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RESEARCH STATEMENT There are two main thrusts in my research group: evolutionary robotics and machine science. In our **evolutionary robotics** work, our long-term goal is to enable increasingly large numbers of non-experts to direct the evolution of increasingly complex, capable, and autonomous machines to perform a widening array of difficult tasks. This involves work in theoretical biology: what mechanisms from biological evolution must be incorporated into an evolutionary robotics system to increase its evolvability? It involves work in embodied cognition: how does one spread ‘computation’ out across not only the neural controller of the machine, but also its morphology? It involves work in computational neuroscience: what kinds of neural models should be instantiated in our evolving robots? Finally, our work has psychological and philosophical implications: if a robot evolves that exhibits the behavioral manifestations of high-level cognitive competencies such as self-awareness, how can we determine whether a robot actually possesses, rather than just simulates, that competency? In our work on **machine science**, we attempt to automate as best we can all aspects of the scientific process: hypothesis generation, selection of phenomenon to measure, experimental design, and data collection. (Machine learning, in contrast, only focuses on hypothesis generation.) My overall strategy is to select generally high-risk, high-reward research questions that, if validated, are likely to change our thinking about seemingly obvious approaches, such as focusing only on control, rather than both morphology and control, in robotics.

APPOINTMENTS

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- 2015– **Professor**, Department of Computer Science
 - 2015– Cyril G. Veinott Green and Gold Professor, Department of Computer Science, College of Engineering & Mathematical Sciences, University of Vermont
 - 2015–2019 Director, [Vermont Advanced Computing Core](#), UVM’s high performance computing facility.
 - 2014–2018 Consultant, [Xemo Corporation](#) (spinoff from laboratory)
 - 2012–2015 **Associate Professor**, Department of Computer Science
 College of Engineering & Mathematical Sciences, University of Vermont
 - 2014– *Secondary appointment in the School of Engineering, UVM*
 - 2013– *Secondary appointment in the Neuroscience Graduate Program, UVM*
 - 2011–2015 Vice chair, [Vermont Complex Systems Center](#)
 - 2006–2012 **Assistant Professor**, Department of Computer Science
 College of Engineering & Mathematical Sciences, University of Vermont
 - 2006– Director, [Morphology, Evolution & Cognition Laboratory](#)
 - 2003–2006 **Postdoctoral Associate**, Cornell University

Advisor: Hod Lipson, Director of the Creative Machines Laboratory

1998 Software Engineer, Computing Devices Canada

EDUCATION

1999–2003 **Ph.D.**, Department of Informatics, University of Zurich, Switzerland
Incremental Approaches to the Combined Evolution of a Robot's Body and Brain.
Advisor: Rolf Pfeifer, Director of the Zurich Artificial Intelligence Laboratory

1998–1999 **M.S.**, Evolutionary & Adaptive Systems, University of Sussex, UK
Evolving Heterogeneity: Implications for Agent-Based Systems and Collective Problem Solving.
Advisor: Inman Harvey

1993–1997 **B.Sc.**, Honors Computer Science, McMaster University, Canada (graduated *Summa Cum Laude*)

1994 Study abroad program, Corpus Christi College, Oxford University, UK

CURRENT FUNDING

2020–2022 **NSF NAIRI** Planning award, \$500,000
The Proteus Institute: Intelligence through change.

2020–2024 Army **CRREL** award, \$10M

2018–2021 **NSF EFRI** award (co-PI; PI: Rebecca Kramer-Bottiglio), \$496,333
C3 SoRo: Programmable Skins for Moldable and Morphogenetic Soft Robots.

2018–2022 **DARPA L2M** award (co-PI; PI: Michael Levin, Tufts), \$268,174
Somatic Computation via Bioelectricity for Novel Life-time Learning Machines.

2018–2022 **Sloan Foundation** award, \$683,273
Developing an In-Browser, Elastic Supercomputer

PAST FUNDING

2018–2020 **NSF MRI** award (co-PI; PI: Adrian Del Maestro), \$893,120
Acquisition of a GPU Accelerated Vermont Advanced Computing Core.

2014–2018 **NSF BIGDATA** award (co-PI; PI: James Bagrow, UVM), \$600,000
Hunch & Crunch: Iterative Crowdsourced Hypothesis Generation.

2016–2019 **Army Research Office** award, \$400,000
Morphological Plasticity for the Design, Control, and Deployment of Complex Engineering Systems.

2013–2018 **NSF INSPIRE** award (co-PI; PI: Ken Livingston, Vassar College), \$500,000
Evolvability and the emergence of modularity.

2016–2017 **NSF EAGER** award, \$100,000
Scalable crowdsourced reinforcement of robot behavior.

2015–2017 **NASA ROSES** award (co-PI; PI: Kamalika Das), \$300,000
Uncovering effects of climate variables on global vegetation.

- 2010–2017 **NSF CAREER/PECASE** award, \$499,999
Exploring the Ultimate Mechanisms of Embodied Cognition.
- 2011–2015 **DARPA MSEE** award, \$614,830
Continually Plastic Modeling of Non-Stationary Systems.
- 2011–2014 **DARPA M3** award (co-PI: PI: Greg Hornby, NASA Ames), \$200,000
Rapid Human-Computer Interactive Conceptual Design of Mobile and Manipulative Robot Systems.
- 2007–2011 **Microsoft Research New Faculty Fellowship**, \$200,000
- 2007–2009 **NSF SGER** award, \$192,391
Exploiting ‘Like Me’ Hypotheses for Learning Robots

BOOKS

1. Pfeifer, R. and J. Bongard (2006)
How the Body Shapes the Way We Think: A New View of Intelligence,
Boston, MA: MIT Press. (Translated into Chinese, Japanese, Arabic and an E-book)

ARTICLES

40. D Blackiston, E Lederer, S Kriegman, S Garnier, J Bongard, M Levin (2021)
[A cellular platform for the development of synthetic living machines.](#)
Science Robotics, 6(52).
39. JC Bongard & M Levin (2021)
[Living things are not \(20th century\) machines.](#)
Frontiers in Ecology and Evolution, <https://doi.org/10.3389/fevo.2021.650726>
38. DS Shah, JP Powers, LG Tilton, S Kriegman, J Bongard & R Kramer-Bottiglio (2020)
[A soft robot that adapts to environments through shape change.](#)
Nature Machine Intelligence, <https://doi.org/10.1038/s42256-020-00263-1>
37. F Veenstra, P Gonzalez de Prado Salas, K Stoy, J Bongard, S Risi (2020).
[Death and progress: How evolvability is influenced by intrinsic mortality.](#)
Artificial Life, 26(1): 90-111.
36. D Shah, B Yang, S Kriegman, M Levin, J Bongard, R Kramer-Bottiglio (2020).
[Shape changing robots: bioinspiration, simulation, and physical realization.](#)
Advanced Materials. e202002882.
35. S Kriegman, D Blackiston, M Levin, J Bongard. (2020).
[A scalable pipeline for the design of reconfigurable organisms.](#)
Proceedings of the National Academy of Science, 117(4): 1853-1859.
34. I Rahwan, M Cebrian, N Obradovich, J Bongard, J-F Bonnefon, C Breazeal, JW Crandall, NA Christakis, ID Couzin, MO Jackson, NR Jennings, E Kamar, IM Kloumann, H Laroche, D Lazer, R McElreath, A Mislove, DC Parkes, A Pentland, ME Roberts, A Shariff, JB Tenenbaum & M Wellman (2019).
[Machine behavior.](#)
Nature, 568: 477486
33. Rounds, T., Bongard, J., Hines, P., & Harvey, J. (2019).
[A crowdsourcing approach to understand weight and weight loss in men.](#)

