



March 26, 2021

Problem 1:

- a) The finite-difference version of this scheme also determines the behavior of the error,

$$\epsilon_f(t + \Delta t, x) = \epsilon_f(t, x) + \Delta t \frac{\epsilon_f(t, x + \Delta x) - 2\epsilon_f(t, x) + \epsilon_f(t, x - \Delta x)}{\Delta x^2}.$$

- b) Assuming the error takes the form

$$\epsilon_f(t, x) = E(t)e^{ikx},$$

we end up with the equation

$$E(t + \Delta t)e^{ikx} = E(t)e^{ikx} + \frac{\Delta t}{\Delta x^2}E(t)e^{ikx} [e^{ik\Delta x} - 2 + e^{-ik\Delta x}].$$

which reduces to

$$E(t + \Delta t) = E(t) \left[1 - \frac{\Delta t}{\Delta x^2} 4 \sin^2(k\Delta x/2) \right].$$

- c) We would like for

$$\left| E(t) \left[1 - \frac{\Delta t}{\Delta x^2} 4 \sin^2(k\Delta x/2) \right] \right| \leq |E(t)|,$$

or

$$\left| 1 - \frac{\Delta t}{\Delta x^2} 4 \sin^2(k\Delta x/2) \right| \leq 1.$$

Note that \sin^2 is always positive, between 1 and 0, and Δx and Δt will be positive assuming usual finite differencing integration. We would therefore like

$$\frac{\Delta t}{\Delta x^2} \leq \frac{1}{2}$$

for stability: we can therefore carefully choose a Δx and Δt to ensure stability of this method.