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Part 1: Automated GPS Data Processing

1.1: Download the data and import into MATLAB

```
function [] = detrendGPS(filename)
nHeaderLine = 0;
fid = fopen( fullfile('H:\Classes_Teaching_Fall 2016\Computation
\GEOS397\Homework\08', filename), 'r');
line = fgetl( fid ); % get the first line
nHeaderLine = nHeaderLine + 1;
line = fgetl( fid ); % get the second line
while strcmp(line(1:2),'%')
nHeaderLine = nHeaderLine + 1;
line = fgetl( fid ); % get the second line
end
nHeaderLine = nHeaderLine + 1;
fclose(fid);
fileID=fopen(filename);
C = textscan(fileID, '%f%d%d%f%f%f%f%f%f, 'HeaderLines',
nHeaderLine);
fclose(fileID);
Not enough input arguments.
Error in detrendGPS (line 6)
fid = fopen( fullfile('H:\Classes_Teaching_Fall 2016\Computation
\GEOS397\Homework\08', filename), 'r');
```

1.2: Strip out the relevant data

```
tDecyear = C{1}; % Time [decimal year]
tDaynum = C{3}; % Time [integer day number]
Nposition = C{4}*100; % North Position [cm]
Eposition = C{5}*100; % East Position [cm]
vertPosition = C{6}*100; % Vertical Position [cm]
% 1.3: Process the GPS data
stationName = filename(1:4); % pulls first four characters = station name
order = 1; % polynomial order
```

```
pN = polyfit(tDecyear, Nposition, order);  % generate trendline for N
position
trendN = polyval( pN, tDecyear );
pE = polyfit(tDecyear, Eposition, order);  % generate trendline for E
position
trendE = polyval( pE, tDecyear );
for vert position
trendVert = polyval( pVert, tDecyear );
residualN
           = Nposition - trendN;
                                      % residuals remaining
after subtracting trendline values
residualE = Eposition - trendE;
residualVert = vertPosition - trendVert;
                                 % pulls first four
stationName
                = filename(1:4);
characters = station name
                = tDecyear(end)-tDecyear(1); % time elapsed in
totalTime
decimal years
numDays
               = length(tDaynum);
                                           % number of days
elapsed
totEdisplacement = (Eposition(end) - Eposition(1)); % East
displacement [cm]
totNdisplacement = (Nposition(end) - Nposition(1)); % North
displacement [cm]
totVdisplacement = (vertPosition(end) - vertPosition(1)); % Vert
displacement [cm]
meanEvelocity = totEdisplacement/totalTime; % East velocity [cm/
yr]
meanNvelocity = totNdisplacement/totalTime; % North velocity
 [cm/yr]
meanVertvelocity = totVdisplacement/totalTime; % Vertical velocity
 [cm/yr]
fprintf ('Site Name: %s\n', stationName)
fprintf ('Time span: %2.2f [yrs]\n', totalTime)
fprintf ('Number of days with data: %d\n', numDays)
fprintf ('Total north displacement: %.2f [cm]\n',
totNdisplacement)
fprintf ('Total east displacement:
                                  %.2f [cm]\n',
totEdisplacement)
fprintf ('Total vertical displacement: %.2f [cm]\n',
totVdisplacement)
fprintf ('Avg vertical velocity: %.3f [cm/yr]\n', meanVertvelocity)
fprintf ('Avg north velocity using best-fit polynomial:
                                                     %.3f [cm/
yr]\n', pN(1)
fprintf ('Avg east velocity using best-fit polynomial: %.3f [cm/
yr]\n', pE(1)
fprintf ('Avg vertical velocity best-fit polynomial: %.3f [cm/yr]\n
n', pVert(1))
```

```
h = figure;
str=sprintf('North, East and Vertical Displacement Residuals at
Station %s \n', stationName);
subplot (3,1,1)
plot(tDecyear, residualN, 'ob-','MarkerSize',3);
title(str)
xlabel('Time [yr]')
ylabel('N Residuals [cm]', 'FontSize', 7.5)
hold on;
subplot (3,1,2)
plot (tDecyear, residualE,'-or','MarkerSize',3);
xlabel('Time [yr]')
ylabel('E Residuals[cm]','FontSize',7.5)
hold on;
subplot (3,1,3)
plot (tDecyear, residualVert, '-og', 'MarkerSize', 3);
xlabel('Time [yr]')
ylabel('Vert. Residuals[cm]','FontSize',7.5)
```

1.4 Compare the best-fit polynomial

```
[V,map] = imread('VelocityTable_HW8.PNG', 'png');
imshow(V,map)
% ANSWER QUESTION HERE
```

1.5 Process the residuals

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