

# JOHN LYLE

johnlyleiv@gmail.com • (702) 757-5258 • Portfolio: [jbliv.github.io](https://jbliv.github.io)

## EDUCATION

<b>The University of Texas at Austin</b>	Master of Science, Mechanical Engineering Research Assistant in the Nuclear Robotics Group	May 2026
<b>The University of Texas at Austin</b>	Bachelor of Science, Mechanical Engineering Concentration: Robotics and Mechatronics Overall GPA: 3.77	May 2025

## EXPERIENCE

**Samsung Austin Semiconductor** – *Controls Engineering Intern* May 2024 – August 2024

- Designed and implemented control logic for redundant sensor usage in HVAC processes to improve uptime by 5%
- Identified control logic errors based off operator feedback and created a solution using ladder logic in Siemens STEP 7
- Created and performed an audit plan for verifying PLC panel installation prior to initial factory startup

**Nuclear Robotics Group, The University of Texas at Austin** – *Undergraduate Research Assistant* January 2024 - Present

- Utilized ROS2 to create a teleoperation solution for multi-robot systems through a single user interface
- Designed and manufactured aluminum adapter plate using a CNC for increased max load on end effector of a robot arm
- Used MoveIt Pro software to create decision trees for motion planning simulation using a robot arm

**Contoro Robotics** – *Robotics Engineering Co-Op* May 2023 – December 2023

- Programmed a ROS2 Node in C++ on Linux to interface with a haptic feedback teleoperation robot using impedance control
- Created a test fixture to evaluate torque bandwidth and positional hysteresis of a Bowden cable actuator
- Prototyped a custom handheld controller with one analog and three digital inputs using analog to digital signal processing
- Fabricated a safety control box and light curtain system to maintain a safe operation region surrounding an industrial robot
- Redesigned control box and robot stand to reduce footprint and cable clutter using sheet metal design in SOLIDWORKS

**Texas Inventionworks, The University of Texas at Austin** – *Student Associate* January 2023 - Present

- Assisted and advised students on designing and manufacturing projects such as concrete bowling balls, drones, and RC cars
- Developed a new training for manufacturing a ring on the lathe to increase student confidence and usage of machines

**RadLab, The University of Texas at Austin** – *Undergraduate Research Assistant* June 2022 - April 2023

- Updated and revamped C++ code for an Arduino system to meet new design requirements and safe operation standards
- Worked with a team to design and produce a fleet of wireless gas samplers to track emissions from nuclear weapons testing
- Prototyped a 3D printed alternative to a locking mechanism lowering costs of that part by 90%
- Identified and remedied design flaws resulting in four times higher pressure ratings and savings of \$500 per sampler

## ACADEMIC PRESENTATIONS AND PERSONAL PROJECTS

**Wireless Independent Noble Gas Sampler: Software Overview** – *American Nuclear Society Student Conference* April 2023

- Presented a poster on the WINGS project and its impact on non-proliferation efforts and future project goals

## LEADERSHIP EXPERIENCE AND ACTIVITIES

**American Society of Mechanical Engineer** – *Vice President, External Affairs Officer* Fall 2021 - Present

- Direct a team of 15 officers to host academic, community service, professional, and social events for 900+ student members

## AWARDS

- Outstanding Student Organization Award (ASME) - *The University of Texas at Austin, Tower Awards*
- Best Service Organization (ASME) – *The University of Texas at Austin, Swing Out Awards*

## SKILLS

**Manufacturing Methods:** CNC Mill, Manual Mill, Lathe, Laser Cutter, Sheet Metal DFM, Injection Molding, FDM & SLA 3D Printing

**Programming Languages:** Python, Matlab, C++, ROS2, Ladder Logic

**CAD and CAM:** Solidworks, Fusion 360, Onshape

**Electronics:** Soldering, SMD Rework, Circuit Design, Circuit Analysis

**Operating Systems and Development Platforms:** Linux, Windows, Arduino, Raspberry Pi