

Josh C Bongard

Curriculum Vitae

E428 Innovation Hall
University of Vermont, Burlington, VT 05405
[jbongard.github.io](https://github.com/jbongard)
www.meclab.org
[@DoctorJosh](#)
josh.bongard@uvm.edu
Citations: [Google Scholar](#).

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APPOINTMENTS

- 2015– **Professor**, Department of Computer Science
- 2015– Cyril G. Veinott Green and Gold Professor, Department of Computer Science,
College of Engineering & Mathematical Sciences, University of Vermont
- 202– Co-Chief Scientific Officer (Co-CSO), [Fauna Systems](#) (spinoff from laboratory)
- 2015–2019 Director, [Vermont Advanced Computing Core](#), UVM’s high performance computing facility.
- 2014–2018 Consultant, [Xemo Corporation](#) (spinoff from laboratory)
- 2012–2015 **Associate Professor**, Department of Computer Science
College of Engineering & Mathematical Sciences, University of Vermont
- 2014– *Secondary appointment in the School of Engineering, UVM*
- 2013– *Secondary appointment in the Neuroscience Graduate Program, UVM*
- 2011–2015 Vice chair, [Vermont Complex Systems Center](#)
- 2006–2012 **Assistant Professor**, Department of Computer Science
College of Engineering & Mathematical Sciences, University of Vermont
- 2006– Director, [Morphology, Evolution & Cognition Laboratory](#)
- 2003–2006 **Postdoctoral Associate**, Cornell University
Advisor: Hod Lipson, Director of the Creative Machines Laboratory
- 1998 Software Engineer, Computing Devices Canada

EDUCATION

- 1999–2003 **Ph.D.**, Department of Informatics, University of Zurich, Switzerland
[Incremental Approaches to the Combined Evolution of a Robot’s Body and Brain](#).
Advisor: Rolf Pfeifer, Director of the Zurich Artificial Intelligence Laboratory
- 1998–1999 **M.S.**, Evolutionary & Adaptive Systems, University of Sussex, UK
[Evolving Heterogeneity: Implications for Agent-Based Systems and Collective Problem Solving](#).
Advisor: Inman Harvey
- 1993–1997 **B.Sc.**, Honors Computer Science, McMaster University, Canada (graduated *Summa Cum Laude*)
- 1994 Study abroad program, Corpus Christi College, Oxford University, UK

TOTAL FUNDING

\$11.2M total (\$4M current; \$7.2M past).

CURRENT FUNDING

- 2024– **Cold Regions Research and Engineering Lab (CRREL)** award (PI). \$8.5M (\$2.3M to Bongard Lab)
Biological Instruments for Observation of Sensitive Environments

Naturally, Silently, and Encryptionally (BIOSENSE).

- 2024– **Army Research Office** award (Co-PI). \$999,999 (\$500K to Bongard Lab)
Giving Cells a Voice.
- 2023– **Army Research Office** award (PI). \$584,373 to Bongard Lab
Embodied Endosymbiosis.
- 2022– **Army Research Office** award. \$650,001. (\$175K to Bongard Lab)
AI guided biotronic inter-kingdom interoperability: a universal adaptor for life.
- 2022– **Sloan Foundation** award (Co-PI; PI: Don Ingber, Harvard). \$82,558 to Bongard Lab.
Principles of Molecular and Cellular Self Organization.
- 2021– **NSF DMREF** award (co-PI; PI: Rebecca Kramer-Bottiglio). \$401,103 to Bongard Lab.
Design and Optimization of Granular Metamaterials using Artificial Evolution.

PAST FUNDING

- 2020–2024 **Army CRREL** award (Co-PI: PI Jeffrey Marshall), \$10M (\$200K to Bongard Lab)
- 2020–2022 **NSF NAIRI** Planning award, \$500,000 (\$257K to Bongard Lab)
The [Proteus Institute](#): Intelligence through change.
- 2018–2022 **NSF EFRI** award (co-PI; PI: Rebecca Kramer-Bottiglio), \$2M (\$496,333 to Bongard Lab).
C3 SoRo: Programmable Skins for Moldable and Morphogenetic Soft Robots.
- 2018–2021 **Sloan Foundation** award, \$683,273 to Bongard Lab.
[Developing an In-Browser, Elastic Supercomputer](#)
- 2018–2021 **DARPA L2M** award (co-PI; PI: Michael Levin, Tufts), \$2M. (\$268,174 to Bongard Lab.)
Somatic Computation via Bioelectricity for Novel Life-time Learning Machines.
- 2018–2020 **NSF MRI** award (co-PI; PI: Adrian Del Maestro), \$893,120
Acquisition of a GPU Accelerated Vermont Advanced Computing Core.
- 2014–2018 **NSF BIGDATA** award (co-PI; PI: James Bagrow, UVM), \$1.4M (\$280K to Bongard Lab)
Hunch & Crunch: Iterative Crowdsourced Hypothesis Generation.
- 2016–2019 **Army Research Office** award, \$400,000 to Bongard Lab.
Morphological Plasticity for the Design, Control, and Deployment of Complex Engineering Systems.
- 2013–2018 **NSF INSPIRE** award (co-PI; PI: Ken Livingston, Vassar College), \$1M (\$462K to Bongard Lab)
Evolvability and the emergence of modularity.
- 2016–2017 **NSF EAGER** award, \$100,000 to Bongard Lab.
Scalable crowdsourced reinforcement of robot behavior.
- 2015–2017 **NASA ROSES** award (co-PI; PI: Kamalika Das), \$1M (\$388K to Bongard Lab)
Uncovering effects of climate variables on global vegetation.
- 2010–2017 **NSF CAREER/PECASE** award, \$499,999 to Bongard Lab.
Exploring the Ultimate Mechanisms of Embodied Cognition.

- 2011–2015 **DARPA MSEE** award, \$614,830 to Bongard Lab.
Continually Plastic Modeling of Non-Stationary Systems.
- 2011–2014 **DARPA M3** award (co-PI: PI: Greg Hornby, NASA Ames), \$200,000 (\$141K to Bongard Lab)
Rapid Human-Computer Interactive Conceptual Design of Mobile and Manipulative Robot Systems.
- 2007–2011 **Microsoft Research New Faculty Fellowship**, \$200,000 to Bongard Lab.
- 2007–2009 **NSF SGER** award, \$192,391 to Bongard Lab.
Exploiting ‘Like Me’ Hypotheses for Learning Robots

BOOKS

1. Pfeifer, R. and J. Bongard (2006)
[*How the Body Shapes the Way We Think: A New View of Intelligence*](#),
Boston, MA: MIT Press. (Translated into Chinese, Japanese, Arabic and an E-book)

ARTICLES

52. R Baines, F Fish, J Bongard & R Kramer-Bottiglio (2024).
[Robots that evolve on demand.](#)
Nature Reviews Materials.
51. Varley, T. F., & Bongard, J. (2024).
[Evolving higher-order synergies reveals a trade-off between stability and information-integration capacity in complex systems.](#)
Chaos: An Interdisciplinary Journal of Nonlinear Science, 34(6).
50. Kagan BJ, Mahlis M, Bhat A, Bongard J, Cole VM, Corlett P, Gyngell C, Hartung T, Jupp B, Levin M, Lysaght T. (2024).
[Toward a nomenclature consensus for diverse intelligent systems: Call for collaboration.](#)
The Innovation. 2024 Sep 9;5(5).
49. T Varley, J Bongard (2024).
[Evolving higher-order synergies reveals a trade-off between stability and information-integration capacity in complex systems.](#)
Chaos 34, 063127
48. D Blackiston, H Dromiack, C Grasso, T Varley, DG Moore, K Srinivasan, O Sporns, J Bongard, M Levin, SI Walker (2024).
[Revealing non-trivial information structures in aneural biological tissues via functional connectivity.](#)
bioRxiv.
47. D Matthews, A Spielberg, D Rus, S Kriegman, J Bongard (2023).
[Efficient automatic design of robots.](#)
Proceedings of the National Academy of Sciences, 120(41): e2305180120.
46. D Blackiston, S Kriegman, J Bongard & M Levin (2023).
[Biological Robots: Perspectives on an Emerging Interdisciplinary Field.](#)
Soft Robotics. doi.org/10.1089/soro.2022.0142.
45. J Bongard & M Levin (2023).
There’s Plenty of Room Right Here: Biological Systems as Evolved, Overloaded, Multi-scale Machines.

Biomimetics, 8, 110.

44. J Bongard (2022).
[From bioinspired to biological robots, and back again.](#)
IOP Conference Series: Materials Science and Engineering, 1261 (1), 012004.
43. D Kudithipudi, M Aguilar-Simon, J Babb, M Bazhenov, D Blackiston, J Bongard, AP Brna, S Chakravarthi Raja, N Cheney, J Clune, A Daram, S Fusi, P Helfer, L Kay, N Ketz, Z Kira, S Kolouri, JL Krichmar, S Kriegman, M Levin, S Madireddy, S Manicka, A Marjaninnejad, B McNaughton, R Miikulainen, Z Navratilova, T Pandit, A Parker, PK Pilly, S Risi, TJ Sejnowski, A Soltoggio, N Soures, AS Tolia, D Urbina-Melendez, FJ Valero-Cuevas, GM van de Ven, JT Vogelstein, F Wang, R Weiss, A Yanguas-Gil, X Zou, H Siegelmann (2022)
[Biological underpinnings for lifelong learning machines.](#)
Nature Machine Intelligence 4: 1967-210.
42. CA Aubin, B Gorissen, E Milana, PR Buskohl, N Lazarus, GA Slipper, C Keplinger, J Bongard, F Iida, JA Lewis, RF Shepherd (2022)
[Towards enduring autonomous robots via embodied energy.](#)
Nature 602(7897): 393-402.
41. S Kriegman, D Blackiston, M Levin, J Bongard (2021)
[Kinematic self-replication in reconfigurable organisms.](#)
Proceedings of the National Academy of Sciences, 118(49): e2112672118.
40. D Blackiston, E Lederer, S Kriegman, S Garnier, J Bongard, M Levin (2021)
[A cellular platform for the development of synthetic living machines.](#)
Science Robotics, 6(52).
39. JC Bongard & M Levin (2021)
[Living things are not \(20th century\) machines.](#)
Frontiers in Ecology and Evolution, <https://doi.org/10.3389/fevo.2021.650726>
38. DS Shah, JP Powers, LG Tilton, S Kriegman, J Bongard & R Kramer-Bottiglio (2020)
[A soft robot that adapts to environments through shape change.](#)
Nature Machine Intelligence, <https://doi.org/10.1038/s42256-020-00263-1>
37. F Veenstra, P Gonzalez de Prado Salas, K Stoy, J Bongard, S Risi (2020).
[Death and progress: How evolvability is influenced by intrinsic mortality.](#)
Artificial Life, 26(1): 90-111.
36. D Shah, B Yang, S Kriegman, M Levin, J Bongard, R Kramer-Bottiglio (2020).
[Shape changing robots: bioinspiration, simulation, and physical realization.](#)
Advanced Materials. e202002882.
35. S Kriegman, D Blackiston, M Levin, J Bongard. (2020).
[A scalable pipeline for the design of reconfigurable organisms.](#)
Proceedings of the National Academy of Sciences, 117(4): 1853-1859.
34. I Rahwan, M Cebrian, N Obradovich, J Bongard, J-F Bonnefon, C Breazeal, JW Crandall, NA Christakis, ID Couzin, MO Jackson, NR Jennings, E Kamar, IM Kloumann, H Larochelle, D Lazer, R McElreath, A Mislove, DC Parkes, A Pentland, ME Roberts, A Shariff, JB Tenenbaum & M Wellman (2019).
[Machine behavior.](#)
Nature, 568: 477486

