

# JOHN LYLE

johnlyleiv@gmail.com • (702) 757-5258 • LinkedIn.com/in/johnlyleiv

## EDUCATION

---

<b>The University of Texas at Austin</b>	Bachelor of Science, Mechanical Engineering Concentration: Robotics and Mechatronics Overall GPA: 3.77	May 2025
--	--	----------

## EXPERIENCE

---

<b>Nuclear Robotics Group, The University of Texas at Austin</b> – <i>Undergraduate Research Assistant</i>	January 2024 - Present
--	------------------------

- Designed and manufactured aluminum adapter plate using a CNC for increased max load on end effector of a robot arm
- Used Movelt Pro software to create decision trees for motion planning simulation using a robot arm

---

<b>Contoro Robotics</b> – <i>Robotics Engineering Co-Op</i>	May 2023 – December 2023
---	--------------------------

- Programmed a ROS2 Node in C++ to interface with a haptic feedback teleoperation robot using impedance control
- Created a test fixture to evaluate torque bandwidth and positional hysteresis of a Bowden cable actuator
- Prototyped a custom handheld controller with one analog and three digital inputs using analog to digital signal processing
- Fabricated a safety control box and light curtain system to maintain a safe operation region surrounding an industrial robot
- Redesigned control box and robot stand to reduce footprint and cable clutter using sheet metal design in SOLIDWORKS

---

<b>Texas Inventionworks, The University of Texas at Austin</b> – <i>Student Associate</i>	January 2023 - Present
---	------------------------

- Assisted and advised students on designing and manufacturing projects such as concrete bowling balls, drones, and RC cars
- Developed a new training for manufacturing a ring on the lathe to increase student confidence and usage of machines
- Trained students on safe and efficient use of maker space machines including 3D printers, manual mills, and lathes

---

<b>RadLab, The University of Texas at Austin</b> – <i>Undergraduate Research Assistant</i>	June 2022 - April 2023
--	------------------------

- Updated and revamped C++ code for an Arduino system to meet new design requirements and safe operation standards
- Worked with a team to design and produce a fleet of wireless gas samplers to track emissions from nuclear weapons testing
- Prototyped a 3D printed alternative to a locking mechanism lowering costs of that part by 90%
- Identified and remedied design flaws resulting in four times higher pressure ratings and savings of \$500 per sampler

## ACADEMIC PRESENTATIONS AND PERSONAL PROJECTS

---

<b>Wireless Independent Noble Gas Sampler: Software Overview</b> – <i>American Nuclear Society Student Conference</i>	April 2023
---	------------

- Presented a poster on the WINGS project and its impact on non-proliferation efforts and future project goals

### Optimal Schedule Creation Program

- Developed to create the most optimal schedule for a student organization snack shop based on officer availability
- Implemented object-oriented programming and custom classes to create a tree-based data structure for creating schedules

## LEADERSHIP EXPERIENCE AND ACTIVITIES

---

<b>American Society of Mechanical Engineer</b> – <i>Vice President, External Affairs Officer</i>	Fall 2021 - Present
--	---------------------

- Direct a team of 15 officers to host academic, community service, professional, and social events for 900+ student members

## AWARDS

- 
- University Honors (4 semesters)
  - Outstanding Student Organization Award (ASME) - *The University of Texas at Austin, Tower Awards*
  - Best Service Organization (ASME) – *The University of Texas at Austin, Swing Out Awards*
  - BASF Academic Excellence Scholarship

## SKILLS

---

**Manufacturing Methods:** CNC Mill, Manual Mill, Lathe, Laser Cutter, Sheet Metal DFM, Injection Molding, FDM & SLA 3D Printing

**Programming Languages:** Python, Matlab, C++, ROS2

**CAD and CAM:** Solidworks, Fusion 360, Onshape

**Electronics:** Soldering, SMD Rework, Circuit Design, Circuit Analysis

**Operating Systems and Development Platforms:** Linux, Windows, Arduino, Raspberry Pi