- Preventive Medicine Reports*, 13, 224.
32. Kriegman, S., Cheney, N., & Bongard, J. (2018).
[How morphological development can guide evolution.](#)
Nature Scientific Reports, 8(1): 13934.
 31. F Corucci, N Cheney, F Giorgio-Serchi, J Bongard, and C Laschi (2018)
[Evolving Soft Locomotion in Aquatic and Terrestrial Environments: Effects of Material Properties and Environmental Transitions.](#)
Soft Robotics, 5(4): 475-495.
 30. N Cheney, J Bongard, V SunSpiral, H Lipson (2018)
[Scalable co-optimization of morphology and control in embodied machines.](#)
Journal of The Royal Society Interface, 15(143): 20170937
 29. A Bernatskiy, J Bongard (2018)
[Evolving morphology automatically reformulates the problem of designing modular control.](#)
Adaptive Behavior 26(2): 47-64
 28. MD Wagdy, JC Bongard, JP Bagrow & PDH Hines (2017)
[Crowdsourcing Predictors of Residential Electric Energy Usage.](#)
IEEE Systems Journal, PP(99):1–10.
 27. D Buckingham & JC Bongard (2017)
[Physical Scaffolding Accelerates the Evolution of Robot Behavior.](#)
Artificial Life, 23(3):351-373.
 26. F Corucci, N Cheney, S Kriegman, J Bongard, C Laschi (2017)
[Evolutionary developmental soft robotics as a framework to study intelligence and adaptive behavior in animals and plants.](#)
Frontiers in Robotics and AI.
 25. N Livingston, A Bernatskiy, K Livingston, ML Smith, J Schwarz, JC Bongard, D Wallach & JH Long Jr (2016)
[Modularity and sparsity: evolution of neural net controllers in physically embodied robots.](#)
Frontiers in Robotics and AI.
 24. T Taylor, JE Auerbach, J Bongard, J Clune, S Hickinbotham, C Ofria, M Oka, S Risi, KO Stanley, & J Yosinski (2016)
[WebAL comes of age: A review of the first 21 years of artificial life on the web.](#)
Artificial Life, 22(3) 364–407.
 23. C Cappelle, A Bernatskiy, K Livingston, N Livingston, J Bongard (2016)
Morphological modularity can enable the evolution of robot behavior to scale linearly.
Frontiers in Robotics and AI, 3: 59.
 22. J Bongard (2015)
[Using robots to investigate the evolution of adaptive behavior.](#)
Current Opinion in Behavioral Sciences, 6: 168–173.
 21. M Wagdy & J Bongard (2015)
[Combining computational and social effort for collaborative problem solving.](#)
PLoS ONE, DOI: 10.1371/journal.pone.014524.

20. D Buckingham, C Skalka, and J Bongard (2015)
Inductive machine learning for improved estimation of catchment-scale snow water equivalent.
Journal of Hydrology, 524: 311-325.
19. R Swain, A Berger, J Bongard, & P Hines (2015)
Participation and contribution in crowdsourced surveys.
PLoS ONE, DOI: 10.1371/journal.pone.0120521.
18. Bongard, J. C. & Lipson, H. (2014)
Evolved machines shed light on robustness and resilience.
Proceedings of the IEEE, **102**(5): 899–914.
17. Lu, Z. Wu, X. & Bongard, J. C. (2014)
Active learning through adaptive heterogeneous ensembling.
IEEE Transactions on Knowledge and Data Engineering, DOI: 10.1109/TKDE.2014.2304474.
16. Bevelander, K. E., Kaipainen, K., Swain, R., Dohle, S., Bongard, J. C., Hines, P. D. H. & Wansink, B. (2014)
Crowdsourcing novel childhood predictors of adult obesity.
PLoS ONE, 9(2): e87756
15. Auerbach, J. E. & Bongard, J. C. (2014)
Environmental influence on the evolution of morphological complexity in machines.
PLoS Computational Biology, 10(1): e1003399
14. Bongard, J. C. (2013)
Evolutionary robotics.
Communications of the ACM, 56(8): 74—85.
13. Bongard, J. C., Hines, P. D. H., Conger, D., Hurd, P., and Lu, Z. (2012)
Crowdsourcing predictors of behavioral outcomes.
IEEE Transactions on Systems, Man, and Cybernetics, Part A, 43(1): 176–185.
12. Bongard, J. C. (2011)
Morphological change in machines accelerates the evolution of robust behavior.
Proceedings of the National Academy of Sciences, 108(4): 1234-1239.
11. Bongard, J. C. (2011).
Innocent until proven guilty: Reducing robot shaping from polynomial to linear time.
IEEE Transactions on Evolutionary Computation, 15(4): 571—85.
10. Kaipa, K., Bongard, J., Meltzoff, A. (2010).
Self discovery enables robot social cognition: Are you my teacher?
Neural Networks, 23: 1113-1124.
9. Bongard, J. C. (2010).
The utility of evolving simulated robot morphology increases with task complexity for object manipulation. *Artificial Life*, 16(3): 201-223.
8. Rughani, A. I., Dumont, T. M., Lu, Z., Bongard, J., Horgan, M. A., Penar, P. L., Tranmer, B. I. (2009).
Use of an artificial neural network to predict head injury outcome.
Journal of Neurosurgery, 113(3): 585–90.
7. Bongard J. C. (2009).

Accelerating self-modeling in cooperative robot teams.
IEEE Transactions on Evolutionary Computation, 13(2): 321-332.

6. Bongard, J. and H. Lipson (2007)
Automated reverse engineering of nonlinear dynamical systems.
Proceedings of the National Academy of Sciences, 104(24): 9943-9948.
5. Bongard, J., V. Zykov and H. Lipson (2006)
Resilient machines through continuous self-modeling.
Science, 314: 1118-1121.
4. Kouchmeshky, B., W. Aquino, H. Lipson and J. Bongard (2006)
Co-evolutionary strategy for structural damage identification using minimal physical testing.
International Journal for Numerical Methods in Engineering, 69(5): 1085-1107.
3. Bongard, J. and H. Lipson (2005)
Active coevolutionary learning of deterministic finite automata.
Journal of Machine Learning Research, 6(Oct): 1651-1678.
2. Bongard, J. and H. Lipson (2005)
Nonlinear system identification using coevolution of models and tests.
IEEE Transactions on Evolutionary Computation, 9(4): 361-384.
1. Pfeifer, R., F. Iida and J. Bongard (2005)
New robotics: design principles for intelligent systems.
Artificial Life Special Issue on New Robotics, Evolution and Embodied Cognition, 11(1-2): 99-120.

BOOK CHAPTERS

7. A Cangelosi, J Bongard, MH Fischer, S Nolfi (2015)
[Embodied intelligence](#).
Springer Handbook of Computational Intelligence, pp. 697-714
6. Bongard, J. C. (2014)
Evolving morphological computation.
Opinions and Outlooks on Morphological Computation, ISBN: 978-3-033-04515-6
5. Bongard, J. C. (2014)
Why morphology matters.
Horizons of of Evolutionary Robotics, MIT Press, pp. 125–152.
4. Icke, I., Allgaier, N. A., Danforth, C. M., Whelan, R., Garavan, H., Bongard, J. C. (2013)
A Deterministic and Symbolic Regression Hybrid Applied to Resting-State fMRI data.
Genetic Programming Theory and Practice IX, Springer.
3. Bongard, J. C. (2011)
The ‘What’, ‘How’ and the ‘Why’ of Evolutionary Robotics.
In Doncieux, S., Bredeche, N., Mouret, J.-B. (eds.),
New Horizons in Evolutionary Robotics (Studies in Computational Intelligence), 341: 29-35.
2. Bongard, J. C. (2011)
A Functional Crossover Operator for Genetic Programming.
Genetic Programming Theory and Practice VII, Springer, pp. 195—210

1. Bongard, J. and R. Pfeifer (2003)
Evolving complete agents using artificial ontogeny,
Morpho-functional Machines: The New Species, Springer-Verlag, pp. 237—258.