33. Rounds, T., Bongard, J., Hines, P., & Harvey, J. (2019).
[A crowdsourcing approach to understand weight and weight loss in men.](#)
Preventive Medicine Reports, 13, 224.
32. Kriegman, S., Cheney, N., & Bongard, J. (2018).
[How morphological development can guide evolution.](#)
Nature Scientific Reports, 8(1): 13934.
31. F Corucci, N Cheney, F Giorgio-Serchi, J Bongard, and C Laschi (2018)
[Evolving Soft Locomotion in Aquatic and Terrestrial Environments: Effects of Material Properties and Environmental Transitions.](#)
Soft Robotics, 5(4): 475-495.
30. N Cheney, J Bongard, V SunSpiral, H Lipson (2018)
[Scalable co-optimization of morphology and control in embodied machines.](#)
Journal of The Royal Society Interface, 15(143): 20170937
29. A Bernatskiy, J Bongard (2018)
[Evolving morphology automatically reformulates the problem of designing modular control.](#)
Adaptive Behavior 26(2): 47-64
28. MD Wagdy, JC Bongard, JP Bagrow & PDH Hines (2017)
[Crowdsourcing Predictors of Residential Electric Energy Usage.](#)
IEEE Systems Journal, PP(99):1–10.
27. D Buckingham & JC Bongard (2017)
[Physical Scaffolding Accelerates the Evolution of Robot Behavior.](#)
Artificial Life, 23(3):351-373.
26. F Corucci, N Cheney, S Kriegman, J Bongard, C Laschi (2017)
[Evolutionary developmental soft robotics as a framework to study intelligence and adaptive behavior in animals and plants.](#)
Frontiers in Robotics and AI.
25. N Livingston, A Bernatskiy, K Livingston, ML Smith, J Schwarz, JC Bongard, D Wallach & JH Long Jr (2016)
[Modularity and sparsity: evolution of neural net controllers in physically embodied robots.](#)
Frontiers in Robotics and AI.
24. T Taylor, JE Auerbach, J Bongard, J Clune, S Hickinbotham, C Ofria, M Oka, S Risi, KO Stanley, & J Yosinski (2016)
[WebAL comes of age: A review of the first 21 years of artificial life on the web.](#)
Artificial Life, 22(3) 364–407.
23. C Cappelle, A Bernatskiy, K Livingston, N Livingston, J Bongard (2016)
Morphological modularity can enable the evolution of robot behavior to scale linearly.
Frontiers in Robotics and AI, 3: 59.
22. J Bongard (2015)
[Using robots to investigate the evolution of adaptive behavior.](#)
Current Opinion in Behavioral Sciences, 6: 168–173.
21. M Wagdy & J Bongard (2015)
[Combining computational and social effort for collaborative problem solving.](#)

PLoS ONE, DOI: 10.1371/journal.pone.014524.

20. D Buckingham, C Skalka, and J Bongard (2015)
Inductive machine learning for improved estimation of catchment-scale snow water equivalent.
Journal of Hydrology, 524: 311-325.
19. R Swain, A Berger, J Bongard, & P Hines (2015)
Participation and contribution in crowdsourced surveys.
PLoS ONE, DOI: 10.1371/journal.pone.0120521.
18. Bongard, J. C. & Lipson, H. (2014)
Evolved machines shed light on robustness and resilience.
Proceedings of the IEEE, **102**(5): 899–914.
17. Lu, Z. Wu, X. & Bongard, J. C. (2014)
Active learning through adaptive heterogeneous ensembling.
IEEE Transactions on Knowledge and Data Engineering, DOI: 10.1109/TKDE.2014.2304474.
16. Bevelander, K. E., Kaipainen, K., Swain, R., Dohle, S., Bongard, J. C., Hines, P. D. H.
& Wansink, B. (2014)
Crowdsourcing novel childhood predictors of adult obesity.
PLoS ONE, 9(2): e87756
15. Auerbach, J. E. & Bongard, J. C. (2014)
Environmental influence on the evolution of morphological complexity in machines.
PLoS Computational Biology, 10(1): e1003399
14. Bongard, J. C. (2013)
Evolutionary robotics.
Communications of the ACM, 56(8): 74—85.
13. Bongard, J. C., Hines, P. D. H., Conger, D., Hurd, P., and Lu, Z. (2012)
Crowdsourcing predictors of behavioral outcomes.
IEEE Transactions on Systems, Man, and Cybernetics, Part A, 43(1): 176–185.
12. Bongard, J. C. (2011)
Morphological change in machines accelerates the evolution of robust behavior.
Proceedings of the National Academy of Sciences, 108(4): 1234-1239.
11. Bongard, J. C. (2011).
Innocent until proven guilty: Reducing robot shaping from polynomial to linear time.
IEEE Transactions on Evolutionary Computation, 15(4): 571—85.
10. Kaipa, K., Bongard, J., Meltzoff, A. (2010).
Self discovery enables robot social cognition: Are you my teacher?
Neural Networks, 23: 1113-1124.
9. Bongard, J. C. (2010).
The utility of evolving simulated robot morphology increases with task complexity
for object manipulation. *Artificial Life*, 16(3): 201-223.
8. Rughani, A. I., Dumont, T. M., Lu, Z., Bongard, J., Horgan, M. A., Penar, P. L., Tranmer, B. I. (2009).
Use of an artificial neural network to predict head injury outcome.
Journal of Neurosurgery, 113(3): 585–90.

7. Bongard J. C. (2009).
Accelerating self-modeling in cooperative robot teams.
IEEE Transactions on Evolutionary Computation, 13(2): 321-332.
6. Bongard, J. and H. Lipson (2007)
Automated reverse engineering of nonlinear dynamical systems.
Proceedings of the National Academy of Sciences, 104(24): 9943-9948.
5. Bongard, J., V. Zykov and H. Lipson (2006)
Resilient machines through continuous self-modeling.
Science, 314: 1118-1121.
4. Kouchmeshky, B., W. Aquino, H. Lipson and J. Bongard (2006)
Co-evolutionary strategy for structural damage identification using minimal physical testing.
International Journal for Numerical Methods in Engineering, 69(5): 1085-1107.
3. Bongard, J. and H. Lipson (2005)
Active coevolutionary learning of deterministic finite automata.
Journal of Machine Learning Research, 6(Oct): 1651-1678.
2. Bongard, J. and H. Lipson (2005)
Nonlinear system identification using coevolution of models and tests.
IEEE Transactions on Evolutionary Computation, 9(4): 361-384.
1. Pfeifer, R., F. Iida and J. Bongard (2005)
New robotics: design principles for intelligent systems.
Artificial Life Special Issue on New Robotics, Evolution and Embodied Cognition, 11(1-2): 99-120.

BOOK CHAPTERS

7. A Cangelosi, J Bongard, MH Fischer, S Nolfi (2015)
[Embodied intelligence](#).
Springer Handbook of Computational Intelligence, pp. 697-714
6. Bongard, J. C. (2014)
Evolving morphological computation.
Opinions and Outlooks on Morphological Computation, ISBN: 978-3-033-04515-6
5. Bongard, J. C. (2014)
Why morphology matters.
Horizons of Evolutionary Robotics, MIT Press, pp. 125–152.
4. Icke, I., Allgaier, N. A., Danforth, C. M., Whelan, R., Garavan, H., Bongard, J. C. (2013)
A Deterministic and Symbolic Regression Hybrid Applied to Resting-State fMRI data.
Genetic Programming Theory and Practice IX, Springer.
3. Bongard, J. C. (2011)
The ‘What’, ‘How’ and the ‘Why’ of Evolutionary Robotics.
In Doncieux, S., Bredeche, N., Mouret, J.-B. (eds.),
New Horizons in Evolutionary Robotics (Studies in Computational Intelligence), 341: 29-35.
2. Bongard, J. C. (2011)
A Functional Crossover Operator for Genetic Programming.

1. Bongard, J. and R. Pfeifer (2003)
Evolving complete agents using artificial ontogeny,
Morpho-functional Machines: The New Species, Springer-Verlag, pp. 237—258.

