

- HW: 1) Complete in-class Notebook
 2) look @ sol's & correct FFT from last week
 3) Work on projects

Probability & Randomness

- 1) Random # generators
- 2) PDF transforms
- 3) Markov Chains
- 4) Monte-Carlo Algs. (Ising Model)

RNGs.

"True" RNGs

eg. specialized hardware,

- RF Noise/Static
- Atmospheric Noise
- Lava lamps
- \vdots

Pseudo-RNGs

- Recurrence Relation to get another random # from a previous #
- Mersenne Twister ~ 6000 digits
 $\sim 10^{6000}$ #'s

PDF Transforms:

given some PDF $P_X(x)$, $\text{prob. } P_Y$
 $P(x_a \leq x \leq x_b) = \int_{x_a}^{x_b} P_X(x) dx$

want to know $P_Y(y)$, or $x \leftrightarrow y$

$$\begin{aligned} & \Uparrow \text{ given } y(x) \\ & \int_{y(x_a)}^{y(x_b)} dy \frac{dx}{dy} P_X(x(y)) \\ & \quad \underbrace{\hspace{10em}} \\ & = P_Y(y) \end{aligned}$$

eg. have $P_X(x) = \begin{cases} 1 & \text{if } 0 \leq x < 1 \end{cases}$

eg. have $P_X(x) = \begin{cases} 1 & \text{if } 0 \leq x < 1 \\ 0 & \text{otherwise} \end{cases}$

Want $P_Y(y) = \begin{cases} y & \text{if } 0 \leq y < \sqrt{2} \\ 0 & \text{otherwise} \end{cases}$

Normalization

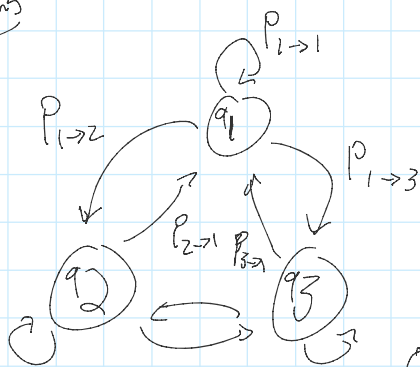
$$y \, dy = 1 \, dx \quad \text{where } P \neq 0$$

$$\frac{1}{2} y^2 = x + c \quad \begin{array}{l} \text{Want } y = \sqrt{2} \text{ @ } x = 1 \\ y = 0 \text{ @ } x = 0 \end{array}$$

$$\Rightarrow c = 0$$

$$x = y^2/2, \quad y = \sqrt{2}x$$

Markov Chains



State vector $\vec{q} = \begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix} \leftarrow$ Prob. of being in state 1, 2, 3

one "step": $\vec{q}' = \underline{\underline{P}} \vec{q}$

$$\begin{pmatrix} q'_1 \\ q'_2 \\ q'_3 \end{pmatrix} = \begin{pmatrix} P_{1 \rightarrow 1} & P_{2 \rightarrow 1} & P_{3 \rightarrow 1} \\ P_{1 \rightarrow 2} & P_{2 \rightarrow 2} & P_{3 \rightarrow 2} \\ P_{1 \rightarrow 3} & P_{2 \rightarrow 3} & P_{3 \rightarrow 3} \end{pmatrix} \begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix}$$

Col's should sum to 1

$$2 \text{ steps: } q' = P^2 q$$

$$N \text{ steps: } q' = P^N q$$

$$\text{Can take } N \rightarrow \infty, \quad P = V D V^{-1}$$

$$P^N = V D^N V^{-1}$$

eigen vals = 1 states are "left"

"stationary" states