PEER-REVIEWED CONFERENCE PUBLICATIONS

81. Kriegman, Sam, Amir Mohammadi Nasab, Dylan Shah, Hannah Steele, Gabrielle Branin, Michael Levin, Josh Bongard, and Rebecca Kramer-Bottiglio (2020).
Scalable sim-to-real transfer of soft robot designs.
Third IEEE International Conference on Soft Robotics (RoboSoft), pp. 359-366.
80. Rosser, K., Kok, J., Chahl, J., Bongard, J. (2020)
Sim2real gap is non-monotonic with robot complexity for morphology-in-the-loop flapping wing design.
IEEE International Conference on Robotics and Automation (ICRA) (pp. 7001-7007).
79. Matthews, David, and Josh Bongard (2020).
Crowd grounding: finding semantic and behavioral alignment through human robot interaction
Procs. of the Artificial Life Conference, pp. 148-156.
78. Powers, Joshua, Ryan Grindle, Sam Kriegman, Lapo Frati, Nick Cheney, and Josh Bongard (2020).
Morphology Dictates Learnability in Neural Controllers.
Procs. of the Artificial Life Conference, pp. 52-59.
77. Powers, J., Pell, S. and Bongard, J. (2020).
A Framework for Search and Application Agnostic Interactive Optimization.
Procs. of the Artificial Life Conference, pp. 60-68.
76. S Kriegman, S walker, D Shah, M Levin, R Kramer-Bottiglio, J Bongard (2019).
[Automated shapeshifting for function recovery in damaged robots.](#)
Robotics: Science and Systems Proceedings, 10.15607/RSS.2019.XV.028
75. S Beaulieu, S Kriegman, JC Bongard (2018).
[Combating catastrophic forgetting with developmental compression.](#)
GECCO Conference Proceedings, pp. 386–393
74. S Kriegman, N Cheney, F Corucci, JC Bongard (2018).
[Interceptive robustness through environment-mediated morphological development.](#)
GECCO Conference Proceedings, pp. 109–116.
73. F Veenstra, PG de Prado Salas, J Bongard, K Stoy, S Risi (2018).
[Intrinsic Mortality Governs Evolvability.](#)
Artificial Life Conference Proceedings, pp. 242-249.
72. C Cappelle, J Bongard (2018).
[Embodied Embeddings for Hyperneat.](#)
Artificial Life Conference Proceedings, pp. 461-468
71. A Kodali, M Szubert, K Das, S Ganguly, J Bongard (2018).
[Understanding climate-vegetation interactions in global rainforests through a GP-tree analysis.](#)
Parallel Problem Solving from Nature (PPSN) Conference Proceedings, pp. 525-536
70. J Powers, S Kriegman, J Bongard (2018).
[The effects of morphology and fitness on catastrophic interference.](#)
Artificial Life Conference Proceedings, pp. 606-613

69. A Bernatskiy & JC Bongard (2017).
[Choice of robot morphology can prohibit modular control and disrupt evolution.](#)
Procs of the European Conference on Artificial Life, Nancy, France.
68. S Kriegman, N Cheney, F Corucci, JC Bongard (2017).
[A minimal developmental model can increase evolvability in soft robots.](#)
Proceedings of the Genetic and Evolutionary Computation Conference, pp 131-138.
67. C Cappelle, A Bernatskiy, J Bongard (2017).
[Reducing Training Environments in Evolutionary Robotics Through Ecological Modularity.](#)
Proceedings of the Conference on Biomimetic and Biohybrid Systems, pp 95-106.
66. M Szubert, A Kodali, S Ganguly, K Das & JC Bongard (2016)
[Semantic forward propagation for symbolic regression.](#)
Procs of the Parallel Problem Solving from Nature (PPSN) Conference, Edinburgh, UK.
65. S Kriegman, M Szubert, JC Bongard & C Skalka (2016)
[Evolving spatially aggregated features from satellite imagery for regional modeling.](#)
Procs of the Parallel Problem Solving from Nature (PPSN) Conference, Edinburgh, UK.
64. N Powell & JC Bongard (2016)
[Exploring uncertainty and movement in categorical perception using robots.](#)
Procs of the Parallel Problem Solving from Nature (PPSN) Conference, Edinburgh, UK.
63. M Szubert, A Kodali, S Ganguly, K Das & JC Bongard (2016)
[Reducing antagonism between behavioral diversity and fitness in semantic genetic programming.](#)
Procs of the Genetic and Evolutionary Computation Conference (GECCO), Denver, CO.
62. N Cheney, JC Bongard, V SunSpiral & H Lipson (2016)
[On the difficulty of co-optimizing morphology and control in evolved virtual creatures.](#)
15th Intl Conference on the Simulation and Synthesis of Living Systems (ALife 2016), Cancun, MX.
61. F Corucci, N Cheney, H Lipson, C Laschi & JC Bongard (2016)
[Material properties affect evolution's ability to exploit morphological computation in growing soft-bodied creatures.](#)
15th Intl Conference on the Simulation and Synthesis of Living Systems (ALife 2016), Cancun, MX.
60. J Anetsberger & JC Bongard (2016)
[Robots can ground crowd-proposed symbols by forming theories of group mind.](#)
15th Intl Conference on the Simulation and Synthesis of Living Systems (ALife 2016), Cancun, MX.
59. M Wagdy & JC Bongard (2016)
[Social contribution in the design of adaptive machines on the web.](#)
15th Intl Conference on the Simulation and Synthesis of Living Systems (ALife 2016), Cancun, MX.
58. McAndrew, T. C., Bongard, J. C., Danforth, C. M., Dodds, P. S., Hines, P. D., & Bagrow, J. P. (2016).
What we write about when we write about causality: Features of causal statements across large-scale social discourse.
ASONAM 16.
57. M Wagdy & JC Bongard (2015)
[Crowdseeding: a novel approach for designing bioinspired machines.](#)

Fourth Intl Conf on Biomimetics and Biohybrid Systems (Living Machines 2015), Barcelona, Spain.

56. K Zieba & JC Bongard (2015)
[An embodied approach for evolving robust visual classifiers.](#)
Procs of the Genetic and Evolutionary Computation Conference, Madrid, Spain.
55. A Yousefi, JC Bongard & C Skalka (2015)
[A Genetic Programming approach to cost-sensitive control in resource constrained sensor systems.](#)
Procs of the Genetic and Evolutionary Computation Conference, Madrid, Spain.
54. N Cheney, JC Bongard & H Lipson (2015)
[Evolving soft robots in tight spaces.](#)
Procs of the Genetic and Evolutionary Computation Conference, Madrid, Spain.
53. JC Bongard, A Bernatskiy, K Livingston, N Livingston, J Long & M Smith (2015)
[Evolving robot morphology facilitates the evolution of neural modularity and evolvability.](#)
Procs of the Genetic and Evolutionary Computation Conference, Madrid, Spain.
52. Wagdy, M., Bongard, J. C. (2014)
Collective Design of Robot Locomotion.
Procs of the 14th Intl Conf on the Synthesis and Simulation of Living Systems, New York City.
Acceptance rate: 49.8%. Citations: 4
51. Bernatskiy, A., Hornby, G., Bongard, J. C. (2014)
Improving Robot Behavior Optimization by Combining User Preferences.
Procs of the 14th Intl Conf on the Synthesis and Simulation of Living Systems, New York City.
Acceptance rate: 49.8%. Citations: 3
50. Icke, I., Bongard, J. C. (2013)
Improving Genetic Programming Based Symbolic Regression Using Deterministic Machine Learning.
Procs of the IEEE Congress on Evolutionary Computation, Cancun, MX.
Citations: 9
49. Icke, I., Bongard, J. C. (2013)
Modeling Hierarchy using Symbolic Regression.
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48. Celis, S., Hornby, G. S., Bongard, J. C. (2013)
Avoiding Local Optima with User Demonstrations and Low-level Control.
Procs of the IEEE Congress on Evolutionary Computation, Cancun, MX.
Citations: 8
47. Bongard, J. C., Hornby, G. S. (2013)
Combining Fitness-based Search and User Modeling in Evolutionary Robotics,
Procs of the Genetic and Evolutionary Computation Conference, pp. 159-166.
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46. Auerbach, J. E., Bongard, J. C. (2012)
On the Relationship Between Environmental and Mechanical Complexity in Evolved Robots.
ALife XIII, pp. 309-316, DOI: 10.7551/978-0-262-31050-5-ch041.
Acceptance rate: 50%. Citations: 17
45. Auerbach, J. E., Bongard, J. C. (2012)