PEER-REVIEWED CONFERENCE PUBLICATIONS

102. Goyal, M., Lambo, M., Bongard, J., & Kramer-Bottiglio, R. (2024).
[Merging Variable Stiffness Fiber Patterns on Multi-Shape Robotic Sheets](#).
In 2024 IEEE 7th International Conference on Soft Robotics (RoboSoft) (pp. 894-899).
101. Bielawski, K., Gaylinn, N., Lunn, C., Motia, K., & Bongard, J. (2024).
[Evolving Hierarchical Neural Cellular Automata](#).
In *Proceedings of the Genetic and Evolutionary Computation Conference* (pp. 78-86).
100. Bertschinger, A., Bagrow, J., & Bongard, J. (2024).
[Evolving Form and Function: Dual-Objective Optimization in Neural Symbolic Regression Networks](#).
In *Proceedings of the Genetic and Evolutionary Computation Conference* (pp. 277-285).
99. Gaylinn, N., & Bongard, J. (2024).
[A Meta-Evolutionary Algorithm for Co-evolving Genotypes and Genotype/Phenotype Maps](#).
In *Procs. of the Genetic and Evolutionary Computation Conference Companion* (pp. 467-470).
98. Bielawski, Kam, and Josh Bongard (2024).
[Enabling Evolvability with Neutral Networks in Multiscale Neural Cellular Automata](#).
Proceedings of ALife.
97. Bielawski, K., Rozlivek, J., Hoffmann, M., & Bongard, J. (2024).
[Best Practices for Differentiable Soft Robot Modeling and Optimization with the Material Point Method](#).
In *Artificial Life Conference Proceedings* 36 (Vol. 2024, No. 1, p. 11).
96. Beaulieu, S., Welch, P., Parsa, A., O'Hern, C., Kramer-Bottiglio, R., & Bongard, J. (2024).
[Refractive Computation: parallelizing logic gates across driving frequencies in a mechanical polycomputer](#).
In *ALIFE 2024: Proceedings of the 2024 Artificial Life Conference*.
95. P Welch, C Grasso, G Gumuskaya, M Levin, J Bongard (2023).
[Searching in the Dark: Evolving Biobot Swarm Compositions to Efficiently Explore Obstructed Environments](#).
Proceedings of the 2023 Artificial Life Conference, <https://doi.org/10.1162/isal.a.00683>.
94. A Bertschinger, Q Davis, J Bagrow, J Bongard (2023).
[The Metric is the Message: Benchmarking Challenges for Neural Symbolic Regression](#).
Joint European Conference on Machine Learning and Knowledge Discovery in Databases, pp. 161-177.
93. A Parsa, S Witthaus, N Pashine, C O'Hern, R Kramer-Bottiglio & J Bongard (2023).
[Universal Mechanical Polycomputation in Granular Matter](#).
Proceedings of the Genetic and Evolutionary Computation Conference (GECCO).
92. C Grasso & J Bongard (2023).
[Selection for short-term empowerment accelerates the evolution of homeostatic neural cellular automata](#).
Proceedings of the Genetic and Evolutionary Computation Conference (GECCO).
91. Pigozzi, F., Woodman, S., Medvet, E., Kramer-Bottiglio, R. and Bongard, J. (2023).

[Morphology Choice Affects the Evolution of Affordance Detection in Robots.](#)

Proceedings of the Genetic and Evolutionary Computation Conference (GECCO) (pp. 211-219).

90. Q Davis & J Bongard (2022).
Step Size is a Consequential Parameter in Continuous Cellular Automata.
Proceedings of the Artificial Life Conference.
89. Q Davis & J Bongard (2022).
Glaberish: Generalizing the continuously-valued Lenia framework to arbitrary Life-like cellular automata.
Proceedings of the Artificial Life Conference.
88. A Parsa, D Wang, CS O'Hern, MD Shattuck, R Kramer-Bottiglio, J Bongard (2022).
Evolving Programmable Computational Metamaterials.
Proceedings of the Genetic and Evolutionary Computation Conference (GECCO).
87. C Grasso & J Bongard (2022).
Empowered Neural Cellular Automata.
Proceedings of the Genetic and Evolutionary Computation Conference (GECCO).
86. Q Davis & J Bongard (2022).
Selecting Continuous Life-Like Cellular Automata for Halting Unpredictability:
Evolving for Abiogenesis.
Proceedings of the Artificial Life Conference.
85. Parsa A, Wang D, OHern CS, Shattuck MD, Kramer-Bottiglio R, Bongard J. (2022).
Evolution of Acoustic Logic Gates in Granular Metamaterials.
Intl. Conf. on the Applications of Evolutionary Computation, pp. 93-109. Springer.
84. S Kriegman, AM Nasab, D Blackiston, H Steele, M Levin, R Kramer-Bottiglio, J Bongard (2021).
Scale invariant robot behavior with fractals.
Proceedings of the Robotics: Science and Systems Conference.
83. J Powers, R Grindle, L Frati, J Bongard (2021).
A good body is all you need: avoiding catastrophic interference via agent architecture search.
arXiv preprint arXiv:2108.08398
82. B Yang, J Powers, A Parsa, J Bongard, R Kramer-Bottiglio (2021).
Shape Matching: Evolving Fiber Constraints on a Pneumatic Bilayer.
2021 IEEE 4th International Conference on Soft Robotics (RoboSoft), 630-635.
81. Kriegman, Sam, Amir Mohammadi Nasab, Dylan Shah, Hannah Steele, Gabrielle Branin, Michael Levin, Josh Bongard, and Rebecca Kramer-Bottiglio (2020).
Scalable sim-to-real transfer of soft robot designs.
Third IEEE International Conference on Soft Robotics (RoboSoft), pp. 359-366.
80. Rosser, K., Kok, J., Chahl, J., Bongard, J. (2020)
Sim2real gap is non-monotonic with robot complexity for morphology-in-the-loop flapping wing design.
IEEE International Conference on Robotics and Automation (ICRA) (pp. 7001-7007).
79. Matthews, David, and Josh Bongard (2020).
Crowd grounding: finding semantic and behavioral alignment through human robot interaction
Procs. of the Artificial Life Conference, pp. 148-156.
78. Powers, Joshua, Ryan Grindle, Sam Kriegman, Lapo Frati, Nick Cheney, and Josh Bongard (2020).

- Morphology Dictates Learnability in Neural Controllers.
Procs. of the Artificial Life Conference, pp. 52-59.
77. Powers, J., Pell, S. and Bongard, J. (2020).
A Framework for Search and Application Agnostic Interactive Optimization.
Procs. of the Artificial Life Conference, pp. 60-68.
 76. S Kriegman, S walker, D Shah, M Levin, R Kramer-Bottiglio, J Bongard (2019).
[Automated shapeshifting for function recovery in damaged robots.](#)
Robotics: Science and Systems Proceedings, 10.15607/RSS.2019.XV.028
 75. S Beaulieu, S Kriegman, JC Bongard (2018).
[Combating catastrophic forgetting with developmental compression.](#)
GECCO Conference Proceedings, pp. 386–393
 74. S Kriegman, N Cheney, F Corucci, JC Bongard (2018).
[Interceptive robustness through environment-mediated morphological development.](#)
GECCO Conference Proceedings, pp. 109–116.
 73. F Veenstra, PG de Prado Salas, J Bongard, K Stoy, S Risi (2018).
[Intrinsic Mortality Governs Evolvability.](#)
Artificial Life Conference Proceedings, pp. 242-249.
 72. C Cappelle, J Bongard (2018).
[Embodied Embeddings for Hyperneat.](#)
Artificial Life Conference Proceedings, pp. 461-468
 71. A Kodali, M Szubert, K Das, S Ganguly, J Bongard (2018).
[Understanding climate-vegetation interactions in global rainforests through a GP-tree analysis.](#)
Parallel Problem Solving from Nature (PPSN) Conference Proceedings, pp. 525-536
 70. J Powers, S Kriegman, J Bongard (2018).
[The effects of morphology and fitness on catastrophic interference.](#)
Artificial Life Conference Proceedings, pp. 606-613
 69. A Bernatskiy & JC Bongard (2017).
[Choice of robot morphology can prohibit modular control and disrupt evolution.](#)
Procs of the European Conference on Artificial Life, Nancy, France.
 68. S Kriegman, N Cheney, F Corucci, JC Bongard (2017).
[A minimal developmental model can increase evolvability in soft robots.](#)
Proceedings of the Genetic and Evolutionary Computation Conference, pp 131-138.
 67. C Cappelle, A Bernatskiy, J Bongard (2017).
[Reducing Training Environments in Evolutionary Robotics Through Ecological Modularity.](#)
Proceedings of the Conference on Biomimetic and Biohybrid Systems, pp 95-106.
 66. M Szubert, A Kodali, S Ganguly, K Das & JC Bongard (2016)
[Semantic forward propagation for symbolic regression.](#)
Procs of the Parallel Problem Solving from Nature (PPSN) Conference, Edinburgh, UK.
 65. S Kriegman, M Szubert, JC Bongard & C Skalka (2016)
[Evolving spatially aggregated features from satellite imagery for regional modeling.](#)
Procs of the Parallel Problem Solving from Nature (PPSN) Conference, Edinburgh, UK.

64. N Powell & JC Bongard (2016)
[Exploring uncertainty and movement in categorical perception using robots.](#)
Procs of the Parallel Problem Solving from Nature (PPSN) Conference, Edinburgh, UK.
63. M Szubert, A Kodali, S Ganguly, K Das & JC Bongard (2016)
[Reducing antagonism between behavioral diversity and fitness in semantic genetic programming.](#)
Procs of the Genetic and Evolutionary Computation Conference (GECCO), Denver, CO.
62. N Cheney, JC Bongard, V SunSpiral & H Lipson (2016)
[On the difficulty of co-optimizing morphology and control in evolved virtual creatures.](#)
15th Intl Conference on the Simulation and Synthesis of Living Systems (ALife 2016), Cancun, MX.
61. F Corucci, N Cheney, H Lipson, C Laschi & JC Bongard (2016)
[Material properties affect evolution's ability to exploit morphological computation in growing soft-bodied creatures.](#)
15th Intl Conference on the Simulation and Synthesis of Living Systems (ALife 2016), Cancun, MX.
60. J Anetsberger & JC Bongard (2016)
[Robots can ground crowd-proposed symbols by forming theories of group mind.](#)
15th Intl Conference on the Simulation and Synthesis of Living Systems (ALife 2016), Cancun, MX.
59. M Wagdy & JC Bongard (2016)
[Social contribution in the design of adaptive machines on the web.](#)
15th Intl Conference on the Simulation and Synthesis of Living Systems (ALife 2016), Cancun, MX.
58. McAndrew, T. C., Bongard, J. C., Danforth, C. M., Dodds, P. S., Hines, P. D., & Bagrow, J. P. (2016).
 What we write about when we write about causality: Features of causal statements across large-scale social discourse.
 ASONAM 16.
57. M Wagdy & JC Bongard (2015)
[Crowdseeding: a novel approach for designing bioinspired machines.](#)
Fourth Intl Conf on Biomimetics and Biohybrid Systems (Living Machines 2015), Barcelona, Spain.
56. K Zieba & JC Bongard (2015)
[An embodied approach for evolving robust visual classifiers.](#)
Procs of the Genetic and Evolutionary Computation Conference, Madrid, Spain.
55. A Yousefi, JC Bongard & C Skalka (2015)
[A Genetic Programming approach to cost-sensitive control in resource constrained sensor systems.](#)
Procs of the Genetic and Evolutionary Computation Conference, Madrid, Spain.
54. N Cheney, JC Bongard & H Lipson (2015)
[Evolving soft robots in tight spaces.](#)
Procs of the Genetic and Evolutionary Computation Conference, Madrid, Spain.
53. JC Bongard, A Bernatskiy, K Livingston, N Livingston, J Long & M Smith (2015)
[Evolving robot morphology facilitates the evolution of neural modularity and evolvability.](#)
Procs of the Genetic and Evolutionary Computation Conference, Madrid, Spain.
52. Wagdy, M., Bongard, J. C. (2014)
 Collective Design of Robot Locomotion.

