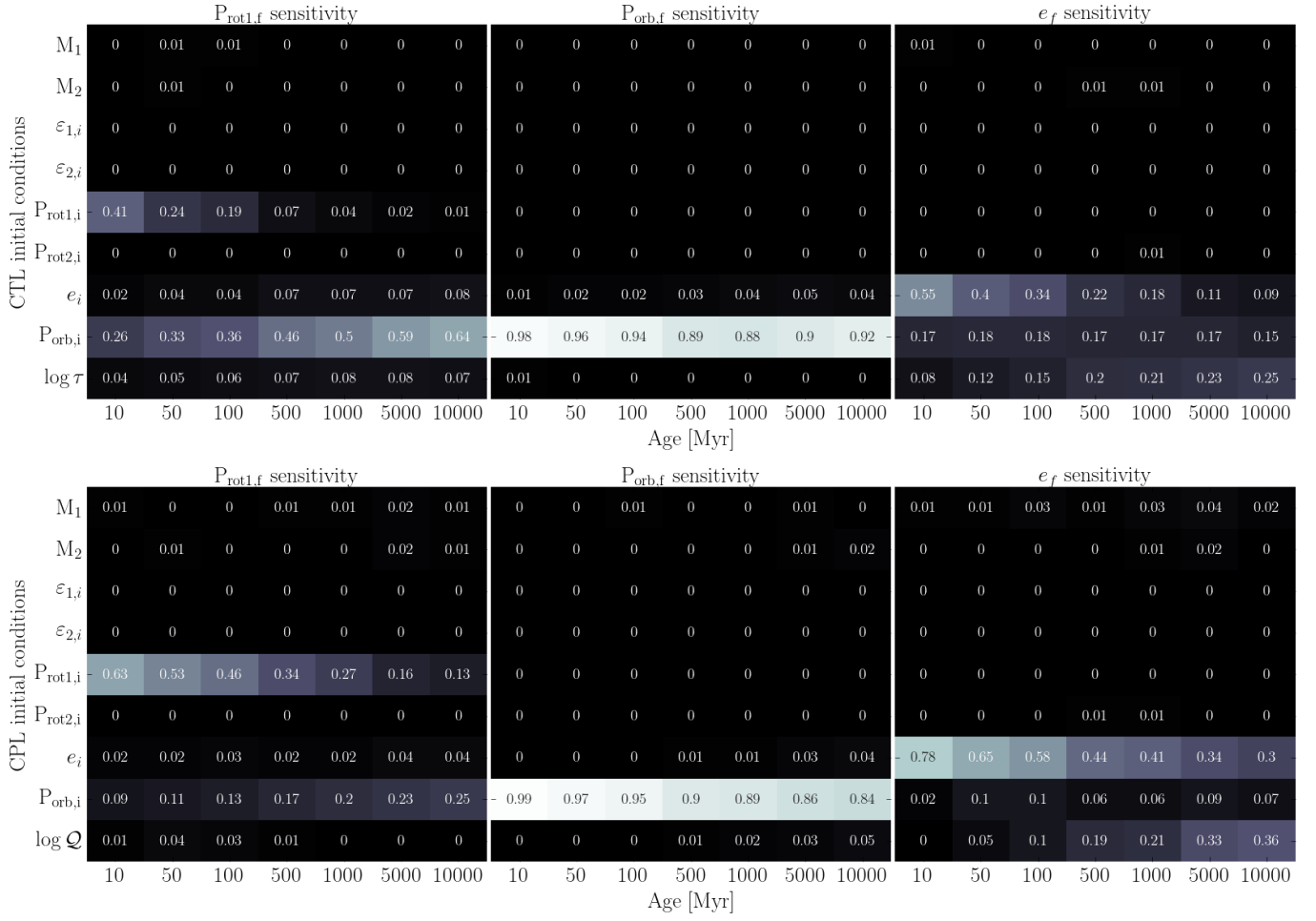
- MCMC recovery test on real data (4 parameters + age)?
 - if there's an open cluster system in a tide-sensitive age range
 - comparison with the synthetic data tests may be able to tell us how much posterior uncertainty is due to which input parameters/observational uncertainties/degeneracies?

4. DISCUSSION

5. CONCLUSION

Figure 1. EQTIDE + STELLAR: CPL model**Figure 2.** EQTIDE + STELLAR: CTL model

APPENDIX



REFERENCES