- On the Relationship Between Environmental and Morphological Complexity in Evolved Robots,
Procs of the Genetic and Evolutionary Computation Conference, pp. 521-528.
 Acceptance rate: 36%. Citations: 35
44. Hornby, G. S., Bongard, J. C. (2012)
 Accelerating Interactive Evolutionary Algorithms through Comparative and Predictive User Models,
Procs of the Genetic and Evolutionary Computation Conference, DOI: 10.1145/2330163.2330196.
 Acceptance rate: 36%. Citations: 10
 43. Hornby, G. S., Bongard, J. C. (2012)
 Learning Comparative User Models for Accelerating Human Computer Collaborative Search.
Procs of the Evolutionary and Biologically Inspired Music, Sound, Art and Design Conf, pp. 117-128.
 Citations: 6
 42. Auerbach, J. E., Bongard, J. C. (2011)
 Evolving Complete Robots with CPPN-NEAT: The Utility of Recurrent Connections,
Procs of the Genetic and Evolutionary Computation Conference, pp. 1475–1482, ACM: NY, USA
 Acceptance rate: 38%
 Citations: 15
 41. Bongard, J. C. (2011)
 Spontaneous Evolution of Structural Modularity in Robot Neural Network Controllers,
Procs of the Genetic and Evolutionary Computation Conference, pp. 251–258, ACM: NY, USA.
 Acceptance rate: 38%
 Citations: 16
 40. Bongard, J. C. (2011)
 Morphological and Environmental Scaffolding Synergize when Evolving Robot Controllers,
Procs of the Genetic and Evolutionary Computation Conference, pp. 179–186, ACM: NY, USA
 Acceptance rate: 38%
 Citations: 14
 39. Auerbach, J. E., Bongard, J. C. (2010)
 Dynamic Resolution in the Co-Evolution of Morphology and Control,
Procs of the 12th Intl Conf on the Synthesis and Simulation of Living Systems.
 Citations: 33
 38. Lu, Z., Wu, X., Zhu, X., Bongard, J. (2010)
 Ensemble Pruning via Individual Contribution Ordering,
The 16th ACM SIGKDD Conference on Knowledge Discovery and Data Mining.
 Citations: 46
 37. Auerbach, J. E., Bongard, J. C. (2010)
 Evolving CPPNs to Grow Three Dimensional Structures.
Procs of the Genetic and Evolutionary Computation Conference, Portland, OR.
 Acceptance rate: 45%. Citations: 34
 36. Bongard, J. C. (2010)
 A Probabilistic Functional Crossover Operator for Genetic Programming.
Procs of the Genetic and Evolutionary Computation Conference, Portland, OR.
 Acceptance rate: 45%. Citations: 8
 35. Bongard, J. C., Hornby, G. S. (2010)
 Guarding Against Premature Convergence while Accelerating Evolutionary Search.

- Procs of the Genetic and Evolutionary Computation Conference*, Portland, OR.
Acceptance rate: 45%. Citations: 24
34. Lu, Z., Wu, X., Bongard, J. (2010)
Adaptive Informative Sampling for Active Learning.
Procs of The SIAM Conference on Data Mining (SDM 2010), Columbus, Ohio, USA
Citations: 5
 33. Lu, Z., Wu, X., Bongard, J. C. (2009)
Active Learning with Adaptive Heterogeneous Ensembles.
Procs of the Intl Conf on Data Mining, Miami, FL.
Citations: 11
 32. Kaipa, K., Bongard, J. C., Meltzoff A. N. (2009)
Combined Structure and Motion Extraction from Visual Data Using Evolutionary Active Learning.
Procs of the Genetic and Evolutionary Computation Conference, Montreal Canada.
Acceptance rate: 41.4%. Citations: 1
 31. Auerbach, J., Bongard, J. C. (2009)
Evolution of Functional Specialization in a Morphologically Homogeneous Robot,
Procs of the Genetic and Evolutionary Computation Conference, Montreal Canada.
Acceptance rate: 41.4%. Citations: 7
 30. Auerbach, J., Bongard, J. C. (2009)
How Robot Morphology and Training Order Affect the Learning of Multiple Behaviors,
IEEE Congress on Evolutionary Computation, Trondheim, Norway.
Citations: 20
 29. Bongard, J. (2008)
Behavior Chaining: Incremental Behavior Integration for Evolutionary Robotics.
Artificial Life XI, MIT Press, Cambridge, MA.
Citations: 42
 28. Bongard, J. (2007)
Synthesizing Physically-Realistic Environmental Models from Robot Exploration,
Advances in Artificial Life: 9th European Conference, Springer-Verlag, Berlin, pp. 806-815.
Citations: 4
 27. Bongard, J. (2007)
Action-Selection and Crossover Strategies for Self-Modeling Machines,
Procs of the Genetic and Evolutionary Computation Conf, ACM Press, New York, NY, pp. 198-205.
Acceptance rate: 46.1%. Citations: 7
 26. Bongard, J. (2007)
Exploiting Multiple Robots to Accelerate Self-Modeling,
Procs of the Genetic and Evolutionary Computation Conf, ACM Press, New York, NY, pp. 214-221.
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 25. Lipson, H., J. Bongard, V. Zykov and E. Malone (2006)
Evolutionary Robotics for Legged Machines: From Simulation to Physical Reality,
Procs of the Intelligent Autonomous Systems Conf (IAS-9), pp. 11—18.
Citations: 42
 24. Bongard, J., V. Zykov and H. Lipson (2006)

- Automated Synthesis of Body Schema using Multiple Sensor Modalities,
ALIFE X, pp. 220—226.
Citations: 27
23. Bongard, J. and H. Lipson (2005)
Automatic Synthesis of Multiple Internal Models Through Active Exploration,
AAAI Fall Symposium on Reactive to Anticipatory Cognitive Embodied Systems, Arlington, VA.
Citations: 7
 22. Bongard, J. and H. Lipson (2005)
'Managed Challenge' Alleviates Disengagement in Co-evolutionary System Identification,
Procs of the Genetic and Evolutionary Computation Conference, ACM, pp. 531-538.
Acceptance rate: 46.1%. Citations: 21
 21. White, P., V. Zykov and J. Bongard (2005)
Three Dimensional Stochastic Reconfiguration of Modular Robots,
Robotics: Science and Systems, Cambridge, MA.
Citations: 157
 20. Bongard J. and Lipson H. (2005)
Reinventing the Wheel: Experiments in Evolutionary Geometry,
Late Breaking Papers of the Genetic and Evolutionary Computation Conf, Washington DC.
Citations: 2
 19. Zykov, V., J. Bongard and H. Lipson (2005)
Co-evolutionary Variance Can Guide Physical Testing in Evolutionary System Identification,
Procs of the NASA/DoD Conf on Evolvable Hardware, June, Washington DC, pp. 213-220.
Citations: 10
 18. Lipson, H. and J. Bongard (2004)
An Exploration-Estimation Algorithm for Synthesis and Analysis
of Engineering Systems Using Minimal Physical Testing,
Procs of the ASME Design Engineering Conferences, Salt Lake City, UT.
Citations: 17
 17. Zykov, V., J. Bongard and H. Lipson (2004)
Evolving Dynamic Gaits on a Physical Robot,
Late Breaking Papers for the Genetic and Evolutionary Computation Conf, Seattle, WA.
Citations: 61
 16. Bongard, J. and H. Lipson (2004)
Once More Unto the Breach: Co-evolving a Robot and its Simulator,
Procs of the Intl Conf on the Simulation and Synthesis of Living Systems (ALIFE9), pp. 57-62.
Citations: 37
 15. Bongard, J. and H. Lipson (2004)
Automated Robot Function Recovery after Unanticipated Failure
or Environmental Change using a Minimum of Hardware Trials,
Procs of the NASA/DoD Conference on Evolvable Hardware, IEEE Computer Society, pp. 169-176.
Citations: 32
 14. Bongard, J. and H. Lipson (2004)
Automating Genetic Network Inference with Minimal Physical Experimentation Using Coevolution,
Procs of the Genetic and Evolutionary Computation Conf, Springer, pp. 333-345.