Procs of the 14th Intl Conf on the Synthesis and Simulation of Living Systems, New York City.
Acceptance rate: 49.8%. Citations: 4

51. Bernatskiy, A., Hornby, G., Bongard, J. C. (2014)
Improving Robot Behavior Optimization by Combining User Preferences.
Procs of the 14th Intl Conf on the Synthesis and Simulation of Living Systems, New York City.
Acceptance rate: 49.8%. Citations: 3
50. Icke, I., Bongard, J. C. (2013)
Improving Genetic Programming Based Symbolic Regression Using Deterministic Machine Learning.
Procs of the IEEE Congress on Evolutionary Computation, Cancun, MX.
Citations: 9
49. Icke, I., Bongard, J. C. (2013)
Modeling Hierarchy using Symbolic Regression.
Procs of the IEEE Congress on Evolutionary Computation, Cancun, MX.
Citations: 0
48. Celis, S., Hornby, G. S., Bongard, J. C. (2013)
Avoiding Local Optima with User Demonstrations and Low-level Control.
Procs of the IEEE Congress on Evolutionary Computation, Cancun, MX.
Citations: 8
47. Bongard, J. C., Hornby, G. S. (2013)
Combining Fitness-based Search and User Modeling in Evolutionary Robotics,
Procs of the Genetic and Evolutionary Computation Conference, pp. 159-166.
Acceptance rate: 36%. Citations: 16
46. Auerbach, J. E., Bongard, J. C. (2012)
On the Relationship Between Environmental and Mechanical Complexity in Evolved Robots.
ALife XIII, pp. 309-316, DOI: 10.7551/978-0-262-31050-5-ch041.
Acceptance rate: 50%. Citations: 17
45. Auerbach, J. E., Bongard, J. C. (2012)
On the Relationship Between Environmental and Morphological Complexity in Evolved Robots,
Procs of the Genetic and Evolutionary Computation Conference, pp. 521-528.
Acceptance rate: 36%. Citations: 35
44. Hornby, G. S., Bongard, J. C. (2012)
Accelerating Interactive Evolutionary Algorithms through Comparative and Predictive User Models,
Procs of the Genetic and Evolutionary Computation Conference, DOI: 10.1145/2330163.2330196.
Acceptance rate: 36%. Citations: 10
43. Hornby, G. S., Bongard, J. C. (2012)
Learning Comparative User Models for Accelerating Human Computer Collaborative Search.
Procs of the Evolutionary and Biologically Inspired Music, Sound, Art and Design Conf, pp. 117-128.
Citations: 6
42. Auerbach, J. E., Bongard, J. C. (2011)
Evolving Complete Robots with CPPN-NEAT: The Utility of Recurrent Connections,
Procs of the Genetic and Evolutionary Computation Conference, pp. 1475-1482, ACM: NY, USA
Acceptance rate: 38%
Citations: 15

41. Bongard, J. C. (2011)
Spontaneous Evolution of Structural Modularity in Robot Neural Network Controllers,
Procs of the Genetic and Evolutionary Computation Conference, pp. 251–258, ACM: NY, USA.
Acceptance rate: 38%
Citations: 16
40. Bongard, J. C. (2011)
Morphological and Environmental Scaffolding Synergize when Evolving Robot Controllers,
Procs of the Genetic and Evolutionary Computation Conference, pp. 179–186, ACM: NY, USA
Acceptance rate: 38%
Citations: 14
39. Auerbach, J. E., Bongard, J. C. (2010)
Dynamic Resolution in the Co-Evolution of Morphology and Control,
Procs of the 12th Intl Conf on the Synthesis and Simulation of Living Systems.
Citations: 33
38. Lu, Z., Wu, X., Zhu, X., Bongard, J. (2010)
Ensemble Pruning via Individual Contribution Ordering,
The 16th ACM SIGKDD Conference on Knowledge Discovery and Data Mining.
Citations: 46
37. Auerbach, J. E., Bongard, J. C. (2010)
Evolving CPPNs to Grow Three Dimensional Structures.
Procs of the Genetic and Evolutionary Computation Conference, Portland, OR.
Acceptance rate: 45%. Citations: 34
36. Bongard, J. C. (2010)
A Probabilistic Functional Crossover Operator for Genetic Programming.
Procs of the Genetic and Evolutionary Computation Conference, Portland, OR.
Acceptance rate: 45%. Citations: 8
35. Bongard, J. C., Hornby, G. S. (2010)
Guarding Against Premature Convergence while Accelerating Evolutionary Search.
Procs of the Genetic and Evolutionary Computation Conference, Portland, OR.
Acceptance rate: 45%. Citations: 24
34. Lu, Z., Wu, X., Bongard, J. (2010)
Adaptive Informative Sampling for Active Learning.
Procs of The SIAM Conference on Data Mining (SDM 2010), Columbus, Ohio, USA
Citations: 5
33. Lu, Z., Wu, X., Bongard, J. C. (2009)
Active Learning with Adaptive Heterogeneous Ensembles.
Procs of the Intl Conf on Data Mining, Miami, FL.
Citations: 11
32. Kaipa, K., Bongard, J. C., Meltzoff A. N. (2009)
Combined Structure and Motion Extraction from Visual Data Using Evolutionary Active Learning.
Procs of the Genetic and Evolutionary Computation Conference, Montreal Canada.
Acceptance rate: 41.4%. Citations: 1
31. Auerbach, J., Bongard, J. C. (2009)
Evolution of Functional Specialization in a Morphologically Homogeneous Robot,

Procs of the Genetic and Evolutionary Computation Conference, Montreal Canada.
Acceptance rate: 41.4%. Citations: 7

30. Auerbach, J., Bongard, J. C. (2009)
How Robot Morphology and Training Order Affect the Learning of Multiple Behaviors,
IEEE Congress on Evolutionary Computation, Trondheim, Norway.
Citations: 20
29. Bongard, J. (2008)
Behavior Chaining: Incremental Behavior Integration for Evolutionary Robotics.
Artificial Life XI, MIT Press, Cambridge, MA.
Citations: 42
28. Bongard, J. (2007)
Synthesizing Physically-Realistic Environmental Models from Robot Exploration,
Advances in Artificial Life: 9th European Conference, Springer-Verlag, Berlin, pp. 806-815.
Citations: 4
27. Bongard, J. (2007)
Action-Selection and Crossover Strategies for Self-Modeling Machines,
Procs of the Genetic and Evolutionary Computation Conf, ACM Press, New York, NY, pp. 198-205.
Acceptance rate: 46.1%. Citations: 7
26. Bongard, J. (2007)
Exploiting Multiple Robots to Accelerate Self-Modeling,
Procs of the Genetic and Evolutionary Computation Conf, ACM Press, New York, NY, pp. 214-221.
Acceptance rate: 46.1%. Citations: 3
25. Lipson, H., J. Bongard, V. Zykov and E. Malone (2006)
Evolutionary Robotics for Legged Machines: From Simulation to Physical Reality,
Procs of the Intelligent Autonomous Systems Conf (IAS-9), pp. 11—18.
Citations: 42
24. Bongard, J., V. Zykov and H. Lipson (2006)
Automated Synthesis of Body Schema using Multiple Sensor Modalities,
ALIFE X, pp. 220—226.
Citations: 27
23. Bongard, J. and H. Lipson (2005)
Automatic Synthesis of Multiple Internal Models Through Active Exploration,
AAAI Fall Symposium on Reactive to Anticipatory Cognitive Embodied Systems, Arlington, VA.
Citations: 7
22. Bongard, J. and H. Lipson (2005)
'Managed Challenge' Alleviates Disengagement in Co-evolutionary System Identification,
Procs of the Genetic and Evolutionary Computation Conference, ACM, pp. 531-538.
Acceptance rate: 46.1%. Citations: 21
21. White, P., V. Zykov and J. Bongard (2005)
Three Dimensional Stochastic Reconfiguration of Modular Robots,
Robotics: Science and Systems, Cambridge, MA.
Citations: 157
20. Bongard J. and Lipson H. (2005)

Reinventing the Wheel: Experiments in Evolutionary Geometry,
Late Breaking Papers of the Genetic and Evolutionary Computation Conf, Washington DC.
 Citations: 2

19. Zykov, V., J. Bongard and H. Lipson (2005)
 Co-evolutionary Variance Can Guide Physical Testing in Evolutionary System Identification,
Procs of the NASA/DoD Conf on Evolvable Hardware, June, Washington DC, pp. 213-220.
 Citations: 10
18. Lipson, H. and J. Bongard (2004)
 An Exploration-Estimation Algorithm for Synthesis and Analysis
 of Engineering Systems Using Minimal Physical Testing,
Procs of the ASME Design Engineering Conferences, Salt Lake City, UT.
 Citations: 17
17. Zykov, V., J. Bongard and H. Lipson (2004)
 Evolving Dynamic Gaits on a Physical Robot,
Late Breaking Papers for the Genetic and Evolutionary Computation Conf, Seattle, WA.
 Citations: 61
16. Bongard, J. and H. Lipson (2004)
 Once More Unto the Breach: Co-evolving a Robot and its Simulator,
Procs of the Intl Conf on the Simulation and Synthesis of Living Systems (ALIFE9), pp. 57-62.
 Citations: 37
15. Bongard, J. and H. Lipson (2004)
 Automated Robot Function Recovery after Unanticipated Failure
 or Environmental Change using a Minimum of Hardware Trials,
Procs of the NASA/DoD Conference on Evolvable Hardware, IEEE Computer Society, pp. 169-176.
 Citations: 32
14. Bongard, J. and H. Lipson (2004)
 Automating Genetic Network Inference with Minimal Physical Experimentation Using Coevolution,
Procs of the Genetic and Evolutionary Computation Conf, Springer, pp. 333-345.
 Acceptance rate: 50%. Citations: 28
13. Bongard, J. and H. Lipson (2004)
 Automated Damage Diagnosis and Recovery for Remote Robotics,
Procs of the International Conf on Robotics and Automation (ICRA), Omnipress, pp. 3545-3550.
 Citations: 35
12. Bongard, J. (2002)
 Evolved Sensor Fusion and Dissociation in an Embodied Agent,
Procs of the EPSRC/BBSRC Intl Workshop on Biologically-Inspired Robotics, pp. 102-109.
 Citations: 8
11. Frutiger, D. R., Bongard, J. and F. Iida (2002)
 Iterative Product Engineering: Evolutionary Robot Design,
Procs of the Fifth Intl Conf on Climbing and Walking Robots, pp. 619-629.
 Citations: 16
10. Bongard, J. and R. Pfeifer (2002)
 A Method for Isolating Morphological Effects on Evolved Behaviour,
Procs of the Seventh Intl Conf on the Simulation of Adaptive Behaviour (SAB2002), pp. 305-311.

