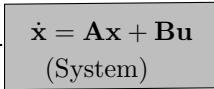


System input



$$\mathbf{u} \in \mathbb{R}^m$$



$$\mathbf{x} \in \mathbb{R}^n$$



$$\mathbf{y} \in \mathbb{R}^p$$



System output