Acceptance rate: 50%. Citations: 28

13. Bongard, J. and H. Lipson (2004)
Automated Damage Diagnosis and Recovery for Remote Robotics,
Procs of the International Conf on Robotics and Automation (ICRA), Omnipress, pp. 3545-3550.
Citations: 35
12. Bongard, J. (2002)
Evolved Sensor Fusion and Dissociation in an Embodied Agent,
Procs of the EPSRC/BBSRC Intl Workshop on Biologically-Inspired Robotics, pp. 102-109.
Citations: 8
11. Frutiger, D. R., Bongard, J. and F. Iida (2002)
Iterative Product Engineering: Evolutionary Robot Design,
Procs of the Fifth Intl Conf on Climbing and Walking Robots, pp. 619-629.
Citations: 16
10. Bongard, J. and R. Pfeifer (2002)
A Method for Isolating Morphological Effects on Evolved Behaviour,
Procs of the Seventh Intl Conf on the Simulation of Adaptive Behaviour (SAB2002), pp. 305-311.
Citations: 48
9. Bongard, J. and R. Pfeifer (2002)
Relating Neural Network Performance to Morphological Differences in Embodied Agents,
Procs of the Sixth Intl Conf on Cognitive and Neural Systems, Boston, USA.
Citations: 1
8. Bongard, J. (2002)
Evolving Modular Genetic Regulatory Networks,
Procs of the IEEE Congress on Evolutionary Computation (CEC2002), IEEE Press, pp. 1872-1877.
Citations: 204
7. Paul, C. and J. Bongard (2001)
The Road Less Travelled: Morphology in the Optimization of Biped Robot Locomotion,
Procs of the IEEE/RSJ Intl Conf on Intelligent Robots and Systems (IROS2001), Hawaii, USA.
Citations: 74
6. Bongard, J. and C. Paul (2001)
Making Evolution an Offer It Can't Refuse: Morphology and the Extradimensional Bypass,
Procs of the Sixth European Conf on Artificial Life, Springer-Verlag, pp. 401-412.
Citations: 58
5. Bongard, J. and R. Pfeifer (2001)
Repeated Structure and Dissociation of Genotypic and Phenotypic Complexity in Artificial Ontogeny,
Procs of the Genetic and Evolutionary Computation Conf, Morgan Kaufmann, pp. 829-836.
Citations: 166
4. Bongard, J. and C. Paul (2000)
Investigating Morphological Symmetry and Locomotive Efficiency using Virtual Embodied Evolution,
Procs of the Sixth Intl Conf on the Simulation of Adaptive Behaviour, MIT Press, pp. 420-429.
Citations: 74
3. Bongard, J. (2000)
Reducing Collective Behavioural Complexity through Heterogeneity,

Artificial Life VII, MIT Press, pp. 327-336.
Citations: 5

2. Bongard, J. (2000)
The Legion System: A Novel Approach to Evolving Heterogeneity for Collective Problem Solving,
Procs of the Third Euro Conf on Genetic Programming, Springer-Verlag, pp. 25—37.
Citations: 37
1. Bongard, J. (1999)
Coevolutionary Dynamics of a Multi-Population Genetic Programming System,
Procs of the Fifth Euro Conf on Artificial Life, Springer-Verlag, pp. 316-321.
Citations: 5

MINIMALLY- REVIEWED PUBLICATIONS

20. Bongard, J. C. (2017)
[The symbol grounding problem.](#)
Invited Response to the 2017 Edge Question:
“What scientific term or concept ought to be more widely known?”
19. JC Bongard (2016)
[Evolving soft robots.](#) *Soft Robotics* 3(2): 43-44. Editorial.
18. A Larson, A Bernatskiy, C Cappelle, K Livingston, N Livingston,
J Long, J Schwarz, M Smith & JC Bongard (2016)
[Recombination hotspots promote the evolvability of modular systems.](#)
Procs of the Genetic and Evolutionary Computation Conference (GECCO 2016). Poster.
17. Bongard, J. C. (2016)
[I, For One.](#)
Invited Response to the 2016 Edge Question:
“What do you consider the most interesting [scientific] news?”
16. Bongard, J. C. (2015)
[Manipulators and Manipulanda.](#)
Invited Response to the 2015 Edge Question:
“What do you think about machines that think?”
15. JP Bagrow, S Desu, MR Frank, N Manukyan, L Mitchell, A Reagan, EE Bloedorn, LB Booker,
LK Branting, MJ Smith, BF Tivnan, CM Danforth, PS Dodds, JC Bongard (2013).
Shadow networks: Discovering hidden nodes with models of information flow.
arXiv preprint arXiv: 1312.6122
14. Hornby, G. S. & Bongard, J. C. (2013).
Accelerating Interactive Evolutionary Algorithms through User Modeling.
International Conference on Intelligent User Interfaces.
13. Celis, S., Bongard, J. C. (2012)
Not All Physics Simulators Can Be Wrong in the Same Way.
Genetic and Evolutionary Computation Conference, pp. 659-660.
12. Beliveau, P., Hornby, G. S., Bongard, J. C. (2012)
Interactive Simulated Robot Construction and Controller Evolution.
Genetic and Evolutionary Computation Conference, pp. 627- 628.

11. Bongard, J. C., Beliveau, P., Hornby, G. S. (2012)
Avoiding Local Optima with Interactive Evolutionary Robotics.
Genetic and Evolutionary Computation Conference, pp. 1405—1406.
10. Bongard, J. C. (2011)
How evolution shapes the way roboticists think.
Procs of the 2nd European Future Technologies Conf and Exhibition (FET 11), 7: 8-10.
9. Bongard, J. (2011).
Morphogenetic robotics recapitulates artificial ontogeny.
Newsletter of the Autonomous Mental Development Technical Committee. 8(2): 3-4.
8. Bongard, J. (2009).
Biologically inspired computing.
IEEE Computer, 42(4): 95—98.
7. Lu, Z., Bongard, J. C. (2009)
Exploiting Multiple Classifier Types with Active Learning.
Genetic and Evolutionary Computation Conference (GECCO 2009), Montreal Canada.
6. Bongard, J. C. (2009)
The Impact of Jointly Evolving Robot Morphology and Control on Adaptation Rate.
Genetic and Evolutionary Computation Conference (GECCO 2009), Montreal Canada.
5. Bongard, J. (2008).
Probabilistic Robotics Book Review.
Artificial Life, 14(2): 227—229.
4. Bongard, J. (2008)
Embodied cognition: the other morphology.
The Neuromorphic Engineer, DOI: 10.2417/1200812.1420.
3. Lungarella, M., Iida, F., Bongard, J. and Pfeifer, R. (2008)
AI in the 21st century – with historical reflections,
Proceedings of the 50th Anniversary Summit of Artificial Intelligence, pp. 1-8.
2. Lu, Z., Rughani, A. I., Tranmer, B. I., Bongard, J. (2008)
Informative Sampling for Large Unbalanced Data Sets,
Fourth Workshop on Medical Applications of Genetic and Evolutionary Computation at GECCO 2008.
1. Conduit, R., Adami, C., Lipson, H., Zykov, V. and Bongard, J. (2007).
To sleep, perchance to dream.
Science, 315: 1219-1220.