Citations: 48

9. Bongard, J. and R. Pfeifer (2002)
Relating Neural Network Performance to Morphological Differences in Embodied Agents,
Procs of the Sixth Intl Conf on Cognitive and Neural Systems, Boston, USA.
Citations: 1
8. Bongard, J. (2002)
Evolving Modular Genetic Regulatory Networks,
Procs of the IEEE Congress on Evolutionary Computation (CEC2002), IEEE Press, pp. 1872-1877.
Citations: 204
7. Paul, C. and J. Bongard (2001)
The Road Less Travelled: Morphology in the Optimization of Biped Robot Locomotion,
Procs of the IEEE/RSJ Intl Conf on Intelligent Robots and Systems (IROS2001), Hawaii, USA.
Citations: 74
6. Bongard, J. and C. Paul (2001)
Making Evolution an Offer It Can't Refuse: Morphology and the Extradimensional Bypass,
Procs of the Sixth European Conf on Artificial Life, Springer-Verlag, pp. 401-412.
Citations: 58
5. Bongard, J. and R. Pfeifer (2001)
Repeated Structure and Dissociation of Genotypic and Phenotypic Complexity in Artificial Ontogeny,
Procs of the Genetic and Evolutionary Computation Conf, Morgan Kaufmann, pp. 829-836.
Citations: 166
4. Bongard, J. and C. Paul (2000)
Investigating Morphological Symmetry and Locomotive Efficiency using Virtual Embodied Evolution,
Procs of the Sixth Intl Conf on the Simulation of Adaptive Behaviour, MIT Press, pp. 420-429.
Citations: 74
3. Bongard, J. (2000)
Reducing Collective Behavioural Complexity through Heterogeneity,
Artificial Life VII, MIT Press, pp. 327-336.
Citations: 5
2. Bongard, J. (2000)
The Legion System: A Novel Approach to Evolving Heterogeneity for Collective Problem Solving,
Procs of the Third Euro Conf on Genetic Programming, Springer-Verlag, pp. 25—37.
Citations: 37
1. Bongard, J. (1999)
Coevolutionary Dynamics of a Multi-Population Genetic Programming System,
Procs of the Fifth Euro Conf on Artificial Life, Springer-Verlag, pp. 316-321.
Citations: 5

MINIMALLY- REVIEWED PUBLICATIONS

21. J Bongard, K Cho, YL Park, R Shepherd (2025)
[Future Directions of Embodied Intelligence](#)
Report for the Department of Defense.
20. Bongard, J. C. (2017)

The symbol grounding problem.

Invited Response to the 2017 Edge Question:

“What scientific term or concept ought to be more widely known?”

19. JC Bongard (2016)
[Evolving soft robots](#). *Soft Robotics* 3(2): 43-44. Editorial.
18. A Larson, A Bernatskiy, C Cappelle, K Livingston, N Livingston, J Long, J Schwarz, M Smith & JC Bongard (2016)
[Recombination hotspots promote the evolvability of modular systems](#).
Procs of the Genetic and Evolutionary Computation Conference (GECCO 2016). Poster.
17. Bongard, J. C. (2016)
[I, For One](#).
Invited Response to the 2016 Edge Question:
“What do you consider the most interesting [scientific] news?”
16. Bongard, J. C. (2015)
[Manipulators and Manipulanda](#).
Invited Response to the 2015 Edge Question:
“What do you think about machines that think?”
15. JP Bagrow, S Desu, MR Frank, N Manukyan, L Mitchell, A Reagan, EE Bloedorn, LB Booker, LK Branting, MJ Smith, BF Tivnan, CM Danforth, PS Dodds, JC Bongard (2013).
Shadow networks: Discovering hidden nodes with models of information flow.
arXiv preprint arXiv: 1312.6122
14. Hornby, G. S. & Bongard, J. C. (2013).
Accelerating Interactive Evolutionary Algorithms through User Modeling.
International Conference on Intelligent User Interfaces.
13. Celis, S., Bongard, J. C. (2012)
Not All Physics Simulators Can Be Wrong in the Same Way.
Genetic and Evolutionary Computation Conference, pp. 659-660.
12. Beliveau, P., Hornby, G. S., Bongard, J. C. (2012)
Interactive Simulated Robot Construction and Controller Evolution.
Genetic and Evolutionary Computation Conference, pp. 627- 628.
11. Bongard, J. C., Beliveau, P., Hornby, G. S. (2012)
Avoiding Local Optima with Interactive Evolutionary Robotics.
Genetic and Evolutionary Computation Conference, pp. 1405—1406.
10. Bongard, J. C. (2011)
How evolution shapes the way roboticists think.
Procs of the 2nd European Future Technologies Conf and Exhibition (FET 11), 7: 8-10.
9. Bongard, J. (2011).
Morphogenetic robotics recapitulates artificial ontogeny.
Newsletter of the Autonomous Mental Development Technical Committee. 8(2): 3-4.
8. Bongard, J. (2009).
Biologically inspired computing.
IEEE Computer, 42(4): 95—98.

7. Lu, Z., Bongard, J. C. (2009)
Exploiting Multiple Classifier Types with Active Learning.
Genetic and Evolutionary Computation Conference (GECCO 2009), Montreal Canada.
6. Bongard, J. C. (2009)
The Impact of Jointly Evolving Robot Morphology and Control on Adaptation Rate.
Genetic and Evolutionary Computation Conference (GECCO 2009), Montreal Canada.
5. Bongard, J. (2008).
Probabilistic Robotics Book Review.
Artificial Life, 14(2): 227—229.
4. Bongard, J. (2008)
Embodied cognition: the other morphology.
The Neuromorphic Engineer, DOI: 10.2417/1200812.1420.
3. Lungarella, M., Iida, F., Bongard, J. and Pfeifer, R. (2008)
AI in the 21st century – with historical reflections,
Proceedings of the 50th Anniversary Summit of Artificial Intelligence, pp. 1-8.
2. Lu, Z., Rughani, A. I., Tranmer, B. I., Bongard, J. (2008)
Informative Sampling for Large Unbalanced Data Sets,
Fourth Workshop on Medical Applications of Genetic and Evolutionary Computation at GECCO 2008.
1. Conduit, R., Adami, C., Lipson, H., Zykov, V. and Bongard, J. (2007).
To sleep, perchance to dream.
Science, 315: 1219-1220.

PATENTS

- 2021 [“Engineered multicellular organisms”](#).
- 2022 [“Engineered multicellular ciliated organisms and kinematic self-replication thereof”](#).
- 2023 Engineered anthropoids (pending).
- 2024 [Efficient automatic design of physical machines with moving parts](#) (pending).

COMMERCIALIZATION

Co-CSO [Fauna Systems Inc.](#) \$1.25M of \$2.5M Seed round raised to date.

SERVICE

CO-CHAIR [The 2021 International Workshop on Embodied Intelligence](#)
CHAIR [The 2020 Artificial Life Conference](#) (400+ participants; 39 countries)

CO-ORGANIZER [Shape Morphing Soft Robots workshop](#), 2024 RoboSoft Conference

EDITORSHIPS

- 2024 Editorial Board member, [npg Robotics](#).
- 2023 Editorial Board member, [npg Complexity](#).
- 2021 Co-editor, [Swarm Intelligence](#) special issue on Micro and Nano Swarms.
- 2014– Associate Editor, *Frontiers in Robotics and AI*
- 2014– Review Editorial Board, *Evolutionary Robotics*
- 2013– Associate Editor, *Soft Robotics*

	2011–	Action Editor, <i>Neural Computation</i>
	2011–	Academic Editor, <i>Public Library of Science (PLOS) ONE</i>
	2013–	Guest Associate Editor, <i>PLOS Computational Biology</i>
TREASURER		
	2014–	International Society for Artificial Life
MEMBERSHIP		
	2014–	University of Vermont STEM Leadership Council
	2014	<i>13th Intl Conf on the Simulation of Adaptive Behavior</i> , program committee member
	2014	<i>13th Intl Conf on Parallel Problem Solving from Nature</i> , program committee member
	annually	<i>Genetic and Evolutionary Computation Conference</i> , program committee member
	annually	<i>Living Machines Conference</i> , program committee member
	biennially	<i>Artificial Life Conference</i> , program committee member
	biennially	<i>European Conference on Artificial Life Conference</i> , program committee member
	2013	<i>Genetic and Evolutionary Computation Conference</i> , track chair
	2013	<i>Congress on Evolutionary Computation (CEC)</i> , program committee member
	2013–	National affiliate, University of Iowa <i>DeLTa</i> center
	2011–	<i>Federation of American Scientists (FAS)</i> board of sponsors
	2007–	<i>Institute of Electrical and Electronics Engineers (IEEE)</i>
	2006–	<i>Association for Computing Machinery (ACM)</i>
REVIEWER		
		<i>Science</i>
		<i>Nature</i>
		<i>Proceedings of the National Academy of Science (PNAS)</i>
		<i>The MacArthur Foundation</i>
		<i>Science Robotics</i>
		<i>Nature Communications</i>
		<i>PLOS ONE</i>
		<i>PLOS Computational Biology</i>
		<i>Neural Computation</i>
		<i>Journal of Machine Learning Research (JMLR)</i>
		<i>IEEE Transactions on Evolutionary Computation</i>
		<i>IEEE Transactions on Robotics</i>
		<i>Artificial Life</i>
		<i>Adaptive Behavior</i>
		<i>IEEE Transactions on Systems, Man and Cybernetics</i>
		<i>Journal of Neurorobotics</i>
PANELIST		
	2006–	National Science Foundation (NSF) proposal reviews (~ 2 panels / year)
	2020	Department of Energy
	2013	The EC Flagship Initiative ‘Human Brain Project’ proposal reviewing
	2010	National Institutes of Health (NIH) proposal reviewing
INTERNAL		
	2023	Keynote address to the UVM Retired Faculty and Administrative Officers.
	2018	Host of the 2018 <i>Aiken Lecture</i> .
	2018–2022	Graduate Student Coordinator for the Computer Science Department
	2015–	Director, Vermont Advanced Computing Core (UVM’s high performance computing facility)
	2013–	UVM STEM Leadership Council Member
	2011–2015	Vice Chair, Vermont Complex Systems Center
OUTREACH		~10 presentations per year. Representative sample below.

