### Part I.

## Reviewed notation

### 1. Multivariable Regression

- $y:[m \times 1]$  Output variable (dependent variable)
- $X: [m \times (n+1)]$  Input variables (independent variables)
- $\theta: [(n+1) \times 1]$  parameters
- $\bullet$  m: number of observations
- $\bullet$  n: number of parameters
- $h_{\theta} = X\theta$  = regression output, should be as close as possible to y

#### 1.1. Normal resolution

$$\theta = (\theta^T \theta)^{-1} X^T y \tag{1}$$

#### 1.2. Gradient Descent

Gradient descent (some sort of Newton), used as a numerical method to iteratively find the optimum of a function (J in this case)

$$\theta := \theta - \alpha \Delta J(\theta) \tag{2}$$

$$:= \theta - \alpha \frac{1}{m} X^{T} (X\theta - y) \tag{3}$$

### 2. Multivariable regression with Regularization

To automatically choose optimal parameters and avoid from overfitting, an additional feature is introduced  $\lambda$ .

The Normal Method thus becomes

$$\theta = \left(\theta^T \theta + \lambda \begin{pmatrix} 0 & 1 & \dots & 1 \\ \vdots & 1 & \dots & \vdots \\ 0 & 1 & \dots & 1 \end{pmatrix}\right)^{-1} X^T y \tag{4}$$

and the gradient descent algorithm

$$\theta := \theta - \alpha \frac{1}{m} X^{T} (X\theta - y) + \alpha \frac{\lambda}{m} \theta \tag{5}$$

### 3. Logistic Regression

#### 3.1. Variables for one output

- $y \in [0,1]^{m \times 1}$
- $h_{\theta} = \mathbb{P}(y = 1|X; \theta) = g(X\theta)$

### 3.2. Sigmoid

Map  $z \in \mathbb{R}$  to  $g(z) \in [0,1]$ 

$$g(z) = \frac{1}{1 + e^{-z}} \tag{6}$$

#### 3.3. Gradient Descent

$$\theta := \theta - \alpha \frac{1}{m} X^T (g(X\theta) - y) \tag{7}$$

### 3.4. Variables for p outputs - multi-classifier

- $\bullet \ y \in [0,1]^{m \times p}$
- $\theta$  :  $[(n+1) \times p]$
- $X : [m \times (n+1)]$

$$\bullet \ h_{\theta} = \begin{pmatrix} h_{\theta_1} \\ \vdots \\ h_{\theta_p} \end{pmatrix}$$

### 4. Neural Networks

### 4.1. Forward Propagation

- $\bullet$  m: number of observations
- $y:[m \times s_L]$
- $\theta^{(l)} : [(s_l + 1) \times s_{(l+1)}]$

Initialization  $(l = 1, s_1 = n)$ :

$$a^{(1)} = x$$

$$[m \times s_1] = [m \times n]$$

$$\tilde{a}^{(1)} = \tilde{x}$$

$$(8)$$

$$(9)$$

$$(10)$$

$$[m \times s_1] = [m \times n] \tag{9}$$

$$\tilde{a}^{(1)} = \tilde{x} \tag{10}$$

$$[m \times (s_1+1)] = [m \times (n+1)]$$

l < L:

$$\tilde{a}^{(l+1)} = g(a^{(l)}\theta^{(l)}) = g(z^{(l+1)})$$
 (11)

$$[m \times (s_l + 1)] = [m \times (s_l + 1)][(s_l + 1) \times (s_{l+1})]$$
(12)

(12)

$$a^{(l)} = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix} : +\tilde{a}^{(l)} \tag{13}$$

 $\rightarrow$  add a column of ones at the beginning of the matrix

### 4.2. Backward Propagation (in order to find $\Delta J$ )

Initialization l = L:

$$\delta^{(L)} = a^{(L)} - y^{(L)}$$

$$[m \times s_L] = [m \times s_L] - [m \times s_L]$$
(14)

l < L

$$\delta^{(l)} = \tilde{\delta}^{(l+1)} \theta^{T_{(l)}} \circ g'(z^{(l)})$$

$$= \tilde{\delta}^{(l+1)} \theta^{T_{(l)}} \circ a^{(l)} \circ (1 - a^{(l)})$$

$$[m \times (s_l + 1)] = [m \times s_{l+1}] - [s_{l+1} \times (s_l + 1)]$$
(15)

### 4.3. Compute/train a Neural Network

A Neural network is defined by the following dimensions:

- m: number of observations
- $s_l$ : number of node for layer l
- n: number of incoming variables  $n = s_1 (n + 1 \text{ for vector of ones})$
- p: number of output variables  $(p = s_L)$
- L: Number of nodes
- 1.  $a^{(1)} = x$
- 2. forward: get a = (l)
- 3. backward: get  $\delta^{(l)}$
- 4.  $\Delta^{(l)} = a^{T_{(l)}} \tilde{\delta}^{(l+1)}$
- 5.  $\nabla^{(l)} J(\theta) = D^{(l)} = \frac{1}{m} \Delta^{(l)}$
- 6. Optimization to find  $\hat{\theta}^{(l)}$ :  $\min_{\theta} J$