SERVICE

CO-CHAIR [The 2021 International Workshop on Embodied Intelligence](#)
CHAIR [The 2020 Artificial Life Conference](#) (400+ participants; 39 countries)

EDITORSHIPS

2014— Associate Editor, *Frontiers in Robotics and AI*
2014— Review Editorial Board, *Evolutionary Robotics*
2013— Associate Editor, *Soft Robotics*

- 2011– Action Editor, *Neural Computation*
- 2011– Academic Editor, *Public Library of Science (PLOS) ONE*
- 2013– Guest Associate Editor, *PLOS Computational Biology*

TREASURER

- 2014– International Society for Artificial Life

MEMBERSHIP

- 2014– University of Vermont STEM Leadership Council
- 2014 *13th Intl Conf on the Simulation of Adaptive Behavior*, program committee
- 2014 *13th Intl Conf on Parallel Problem Solving from Nature*, program committee
- annually *Genetic and Evolutionary Computation Conference*, program committee
- annually *Living Machines Conference*, program committee
- biennially *Artificial Life Conference*, program committee
- biennially *European Conference on Artificial Life Conference*, program committee
- 2013 *Genetic and Evolutionary Computation Conference*, track chair
- 2013 *Congress on Evolutionary Computation (CEC)*, program committee
- 2013– National affiliate, University of Iowa *DeLTa* center
- 2011– *Federation of American Scientists (FAS)* board of sponsors
- 2007– *Institute of Electrical and Electronics Engineers (IEEE)*
- 2006– *Association for Computing Machinery (ACM)*

REVIEWER

Science
Nature
Proceedings of the National Academy of Science (PNAS)
The MacArthur Foundation
Science Robotics
Nature Communications
PLOS ONE
PLOS Computational Biology
Neural Computation
Journal of Machine Learning Research (JMLR)
IEEE Transactions on Evolutionary Computation
IEEE Transactions on Robotics
Artificial Life
Adaptive Behavior
IEEE Transactions on Systems, Man and Cybernetics
Journal of Neurorobotics

PANELIST

- 2006– National Science Foundation (NSF) proposal reviews (~ 2 panels / year)
- 2020 Department of Energy
- 2013 The EC Flagship Initiative ‘Human Brain Project’ proposal reviewing
- 2010 National Institutes of Health (NIH) proposal reviewing

INTERNAL

- 2018 Host of the 2018 *Aiken Lecture*.
- 2018– Graduate Student Coordinator for the Computer Science Department
- 2015– Director, Vermont Advanced Computing Core (UVM’s high performance computing facility)
- 2013– UVM STEM Leadership Council Member
- 2011–2015 Vice Chair, Vermont Complex Systems Center

OUTREACH

- ~10 presentations per year. Representative sample below.
- 2016 Presentation to Abenaki Nation high school students

2015– [Twitch Plays Robotics](#)
 2012– Governor’s Institute of Vermont presentations (~100 students)
 2014–2017 Burlington High School presentation on robotics.
 2016 [Waldorf School](#) (grades 7 through 12), Toronto
 2016 [Steelesview Public School](#), Toronto (grades 2 and 3)
 2007–2013 [Governor’s Institute of Vermont](#) summer program guest instructor
 2013 Boy Scouts of America guest instructor
 2013 [Reddit AMA](#) (“Ask Me Anything”)
 2013– [Hour of Code](#) visitor, Vermont middle schools.

TEACHING

2014– [Ludobots](#). The world’s only MOOC taught from reddit.
 2010– [Evolutionary Robotics](#)
 2007– [Human Computer Interaction](#)
 2006–2008 *Software Engineering*
 2009 *Embodied Cognition*

ADVISING

POSTDOCS

2020– [Sam Kriegman](#) (Computer Science)
 2017–2018 [Zahra Mahoor](#)
 2015–2017 [Marcin Szubert](#)
 2012–2013 [Ilknur Icke](#)
 2008–2010 [Kaipa Krishnanand](#)

PHD’S

2020– [Amanda Bertschinger](#) (Computer Science)
 2019– [Caitlin Grasso](#) (Computer Science)
 2019– [Atoosa Parsa](#) (Complex Systems & Data Science)
 2017– [Joshua Powers](#) (Computer Science)
 2016–2020 [Sam Kriegman](#) (Computer Science)
 2015–2019 [Collin Cappelle](#) (Computer Science)
 2013– 2018 [Anton Bernatskiy](#) (Computer Science)
 Dissertation: *Improving Scalability of Evolutionary Robotics with Reformulation*.
 2013–2016 [Mark Wagdy](#) (Computer Science))
 Dissertation: *Enabling machine science through distributed human computing*.
 2009–2013 [Joshua Auerbach](#) (Computer Science))
 Dissertation: *The evolution of complexity in autonomous robots*.
 2006–2011 [Zhenyu Lu](#) (Computer Science)
 Dissertation: *Active learning with adaptive heterogeneous ensembles*.

MASTERS

2019– [Sida Liu](#) (Computer Science)
 2018– [Ryan Grindle](#) (Mathematics)
 2019–2020 [Jack Felag](#) (Computer Science)
 2018–2020 [Sarah Pell](#) (Computer Science)
 2017–2018 [Alexander Ram](#) (Computer Science)
 2017–2018 [Ryan Grindle](#) (Mathematics)
 2013–2018 [Roman Popov](#) (Computer Science)

- 2015–2016 [Nate Powell](#) (Statistics)
Dissertation: *The role of Uncertainty in Categorical Perception Utilizing Statistical Learning in Robots.*
- 2015–2016 [Sam Kriegman](#) (Co-advising; statistics)
Dissertation: *Evolving spatially aggregated features from satellite imagery for regional modeling.*
- 2014–2015 [Afsoon Yousefi-Zowj](#) (Computer Science)
Dissertation: *A Genetic Programming approach to cost-sensitive control in wireless sensor networks.*
- 2014–2015 Karol Zieba (Computer Science)
Dissertation: *Evolving multi-modal sensors.*
- 2012–2014 [David Buckingham](#) (Computer Science)
Dissertation: *Inductive learning of snowpack distribution models for improved estimation of areal snow water equivalent.*
- 2012–2014 [Christopher Pierce](#) (Computer Science; project option.)
- 2010–2012 [Somdeb Chatterjee](#) (Computer Science)
Dissertation: *Crowdsourcing predictors for modeling behavioral outcomes.*
- 2010–2012 [Yunfei Zhao](#) (Computer Science; project option.)
- 2008–2010 [Peter Hurd](#) (Computer Science; project option.)

UNDERGRADUATES

- 2019– Nathan Tolley (Computer Science)
- 2019– Kyle Morand (Computer Science)
- 2019– Filip Saulean (Computer Science)
- 2019– Jean-Baptiste Bohl (Computer Science)
- 2019– Everest Witman (Computer Science)
- 2018– David Matthews (Computer Science)
- 2016– Jack Felag (Mathematics)
- 2015–2016 Ari Larson (Computer Science)
- 2014–2015 Mariko Totten (Computer Science)
- 2013–2014 Timothy Rizvanov (Computer Science)
- 2013–2014 Fritz Davenport (Computer Science)
- 2013–2014 Alex Berger (Business administration)
- 2011–2012 Nick Cheney (Computer Science)

PHD DEFENSE COMMITTEE MEMBER

- 2020 [Tønnes Nygaard](#), University of Oslo, Norway
[Karine Miras](#), Vrije Universiteit Amsterdam
Daniel Wilson, UVM
- 2019 [Elijah Bowen](#), Dartmouth
[Simon Hauser](#), EPFL, Switzerland
- 2018 [Eric Clark](#), UVM
- 2016 Thomas McAndrew, UVM
Emily Cody, UVM
- 2014 Morgan Frank, UVM
Nicholas Chaumont, Keck Graduate Institute
Ahmed Hamed, UVM
Jesse van den Kieboom, EPFL, Switzerland
- 2013 Eitan Pechenik, UVM
Song Wang, UVM
Karim Chichakly, UVM
Nicolas Allgaier, UVM
- 2012 Thierry Buecheler, University of Zurich, Switzerland
- 2011 Sylvain Koos, UPMC, France

2010 Peter Duerr, EPFL, Switzerland

STAFF

2018- [Rachel Dotey](#). Software developer for #UVMComputes project.