2023 [FIRST Robotics](#) referee
 2022 Presentation to ~100 sixth graders about xenobots at Shapleigh Middle School.
 2016 Presentation to Abenaki Nation high school students
 2015– [Twitch Plays Robotics](#)
 2012– Governor’s Institute of Vermont presentations (~100 students)
 2014–2017 Burlington High School presentation on robotics.
 2016 [Waldorf School](#) (grades 7 through 12), Toronto
 2016 [Steelesview Public School](#), Toronto (grades 2 and 3)
 2007–2013 [Governor’s Institute of Vermont](#) summer program guest instructor
 2013 Boy Scouts of America guest instructor
 2013 [Reddit AMA](#) (“Ask Me Anything”)
 2013– [Hour of Code](#) visitor, Vermont middle schools.

TEACHING

2014– [Ludobots](#). The world’s only MOOC taught from reddit.
 2022– CS395: [Mind, Morphology, & Machine](#).
 2010– CS206: Evolutionary Robotics. [2023](#). [2022](#). [2021](#). [2020](#). [2019](#). [2018](#). [2017](#). [2016](#).
 2007–2020 CS228: Human Computer Interaction. [2020](#). [2019](#). [2018](#). [2016](#). [2015](#).
 2006–2008 CS205: Software Engineering.
 2009 HCOL: Embodied Cognition.

ADVISING

POSTDOCS

2024– [Alice Hein](#)
 2024– [Nam Le](#)
 2023– [Thomas Varley](#)
 2023– [Shawn Beaulieu](#)

 2021–2022 [Tyrell Davis](#)
 2020–2021 [Sam Kriegman](#)
 2017–2018 [Zahra Mahoor](#)
 2015–2017 [Marcin Szubert](#)
 2012–2013 [Ilknur Icke](#)
 2008–2010 [Kaipa Krishnanand](#)

PHD’S

2023– [Nate Gaylinn](#)
 2022– [Piper Welch](#). NSF GRFP recipient.
 2022– [Kam Bielawski](#)
 2021– [Krishna Srinivasan](#) (Computer Science)
 2020– [Amanda Bertschinger](#) (Computer Science)

 2019–2024 [Caitlin Grasso](#) (Computer Science). [NSF GRFP](#) recipient.
 2019–2024 [Atoosa Parsa](#) (Complex Systems & Data Science)
 2017–2021 [Joshua Powers](#) (Computer Science)
 2016–2020 [Sam Kriegman](#) (Computer Science). 2019/2020 UVM Outstanding Doctoral [Dissertation](#) Award.
 2015–2019 [Collin Cappelle](#) (Computer Science). [Dissertation](#).
 2013– 2018 [Anton Bernatskiy](#) (Computer Science). [Dissertation](#).
 2013–2016 [Mark Wagy](#) (Computer Science)) [Dissertation](#).
 2009–2013 [Joshua Auerbach](#) (Computer Science))
 2006–2011 [Zhenyu Lu](#) (Computer Science)

MASTERS

- 2022– **Mioto Takahashi** (UVM Complex Systems)
- 2022–2024 **Kevin Motia** (UVM Complex Systems)
- 2021–2023 **Natalie Tolley** (Computer Science)
- 2021–2022 **Alexander Medvedeff** (Computer Science)
- 2018–2021 **Ryan Grindle** (Computer Science)
- 2019–2021 **Sida Liu** (Computer Science)
- 2019–2020 **Jack Felag** (Computer Science)
- 2018–2020 **Sarah Pell** (Computer Science)
- 2017–2018 **Alexander Ram** (Computer Science)
- 2017–2018 **Ryan Grindle** (Mathematics)
- 2013–2018 **Roman Popov** (Computer Science)
- 2015–2016 **Nate Powell** (Statistics)
Dissertation: *The role of Uncertainty in Categorical Perception Utilizing Statistical Learning in Robots.*
- 2015–2016 **Sam Kriegman** (Co-advising; statistics)
Dissertation: *Evolving spatially aggregated features from satellite imagery for regional modeling.*
- 2014–2015 **Afsoon Yousefi-Zowj** (Computer Science)
Dissertation: *A Genetic Programming approach to cost-sensitive control in wireless sensor networks.*
- 2014–2015 **Karol Zieba** (Computer Science)
Dissertation: *Evolving multi-modal sensors.*
- 2012–2014 **David Buckingham** (Computer Science)
Dissertation: *Inductive learning of snowpack distribution models for improved estimation of areal snow water equivalent.*
- 2012–2014 **Christopher Pierce** (Computer Science; project option.)
- 2010–2012 **Somdeb Chatterjee** (Computer Science)
Dissertation: *Crowdsourcing predictors for modeling behavioral outcomes.*
- 2010–2012 **Yunfei Zhao** (Computer Science; project option.)
- 2008–2010 **Peter Hurd** (Computer Science; project option.)

UNDERGRADUATES

- 2024– **Evan Rohan**
- 2023–2024 **Emily Ertle** (UVM Honors College)
- 2023–2024 **Alyn Kirsch** (UVM Computer Science)
- 2023–2024 **Freyja Feeney** (UVM Computer Science)
- 2021–2022 **Sidhanth Kafley** (Computer Science)
- 2018–2022 **David Matthews** (Computer Science)
- 2019–2020 **Nathan Tolley** (Computer Science)
- 2019 **Kyle Morand** (Computer Science)
- 2019 **Filip Saulean** (Computer Science)
- 2019 **Jean-Baptiste Bohl** (Computer Science)
- 2019 **Everest Witman** (Computer Science)
- 2016–2018 **Jack Felag** (Mathematics)
- 2015–2016 **Ari Larson** (Computer Science)
- 2014–2015 **Mariko Totten** (Computer Science)
- 2013–2014 **Timothy Rizvanov** (Computer Science)
- 2013–2014 **Fritz Davenport** (Computer Science)
- 2013–2014 **Alex Berger** (Business administration)
- 2011–2012 **Nick Cheney** (Computer Science)

PHD DEFENSE	COMMITTEE MEMBER
2025	Billy Yang, Yale.
2024	Kiyn Chin , Carnegie Mellon University.
2023	Philippe Wyder , Columbia University.
2022	Jeffrey Brabec , University of Vermont.
	Dylan Shah , Yale.
2021	Toby Howison , Cambridge University.
2020	Tønnes Nygaard , University of Oslo, Norway
	Karine Miras , Vrije Universiteit Amsterdam
	Daniel Wilson, UVM
2019	Elijah Bowen , Dartmouth
	Simon Hauser , EPFL, Switzerland
2018	Eric Clark , UVM
2016	Thomas McAndrew, UVM
	Emily Cody, UVM
2014	Morgan Frank, UVM
	Nicholas Chaumont, Keck Graduate Institute
	Ahmed Hamed, UVM
	Jesse van den Kieboom, EPFL, Switzerland
2013	Eitan Pechenik, UVM
	Song Wang, UVM
	Karim Chichakly, UVM
	Nicolas Allgaier, UVM
2012	Thierry Buecheler, University of Zurich, Switzerland
2011	Sylvain Koos, UPMC, France
2010	Peter Duerr, EPFL, Switzerland

STAFF

2018-2021 [Rachel Dotey](#). Software developer for #UVMComputes project.

INVITED TALKS

Nov, 2024	8. Computer designed organisms. TERMIS tissue engineering consortium .
Sept, 2024	7. Evolutionary robotics. UCLA IPAM tutorial.
July, 2024	6. The tip and the iceberg: deep learning and embodiment . CVPR conference (13,000 attendees). Plenary .
May, 2024	5. Developmental biology and robotics for organic machines. Robotics Interagency Working Group .
	4. AIs that predict, discuss and intervene in health outcomes. NNE-CTR seminar.
Apr, 2024	3. AI-driven design of rigid, soft, and biological robots. Northeastern Robotics Institute .
Mar, 2024	2. From rigid to soft to biological robots. Cambridge University .
Feb, 2024	1. From rigid to soft to biological robots . ICANx speaker series. (25K remote attendees)
Nov, 2023	12. “AI & Robotics: the tip of the iceberg.”. Common Events Club , Toronto.
Oct, 2023	11. “AI-designed organisms.” Vermont Academy of Science and Engineering annual meeting (keynote).
July, 2023	10. “ Discovering the adjacent possible with AI .” PIBBSS seminar speaker (invited).
	9. “The origins of xenobots.” Berggruen Institute ‘Futures of Life’ workshop (keynote).
May, 2023	8. Reckless Ideas . Generator Space, Burlington, VT (panelist).
	7. “ AI-designed robots, xenobots, and metamaterials .” Cross Labs, Tokyo.
Apr, 2023	6. “ The world’s first AI-designed organism .” Creative AI Vermont Symposium (keynote).
Mar, 2023	5. “ Morphological pre-training .” Embodied Intelligence Conference.
	4. “ZapGPT.” Army Research Office symposium.
Feb, 2023	3. “Xenobots.” Vermont Council on World Affairs event, hosting Moroccan “Women in STEAM”.
Jan, 2023	2. “From rigid to soft to biological robots.” Intl. Symposium on Artificial Life and Robotics (Plenary) .
	1. “ AI-designed computational metamaterials .” Dynamics Days (invited).