### 5. Support Vector Machine (SVM)

Also referred to as Large Margin Classifiers.

$$J(\theta) = \min_{\theta} C \sum_{i=1}^{m} \left[ y^{(i)} \operatorname{cost}_{1}(\theta^{T} x^{i}) + (1 - y^{(i)}) \operatorname{cost}_{0}(\theta^{T} x^{(i)}) \right] + \frac{1}{2} \sum_{i=1}^{n} \theta_{j}^{2}.$$
 (17)

$$C = \frac{1}{\lambda} \tag{18}$$

## Part II.

# First Version - as in Coursera Course

### **Cost Function**

$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} \frac{1}{2} (h_{\theta}(x^{(i)} - y^{(i)}))^2$$
 (19)

Hypothesis

$$h_{\theta}(\mathbf{x}) = \theta^T \mathbf{x} \tag{20}$$

with  $\mathbf{x} = (1, x_1, ..., x_n)$  and  $\theta = (\theta_0, \theta_1, ..., \theta_n)$ 

**Gradient Descent** Minimize  $J(\theta)$  for  $\theta$ , the algorithm is

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta) \tag{21}$$

where  $\alpha$  is the *learning rate*.

and

$$\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)}$$
(22)

alternatives to gradient descent

- Conjugate gradient
- BFGS
- L-BFGS

#### **Analytical Solution**

$$\theta = (X^T X)^{-1} X^T y \tag{23}$$

### 6. Logistic Regression

classification: y = 0 or y = 1

Want :  $0 \le h_{\theta}(x) \le 1$ 

$$h_{\theta}(x) = g(\theta^T x) \tag{24}$$

with logistic (sigmoid) function  $z \in \mathbb{R}$ :

$$g(z) = \frac{1}{1 + e^{-z}} \in (0, 1) \tag{25}$$

output can be read as  $h_{\theta}(x) = \mathbb{P}(y = 1|x; \theta)$ : probabability that y = 1 given x parametrized by  $\theta$  is h.

### 6.1. Decision Boundary

$$y = \begin{cases} 1 & z > 0 \\ 0 & z < 0 \end{cases} \tag{26}$$

where z is the argumen of g and is usally of the form  $\theta^T x$ 

$$Cost(h_{\theta}(x,y)) = \frac{1}{2}(h_{\theta}(x) - y)^2$$
(27)

#### 6.2. Cost function

$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} \text{Cost}(h_{\theta}(x^{(i)}), y^{(i)})$$
 (28)

$$Cost(h_{\theta}(x,y)) = \begin{cases} -\log(h_{\theta}(x)) & y = 1\\ -\log(1 - h_{\theta}(x)) & y = 0 \end{cases}$$
 (29)

since y = 1 or y = 0:

$$Cost(h_{\theta}(x), y) = -y \log (h_{\theta}(x)) - (1 - y) \log (1 - h_{\theta}(x))$$
(30)

### 7. Regularization

#### 7.1. Problem of overfitting

If too many features  $(\theta)$ , the learned hypothesis may fit the training examples very well  $(J(\theta) \approx 0)$ , but fail to generalize to new examples.

### 7.1.1. Addressing overfitting

- Reduce the number of features
  - Manually select features to be kept
  - Model selection algorithm
- Regularization

#### 7.2. Cost function

add  $\lambda$  to reduce the number of allowed parameters.

$$J(\theta) = \frac{1}{2m} \left[ \sum_{i=1}^{m} (h_{\theta}(x^{i}) - y^{(i)})^{2} + \lambda \sum_{j=1}^{n} \theta_{j}^{2} \right]$$
(31)

If  $\lambda$  is too large, **underfit** occurs.

### 7.3. Regularized Logistic regression

$$J(\theta) = -\frac{1}{m} \left[ \sum_{i=1}^{m} y^{(i)} \log (h_{\Theta}(x^{(i)})) + (1 - y^{(i)}) \log (1 - h_{\Theta}(x^{(i)})) \right] + \frac{\lambda}{2m} \sum_{j=1}^{m} \Theta_{j}^{2}.$$
 (32)

The partial derivative are

$$\frac{\partial J(\theta)}{\partial \theta_0} = \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)} \qquad \text{for } j = 0$$
 (33)

$$\frac{\partial J(\theta)}{\partial \theta_j} = \left(\frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}\right) + \frac{\lambda}{m} \theta_j \quad \text{for } j \ge 1.$$
 (34)

### 8. Neural Networks: Representation

### 8.1. Non-linear hypotheses

### 8.2. Neurons and the brain

### 8.3. Model representation I

Neuron model: Logistic unit

$$\mathbf{x} = (1, x_1, ..., x_n) \text{ and } \theta = (\theta_0, \theta_1, ... \theta_n)$$