INVITED TALKS

- Mar, 2021 “[CDOs](#).” 6th John Cabot University Workshop on posthumanism. (Keynote)
Jan, 2021 “Machine Science.” Kyushu Institute of Technology (Invited)
Jan, 2021 “Evolutionary Robotics.” Kyushu Institute of Technology (Invited)
- Dec, 2020 “[CDOs](#).” ShanghAI Lecture. (Invited)
Nov, 2020 “CDOs.” AAAI Fall Symposium on Abstraction and Analogy. (Invited)
Nov, 2020 “[CDOs](#).” ACM Symposium on Computational Fabrication. (Keynote)
Oct, 2020 “[Computational background of CDOs](#).” UVM Electrical and Biomedical Engineering seminar.
Oct, 2020 “CDOs.” Scifoo. Google.
Oct, 2020 “Crowdsourcing CDO training.” Hybrid Intelligence Round Table. Aarhus University, Denmark.
Oct, 2020 “[CDOs and NLP](#).” Indiana University (Invited)
Oct, 2020 [Panel discussion on small-scale robots](#). Life Summit, AI LA. (Invited)
Sept, 2020 “CDOs.” [Genomics Institute of the Novartis Research Foundation](#) (Invited)
July, 2020 “[Scaling up automated design and manufacture of soft and biological robots](#).” GECCO workshop (Invited)
July, 2020 “Evolving the Physical Structure of Compliant, Soft, and Biological Robots.” (AIM2020; Invited)
June, 2020 “[CDOs](#).” Research and Applied AI Summit ([RAAIS](#)) (Keynote)
Apr, 2020 “Computer designed organisms (CDOs).” Stanford EE Computer Systems Colloquium (Invited)
Jan, 2020 “[word2vec2bot](#).” University of Michigan (Invited)
- Dec, 2019 “Soft robots that evolve and develop.” ShanghAI Lecture Series (Invited)
June, 2019 “[Evolutionary Robotics](#).” Governor’s Institute of Vermont. (Invited)
May, 2019 “Co-optimizing body and control for soft and modular robots.” EPFL, Switzerland. (Invited)
May, 2019 “The effects of Cartesian gravity on robotics.” University of Reading, UK. (Invited)
Mar, 2019 “Sim2real, sim2life, and sim2all.” Yale CS Colloquium (Invited).
Jan, 2019 “[Morphology, evolution and cognition](#).” NECSI Winter School presentation. (Invited)
- Dec, 2018 “What evolutionary robotics can teach us about embodied cognition.” ShanghAI Lecture Series (Invited)
Dec, 2018 [Hour of Code](#) presentation to 50 6th graders, Saint Albans City Elementary School.
Nov, 2018 “Embodiment, Evolution & Meaning.” Santa Fe Institute Workshop on AI and the Barrier to Meaning.
Nov, 2018 “[The moral challenges of robotics and AI](#).” Community AI Forum, Mount Mansfield Union High School.
July, 2018 “[Robots as complex systems](#).” ICCS Conference.
July, 2018 “[The role of embodiment in open-ended evolution](#).” ALife Workshop on Open-ended Evolution.
May, 2018 “[Soft robots that morph and behave simultaneously](#).” ICRA Workshop on Soft Robotics.
May, 2018 “Realizing Explainable AI.” [Open Data Science Conference \(ODSC\) East](#).
Feb, 2018 “[Autonomous yet safe machines](#).” Generator VT, Reckless Ideas seminar series.
- Nov, 2017 [ShanghAI](#) Lecture Series (Invited)
Sept, 2017 IEEE/RSJ Intl. Conference on Intelligent Robots and Systems (IROS) (**Keynote**)
Sept, 2017 Santa Fe Institute Working Group on Morphological Computation (Invited)
June, 2017 Human Brain Project workshop on embodied cognition (Geneva, CH) (Invited)
Feb, 2017 [SFI](#) Workshop: “Evolution and Restraint of Malicious Behavior in Complex Systems” (Invited)
- Oct, 2016 “Speaking to a general audience” for UVM IGERT Smart Grid graduate students (Invited)
Sept, 2016 ASME Smart Materials, Adaptive Structures and Intelligent Systems Conference (Stowe, VT) (Invited)
Sept, 2016 Santa Fe Institute Short Course on Innovation (Austin, TX) (Invited)
Sept, 2016 [Parallel Problem Solving from Nature](#) conference. (University of Stirling, Edinburgh) (**Keynote**)
May, 2016 [Trusted autonomous systems](#). (ACFR, University of Sydney, Australia) (Invited)

May, 2016 Trusted autonomous systems. (Intl. Symp. on Trusted Autonomous Systems, Australia) (**Keynote**)
Mar, 2016 [Some philosophical implications of evolutionary robotics](#). (UPitt [HPS](#) Annual Lecture Series) (Invited)
Feb, 2016 Evo devo robo. ([University of Toronto Cognitive Science Symposium](#)) (Invited)

Dec, 2015 [ShanghAI](#) lecture (simulcast to classrooms in Europe and Asia) (Invited)
Dec, 2015 New Jersey Institute of Technology (host: Gal Haspel, biology) (Invited)
Nov, 2015 UVM Honors College Plenary Lecture (Invited)
Oct, 2015 UMD Workshop on Soft Robotics (Invited)
May, 2015 [Factory of Imagination](#) lecture, Denmark (500 attendees) (**Keynote**)
Feb, 2015 [ShanghAI](#) lecture (simulcast to classrooms in Europe and Asia) (Invited)

Nov, 2014 Cornell Univeristy (host: Robert Shepherd, engineering) (Invited)
Sept, 2014 University of Maryland workshop on soft robotics (Invited)
Aug, 2014 [Scifoo](#) (hosts: Nature, Google, O'Reilly Media, Digital Science) (Invited)
July, 2014 Workshop on Artificial Life and the Web at ALife conference (Invited)
July, 2014 International Society for Artificial Life (ISAL) Summer School (Invited)
June, 2014 DARPA Biological Technologies Office (Invited)
June, 2014 Neural Systems & Behavior Summer School, Woods Hole Marine Biology Lab (Invited)
May, 2014 EPFL, Lausanne, Switzerland (host: Auke Isepeert) (Invited)
Mar, 2014 National STEM Conference (Concept Schools), Cleveland, OH (**Keynote**)
Mar, 2014 Air Force Research Laboratories (AFRL), Rome, NY (Invited)

Dec, 2013 [ShanghAI](#) lecture (simulcast to 15 classrooms in Europe and Asia) (Invited)
Nov, 2013 National Autonomous University of Mexico (host: Carlos Gershenson) (Invited)
Oct, 2013 University of Iowa [Delta Center](#) (host: Mark Blumberg, psychology) (Invited)
Sept, 2013 eSMC neuroscience/robotics graduate summer school (host: Andreas Engel) (Invited)
Sept, 2013 Evolutionary Biology lecture, University of Zurich (host: Andreas Wagner) (Invited)
Aug, 2013 Gordon Research Conference on Neuroethology (host: Heather Eisten, biology) (Invited)
July, 2013 Soft Robotics Workshop at ETH, Zurich (host: Fumiya Iida, robotics) (**Keynote**)
June, 2013 Evolution Meeting, SSE Presidential Symposium (host: Richard Lenski, biology) (Invited)
June, 2013 Evolution Meeting, Education Symposium (host: George Gilchrist, NSF) (Invited)
Mar, 2013 University of Texas at Austin (host: Dana Ballard, Computer Science) (Invited)