- Dec, 2022 28. "From rigid to soft to biological robots." [ShanghAI Lecture](#) (invited).
- Oct, 2022 27. [AI-driven design of robots, xenobots, and metamaterials](#). IROS workshop on computational design.
 26. "AI-designed organisms." Bio-inspired Robotics workshop, University of York, UK.
 25. ["From rigid to soft to biological robots."](#) MorphTalks seminar series, Bristol Robotics Laboratory.
 24. "Xenobots". Synaptic Supercollider. Burlington VT (Invited).
- Sept, 2022 23. "From rigid to soft to biological robots". Simulation of Adaptive Behavior Conference, (invited).
 22. Xenobots. Edwards Symposium on Soft Matter, Cambridge University (invited).
 21. Bottom-up design of xenobots. PI mtg for the Sloan Foundation's Matter-to-Life Program (invited).
- June, 2022 20. How robots and xenobots will shape the way we think. IAS-17 conference (invited).
 19. "Xenobots". University of Vermont Alumni 50th Reunion (invited).
 18. "The innate creativity of AI". Aalto University, Finland (invited).
 17. "AI for biomedical research." [National Academies Board on Life Sciences Meeting](#) (Invited).
- May, 2022 16. "AI-driven design of soft robots and biobots." ARO Biotronics meeting (Invited).
 15. "CDOs". [Dynamic Landscapes](#) K-12 teacher conference. (Keynote).
- Apr, 2022 14. [Xenobot replicators](#). Cross Labs Tokyo workshop (invited)
 13. [From rigid to soft to biological robots](#). RoboSoft conference (**plenary**)
 12. [Empowered neural cellular automata](#). Alt-AI Workshop, RoboSoft conference (invited)
 11. [Xenobot self-replication](#). Embodied Intelligence workshop, RoboSoft conference (invited)
 10. [CGMMs](#). Software workshop, RoboSoft conference (invited)
- Mar, 2022 9. "What is non-embodied AI missing?" [Embodied Intelligence Conference](#) (Invited).
 8. "CDOs." Radboud University, Netherlands (Invited).
- Feb, 2022 7. "Evolving metamaterials/biobots." [AFRL/DoE Energy Consequences of Information](#) symposium (Invited).
 6. [A xither of Xenobots. Math of Collective Intelligence workshop](#), UCLA. (Invited)
- Jan, 2022 5. "CDOs for demolishing dichotomous thinking." [AMOLF](#) group, Netherlands. (Invited)
 4. [L.A.S.E.R. talk](#). Stanford University. (Invited)
 3. ["Kinematic self replication."](#) Quantum Photonics Club. (Invited)
 2. "CDOs; Machine Science." Kyushu Institute of Technology, Japan. (Invited)
 1. "Evolutionary Robotics." Kyushu Institute of Technology, Japan. (Invited)
- Nov, 2021 "Evolutionary robotics/CDOs". [Biophysical Society of Japan Annual Meeting](#). (Invited)
- Oct, 2021 ["Red herrings, iguanas, and xenobots."](#) AI Forward Forum, Tilburg University. (Invited)
- Aug, 2021 "CDOs." [Allen Institute for AI Lecture Series](#). (Invited)
- July, 2021 "Automated design of biological robots." [Biological Distributed Algorithms workshop](#). (Invited)
- July, 2021 "Embodying the products of evolutionary computation." [SFI Frontiers of EC workshop](#). (Invited)
- June, 2021 "CDOs." [Web a Quebec](#) conference. (Keynote)
- May, 2021 "CDOs." [UCL Inst. for the Physics of Living Systems](#) Symposium. (Co-keynote w/ Mike Levin)
 "CDOs." AI-Zürich Conference, Switzerland. (Keynote)
- Mar, 2021 "CDOs." 6th John Cabot University Workshop on posthumanism. Rome. (Keynote)
- Jan, 2021 "Machine Science." Kyushu Institute of Technology, Japan. (Invited)
 "Evolutionary Robotics." Kyushu Institute of Technology, Japan. (Invited)
- Dec, 2020 ["CDOs."](#) ShanghAI Lecture. (Invited)
- Nov, 2020 "CDOs." AAAI Fall Symposium on Abstraction and Analogy. (Invited)
- Nov, 2020 ["CDOs."](#) ACM Symposium on Computational Fabrication. (Keynote)
- Oct, 2020 ["Computational background of CDOs."](#) UVM Electrical and Biomedical Engineering seminar.
- Oct, 2020 "CDOs." [Scifoo](#). Google.
- Oct, 2020 "Crowdsourcing CDO training." Hybrid Intelligence Round Table. Aarhus University, Denmark.
- Oct, 2020 ["CDOs and NLP."](#) Indiana University (Invited)
- Oct, 2020 [Panel discussion on small-scale robots](#). Life Summit, AI LA. (Invited)
- Sept, 2020 "CDOs." [Genomics Institute of the Novartis Research Foundation](#) (Invited)
- July, 2020 ["Scaling up automated design and manufacture of soft and biological robots."](#) GECCO workshop (Invited)
- July, 2020 "Evolving the Physical Structure of Compliant, Soft, and Biological Robots." (AIM2020; Invited)
- June, 2020 ["CDOs."](#) Research and Applied AI Summit ([RAAIS](#)) (Keynote)
- Apr, 2020 "Computer designed organisms (CDOs)." Stanford EE Computer Systems Colloquium (Invited)

Jan, 2020 “[word2vec2bot](#).” University of Michigan (Invited)

Dec, 2019 “Soft robots that evolve and develop.” ShanghAI Lecture Series (Invited)

June, 2019 “[Evolutionary Robotics](#).” Governor’s Institute of Vermont. (Invited)

May, 2019 “Co-optimizing body and control for soft and modular robots.” EPFL, Switzerland. (Invited)

May, 2019 “The effects of Cartesian gravity on robotics.” University of Reading, UK. (Invited)

Mar, 2019 “Sim2real, sim2life, and sim2all.” Yale CS Colloquium (Invited).

Jan, 2019 “[Morphology, evolution and cognition](#).” NECSI Winter School presentation. (Invited)

Dec, 2018 “What evolutionary robotics can teach us about embodied cognition.” ShanghAI Lecture Series (Invited)

Dec, 2018 [Hour of Code](#) presentation to 50 6th graders, Saint Albans City Elementary School.

Nov, 2018 “Embodiment, Evolution & Meaning.” Santa Fe Institute Workshop on AI and the Barrier to Meaning.

Nov, 2018 “[The moral challenges of robotics and AI](#).” Community AI Forum, Mount Mansfield Union High School.

July, 2018 “[Robots as complex systems](#).” ICCS Conference.

July, 2018 “[The role of embodiment in open-ended evolution](#).” ALife Workshop on Open-ended Evolution.

May, 2018 “[Soft robots that morph and behave simultaneously](#).” ICRA Workshop on Soft Robotics.

May, 2018 “Realizing Explainable AI.” [Open Data Science Conference \(ODSC\) East](#).

Feb, 2018 “[Autonomous yet safe machines](#).” Generator VT, Reckless Ideas seminar series.

Nov, 2017 [ShanghAI](#) Lecture Series (Invited)

Sept, 2017 IEEE/RSJ Intl. Conference on Intelligent Robots and Systems (IROS) (**Keynote**)

Sept, 2017 Santa Fe Institute Working Group on Morphological Computation (Invited)

June, 2017 Human Brain Project workshop on embodied cognition (Geneva, CH) (Invited)

Feb, 2017 [SFI](#) Workshop: “Evolution and Restraint of Malicious Behavior in Complex Systems” (Invited)

Oct, 2016 “Speaking to a general audience” for UVM IGERT Smart Grid graduate students (Invited)

Sept, 2016 ASME Smart Materials, Adaptive Structures and Intelligent Systems Conference (Stowe, VT) (Invited)

Sept, 2016 Santa Fe Institute Short Course on Innovation (Austin, TX) (Invited)

Sept, 2016 [Parallel Problem Solving from Nature](#) conference. (University of Stirling, Edinburgh) (**Keynote**)

May, 2016 [Trusted autonomous systems](#). (ACFR, University of Sydney, Australia) (Invited)

May, 2016 Trusted autonomous systems. (Intl. Symp. on Trusted Autonomous Systems, Australia) (**Keynote**)

Mar, 2016 [Some philosophical implications of evolutionary robotics](#). (UPitt [HPS](#) Annual Lecture Series) (Invited)

Feb, 2016 Evo devo robo. ([University of Toronto Cognitive Science Symposium](#)) (Invited)

Dec, 2015 [ShanghAI](#) lecture (simulcast to classrooms in Europe and Asia) (Invited)

Dec, 2015 New Jersey Institute of Technology (host: Gal Haspel, biology) (Invited)

Nov, 2015 UVM Honors College Plenary Lecture (Invited)

Oct, 2015 UMD Workshop on Soft Robotics (Invited)

May, 2015 [Factory of Imagination](#) lecture, Denmark (500 attendees) (**Keynote**)

Feb, 2015 [ShanghAI](#) lecture (simulcast to classrooms in Europe and Asia) (Invited)

Nov, 2014 Cornell Univeristy (host: Robert Shepherd, engineering) (Invited)

Sept, 2014 University of Maryland workshop on soft robotics (Invited)

Aug, 2014 [Scifoo](#) (hosts: Nature, Google, O’Reilly Media, Digital Science) (Invited)

July, 2014 Workshop on Artificial Life and the Web at ALife conference (Invited)

July, 2014 International Society for Artificial Life (ISAL) Summer School (Invited)

June, 2014 DARPA Biological Technologies Office (Invited)

June, 2014 Neural Systems & Behavior Summer School, Woods Hole Marine Biology Lab (Invited)

May, 2014 EPFL, Lausanne, Switzerland (host: Auke Ipeert) (Invited)

Mar, 2014 National STEM Conference (Concept Schools), Cleveland, OH (**Keynote**)

Mar, 2014 Air Force Research Laboratories (AFRL), Rome, NY (Invited)

Dec, 2013 [ShanghAI](#) lecture (simulcast to 15 classrooms in Europe and Asia) (Invited)

Nov, 2013 National Autonomous University of Mexico (host: Carlos Gershenson) (Invited)