### 8.4. Feedforward

• Input layer:

$$a^{(1)} = x \tag{35}$$

• Hidden layer(s)

$$z^2 = \Theta^{(1)}a^{(1)} \tag{36}$$

$$a^{(2)} = g(z^{(2)}) (37)$$

$$z^{(k+1)} = \Theta^{(k)}a^{(k)} \tag{39}$$

$$z^{(k+1)} = \Theta^{(k)}a^{(k)}$$

$$a^{(k+1)} = g(z^{(k+1)})$$
(38)
$$(39)$$

$$(40)$$

• Output layer

$$z^{(3)} = \Theta^{(2)}a^{(2)} \tag{41}$$

$$h_{\Theta} = a^{(3)} = g(z^{(3)})$$
 (42)

- m total number of sample:  $\{(x^{(1)},y^{(1)}),(x^{(2)},y^{(2)}),...,(x^{(m)},y^{(m)})\}$
- $\bullet$  L total number of layers indexed by l
- $s_l$  number of unit per layer (without counting bias unit).
- $\Theta^{(l)}$  has size  $s_{l+1} \times (s_l + 1)$  (The +1 is here to account for the bias unit).
- $\bullet$  Last layer L
  - Binary Classification:  $s_L = 1$
  - Multi-class classification:  $s_L = K$ .

### 9. Neural networks: learning

#### 9.1. Cost function

$$J(\theta) = -\frac{1}{m} \left[ \sum_{i=1}^{m} \sum_{k=1}^{K} y_k^{(i)} \log (h_{\Theta}(x^{(i)}))_k + (1 - y^{(i)}) \log (1 - h_{\Theta}(x^{(i)})_k) \right] + \frac{\lambda}{2m} \sum_{l=1}^{K-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} (\Theta_{ij}^{(l)})^2.$$

$$(43)$$

### 9.2. Backpropagation

In order to  $\min_{\Theta} J(\Theta)$ , need to compute

- $J(\Theta) \Rightarrow$  by plugging values directly into function
- $\frac{\partial}{\partial \Theta_{ij}^{(l)}} J(\Theta) \Rightarrow$  with backpropagation algorithm

$$\begin{cases} \delta^{(L)} = a^{(L)} - y = h_{\Theta} - y & \text{for } l = L \\ \delta^{(l)} = (\Theta^{(l)})^T \delta^{(4)} \circ \frac{d}{dz} g(z^{(l+1)}) & \text{for } 1 < l < L \end{cases}$$
(44)

<sup>1</sup> The intuition being  $\delta$  is the "error" at every node that we try to minimize and converges to the gradient.

Note on  $\frac{d}{dz}g(z)$  for  $g(z) = \frac{1}{1+e^{-z}}$ 

$$\frac{d}{dz}g(z) = \frac{e^{-z}}{1 + e^{-z}} = g(z)(1 - g(z)) \tag{46}$$

#### **Backpropagation Algorithm**

- For i = 1 to m
  - Set  $a(1) = x^{(i)}$
  - Perform forward propagation to compute  $a^{(l)}$  for l=2,..,L
  - Using  $y^{(i)}$  compute  $\delta^{(L)} = a^{(L)} y^{(i)}$
  - Compute  $\delta^{(L-1)}$ ,  $\delta^{L-2}$ , ...,  $\delta^{(2)}$
  - $\Delta_{ij}^{(l)} := \Delta_{ij}^{(l)} + a_j^{(l)} \delta_i^{(l+1)} \text{ or } \Delta^{(l)} := \Delta^{(l)} + \delta(l+1) (a(l))^T$

• 
$$D_{ij}^{(l)} := \frac{1}{m} \Delta_{ij}^{(l)} + \lambda \Theta_{ij}^{(l)} \text{ if } j \neq 0$$

• 
$$D_{ij}^{(l)} := \frac{1}{m} \Delta_{ij}^{(l)}$$
 if  $j = 0$ 

$$\begin{pmatrix} a_{11} & \dots & a_{1m} \\ a_{21} & \dots & \vdots \\ \vdots & \dots & \vdots \\ a_{n1} & \dots & a_{nm} \end{pmatrix} \circ \begin{pmatrix} b_{11} & \dots & b_{1m} \\ b_{21} & \dots & \vdots \\ \vdots & \dots & \vdots \\ b_{n1} & \dots & b_{nm} \end{pmatrix} = \begin{pmatrix} a_{11}b_{11} & \dots & a_{1m}b_{1m} \\ a_{21}b_{21} & \dots & \vdots \\ \vdots & \dots & \vdots \\ a_{n1}b_{n1} & \dots & a_{nm}b_{nm} \end{pmatrix}$$

$$(45)$$

 $<sup>^{1}\</sup>circ$  is the Hadamard product and produces a matrix where all elements ij are a multiplication of the element ij of the two input matrices:

$$\frac{\partial}{\partial \Theta_{ij}^{(l)}} J(\Theta) = D_{ij}^{(l)} \tag{47}$$

# 10. Support Vector Machine (SVM)

$$J(\theta) = \min_{\theta} C \sum_{i=1}^{m} \left[ y^{(i)} \operatorname{cost}_{1}(\theta^{T} x^{i}) + (1 - y^{(i)}) \operatorname{cost}_{0}(\theta^{T} x^{(i)}) \right] + \frac{1}{2} \sum_{i=1}^{n} \theta_{j}^{2}.$$
 (48)

The SVM is a large margin classifier