Nov, 2012 Vassar College (host: John Long, biology) (Invited)
Nov, 2012 Harvard University (host: Radhika Nagpal, engineering) (Invited)
June, 2012 Tufts University (host: Michael Levin, biology) (Invited)
Apr, 2012 Tufts University (host: Barry Trimmer, biology) (Invited)
Jan, 2012 University of Southern California (host: Francisco Valero-Cuevas, bioengineering) (Invited)

Dec, 2011 Castleton State College, Vermont (Invited)
Nov, 2011 Global ShanghAI Lecture series (telecast from Vermont) (Invited)
Oct, 2011 TEDx presentation, University of Vermont (Invited)
July, 2011 Woods Hole Workshop on Computational Neuroscience (host: Terrence Sejnowski) (Invited)
May, 2011 [European Future and Emerging Technologies \(FET\) Conference](#), Budapest (**Keynote**)
Mar, 2011 Annual lecture, Simon Fraser University, Canada (host: Bernard Roitbert) (Invited)
Jan, 2011 Cognitive Dynamical Systems Workshop, Salk Institute (host: T. Sejnowski) (Invited)

Nov, 2010 Defense Sciences Research Council (DSRC), Washington, DC (**Keynote**)
Oct, 2010 Michigan State University (host: Charles Ofria, computer science) (Invited)
Sept, 2010 Perception & Action Workshop, Sante Fe Institute (Invited)
Sept, 2010 Evolutionary Studies Seminar Series, Binghamton University (Invited)
Sept, 2010 Intl Workshop on Guided Self-Organization, Indiana University (Invited)
Sept, 2010 Rensselaer Polytechnic Institute (host: Brent Fajel, cognitive science) (Invited)
Jan, 2010 Advancement of Artificial Cognitive Systems, ETH, Zurich (**Keynote**)

Oct, 2009 University of Massachusetts, Amherst (Invited)
 Oct, 2009 Evolutionary Robotics Workshop at the IEEE IROS Conference (Invited)
 Sept, 2009 Union College, Schenectady, NY (host: John Rieffel, computer science) (Invited)
 May, 2009 McMaster Origins Institute, Canada (Invited)
 Mar, 2009 University of California San Diego (annual lecture; host: T. Sejnowski) (**Keynote**)
 Mar, 2009 Salk Institute (host: T. Sejnowski) (Invited)
 Feb, 2009 Hughes Research Laboratories, Malibu, CA (Invited)
 Feb, 2009 Pragyan technical festival, India (telecast from Vermont) (Invited)

Oct, 2008 Dartmouth College (host: Tanzeem Choudhury) (Invited)
 Oct, 2008 McMaster University, Canada (host: Simon Haykin) (Invited)
 Sept, 2008 NAE's Frontiers of Engineering Symposium, New Mexico (Invited)
 June, 2008 Telluride Neuromorphic Engineering Workshop (Invited)
 June, 2008 Woods Hole Workshop on Computational Neuroscience (Invited)
 May, 2008 Genetic Programming Theory and Practice, University of Michigan (**Keynote**)
 Apr, 2008 Cognitive Engineering Workshop, Sardinia, IT (Invited)
 Jan, 2008 Boston University (host: Steven Grossberg) (Invited)

Oct, 2007 Elder Education Enrichment program, Vermont (Invited)
 Oct, 2007 IBM T. J. Watson Research Center (host: Kerry Bernstein) (Invited)
 Aug, 2007 National Science Foundation *Science of Learning Workshop* (Invited)

2004 AI Lab, University of Zurich, Switzerland (Invited)

2003 EPSRC Workshop on Evolvability, Hertfordshire, UK (Invited)

2002 Biozentrum, University of Basel, Switzerland (Invited)
 2002 Massachusetts Institute of Technology (host: Rodney Brooks) (Invited)
 2002 Woods Hole Marine Biological Laboratory (host: Jelle Atema) (Invited)
 2002 Cognitive Science Department, University of Sussex, UK (Invited)

SELECTED MEDIA COVERAGE

March, 2021 [Machine behavior](#). *Quarantime.today*

March, 2021 [CDOs](#). *The Max Relativo show*.

March, 2021 [The world's first programmable organism](#). *Pioneer Works*

Dec, 2020 ["Xenobots, one of the four big scientific breakthroughs of 2020."](#) *The Week*

Dec, 2020 ["Part Robot, Part Frog."](#) *Discover Magazine*

Nov, 2020 ["The Xenobot future is coming—start planning now."](#) *Wired*

Apr, 2020 ["Meet the xenobots, virtual creatures brought to life."](#) *New York Times*

Jan, 2020 ["Interview with Fredricka Whitfield."](#) *CNN*

Jan, 2020 ["Computer designed organisms."](#) *BBC World Service*

Jan, 2020 ["Interview with Ira Flatow."](#) *Science Friday*

Oct, 2019 ["Soft Robotics Podcast interview"](#). *IEEE RAS*

Apr, 2019 ["Soft Robots Look to New Environments"](#). *Communications of the ACM*

Sept, 2018 ["Robotic Skins' that bring objects to life"](#). *ABC News*

Feb, 2018 ["Generator to Present Big Thinkers in 'Reckless Ideas' Series"](#). *Seven Days*

May, 2016 ["Reddit Brings a UVM Evolutionary Robotics Class to the World"](#). *Seven Days*

Dec, 2014 “[Could A.I. be the end of the human race?](#)” *RT America*

Dec, 2013 “Beware. Scientists are Creating Machines That Can Evolve on Their Own” *Smithsonian Magazine*

July, 2013 “[Are Robots The Future Of Human Evolution?](#)” *Through the Wormhole*

Feb, 2011 “Bringing Up Robots” *American Scientist*

Jan, 2011 “Artificial intelligence based on Darwin’s idea” *Boston Globe*

June, 2008 “When Robots Live Among Us” (cover article) *Discovery Magazine*

Sept, 2007 “ ‘Self-aware’ space rovers would be speedy explorers” *Scientific American*

Nov, 2007 “Six Ideas that Will Change the World” *Esquire*

Jan, 2007 “The GOLEM in the machine” *Die Zeit*

Nov, 2006 “Injured Robot Learns to Limp” *Nature News*

Nov, 2006 “New Robot Shrugs Off Injury” *Science News*

Nov, 2006 “Robotic Recovery” *MIT Technology Review*

Nov, 2006 “Self-Aware Robots” *Discovery Channel*

Nov, 2006 “New Robot Can Sense Damage, Recover” *Forbes*

Nov, 2006 “New Robot Can Sense Damage and Compensate” *USA Today*

Nov, 2006 “Resilient Robot Hobbles Along, Even if Injured” *Scientific American*

Aug, 2002 “ ‘Animals’ grown from an artificial embryo” *New Scientist*

SCHOLARSHIPS AND PRIZES

2021 The National Academy of Sciences’ [Cozzarelli Prize](#).

2020 [Top 10 Biotech Project of the year](#).
[Xenobots](#) nominated for The Design Museum’s [Beazley Design of the Year](#)
 PNAS paper reporting xenobots in Altmetric’s [Top 100](#).

2016 International Society of Artificial Life Education & Outreach Award
 International Society of Artificial Life Best Paper of the Decade Award

2015 Awarded the Cyril G. Veinott Green and Gold Professorship of Computer Science

2014 National STEM Innovation Award (awarded by the [Concept Schools](#))

2013 Scientist of the Year, IEEE Green Mountain Section

2010 Presidential Early Career Award for Scientists and Engineers ([PECASE](#)). [[Photo with Obama](#)]
 NSF CAREER award.

2008 UVM College of Engineering and Mathematical Sciences
 Milt Silveira Junior Faculty Award

2007 One of *MIT Technology Review*’s TR35: [Top 35 Young Innovators Under 35](#)
 Microsoft New Faculty Fellowship

2002 Best Paper Award, Seventh Intl Conf on the Simulation of Adaptive Behavior

1999 Sante Fe Institute Complex Systems Summer School alumnus

1993–1997 McMaster University Dean’s Honour List