Oct, 2013 University of Iowa [Delta Center](#) (host: Mark Blumberg, psychology) (Invited)
 Sept, 2013 eSMC neuroscience/robotics graduate summer school (host: Andreas Engel) (Invited)
 Sept, 2013 Evolutionary Biology lecture, University of Zurich (host: Andreas Wagner) (Invited)
 Aug, 2013 Gordon Research Conference on Neuroethology (host: Heather Eisten, biology) (Invited)
 July, 2013 Soft Robotics Workshop at ETH, Zurich (host: Fumiya Iida, robotics) (**Keynote**)
 June, 2013 Evolution Meeting, SSE Presidential Symposium (host: Richard Lenski, biology) (Invited)
 June, 2013 Evolution Meeting, Education Symposium (host: George Gilchrist, NSF) (Invited)
 Mar, 2013 University of Texas at Austin (host: Dana Ballard, Computer Science) (Invited)

Nov, 2012 Vassar College (host: John Long, biology) (Invited)
 Nov, 2012 Harvard University (host: Radhika Nagpal, engineering) (Invited)
 June, 2012 Tufts University (host: Michael Levin, biology) (Invited)
 Apr, 2012 Tufts University (host: Barry Trimmer, biology) (Invited)
 Jan, 2012 University of Southern California (host: Francisco Valero-Cuevas, bioengineering) (Invited)

Dec, 2011 Castleton State College, Vermont (Invited)
 Nov, 2011 Global ShanghaiAI Lecture series (telecast from Vermont) (Invited)
 Oct, 2011 TEDx presentation, University of Vermont (Invited)
 July, 2011 Woods Hole Workshop on Computational Neuroscience (host: Terrence Sejnowski) (Invited)
 May, 2011 [European Future and Emerging Technologies \(FET\) Conference](#), Budapest (**Keynote**)
 Mar, 2011 Annual lecture, Simon Fraser University, Canada (host: Bernard Roitbert) (Invited)
 Jan, 2011 Cognitive Dynamical Systems Workshop, Salk Institute (host: T. Sejnowski) (Invited)

Nov, 2010 Defense Sciences Research Council (DSRC), Washington, DC (**Keynote**)
 Oct, 2010 Michigan State University (host: Charles Ofria, computer science) (Invited)
 Sept, 2010 Perception & Action Workshop, Sante Fe Institute (Invited)
 Sept, 2010 Evolutionary Studies Seminar Series, Binghamton University (Invited)
 Sept, 2010 Intl Workshop on Guided Self-Organization, Indiana University (Invited)
 Sept, 2010 Rensselaer Polytechnic Institute (host: Brent Fajel, cognitive science) (Invited)
 Jan, 2010 Advancement of Artificial Cognitive Systems, ETH, Zurich (**Keynote**)

Oct, 2009 University of Massachusetts, Amherst (Invited)
 Oct, 2009 Evolutionary Robotics Workshop at the IEEE IROS Conference (Invited)
 Sept, 2009 Union College, Schenectady, NY (host: John Rieffel, computer science) (Invited)
 May, 2009 McMaster Origins Institute, Canada (Invited)
 Mar, 2009 University of California San Diego (annual lecture; host: T. Sejnowski) (**Keynote**)
 Mar, 2009 Salk Institute (host: T. Sejnowski) (Invited)
 Feb, 2009 Hughes Research Laboratories, Malibu, CA (Invited)
 Feb, 2009 Pragyan technical festival, India (telecast from Vermont) (Invited)

Oct, 2008 Dartmouth College (host: Tanzeem Choudhury) (Invited)
 Oct, 2008 McMaster University, Canada (host: Simon Haykin) (Invited)
 Sept, 2008 NAE's Frontiers of Engineering Symposium, New Mexico (Invited)
 June, 2008 Telluride Neuromorphic Engineering Workshop (Invited)
 June, 2008 Woods Hole Workshop on Computational Neuroscience (Invited)
 May, 2008 Genetic Programming Theory and Practice, University of Michigan (**Keynote**)
 Apr, 2008 Cognitive Engineering Workshop, Sardinia, IT (Invited)
 Jan, 2008 Boston University (host: Steven Grossberg) (Invited)

Oct, 2007 Elder Education Enrichment program, Vermont (Invited)
 Oct, 2007 IBM T. J. Watson Research Center (host: Kerry Bernstein) (Invited)
 Aug, 2007 National Science Foundation *Science of Learning Workshop* (Invited)

2004 AI Lab, University of Zurich, Switzerland (Invited)

2003	EPSRC Workshop on Evolvability, Hertfordshire, UK (Invited)
2002	Biozentrum, University of Basel, Switzerland (Invited)
2002	Massachusetts Institute of Technology (host: Rodney Brooks) (Invited)
2002	Woods Hole Marine Biological Laboratory (host: Jelle Atema) (Invited)
2002	Cognitive Science Department, University of Sussex, UK (Invited)
SELECTED	MEDIA COVERAGE <hr/>
June, 2024	From Code to Creature . The Scientist Magazine.
Feb, 2024	Brains are not required . Scientific American.
	You have to give AI a body . Courier Magazine.
Dec, 2023	The scientist who wants to bring AI into contact with the real world . New Scientist.
Oct, 2023	Instant evolution . UVM Today.
Aug, 2023	What Are Dreams For? The New Yorker.
July, 2023	That Time AI Made a Living Robot . The Wondros podcast.
Apr, 2023	AI for CDOs . Wiser Tomorrow podcast.
	Can Intelligence Be Separated From the Body? New York Times .
Mar, 2023	Animal Robot . Scientific American documentary.
Feb, 2023	BBC .
Jan, 2023	Quantum Photonics podcast.
	‘Consciousness’ in robots . New York Times .
Oct, 2022	100 years of robots . Chicago Tribune.
Mar, 2022	How we accidentally started making infinite robots . Real Science.
	All you need to know about coexisting with living robots . The Rhys Lindmark show.
	When robots multiply . Grow by Ginkgo.
Feb, 2022	Nautilus Magazine .
Jan, 2022	AI with AI podcast . (Xenobot segment starts at 18:21)
	Transform India podcast
	Progress, Potential, and Possibilities podcast
	7 Days
	Newsweek .
Dec, 2021	Stephen Colbert
	CNN , BBC , CNBC , Science Friday , Forbes , NPR , New Scientist , The Times , Bloomberg , & 100s more.
Nov, 2021	CBC Television .
July, 2021	Escaped Sapiens podcast.
May, 2021	Soft robotics podcast. With Mike Levin.
April, 2021	Wired Magazine .
April, 2021	Science Friday / CBC News / Washington Post / New Scientist / Science News & 100s more
March, 2021	Machine behavior . <i>Quarantime.today</i>
March, 2021	CDOs . <i>The Max Relativo</i> show.
March, 2021	The world’s first programmable organism . <i>Pioneer Works</i>
Dec, 2020	“Xenobots, one of the four big scientific breakthroughs of 2020.” <i>The Week</i>
Dec, 2020	Discover Magazine .
Nov, 2020	Wired .
Apr, 2020	New York Times .
Jan, 2020	CNN
Jan, 2020	BBC World Service .
Jan, 2020	NPR’s Science Friday .

Hundreds of [additional articles](#) appeared in the global press following the announcement of Xenobots.

- Oct, 2019 “[Soft Robotics Podcast interview](#)”. *IEEE RAS*
- Apr, 2019 “[Soft Robots Look to New Environments](#)”. *Communications of the ACM*
- Sept, 2018 “[Robotic Skins’ that bring objects to life](#)”. *ABC News*
- Feb, 2018 “[Generator to Present Big Thinkers in ‘Reckless Ideas’ Series](#)”. *Seven Days*
- May, 2016 “[Reddit Brings a UVM Evolutionary Robotics Class to the World](#)”. *Seven Days*
- Dec, 2014 “[Could A.I. be the end of the human race?](#)” *RT America*
- Dec, 2013 “Beware. Scientists are Creating Machines That Can Evolve on Their Own” *Smithsonian Magazine*
- July, 2013 “[Are Robots The Future Of Human Evolution?](#)” *Through the Wormhole*
- Feb, 2011 “Bringing Up Robots” *American Scientist*
- Jan, 2011 “Artificial intelligence based on Darwin’s idea” *Boston Globe*
- June, 2008 “When Robots Live Among Us” (cover article) *Discovery Magazine*
- Sept, 2007 “ ‘Self-aware’ space rovers would be speedy explorers” *Scientific American*
- Nov, 2007 “Six Ideas that Will Change the World” *Esquire*
- Jan, 2007 “The GOLEM in the machine” *Die Zeit*
- Nov, 2006 “Injured Robot Learns to Limp” *Nature News*
- Nov, 2006 “New Robot Shrugs Off Injury” *Science News*
- Nov, 2006 “Robotic Recovery” *MIT Technology Review*
- Nov, 2006 “Self-Aware Robots” *Discovery Channel*
- Nov, 2006 “New Robot Can Sense Damage, Recover” *Forbes*
- Nov, 2006 “New Robot Can Sense Damage and Compensate” *USA Today*
- Nov, 2006 “Resilient Robot Hobbles Along, Even if Injured” *Scientific American*
- Aug, 2002 “ ‘Animals’ grown from an artificial embryo” *New Scientist*

SCHOLARSHIPS AND PRIZES

2024 UVM [University Scholar](#).

2022 ISAL Award for [Outstanding Publication of 2021](#).

2021 The National Academy of Sciences’ [Cozzarelli Prize](#). ([Announcement video](#).)
ISAL Award for [Outstanding Publication of 2020](#)

2020 [Top 10 Biotech Project of the year](#).
[Xenobots](#) nominated for The Design Museum’s [Beazley Design of the Year](#)
PNAS paper reporting xenobots in Altmetric’s [Top 100](#).

2016 International Society of Artificial Life Education & Outreach Award
International Society of Artificial Life Best Paper of the Decade Award

2015 Awarded the Cyril G. Veinott Green and Gold Professorship of Computer Science

2014 National STEM Innovation Award (awarded by the [Concept Schools](#))

2013 Scientist of the Year, IEEE Green Mountain Section

- 2010 Presidential Early Career Award for Scientists and Engineers ([PECASE](#)). [[Photo with Obama](#)]
NSF CAREER award.
- 2008 UVM College of Engineering and Mathematical Sciences
Milt Silveira Junior Faculty Award
- 2007 One of *MIT Technology Review*'s TR35: [Top 35 Young Innovators Under 35](#)
Microsoft New Faculty Fellowship
- 2002 Best Paper Award, Seventh Intl Conf on the Simulation of Adaptive Behavior
- 1999 Sante Fe Institute Complex Systems Summer School alumnus
- 1993–1997 McMaster University Dean's Honour List